Sistemi Operativi

Corso di Laurea in Informatica a.a. 2020-2021

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Where Are We?

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 - Processes and Threads
 - CPU Scheduling
 - Synchronization and Deadlock

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 - CPU Scheduling
 - Synchronization and Deadlock
- Today, we will be talking about:
 - Memory Management
- ... Later on:
 - File Systems and I/O Storage
 - Distributed Systems (?)

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- Guarantee isolation between processes
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- Provide a convenient abstraction to the programmer
 - illusion of unlimited amount of memory

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NOTE: In case of purely-interpreted language implementations, translation from source code to executable is done "on-the-fly" by the loaded interpreter

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- 3. Fetch instruction at address 136
- 4. Execute instruction: addition (no memory reference)
- 5. Fetch instruction at address 144
- 6. Execute instruction: store to address [%R2] (1234)

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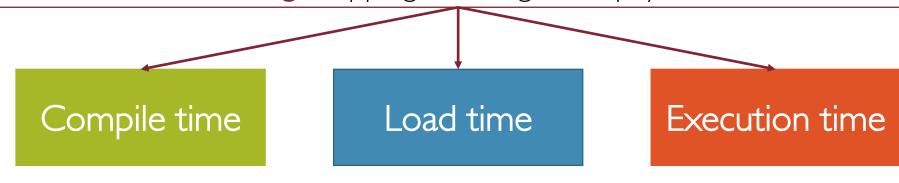


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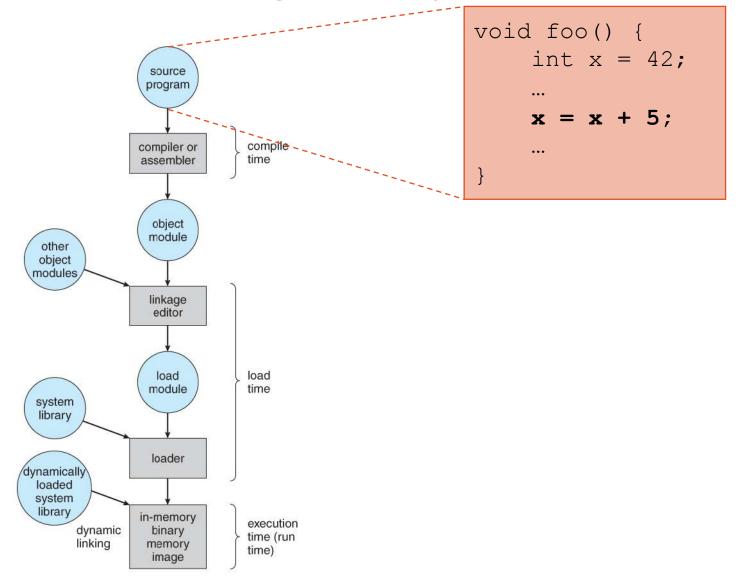
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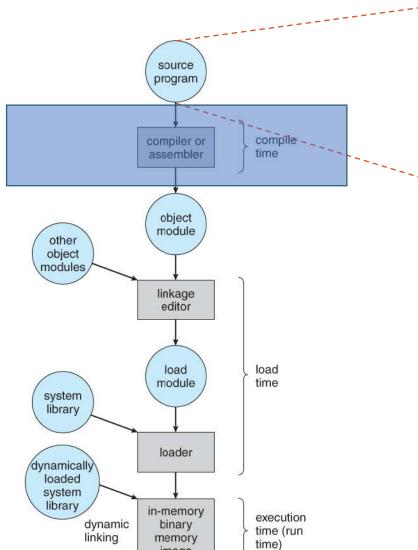
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The program must be recompiled!



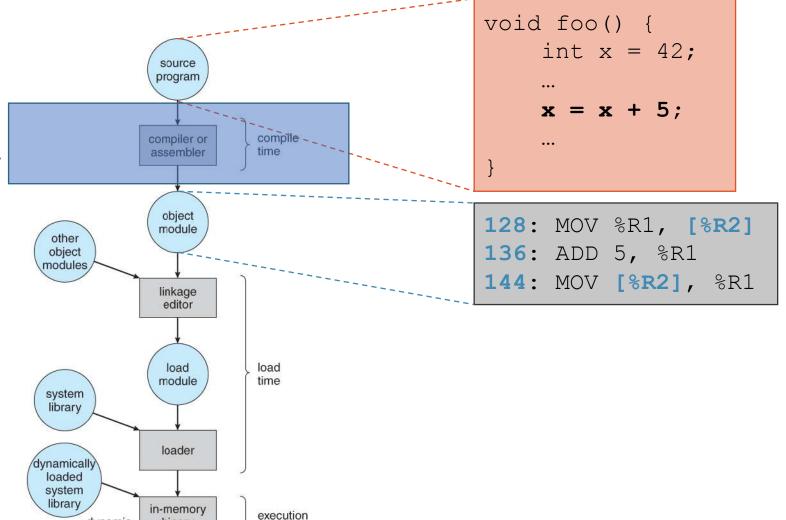
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dynamic

linking

binary

memory

image

time (run

time)

linkage editor

load

module

loader

in-memory

binary

memory

image

system

dynamically loaded system library

dynamic

load

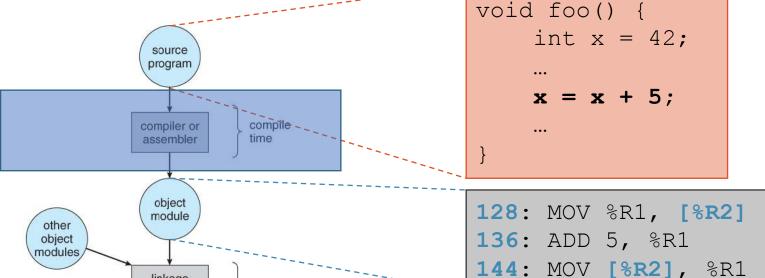
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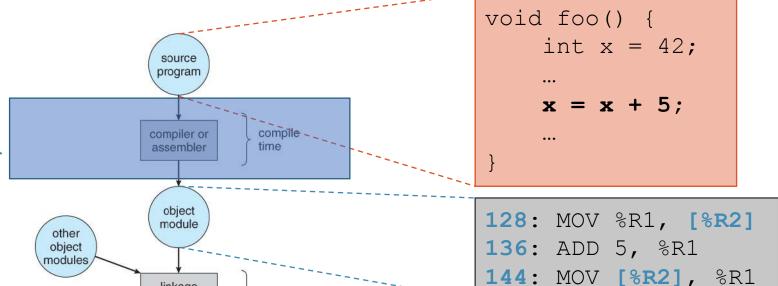
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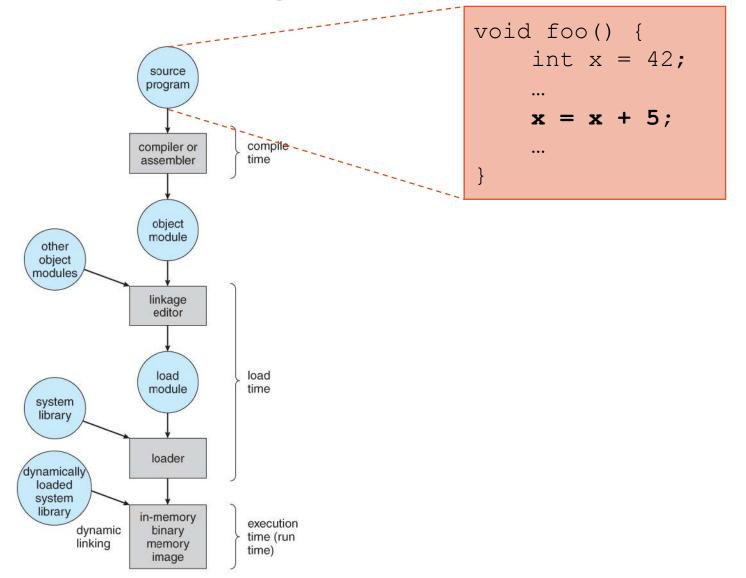
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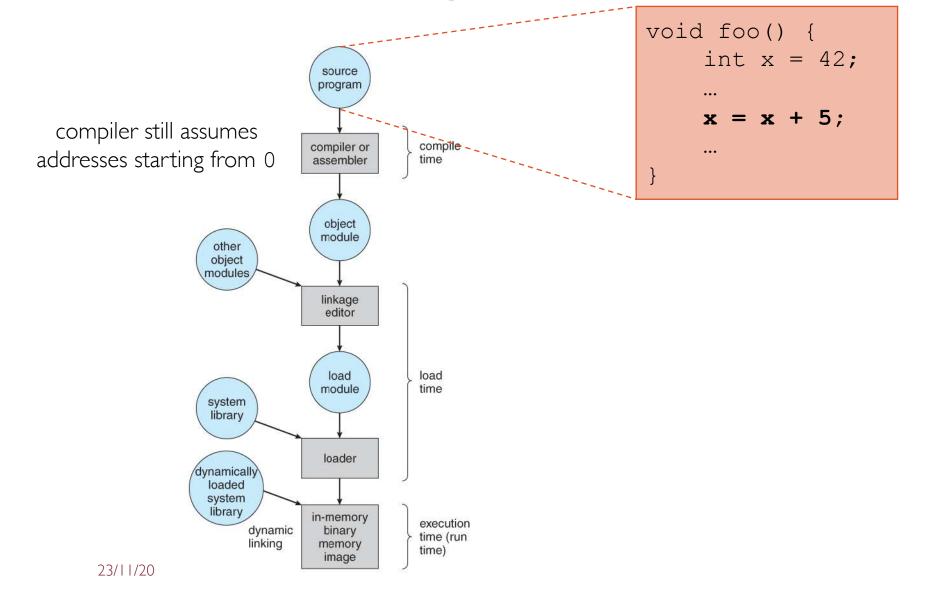
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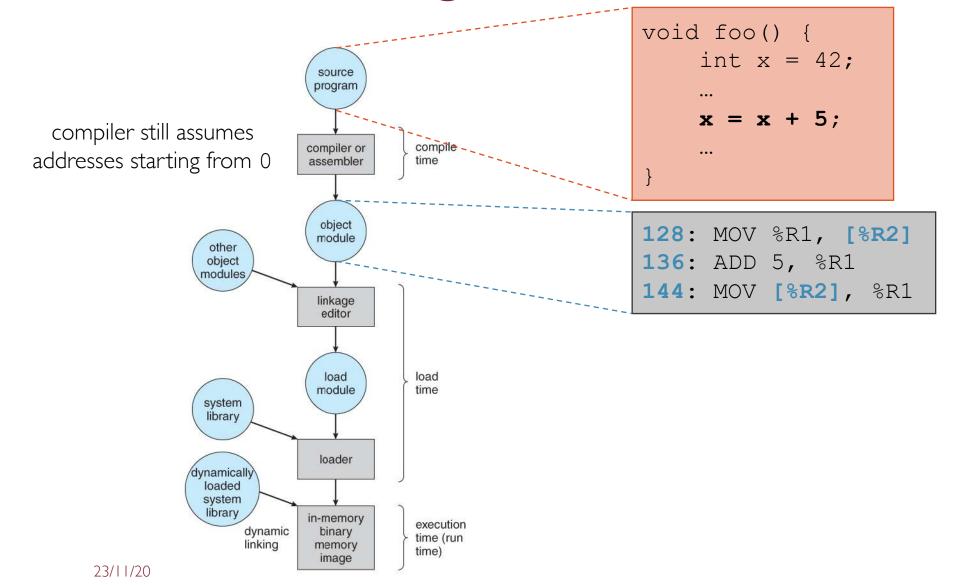
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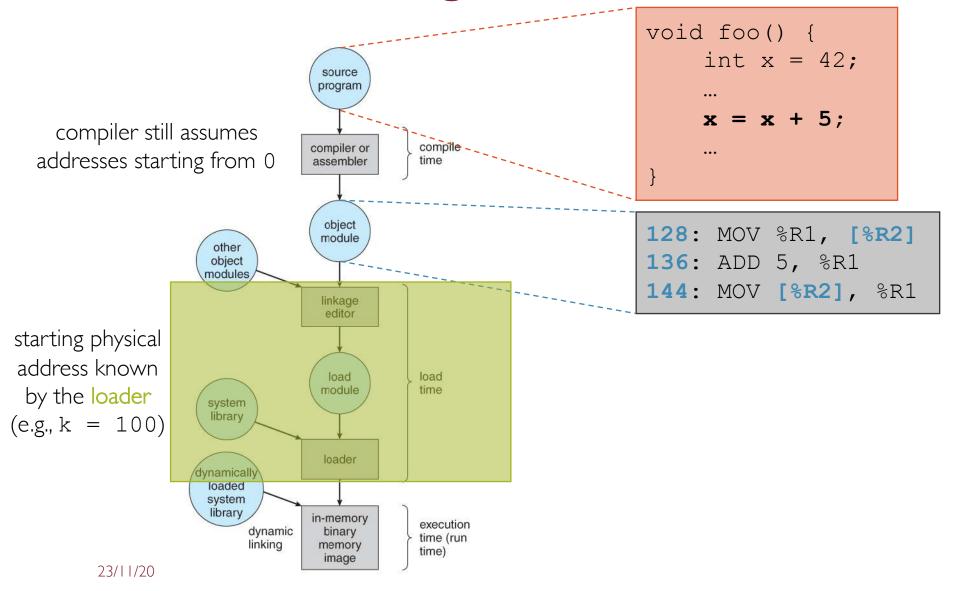


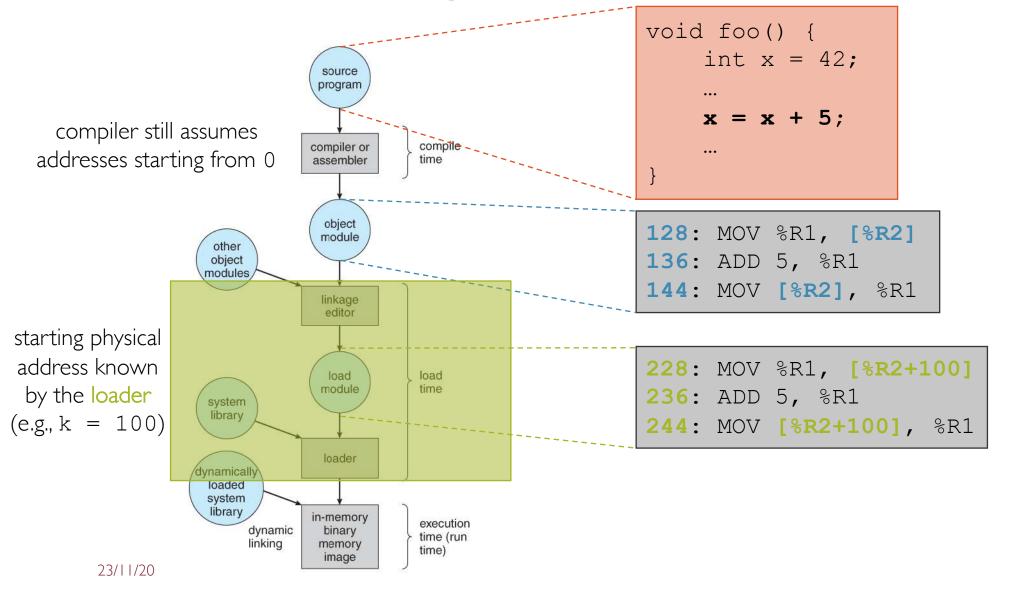


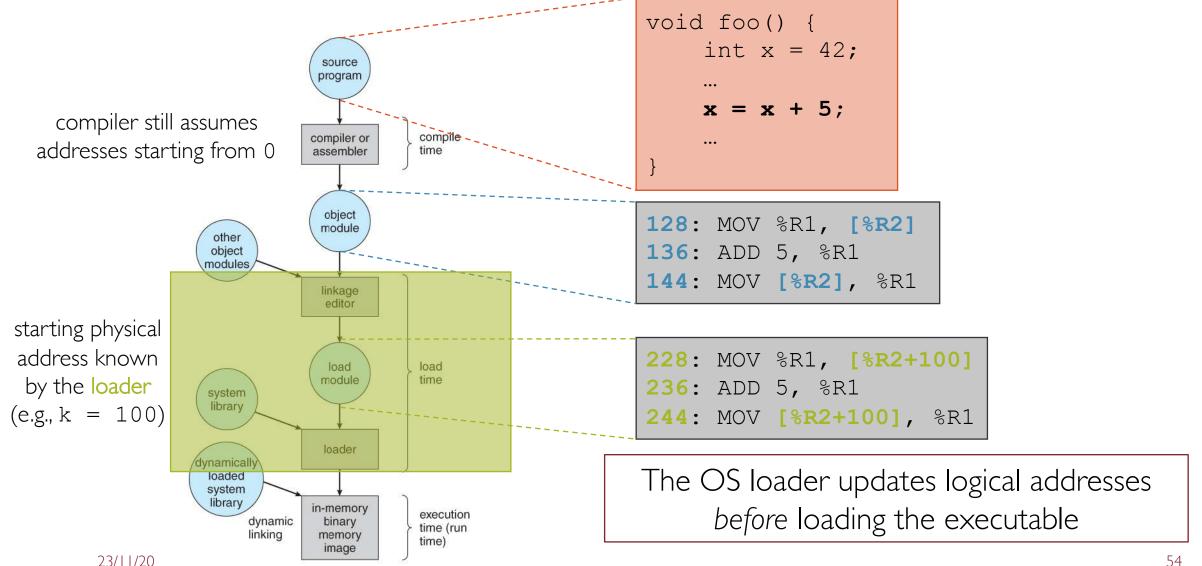
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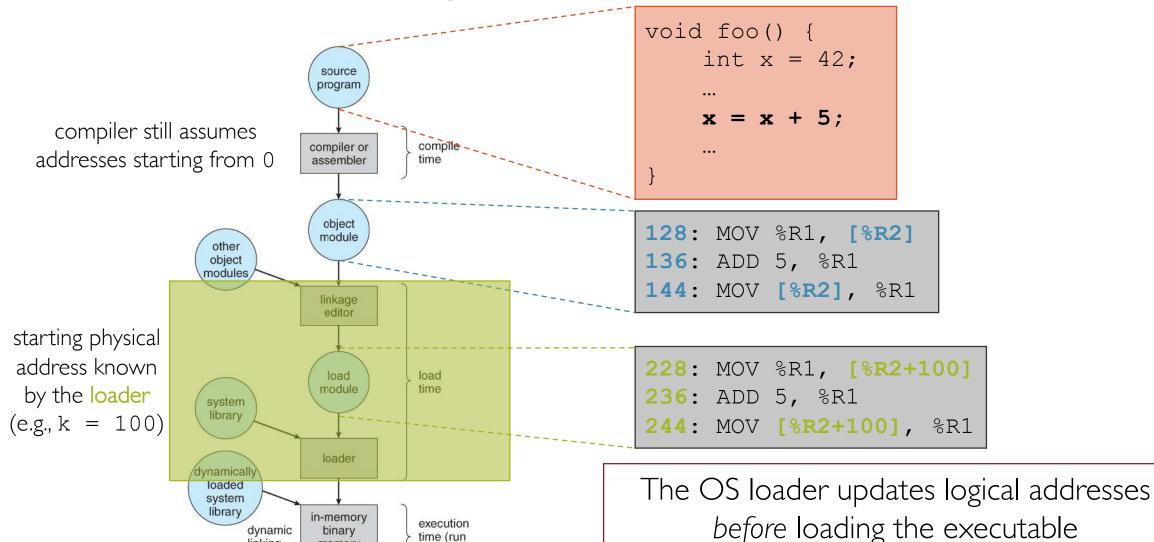


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time (run

time)

memory

image

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physical addresses == logical addresses

• If the program can be moved around in main memory during its execution

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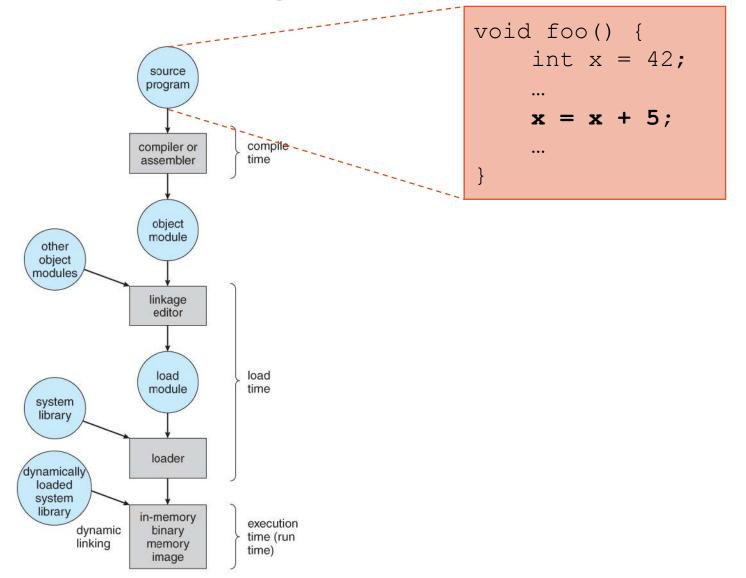
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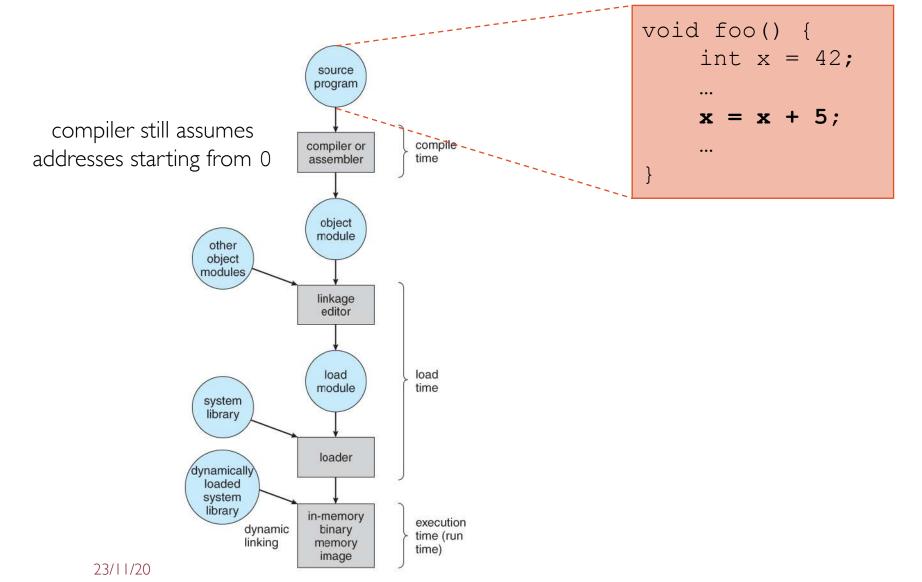
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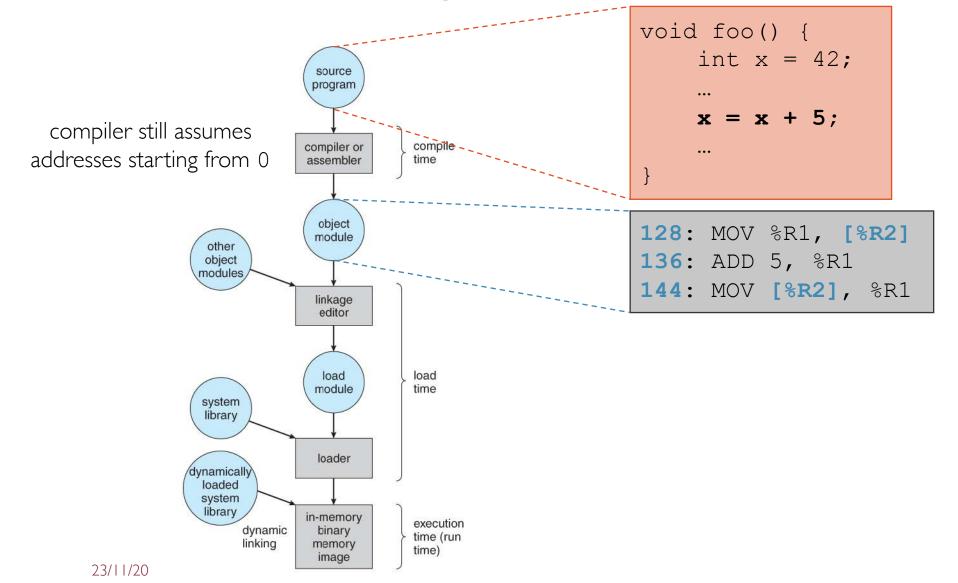
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Most flexible solution implemented by the majority of modern OSs

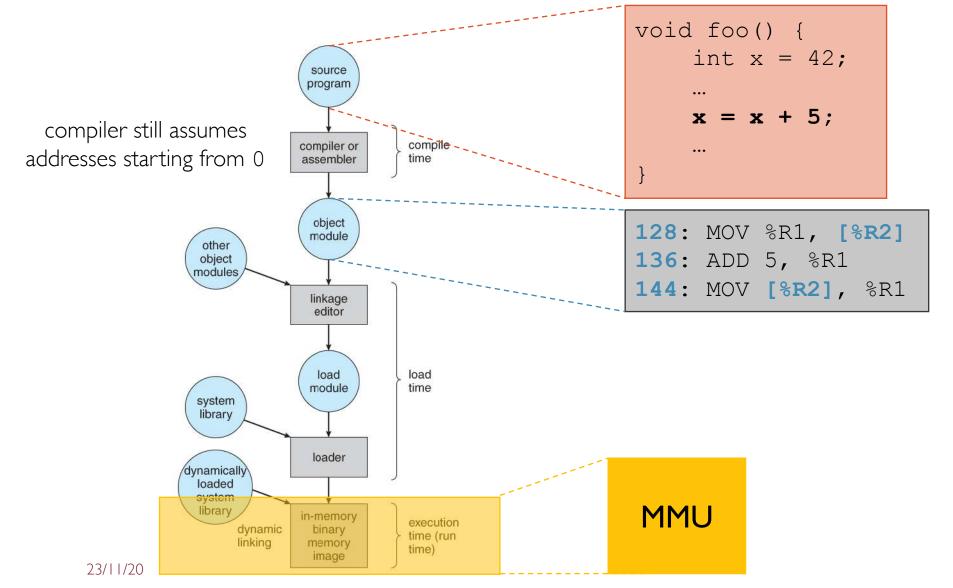


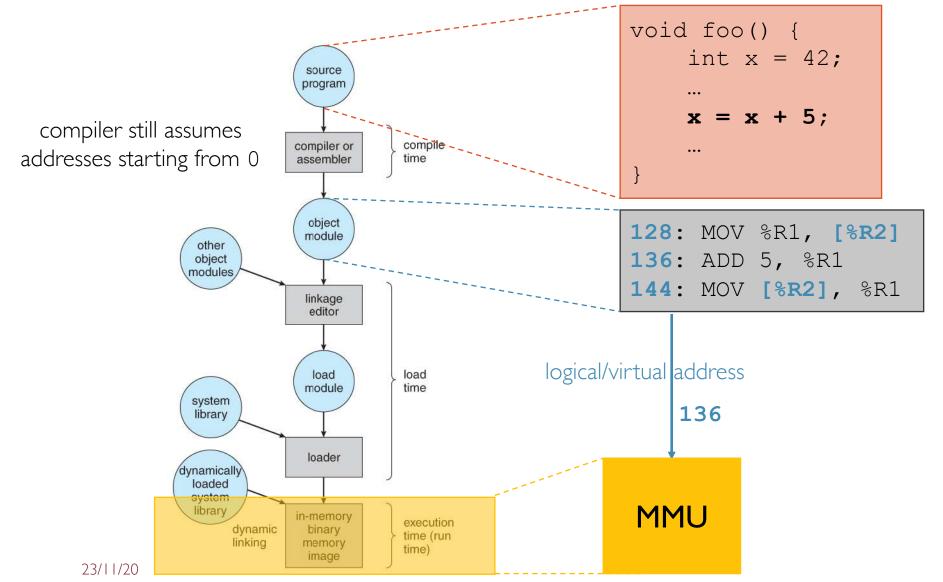


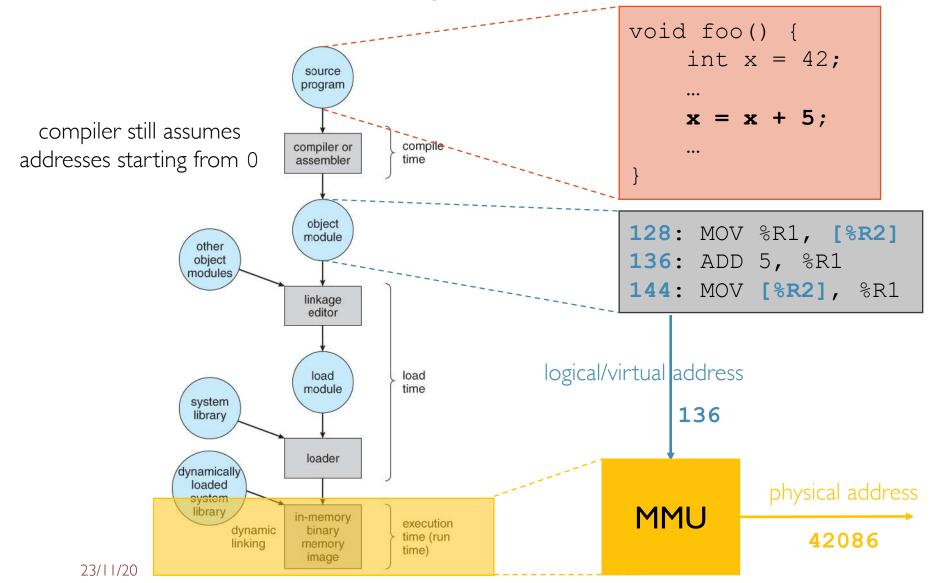
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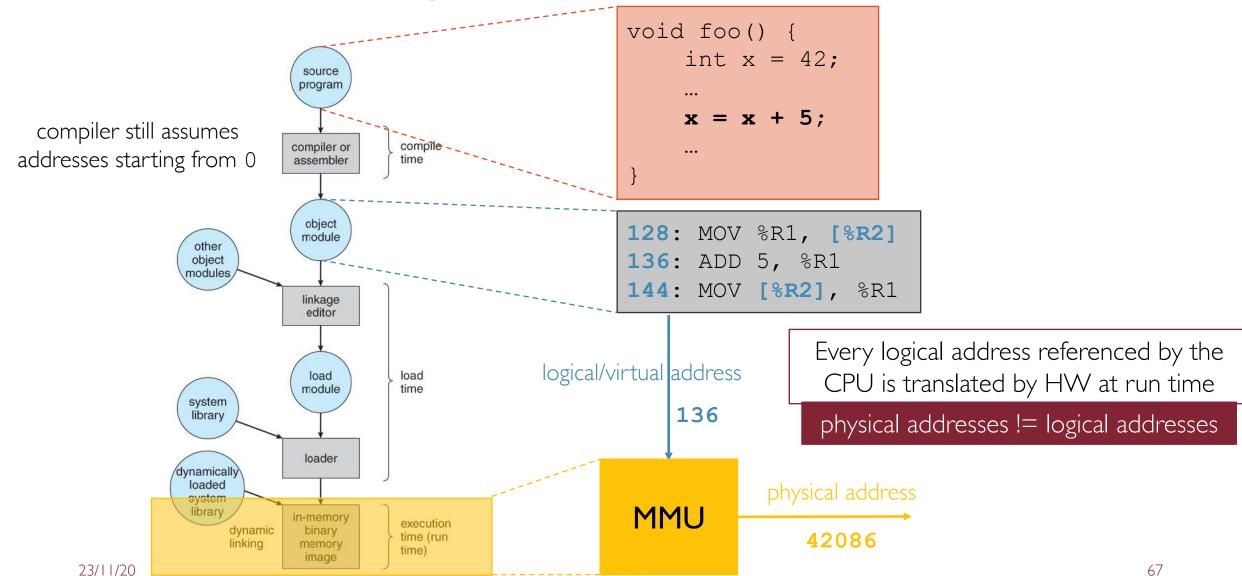


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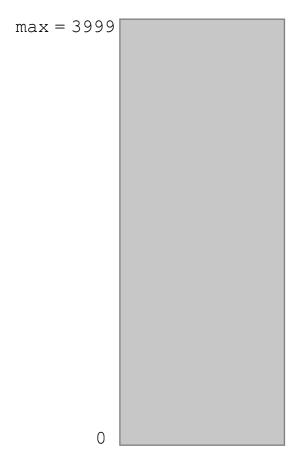
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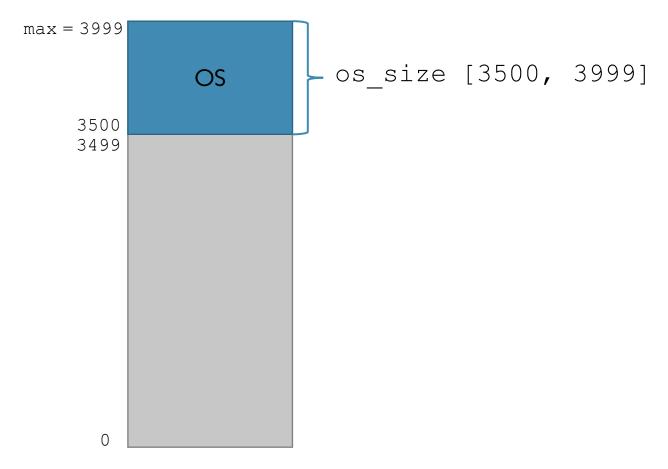
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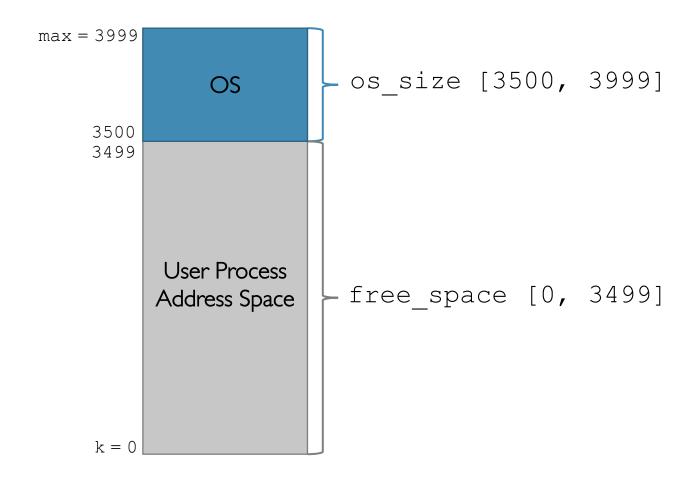
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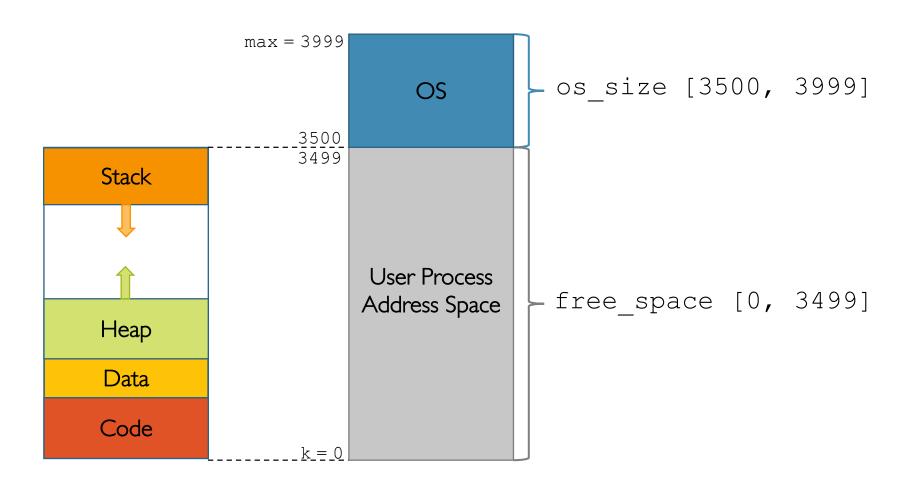


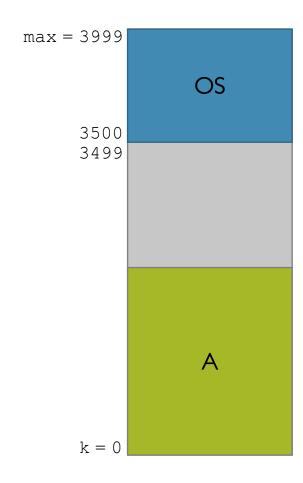
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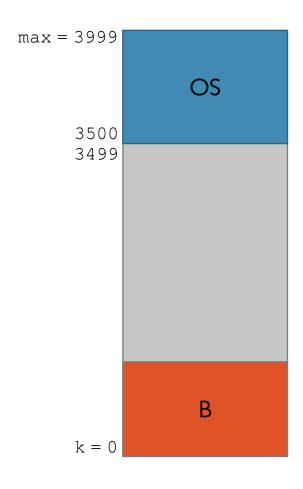
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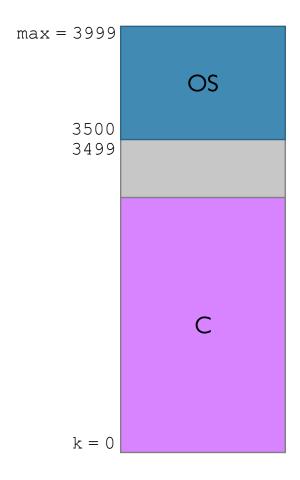
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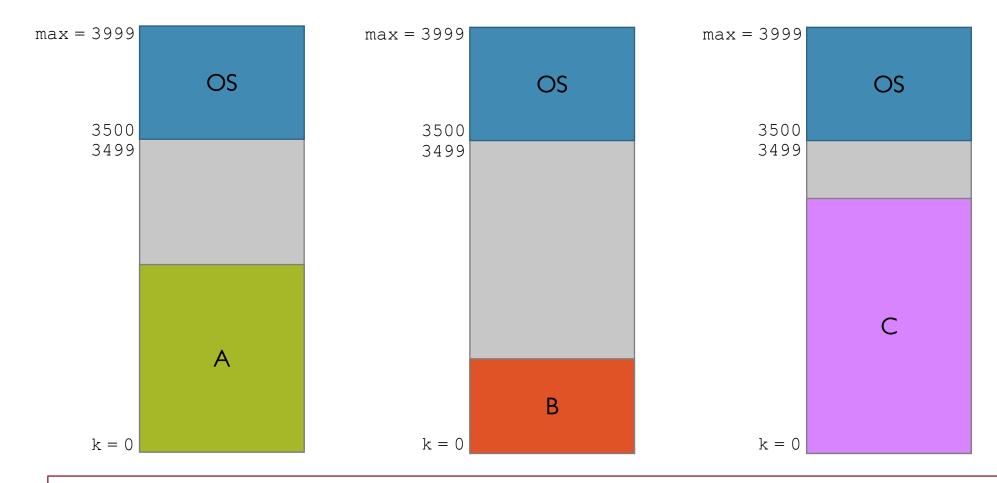




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Very simple! But only one process executes at a time and no OS protection

Manage Multiprogramming Memory: Goals (1)

Sharing

- Several processes coexist in main memory at the same time
- Cooperating processes can share portions of address space

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Transparency

- Processes should not be aware that memory is shared
- Processes should not be aware of which portions of physical memory they are assigned to

Manage Multiprogramming Memory: Goals (11)

Protection/Security

- Processes must not be able to corrupt each other or the OS
- Processes must not be able to read data of other processes

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Efficiency

- CPU and memory performance should not degrade badly due to sharing
- Keep memory fragmentation low

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- Allow transparent sharing of memory: each process' address space may be placed anywhere in memory

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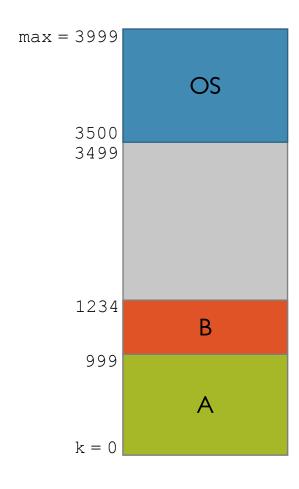
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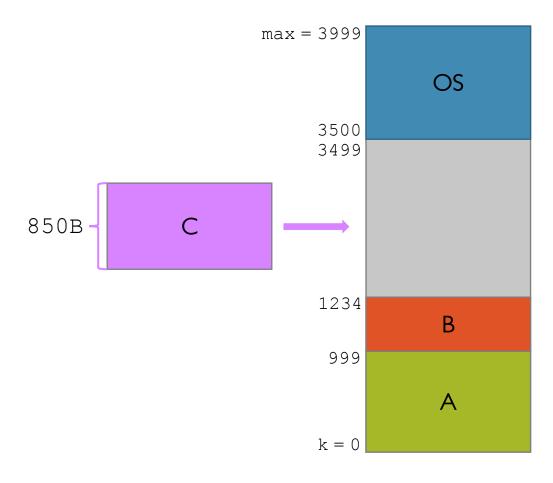
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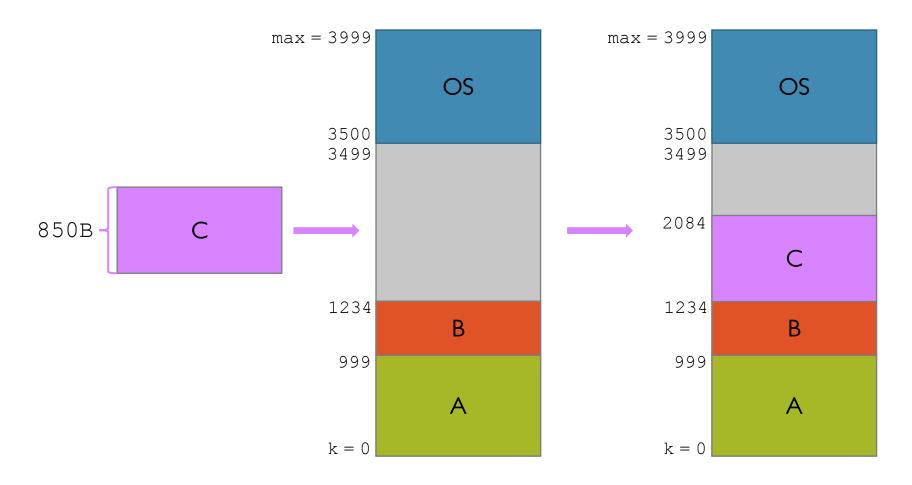
CONs:

- No protection/privacy -> processes can corrupt the OS or other processes
- Address space must be allocated contiguously

 assuming worst-case stack and heap request
- The OS cannot move a process (address space) once allocated in memory







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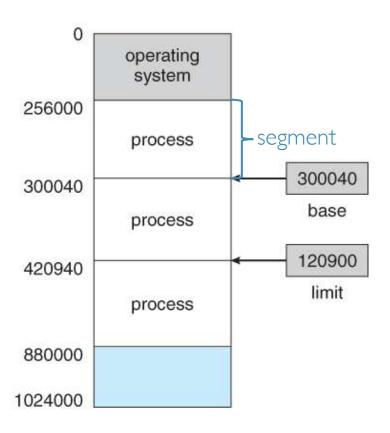
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 - base → start physical memory location of address space
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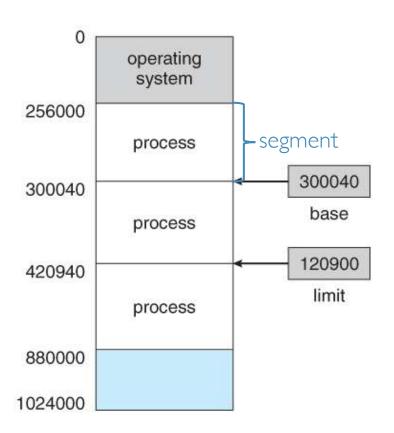
- MMU contains at least 2 registers:
 - base → start physical memory location of address space
 - limit → size limit of address space
- CPU supports at least 2 operating modes:
 - privileged (kernel) mode when the OS is running
 - after issuing any trap (system call, interruption, or exception)
 - when manipulating sensitive resources (e.g., the content of MMU registers)
 - user mode when user process is running
 - while executing process instructions on the CPU

Base and Limit Registers: Idea



Each process is given a contiguous segment of main memory when loaded

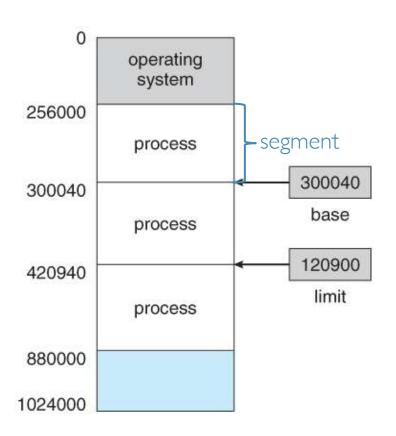
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Protection implemented using two MMU registers: base and limit

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mode MMU limit base

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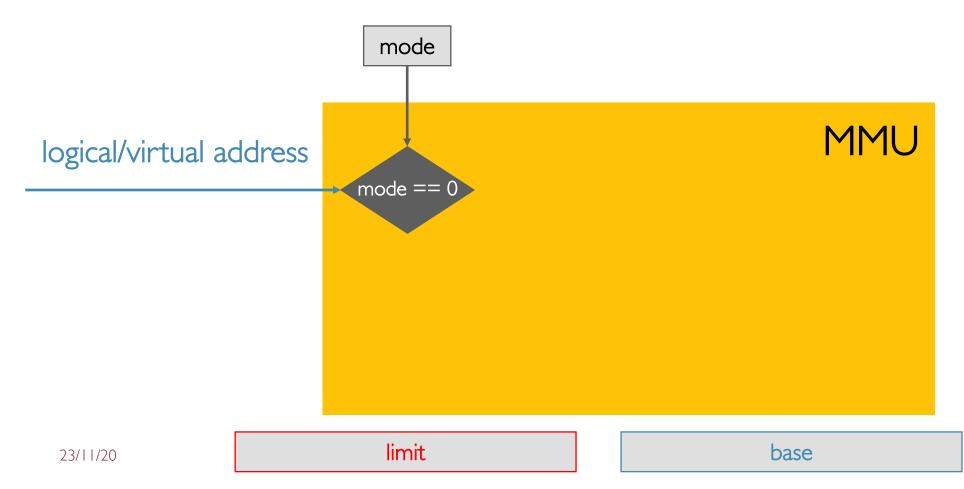
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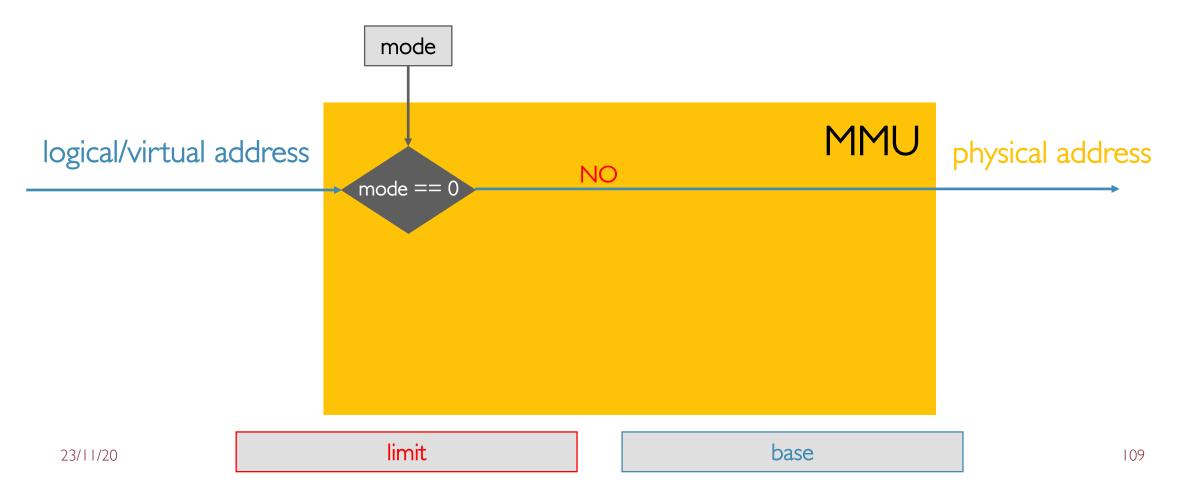
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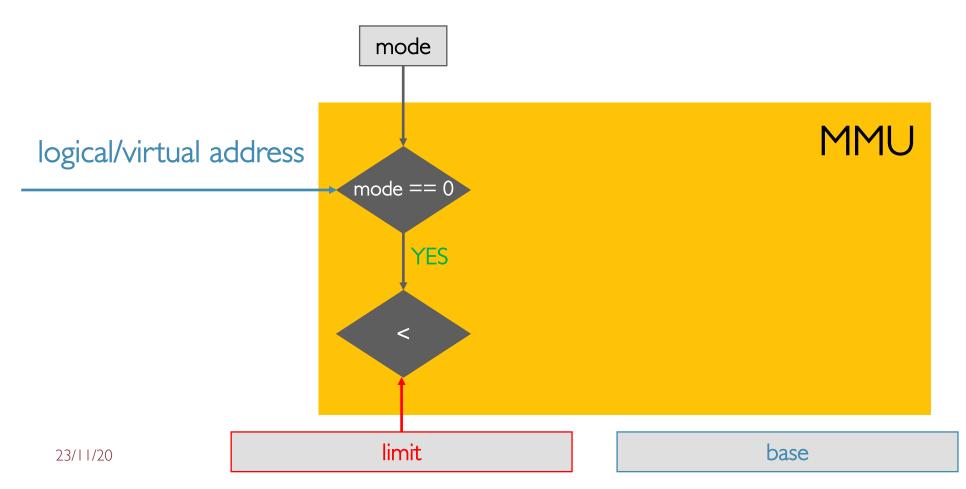
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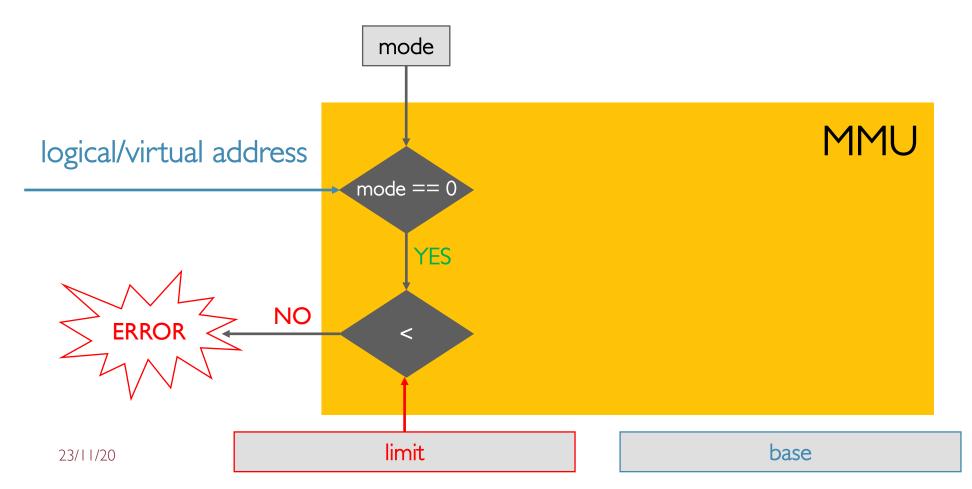


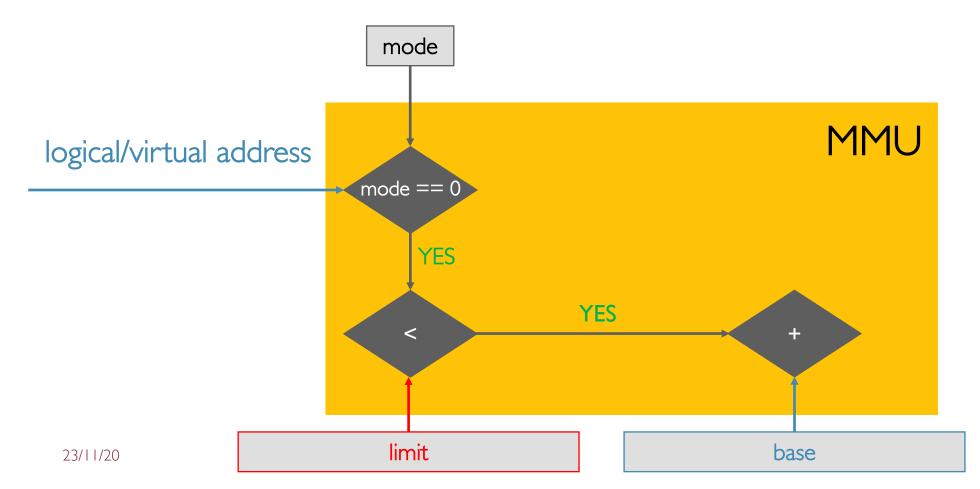


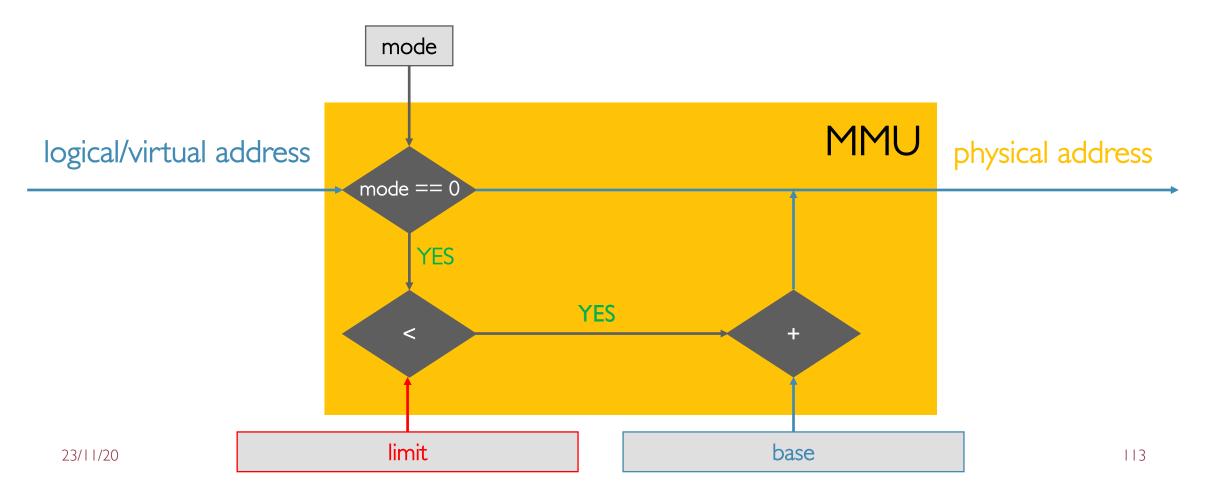
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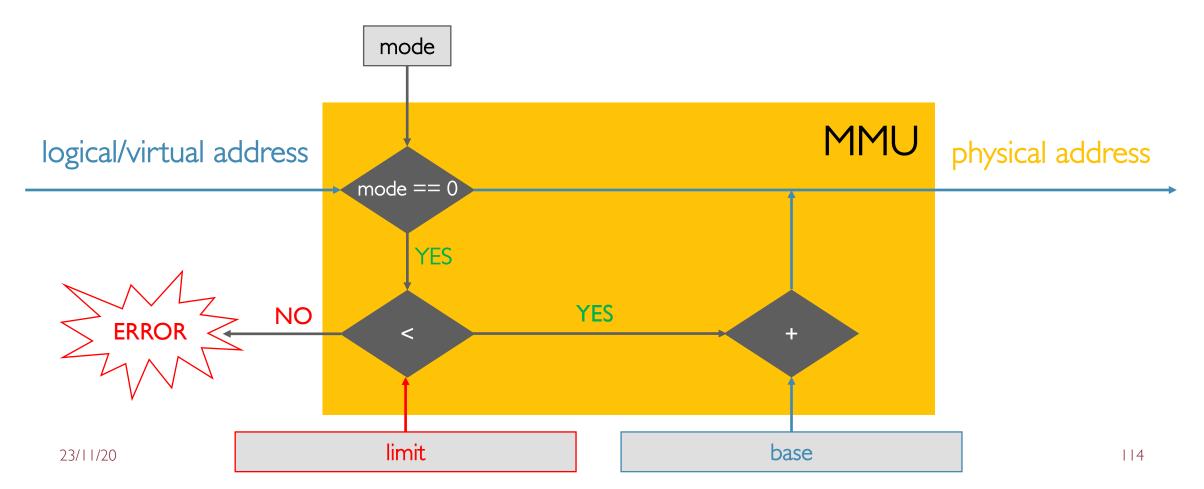
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Dynamic Relocation

PROs:

- Provides protection (both read and write) across address spaces
- OS can easily move a process during execution
- OS can allow process to dynamically grow over time
- Simple, fast hardware implementation (MMU):
 - 2 special registers, one add and one compare operation (done in parallel)

Dynamic Relocation

CONs:

- Little hardware overhead to pay at each memory reference
- Each process must still be allocated contiguously in physical memory (possible memory waste)
- Process is still limited to physical memory size
- Degree of multiprogramming is bound since all memory of all active processes must fit in memory
- No partial sharing of address space (e.g., processes can't share program's text)

Relocation: Properties

- Sharing/Transparency -> processes are unaware of sharing memory
- Protection/Security

 each memory reference is checked in HW
- Efficiency → somewhat achieved but if a process grows it may need to be moved to other location (very slow)

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Dynamic Relocation

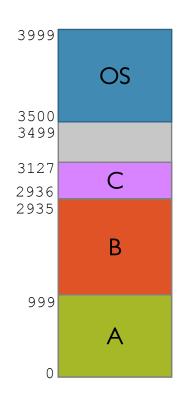
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- Efficiency → somewhat achieved but if a process grows it may need to be moved to other location (very slow)

• So far, we have assumed each process is allocated into a contiguous space of physical memory

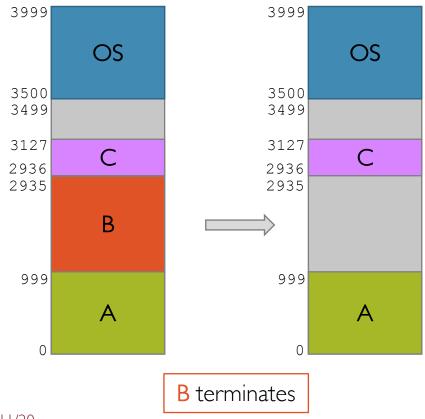
- So far, we have assumed each process is allocated into a contiguous space of physical memory
- One simple method is to divide upfront all available memory dedicated to user processes into equally-sized segments/partitions
 - Assign each process to a segment
 - Implicitly restricts the grade of multiprogramming (i.e., the number of simultaneous processes) and their size
 - No longer used!

An alternative approach is for the OS to keep track of **free** (unused) memory segments, as processes enter the system, grow, and terminate

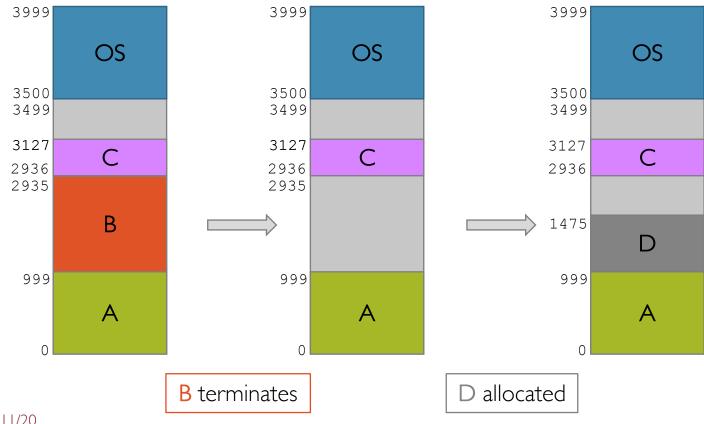
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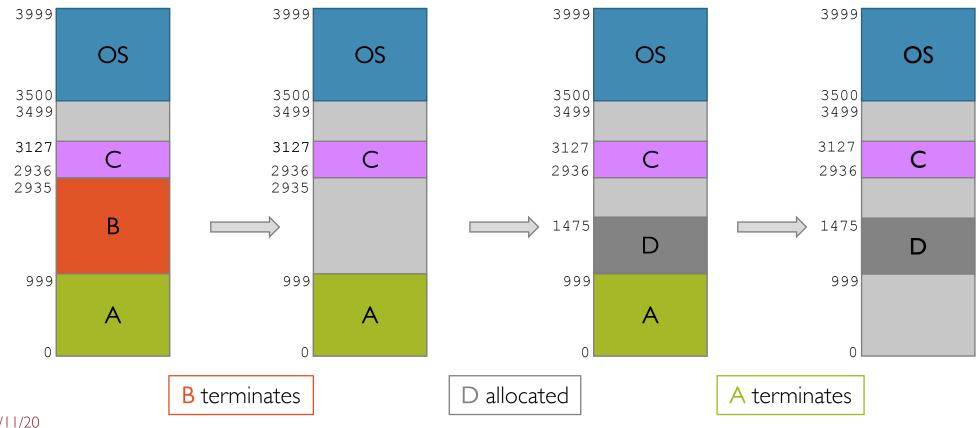
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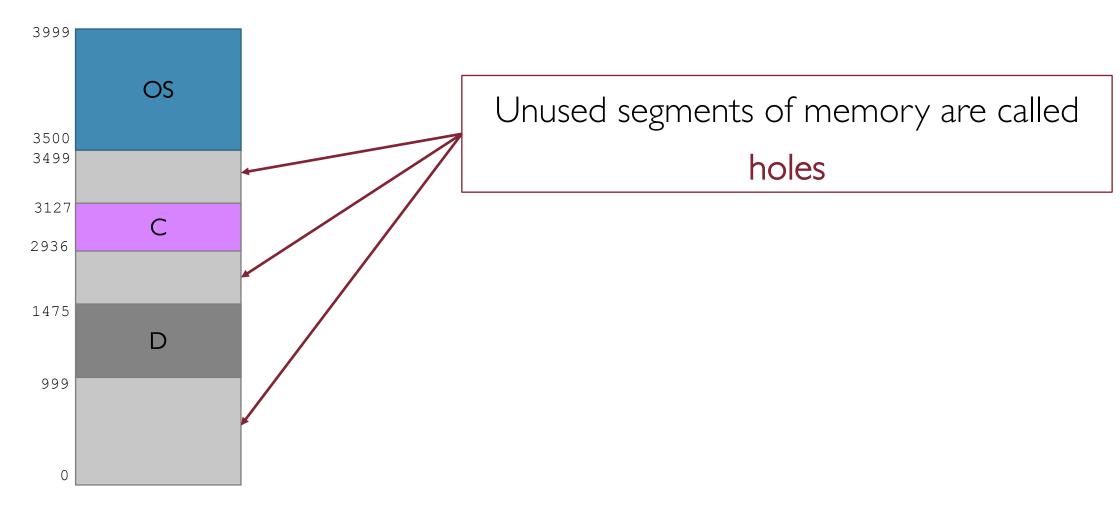


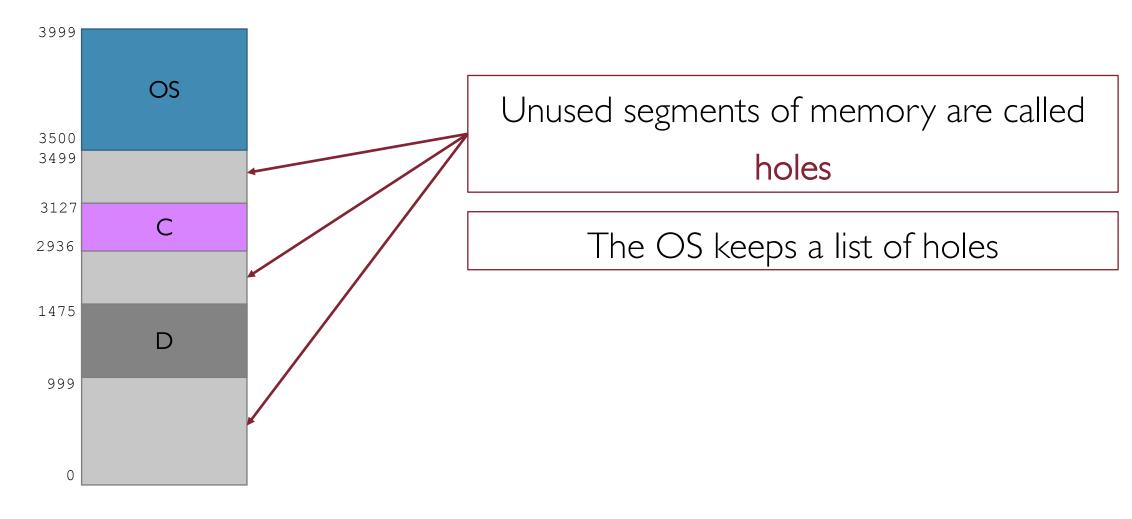
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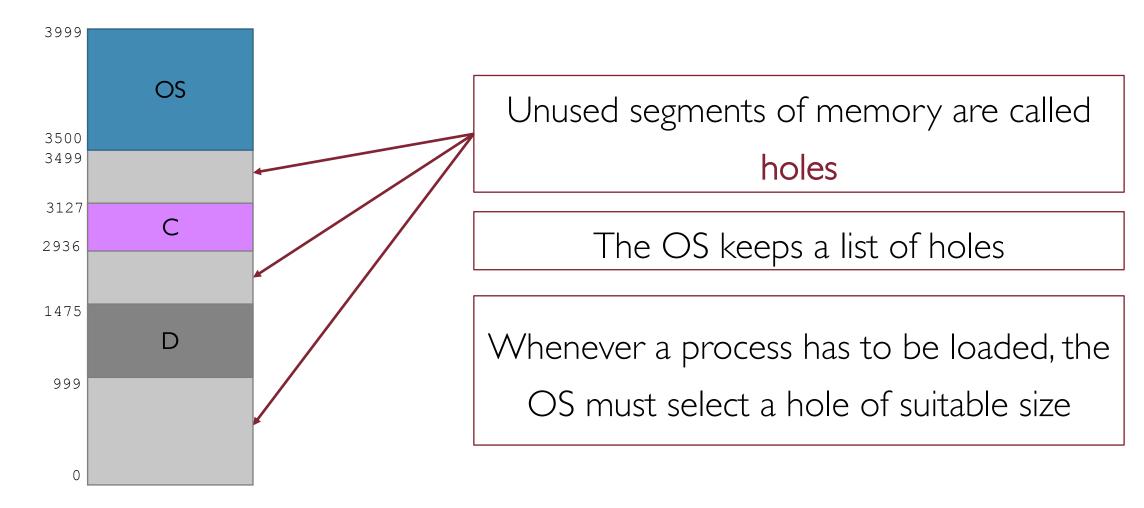


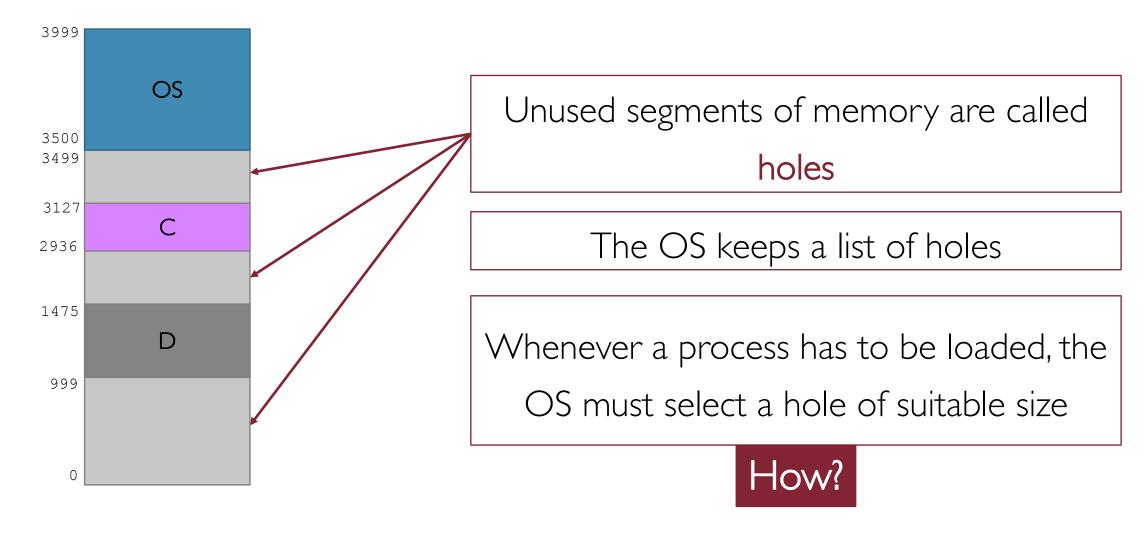
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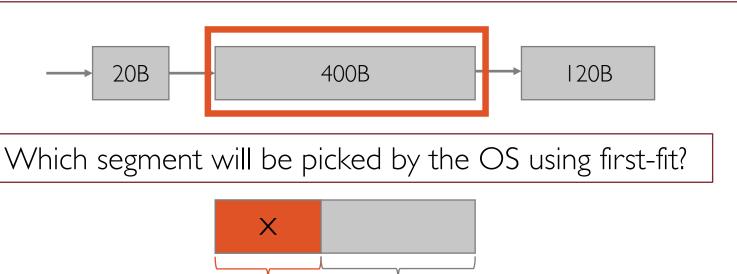
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300B ("wasted")

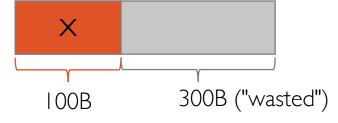
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100B

Suppose process X needs 100B of memory to be loaded, and the list of holes is as follows:



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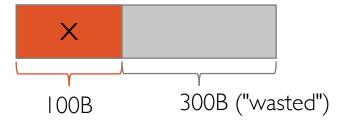


What if afterwards process Y requires 350B?

Suppose process X needs 100B of memory to be loaded, and the list of holes is as follows:



Which segment will be picked by the OS using first-fit?



What if afterwards process Y requires 350B?

We will not be able to satisfy this request even if theoretically we could

• Allocate the smallest hole that is big enough to satisfy the request

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Binary Search Tree (BST)

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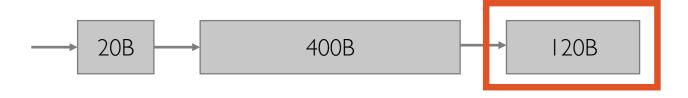


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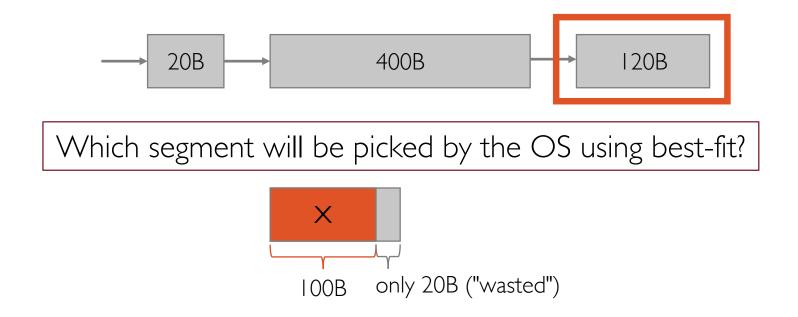
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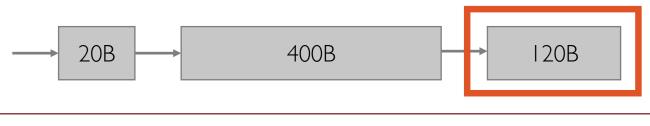


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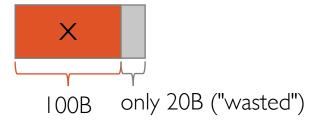
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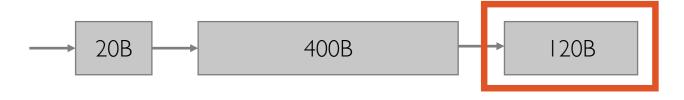


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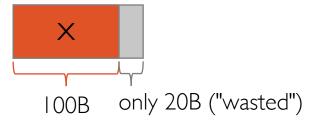


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Suppose process X needs 100B of memory to be loaded, and the list of holes is as follows:



Which segment will be picked by the OS using best-fit?



What if afterwards process Y requires 350B?

We can now assign it the second available hole segment (400B)

• Allocate the largest hole available

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- Simulations show that First-Fit and Best-Fit usually work best
- First-Fit is also generally faster than Best-Fit

Fragmentation

Problem

Individual holes may be too small to serve a process request but they can be large enough if combined together

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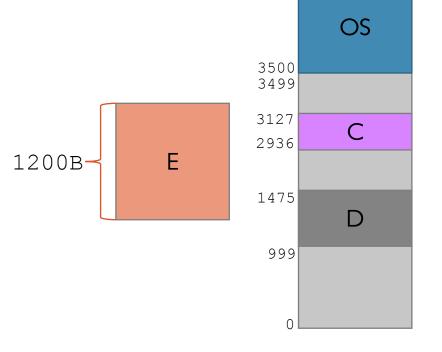
Internal Fragmentation

• Frequent loading and unloading processes causes holes to be broken into small (i.e., unusable) chunks

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3999

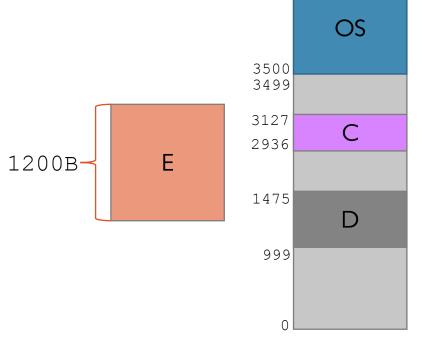
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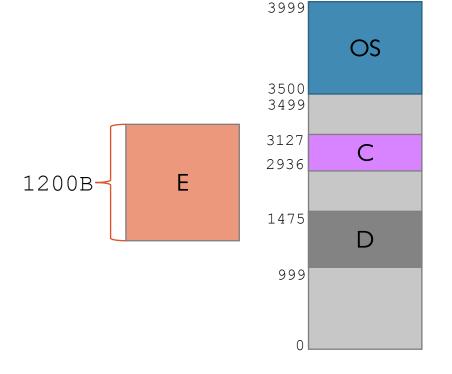
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Goal:

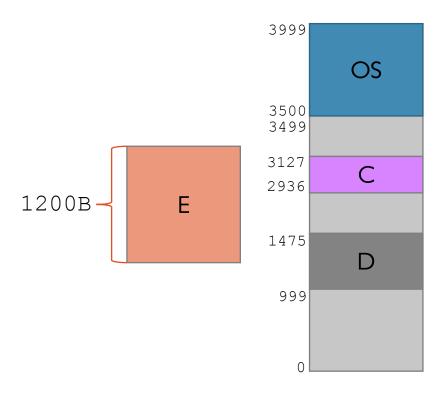
Allocation policy that minimizes wasted space!

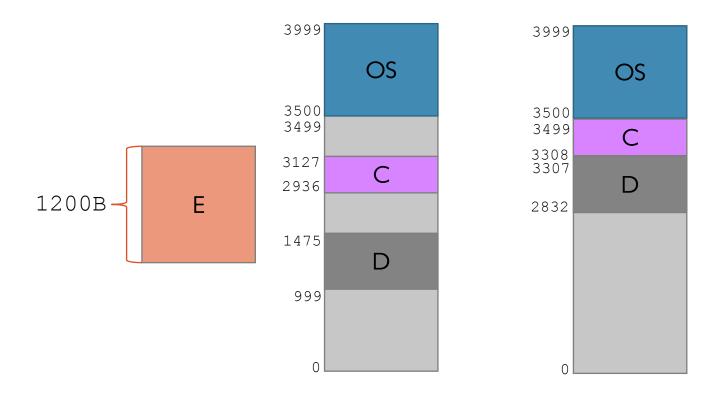


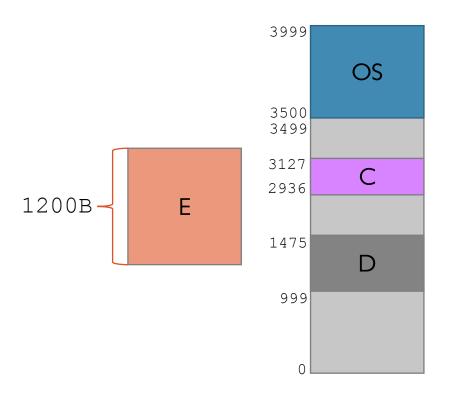
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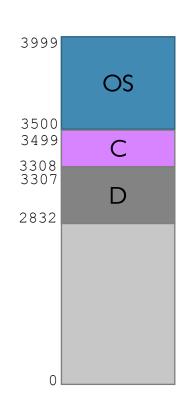
- It happens when memory internal to a segment is wasted
- For example, consider a process whose size is 8,846B and a hole of size 8,848B

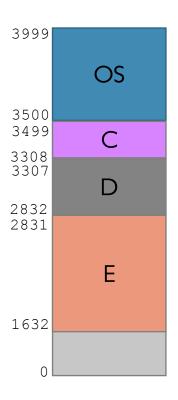
- It happens when memory internal to a segment is wasted
- For example, consider a process whose size is 8,846B and a hole of size 8,848B
- It may be much more efficient to allocate the process the whole block (and waste 2B) rather than keep track of a tiny 2B hole

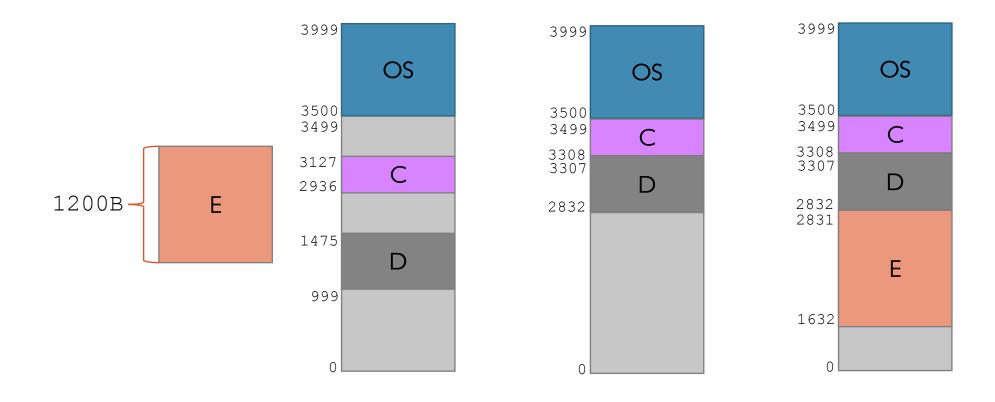




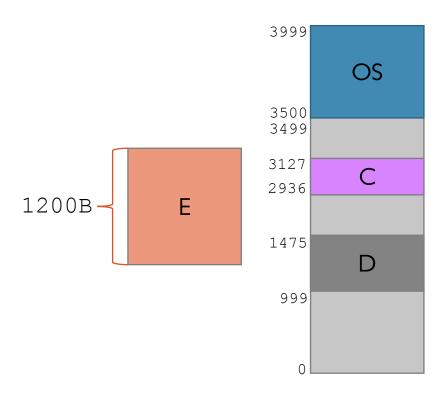


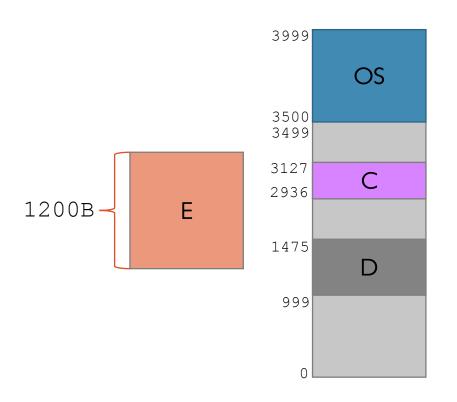


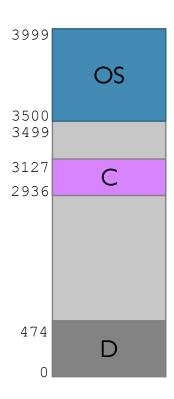


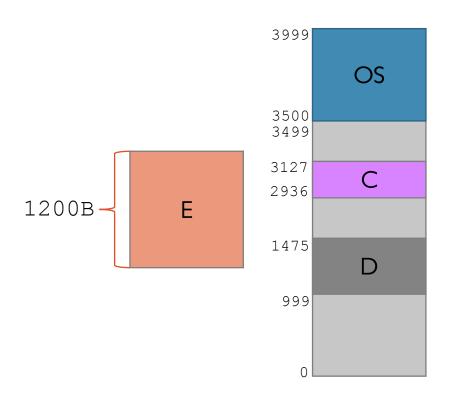


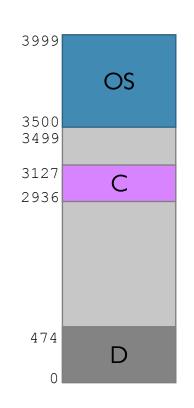
Only one hole is left but two processes need to be moved (C and D)

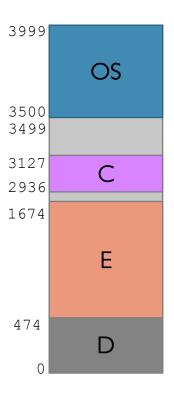


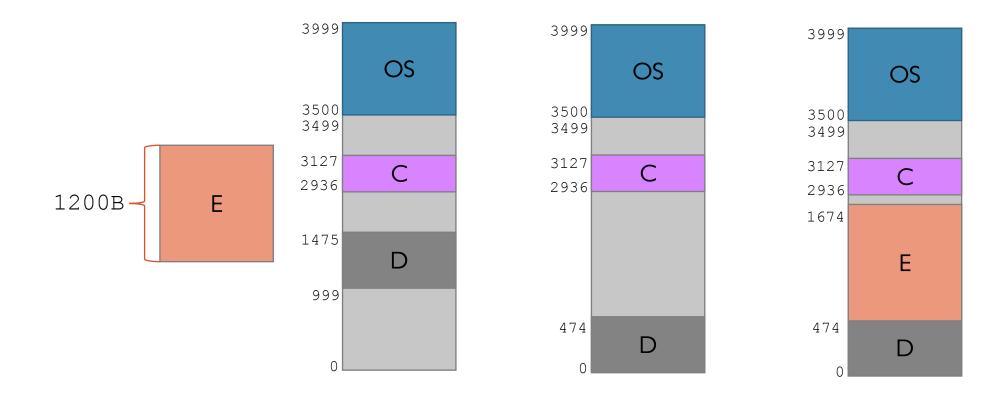












Still some holes left but only one process is moved (D) rather than two

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- That process can be "swapped out" from memory to disk to make room for other processes

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- Using swapping, fragmentation can be tackled easily
 - Just run compaction before swapping-in a process

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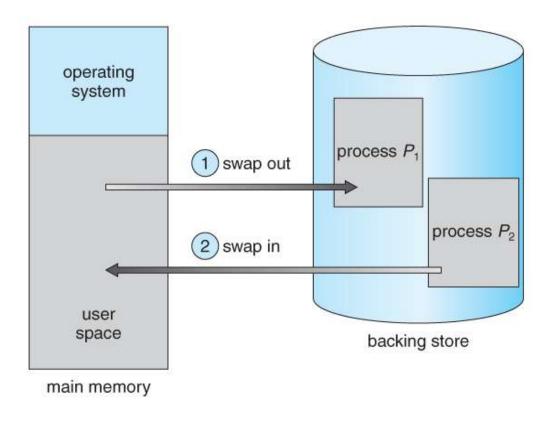
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- Time slice is usually way smaller than that!



Most modern OSs no longer use swapping, because it is too slow and there are faster alternatives available (e.g., paging)

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- More advanced strategies are needed to overcome:
 - contiguous allocation, fragmentation, and entire loading