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Advanced Programming in Prolog

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a.a. 2021/2022

Outline

Previous week:

- The logic programming (and Prolog) paradigm
- Computational model (resolution + unification)
- Basic, idiomatic programming

This week:

- some more advanced programming with Prolog
- other ADTs and libs

Next week:

- meta-programming
- Java/Scala integration with Prolog, by tuProlog

- 1 Building algorithms with Prolog
- 2 Generating combinations and searching space
- 3 The cut predicate
- 4 Inspecting and managing terms
- 5 Algorithms on other ADTs

On building algorithms

Items to discuss

- performance aspects
- tail, non-tail recursions
- immutability and sharing
- generating combinations and searching space of solutions

Progression

- we will start with lists
- then generalize to other ADTs
- meanwhile present libraries
- meanwhile introduce some non-relational construct/predicate

Performance considerations with Prolog

General aspects

- traditionally, Prolog is known for being not “as fast as” C
- professional implementations are actually rather fast
- tuProlog is not fast, for the JVM extra-layer and because it is not a goal of it

Recall our approach to performance

- address the problem only if we have requirements that are not met
- still, we have to know the implications of our programming choices, and choose slower implementations only if they have other good properties, e.g., simplicity, clarity

How can we characterised the performance of a predicate?

- a reasonable approach: in terms of number of resolution steps
- each step requires:
 - ▶ search of matching rule
 - ▶ computation of mgu
 - ▶ update of resolvent under new substitution
- ⇒ might assume it is constant
- ⇒ (it actually depends on the number of rules, of variables, and so on)

The case of built-in lists

The list ADT

- write $[H_1, H_2, \dots, H_n | T]$ instead of $\text{'.'}(H_1, \text{'.'}(H_2, \dots, \text{'.'}(H_n, T) \dots))$
- write $[H_1, H_2, \dots, H_n]$ instead of $[H_1, H_2, \dots, H_n | []]$
- $[H | T]$, $[]$, $[E_1, E_2]$, $[E_1, E_2 | _]$ as example special cases

Functionalities over lists

- all expressed as predicates, used to model I/O behaviour
- the same predicate can often be used both to check properties, extract information, generate lists that match criteria, iterate elements

List predicates in Prolog library

- `member(Element, List)`, similar to our `find/element`
- `append(List1, List2, List)`, similar to our `join`
- `reverse(List, ReversedList)`

Tail recursion, in Prolog

Recall definition of tail recursion

- a recursion is “tail” if the recursive call is the last operation executed before returning

Implication of recursive calls

- with recursive calls, nothing is to be done when the base case is reached, hence computation is done before that, namely, it is done while recurring
- hence, optimisation can (at least in principle) be put in place to avoid the cost of creating activation records for the nested calls
- often (not always), tail recursions are to be achieved by putting extra-arguments in the call, modelling state evolution during recursion

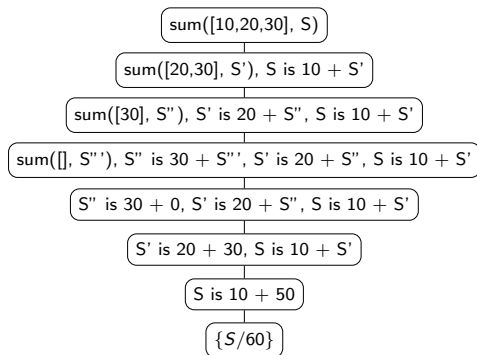
Tail-recursive calls in Prolog

- are featured by the rules where the head predicate occurs only as last goal in the body
- the resolution “chain” is such that computation is done in arguments or substitutions, until the base case is reached
- note that non-tail recursions are often more idiomatic
- Prolog supports tail recursive foldright-like List construction!!

Non-tail recursion with sum/2 (foldleft-like)

```
1 % sum(List,Sum)
2 % relate a List of numbers with the sum of its elements
3 sum([], 0).
4 sum([H|T], N) :- sum(T, N2), N is H + N2.
```

```
1 ?- sum([10,20,30], S). -> S/60
2 ?- sum([], S). -> S/0
3 ?- sum([10,20,30], 60). -> Yes
```



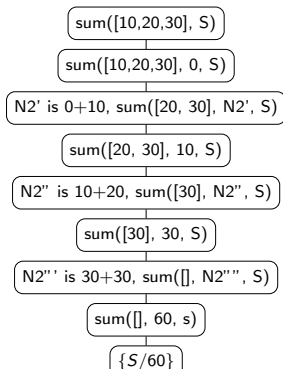
Notes

- the program is quite idiomatic
- computation occurs as recursion is over
- many resolutions steps are needed ($\sim 2 * n$).

Tail recursion with sum/2 (foldleft-like)

```
1 % sum(List,Sum)
2 % relate a List of numbers with the sum of its elements
3 sum(L, S) :- sum(L, 0, S).
4 sum([], S, S).
5 sum([H|T], N, S) :- N2 is H + N, sum(T, N2, S).
```

```
1 ?- sum([10,20,30], S). -> S/60
2 ?- sum([], S). -> S/0
3 ?- sum([10,20,30], 60). -> Yes
```



Notes

- the program is a bit less direct
- computation occurs “during” recursion
- less resolutions steps are needed ($\sim n * 2$).

Tail recursion with join/3 (foldright-like)

```
1 % join(List1, List2, List)
2 % relate List1 and List2 with their concatenation
3 join([], L, L).
4 join([H | T], L, [H | T2]) :- join(T, L, T2).
```

```
1 ?- join([10,20],[30,40,50],L). -> L/[10,20,30,40,50]
```

join([10,20],[30,40,50],L).

join([20],[30,40,50],T2'):{L/[10|T2']}

join([], [30,40,50], T2''):{L/[10|T2'], T2/[20|T2'']}

{L/[10|T2'], T2'/[20|T2''], T2''/[30,40,40]} ≡ {L/[10,20,30,40,50]}

Notes

- foldright-like functions are very easily expressed
- the corresponding recursion is tail!!
- the output list is constructed by $[H|T2]$ unification during recursion
- this is not achieved by FP with immutable structures

Immutability and sharing: update/4

```
1 % update(List1, E1, E2, List2)
2 % relate List1 with a List2 where first occurrence of E1 is updated with
  E2
3 update([], _, _, []).
4 update([E1 | T], E1, E2, [E2 | T]).
5 update([H1 | T1], E1, E2, [H1 | T2]) :- update(T1, E1, E2, T2).
```

```
1 ?- update([10,20,30,40],20,21,L). -> L/[10,21,30,40]
```

update([10,20,30,40],20,21,L)

update([20,30,40],20,21,T2'):{L/[10|T2']}

{L/[10|T2'], T2'/[21|[30,40]]}≡{L/[10,21,30,40]}

Notes

- how is the output list related to the input one?
- Prolog has immutability of data (terms get unified, never modified)
- the output list actually shares [30,40] with the input list

⇒ hence Prolog has intrinsic immutability and sharing of structures

Immutability of Prolog terms

Implication of resolution/unification

- computation happens only by resolution + unification
- hence, data values, which are terms, have no concept of mutability
- terms are just manipulated by unification of:
 - ▶ terms in the resolvent
 - ▶ terms occurring in cloned copies of applied rules

Immutability of terms

- hence, computationally, a term is an entity that never changes
- its subparts could be shared with other terms
- a weak form of side-effect is that by unification a non-ground term could at some point have a variable be “bound” to an actual term

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Full relationality and space-searching

Recall informal definition

- a Prolog predicate is said to be *fully relational* if all its arguments could be handled as either input or output
 - most specifically, when called with a variable in an argument, resolution successfully attempts to iterate over all inputs that would satisfy the predicate
- ⇒ often this property cannot be achieved, especially for complex algorithms

Implication

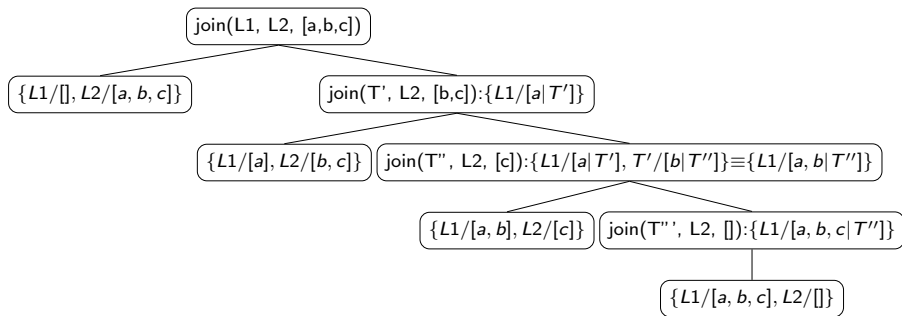
- even if we design a predicate with implicit idea of input arguments and output arguments, a goal could use variables in any place
- so in general we may expect that by resolution Prolog attempts at finding **all** substitutions of variables satisfying the relation
- this could be automatically obtained in simple cases, or should be explicitly programmed in others

Prolog and solution-space searching

- either way, Prolog is a language with inherent ability of well capturing algorithms that need to search solutions in tree-like spaces

Searching solutions with join/3

```
1 % join(List1, List2, List)
2 % relate List1 and List2 with their concatenation
3 join([], L, L).
4 join([H | T], L, [H | T2]) :- join(T, L, T2).
```

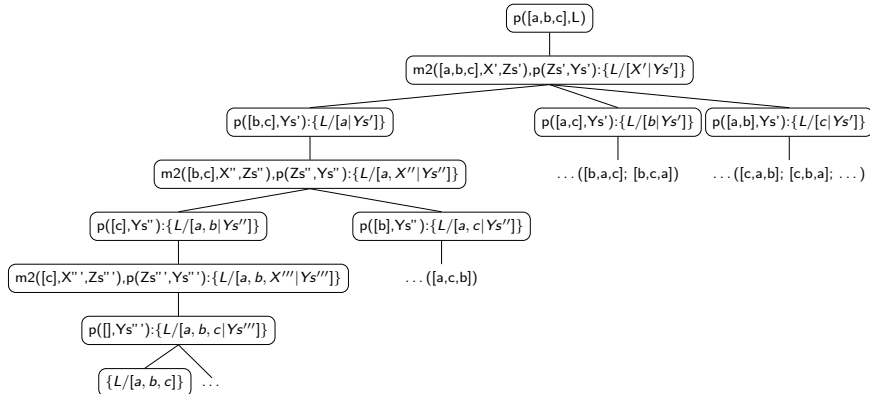


Notes

- we know Prolog will “explore”, since the goal matches multiple rules
- thanks to tail recursion, solutions are created “while exploring”

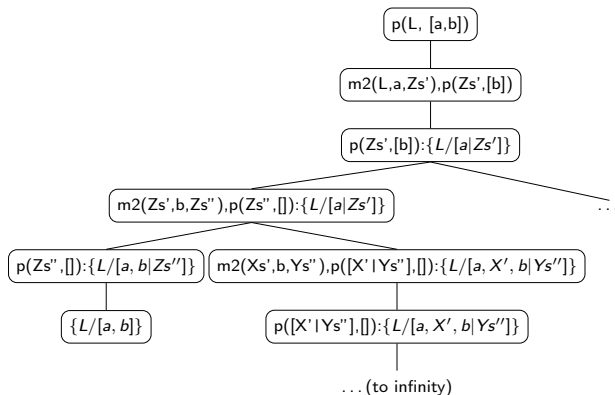
Searching solutions: permutation/2

```
1 % member2(List, Elem, ListWithoutElem)
2 member2([X | Xs], X, Xs).
3 member2([X | Xs], E, [X|Ys]) :- member2(Xs, E, Ys).
4
5 % permutation(Ilist, Olist)
6 permutation([], []).
7 permutation(Xs, [X | Ys]) :- member2(Xs, X, Zs), permutation(Zs, Ys).
```



Full relationality pitfalls: permutation(L, [a,b])?

```
1 % member2(List, Elem, ListWithoutElem)
2 member2([X | Xs], X, Xs).
3 member2([X | Xs], E, [X|Ys]) :- member2(Xs, E, Ys).
4
5 % permutation(Ilist, Olist)
6 permutation([], []).
7 permutation(Xs, [X | Ys]) :- member2(Xs, X, Zs), permutation(Zs, Ys).
```



Pitfalls in searching

In the general case

- Sometimes building fully relational predicates is not very easy
 - ▶ especially with possibly infinite solutions
 - ▶ it is not generally easy to enumerate them all
- This is typically the case when enumeration is not strictly directional
- Example:
 - ▶ checking if a list has elements 10, 20 and 30...
 - ▶ is much easier than enumerating all lists having 10, 20 and 30...

Possible solution in principle

- in certain applications it would still be possible to iteratively extract what needed
- essentially, the idea would be to navigate the resolution tree by breadth-first instead of depth-first strategy
- all solutions would be eventually found, though at very high memory and time costs

Just to be used in documentation: not a Prolog syntax

- Used when describing to a programmer the input/output character of each argument to a predicate
 - ▶ “-” for output elements
 - ▶ “+” for input elements (of any sort)
 - ▶ “@” for input elements that should be ground
 - ▶ “?” for input/output elements
- Not very clear how to handle multi-modalities...

Examples

- `member(?E, ?L).`
- `permutation(+LI, -LO).`
- `append(?L1, ?L2, ?L).`

Exploiting exploration to generate combinations

A general pattern in Prolog

- consider a resolvent G_1, G_2, \dots, G_n
- if G_i gives k_i solutions, and they do not constraint execution of successive goals, then overall we would get $\prod_i k_i$ solutions, obtained by all combinations of solutions of each G_i

```
1 ?- member(X,[10,20,30]), member(Y,[1,2]), Res is X+Y.  
2 --> Res/11;  
3 --> Res/12;  
4 --> Res/21;  
5 --> Res/22;  
6 --> Res/31;  
7 --> Res/32;
```

Composition of goals as sort of for-comprehension

- it recalls very much what for-comprehension and flatMap is about
- what is also called a *monadic computation*
- so in a sense, Prolog computations are always potentially sorts of for-comprehensions

Generating combinations: links in a grid

```
1 interval(A, B, A).
2 interval(A, B, X):- A2 is A+1, A2 < B, interval(A2, B, X).
3
4 neighbour(A, B, A, B2):- B2 is B+1.
5 neighbour(A, B, A, B2):- B2 is B-1.
6 neighbour(A, B, A2, B):- A2 is A+1.
7 neighbour(A, B, A2, B):- A2 is A-1.
8
9 gridlink(N, M, link(X, Y, X2, Y2)):-
10     interval(0, N, X),
11     interval(0, M, Y),
12     neighbour(X, Y, X2, Y2),
13     X2 >= 0, Y2 >= 0, X2 < N, Y2 < M.
```

```
1 ?- gridlink(3,3,L).
2 --> L/link(0,0,0,1);
3 --> L/link(0,0,1,0);
4 ...
5 --> L/link(2,2,2,1);
6 --> L/link(2,2,1,2)
```

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The cut predicate

Limits of resolution

- the pervasive branching nature of Prolog resolution, along with backtracking, are considered one of the “features” of Prolog
- but in certain situations, they are “a bug”
- certain predicates have spurious solutions one wants to neglect
- handling branching situations in certain predicates violate DRY, and can cause performance issues

Controlling the resolution tree

- Prolog offers extra-relation predicates to get / control “how many” or “which” solutions one wants to extract from a goal
- a very important one is called “cut”, performed by 0-ary predicate symbol “!”
- its usage is very frequent, and must be well mastered

Cut motivation: dropping spurious solutions

```
1 % merge(List1,List2,OutList)
2 % merge two sorted lists
3 merge(Xs, [], Xs).
4 merge([], Ys, Ys).
5 merge([X|Xs], [Y|Ys], [X|Zs]) :- X < Y, merge(Xs, [Y | Ys], Zs).
6 merge([X|Xs], [Y|Ys], [Y|Zs]) :- X >= Y, merge([X | Xs], Ys, Zs).
```

```
1 ?- merge([],[],L).
2 --> L/[]; L/[] % two equivalent solutions!
3 ?- merge([10,20],[5,35],L).
4 --> L/[5,10,20,35]; No % a spurious (costly) "No" reply
```

Notes

- both facts could match
- when one of the three tests succeeds, we do not need to check any of the others!
- in general, checking unnecessary conditions could lead to useless (possibly long) computations
- we may want to express a pruning of the Prolog resolution tree!

The cut predicate details

Syntax

- simply a 0-ary “!” predicate defined at the library level, to be used as one of the goals in the body of a rule

Intended meaning

- it causes certain local pending branches to be discarded:
 - ▶ in successive matching clauses
 - ▶ in goals at the left of “!” in current body (if they had other pending solutions)

Precise semantics

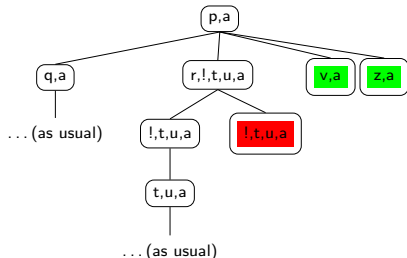
- it is always positively executed, causing a side-effect on the part of the resolution tree yet to be explored
- when a cut is executed, all pending branches below the node that generated the executed cut are “pruned” (i.e., erased away)

What cut prunes

Recall intended meaning

- it causes local pending branches to be discarded:
 - ▶ successive matching clauses (green code below)
 - ▶ pending solutions in goals at the left of “!” in current body (red code below)

```
1 r.  
2 r.  
3 p :- q.  
4 p :- r, !, t, u.  
5 p :- v.  
6 p :- z.
```



Cut motivation: solution of merge/3

```
1 % merge(+List1,+List2,-OutList)
2 % merge two sorted lists
3 merge(Xs, [], Xs) :- !.
4 merge([], Ys Ys).
5 merge([X|Xs], [Y|Ys], [X|Zs]) :- X<Y, !, merge(Xs, [Y|Ys], Zs).
6 merge([X|Xs], [Y|Ys], [Y|Zs]) :- merge([X|Xs], Ys, Zs).
```

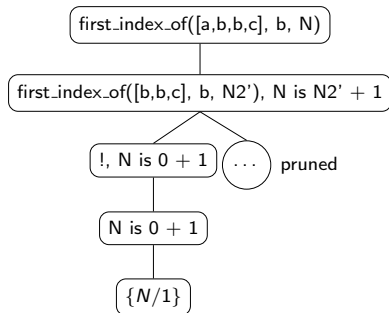
```
1 ?- merge([], [], L).
2 --> L/[]
3 ?- merge([10,20], [5,35], L).
4 --> L/[5,10,20,35]
```

Notes

- the first cut prunes the pending branch of second fact
- the second cut prunes the pending branch of second rule
- note that in second rule we do not need to check \geq again...

Applications: single result in first_index_of/3

```
1 first_index_of([E|_], E, 0) :- !.  
2 first_index_of([_|T], E, N) :- first_index_of(T, E, N2), N is N2 + 1.
```

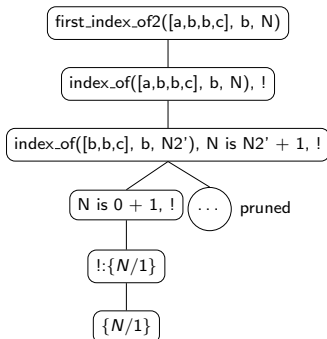


Notes

- as soon as “!, N is 0 + 1” moves to “N is 0 + 1”, all pending branches below “first_index_of([b,b,c]...)” node get pruned
- this causes activation of second clause to be excluded

Applications: alternative approach

```
1 index_of([E|_], E, 0).  
2 index_of([_|T], E, N) :- index_of(T, E, N2), N is N2 + 1.  
3 first_index_of2(L, E, N) :- index_of(L, E, N), !.
```



Notes

- as soon as `!:{N/1}` moves to `{N/1}`, all pending branches below `index_of([b,b,c], N2', b), ...` node get pruned
- this causes additional solutions of `index_of([a,b,b,c], b, N)` to be excluded

Another example: quicksort

```
1 % quicksort(Ilist,Olist)
2 quicksort([], []).
3 quicksort([X | Xs], Ys):-
4     partition(Xs, X, Ls, Bs),
5     quicksort(Ls, L0s),
6     quicksort(Bs, B0s),
7     append(L0s, [X | B0s], Ys).
8
9 % partition (Ilist,Pivot,Littles,Bigs)
10 partition([], _, [], []).
11 partition([X | Xs], Y, [X | Ls], Bs):- X<Y, !, partition(Xs, Y, Ls, Bs).
12 partition([X | Xs], Y, Ls, [X | Bs]):- partition(Xs, Y, Ls, Bs).
```

```
1 ?- partition([10,3,20,5,30,9,40], 10, L1, L2).
2 --> L1/[3,5,9], L2/[10,20,30,40]
3 ?- quicksort([60,10,20,50,30,40],L).
4 --> L/[10,20,30,40,50,60]
```

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Library predicates to deal with terms

Managing terms by unification

- so far unification is our only mean to manage terms
- it has been used to inspect terms (to process “input”) and to create new terms (to produce “output”)
- often, additional expressiveness is needed, though somewhat “extra-relational”, as cut

Usual predicates/operators

- inspect shape of a term: `var/1`, `nonvar/1`, `number/1`, `float/1`, `integer/1`, `atom/1`, `compound`, `ground`
- comparison: `=/2`, `\=/2`, `==/2`, `=\=/2`, `copy_term/2`
- terms as strings: `atom_chars/2`, `atom_codes/2`, `atom_concat/2`, `char_code/2`, `number_chars/2`, `number_codes`
- term structure: `=../2`, `functor/2`, `arg/3`
- I/O over file/console: `write/1`, `nl/0`, ...

Some additional documentation:

- <https://github.com/tuProlog/2p-kt-presentation/releases/tag/1.2.0-2021-06-28T100324> (2p-kt slides)
- <https://github.com/tuProlog/2p-kt/wiki/Prolog-ISO-Standard> (prolog ISO)
- <https://gitlab.com/pika-lab/tuprolog/2p/-/wikis/Releases> (tuprolog-guide-3.3.0)

Inspecting terms

```
1 ?- atom(a).      -> yes
2 ?- atom(10).     -> no
3 ?- atom(a(1)).   -> no
4
5 ?- var(X).       -> yes
6 ?- var(a).       -> no
7 ?- nonvar(X).    -> no
8
9 ?- number(10).   -> yes
10 ?- float(10.1). -> yes
11 ?- integer(10.1). -> no
12
13 ?- compound(10). -> no
14 ?- compound(a).  -> no
15 ?- compound(a(10,20)). -> yes
16 ?- ground(a(10,20)). -> yes
17 ?- ground(a(10,X)). -> no
```

Applications

- typically, to check correctness of inputs

Term comparison

```
1 % unification
2 ?- a(10,b) = a(10,b).   -> yes
3 ?- a(X,b) = a(10,b).    -> yes X/10
4 ?- a(X,b) = a(Y,c).     -> no
5
6 % non-unification (note it never binds)
7 ?- a(10,b) \= a(10,b).  -> no
8 ?- a(X,b) \= a(10,b).   -> no
9 ?- a(X,b) \= a(Y, c).   -> yes
10
11 % equality
12 ?- a(10,b) == a(10,b).  -> yes
13 ?- a(X,b) == a(10,b).   -> no
14 ?- a(X,b) == a(X,b).    -> yes
15
16 % inequality
17 ?- a(10,b) =\= a(10,b). -> no
18 ?- a(X,b) =\= a(10,b).  -> yes
19 ?- a(X,b) =\= a(X,b).   -> no
20
21 % cloning/check-cloning
22 ?- copy_term(a(10,X), Y).      -> yes, Y/a(10,X1)
23 ?- copy_term(a(10,X), a(10,Y)). -> yes
24 ?- copy_term(a(10,X), a(10,X)). -> yes
25 ?- copy_term(a(10,X), a(11,X)). -> no
```

Applications

- to more flexibly handle/compare inputs

Terms as strings

```
1 % atoms to/from sequence of one-char atoms
2 ?- atom_chars(hello,L). -> L/[h,e,l,l,o]
3 ?- atom_chars(X,[h,e,l,l,o]). -> X/hello
4
5 % atoms to/from sequence of ascii codes
6 ?- atom_codes(hello,L). -> L/[104,101,108,108,111]
7 ?- atom_codes(X,[95,48,32,49]). -> X='_0 1'
8 ?- atom('_0 1'). -> yes
9
10 % concatenation
11 ?- atom_concat(aa,bb,X). -> X/aabb
12
13 % numbers vs chars/codes
14 ?- number_chars(100,X). -> X/['1','0','0']
15 ?- number_codes(100,X). -> X/[49,48,48]
```

Applications

- to manipulate numbers/atom/strings, computationally

Compound terms (de)structuring

```
1 % compound term to list
2 ?- p(10,q(20)) =.. L. -> L/[p,10,q(20)]
3 ?- X =.. [p,10,q(20)]. -> X/p(10,q(20))
4
5 % direct extraction/construction
6 ?- functor(p(10,20,30),X,Y). -> X/p, Y/3
7 ?- functor(T,p,3). -> T/p(_,_,_ )
8 ?- arg(2, p(10,20,30),Y). -> Y/20
```

Applications

- to manipulate compound terms, computationally

I/O over console

Expressiveness

- can redirect standard input/output (is to console by default)
- have predicates to write terms as strings (`write/1`, `nl/0`)
- have predicates to read
- we just see usage for “debugging by logging strings”

```
1 sum([], 0).  
2 sum([H|T], N) :- sum(T, N2), write(N2), nl, N is H + N2.  
3 ?- write('start'),nl,sum([10,20,30],N).
```

Console

```
1 start  
2 0  
3 30  
4 50
```

Few examples

```
1 % all(+Term,+List): are all elements in List of kind Term?
2 all(_, []).
3 all(X, [Y | T]):- copy_term(X, Y), all(X, T).
4
5 % fully-relational size
6 size(L, N) :- var(L), !, generate(L, N).
7 size(L, N) :- length(L, N).
8
9 generate([], 0) :- !.
10 generate([_|T], N) :- N2 is N-1, generate(T,N2).
11
12 length([], 0).
13 length([_|T], N) :- length(T, N2), N is N2 + 1.
```

```
1 ?- all(p(X), [p(a), p(b), p(a)]). --> yes
2
3 ?- size([10,20,30], N). --> N/3
4 ?- size(L, 3). --> L/[_,_,_]
```

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DB-like structures

The case of DB table operations

- a table of a DB is simply modelled as a list of compound terms
- select, insert, update are managed as expected
- of course performance can be an issue

```
1 % get_ids(+Table,-List)
2 % gets the List of ids from the Table
3 get_ids([], []).
4 get_ids([user(ID, _, _) | T], [ID | L]) :- get_ids(T, L).
5
6 % query(+Table,+Id,-Tuple)
7 % gets the Tuple with Id from the Table
8 query([user(ID, N, C) | _], ID, user(ID, N, C)).
9 query([_ | T], ID, Tuple):- query(T, ID, Tuple).
10
11 % update(+Table,+Id,+NewTuple,-NewTable)
12 % updates the tuple with Id to Tuple
13 update([user(ID, _, _) | T], ID, Tuple, [Tuple | T]).
14 update([H | T], ID, Tuple, [H | Table]):-update(T, ID, Tuple, Table).
```

```
1 ?- update([user(100,a,b), user(101,c,d)], 101, user(101,c,e), DB).
2 -> DB/[user(100,a,b), user(101,c,e)]
```

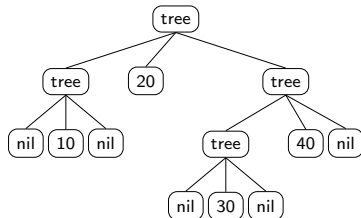

Binary trees: searching elements

Again, a natural modelling

- using functors `tree/3` and `nil/0`
- introducing (relational) operations to find elements

```
1 % search(+Tree, + Elem), relates a tree with any of its elements
2 search(tree(_, E, _), E).
3 search(tree(L, _, _), E) :- search(L, E).
4 search(tree(_, _, R), E) :- search(R, E).
```

```
1 ?- search( tree(tree(nil, 10, nil), 20, tree(tree(nil, 30, nil),
      40, nil)), E ).
2 --> E/20; E/10; E/40; E/30
```



Binary trees: other operations

```
1 % leaves(+Tree,-ListLeaves), returns the list of leaves
2 leaves(nil, []).           % handling void tree
3 leaves(tree(nil, E, nil), [E]) :- !. % handling a leaf
4 leaves(tree(L, _, R), O) :- % general case
5     leaves(L, OL),          % OL are leaves on left
6     leaves(R, OR),          % OR are leaves on right
7     append(OL, OR, O).      % O appends the two
8
9 % leftlist(+Tree,-List), returns the left-most branch as a list
10 leftlist(nil, []).
11 leftlist(tree(nil, E, _), [E]) :- !.
12 leftlist(tree(T, E, _), [E | L]) :- leftlist(T, L).
```

```
1 ?- leaves( tree(tree(nil, 10, nil), 20, tree(tree(nil, 30, nil),
2     40, nil)), L).
3 --> L/[30,40]
4 ?- leftlist( tree(tree(nil, 10, nil), 20, tree(tree(nil, 30, nil),
5     40, nil)), L).
6 --> L/[20,10]
```

N-ary trees with lists

Again, a natural modelling

- using functors `tree/2`, with node on first arg, and list of sons in second

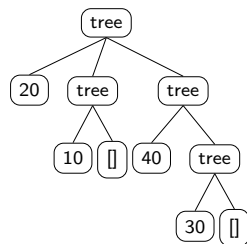
```
1 % searchN(+Tree,?Elem), search Elem in Tree
```

```
2 searchN(tree(E,_), E).
```

```
3 searchN(tree(_,L),E):- member(T, L), search(T, E).
```

```
1 ?- searchN( tree(20, [tree(10, []), tree(40, [tree(30, [])])]), E).
```

```
2 --> E/20; E/10; E/40; E/30
```



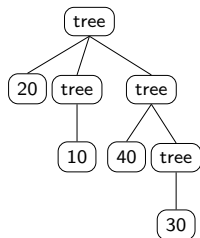
N-ary trees with variable arguments

Modelling

- using functors `tree/1`, `tree/2`, `tree/3`, with node on first arg, and others as sons

```
1 % searchV(+Tree,?Elem), search Elem in Tree
2 searchV(T, E) :- T =.. [tree, E | _].
3 searchV(T, E) :- T =.. [tree, _ | L], member(T2, L), searchV(T2, E).
```

```
1 ?- searchV( tree(20, tree(10), tree(40, tree(30))), E).
2 --> E/20; E/10; E/40; E/30
```



Bidirectional lists

Design sketch

- constant time to move next/prev on the list
- idea: list (1,2,3,4,5,6) modelled by term `bilist([1],[2,3,4,5,6])`
- i.e.: two lists, one from pointer to left, one from pointer to right

Sequence of operations:

- start: `bilist([1],[2,3,4,5,6])`
- move right: `bilist([2,1],[3,4,5,6])`
- move left: `bilist([1],[2,3,4,5,6])`
- `addleft(0)`: `bilist([0],[1,2,3,4,5,6])`
- `addright(10)`: `bilist([0],[10,1,2,3,4,5,6])`

Dynamically expanding lists

Lazy structures in Prolog

- non-ground compound terms can be seen as data structures partially completed
- e.g.: `[1,2,3|_]` is a list starting with 1,2,3, and which we can be completed in several ways
- as a concept, could it be used to model lazy lists?

An example application: an expanding cache for factorials

- `factorial(+N,-Out,?Cache)`
- cache is a partial list of known factorials “up to a point”, e.g.: `[1,1,2,6,24|_]`
- each call might expand the cache, which is both input and output

Dynamically expanding lists: code

```
1 % factorial(+N,-Out,?Cache)
2 % cache is a partial list of factorials [1,1,2,6,24|_]
3 factorial(N, Out, Cache) :- factorial(N, Out, Cache, 0).
4
5 factorial(N, Res, [Res|_], N) :- !, nonvar(Res).
6
7 factorial(N, Out, [H, V | T], I) :-
8     var(V), !, I2 is I + 1, V is H * I2,
9     factorial(N, Out, [V | T], I2).
10
11 factorial(N, Out, [_ , V | T], I) :-
12     I2 is I + 1, factorial(N, Out, [ V | T ], I2).
```

```
1 ?- C = [1,1,2,6|_], factorial(5, Res, C).
2 -> Res/120, C/[1,1,2,6,24,120|_]
```