

# Guided Linking: Dynamic Linking Without the Costs

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LLVM 2020



# Motivating Example

```
// foo.c
void foo(T* p) {
    int n = bar(p);
    // ...
}
```

```
// bar.c
int bar(T* p) {
    return p->size;
}
```

Can be optimized  
(w/ LTO)

# Motivating Example

```
// plugin.so
void foo(T* p) {
    int n = bar(p);
    // ...
}
```

```
// library.so
int bar(T* p) {
    return p->size;
}
```

Can't be optimized

# Motivating Example

```
// plugin.so
```

```
void foo(T* p) {  
    int n = bar(p);  
    // ...  
}
```

```
// library.so
```

```
int bar(T* p) {  
    return p->size;  
}
```

~~Can't be optimized~~  
**Can be optimized  
w/ Guided Linking**

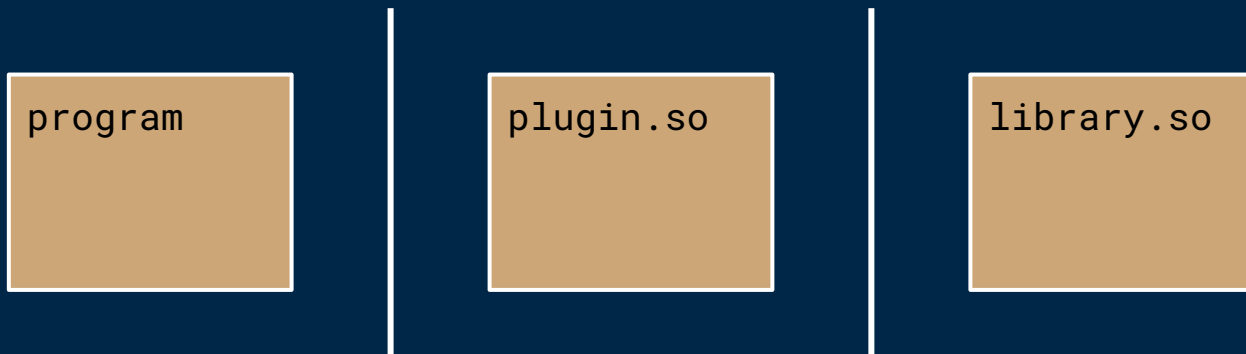
# Guided Linking

- Works on existing software
- Requires no code changes
- Python 9% faster
- Boost 57% smaller (multiple versions optimized together)

# Overview

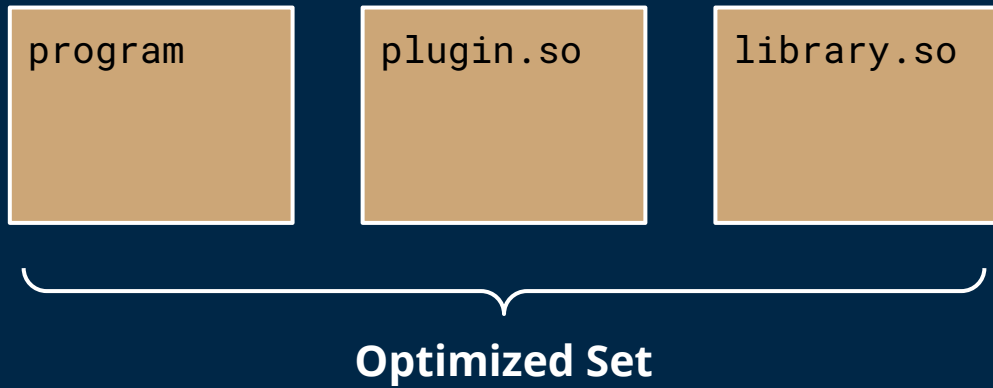
# Problem #1

Each program/library is optimized **separately**



# Solution #1

Optimize multiple programs/libraries at once





# Problem #2

*Set-user-ID?*

*LD\_DYNAMIC\_WEAK?*

*/etc/ld.so.cache?*

Dynamic linking is **unpredictable**

*Modified libraries?*

*Interposing definitions?*

*LD\_PRELOAD?*

*LD\_LIBRARY\_PATH?*

# Solution #2

Developer provides **constraints**

“This bar ( ) will never be  
overridden by a different bar ( ).”

# Guided Linking

"This bar ( ) will  
never be  
overridden."

**Constraints**

program

plugin.so

foo() {}

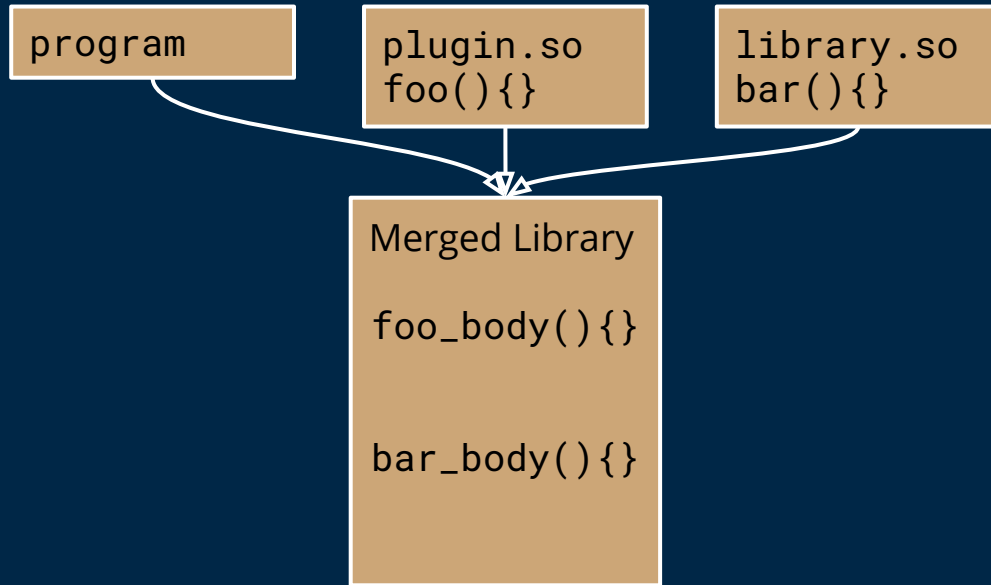
library.so

bar() {}

**Optimized Set**

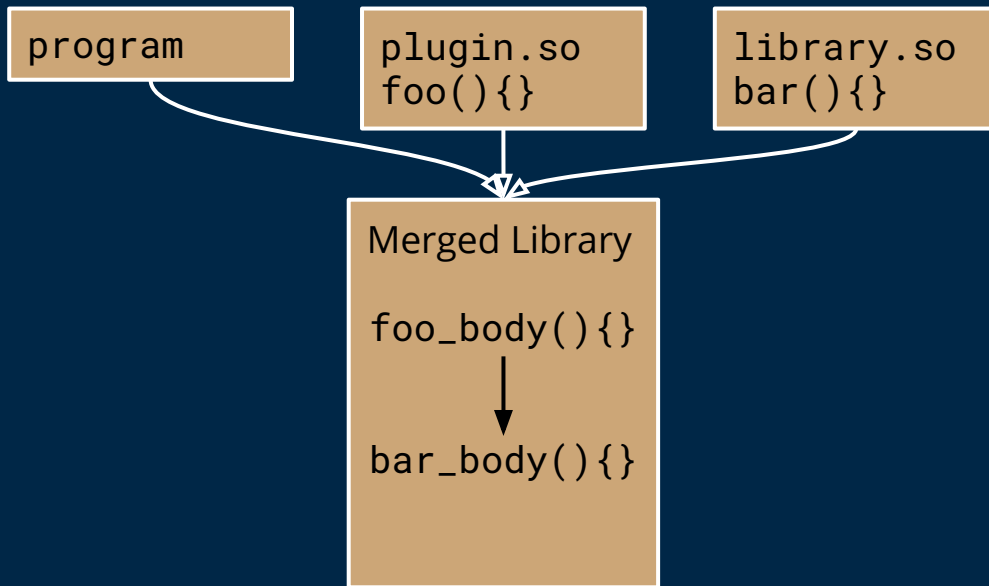
# Step 1: move code to a merged library

“This bar ( ) will  
never be  
overridden.”



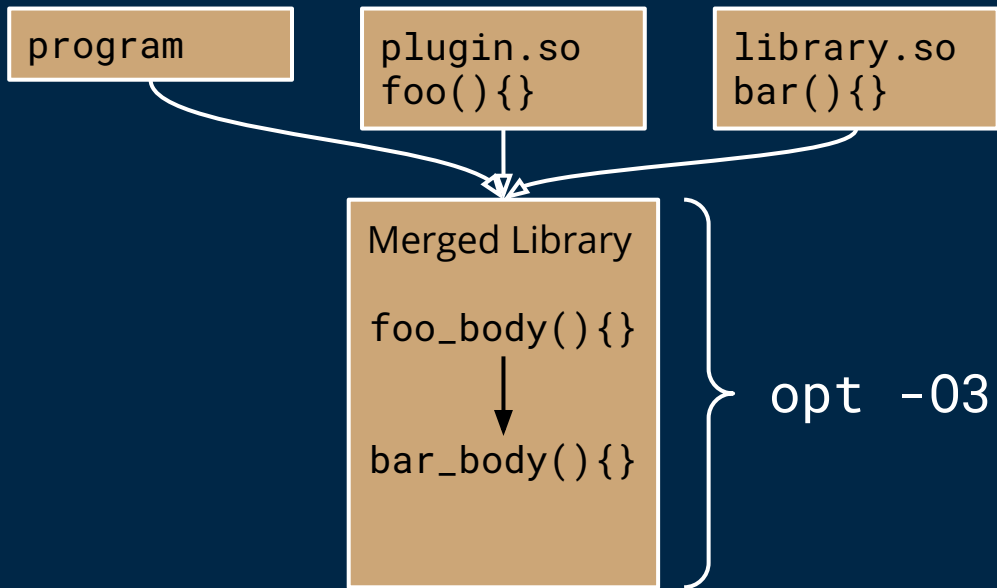
# Step 2: static resolution (when possible)

"This bar ( ) will  
never be  
overridden."



# Step 3: LTO does the rest

"This bar ( ) will  
never be  
overridden."



# Choosing the Optimized Set

# Choosing the Optimized Set

- Arbitrary set of programs, libraries, plugins
- Must be in bitcode form
- Must be distributed as a single unit
  - Slows down upgrades



# Optimized Set Possibilities

- One package
- Entire Docker container
- Entire desktop computer
  - Ship software in bitcode form
  - Re-optimize whenever programs are added

# Constraints

# Available Constraints

<b>NoOverride</b>	No external overrides
<b>NoUse</b>	No external uses
<b>NoPlugin</b>	No use in plugin
<b>NoWeak</b>	No weak uses or external definitions

# Specifying Constraints

default: **NoOverride**, **NoUse**, **NoPlugin**, **NoWeak**

**[Use]**

fun:PyInit\_\*

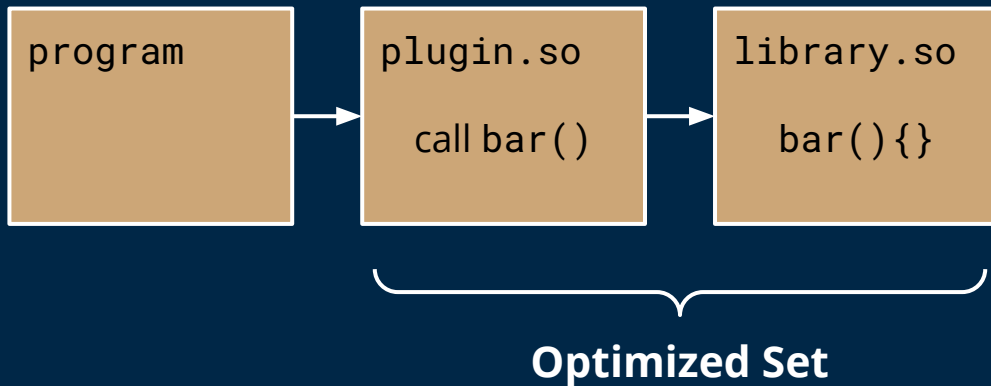


NoOverride: No external overrides



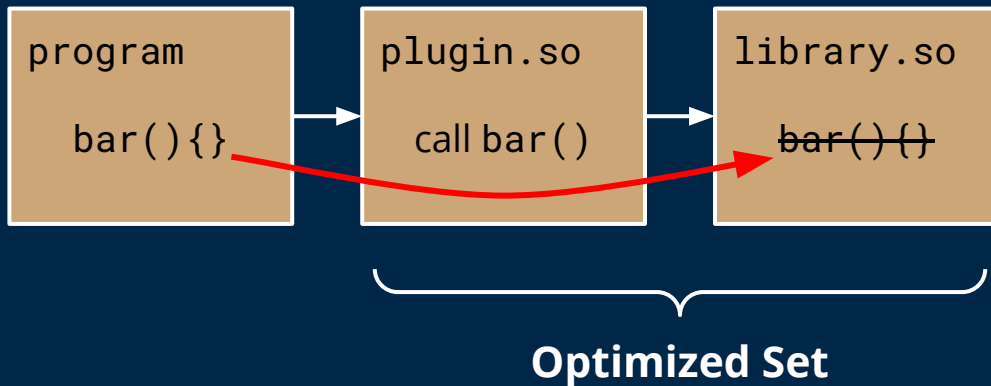
# What We Want

We want to inline `bar()`.



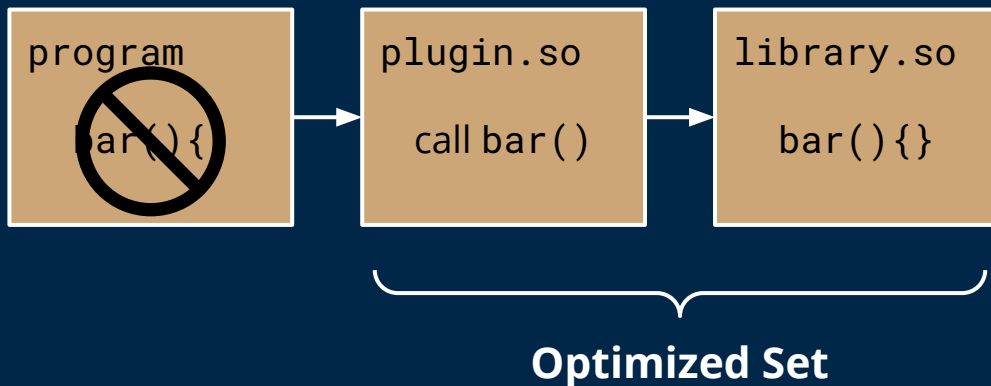
# Without the Constraint

Unsafe to inline.  
What if `bar()` is overridden?



# With the Constraint

**NoOverride** guarantees this won't happen.  
We can safely inline `bar()`.





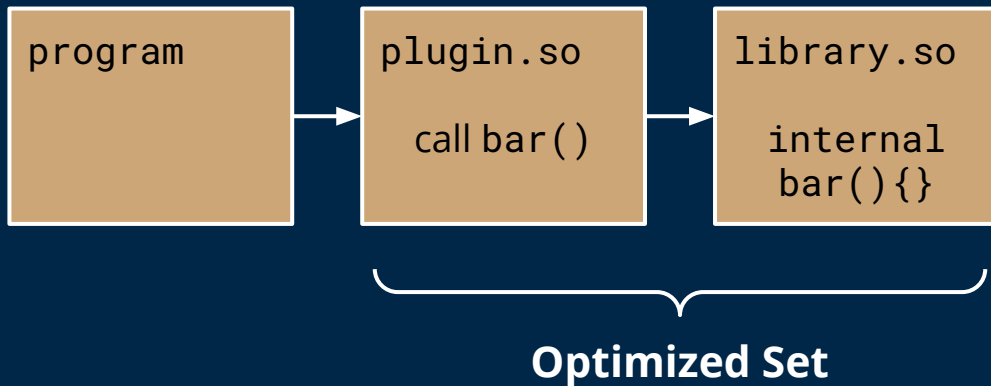


NoUse: No external uses



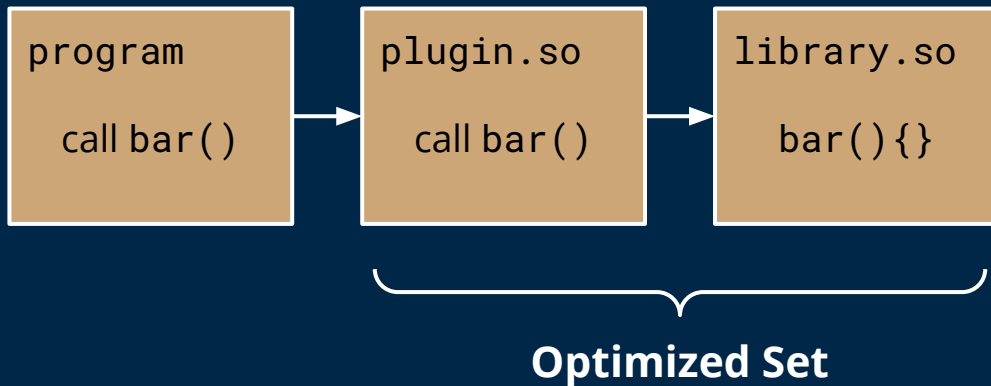
# What We Want

We want to internalize `bar()`  
in the merged library.



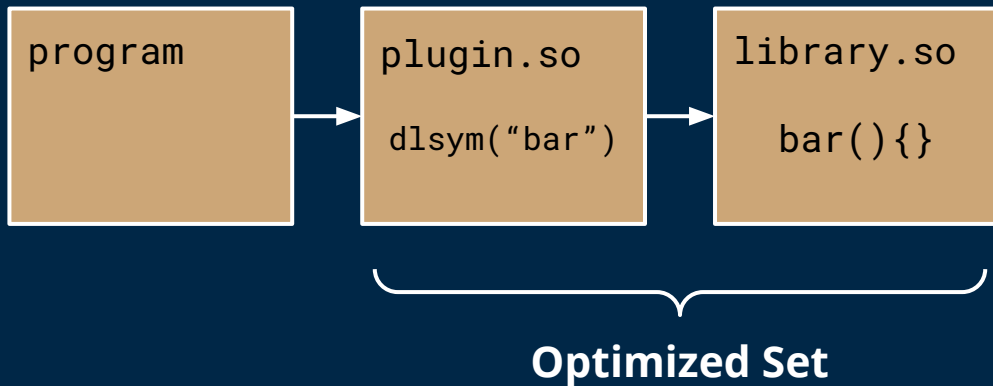
# Without the Constraint 1

Unsafe to internalize.  
Used outside the set.



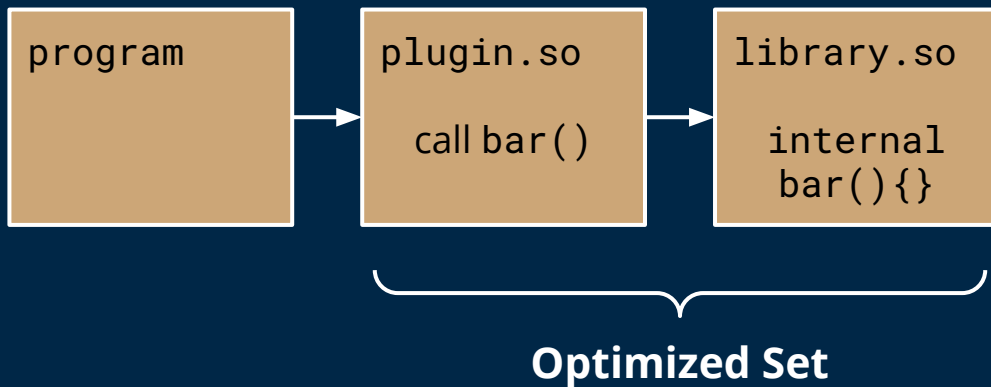
# Without the Constraint 2

Unsafe to internalize.  
Used through dynamic linker.



# With the Constraint

**NoUse** guarantees neither will happen.  
Safe to internalize.



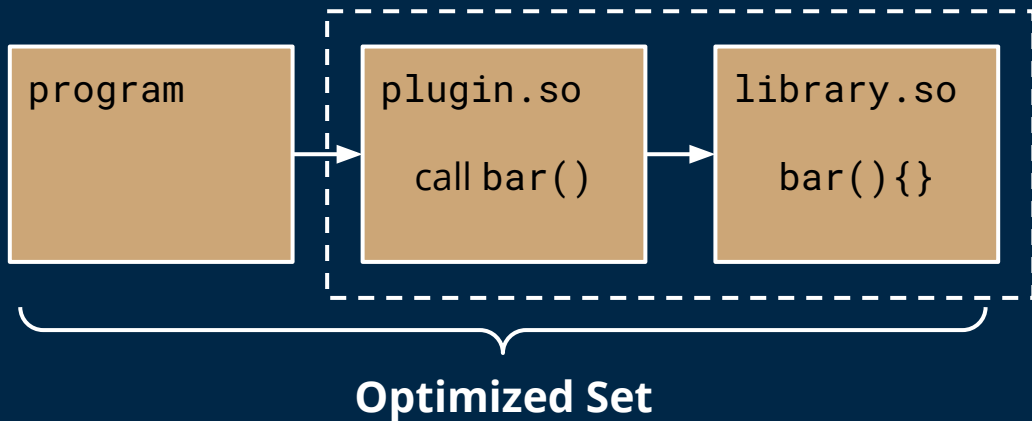


NoPlugin: no use in plugin



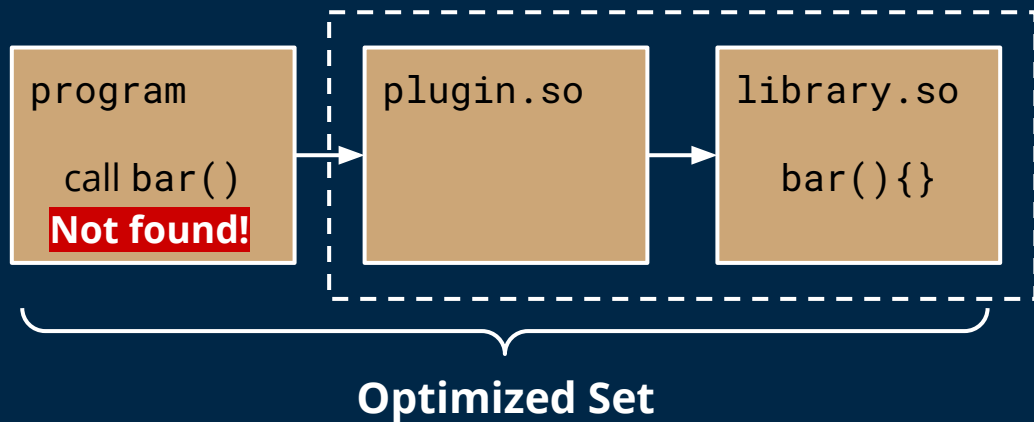
# Background

Each plugin has its own  
lookup scope (RTLD\_LOCAL)



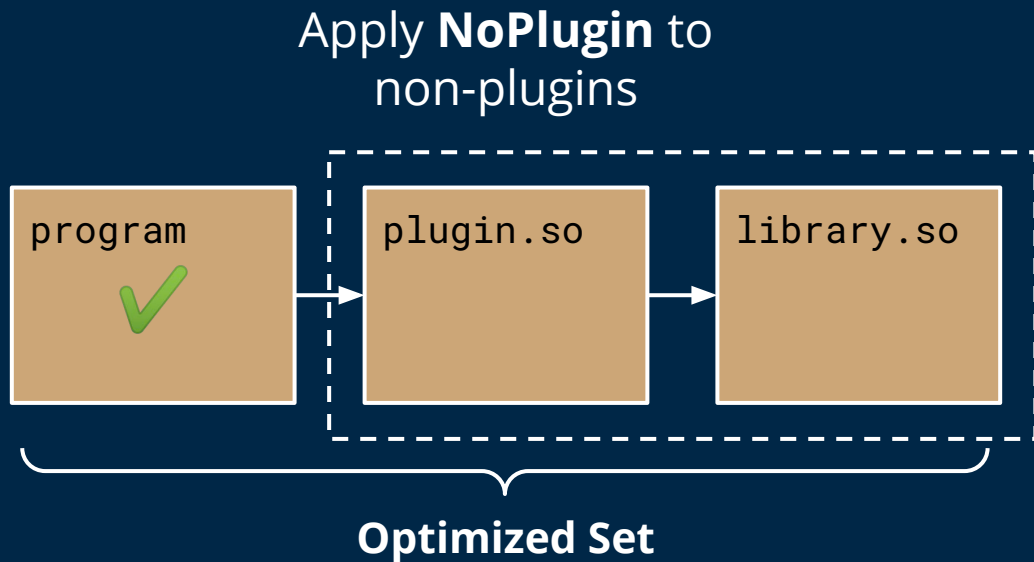
# Moving Code

Moving code that uses external functions  
requires extra work



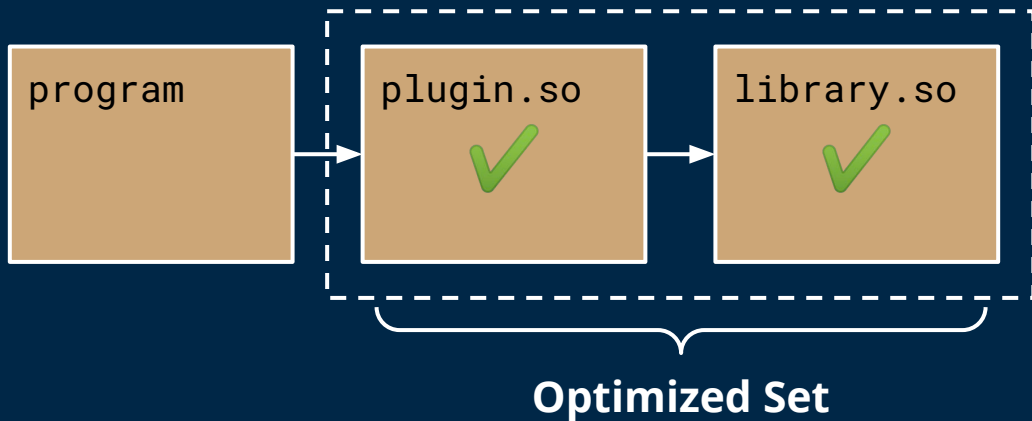


# Applying the Constraint



# Applying the Constraint

Or, reduce optimized set  
to only cover one plugin

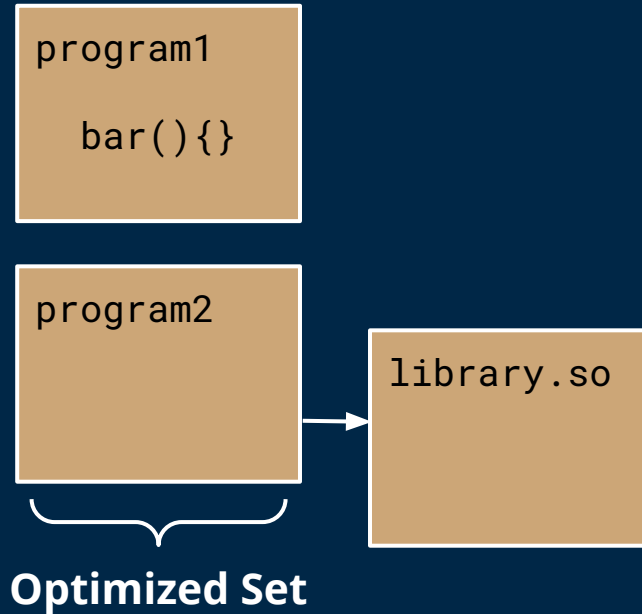




**NoWeak:** no weak uses or external definitions

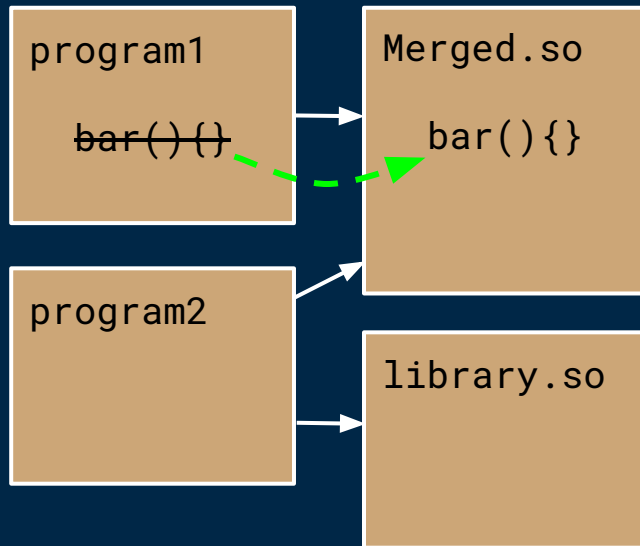


# What We Want



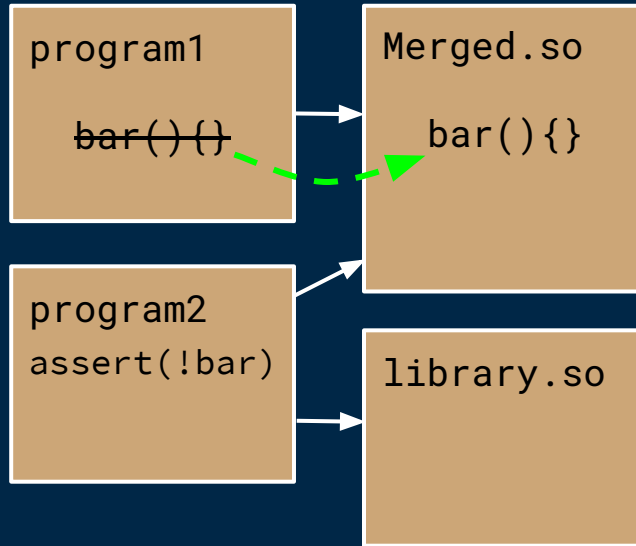
# What We Want

We want to move defs to  
the merged lib



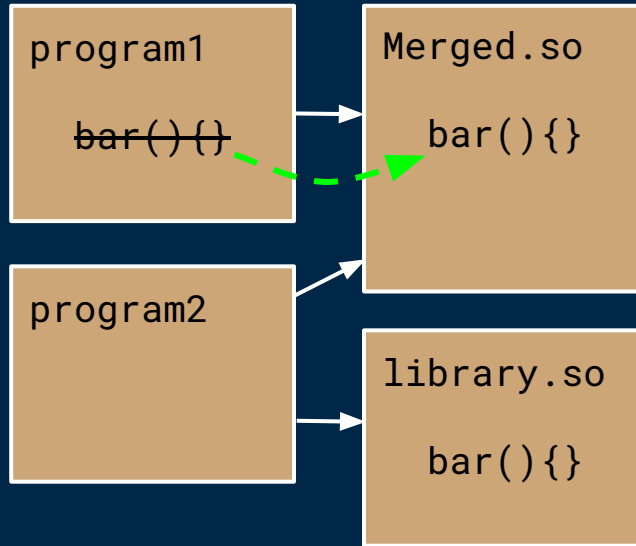
# Without the Constraint

Unsafe with weak uses



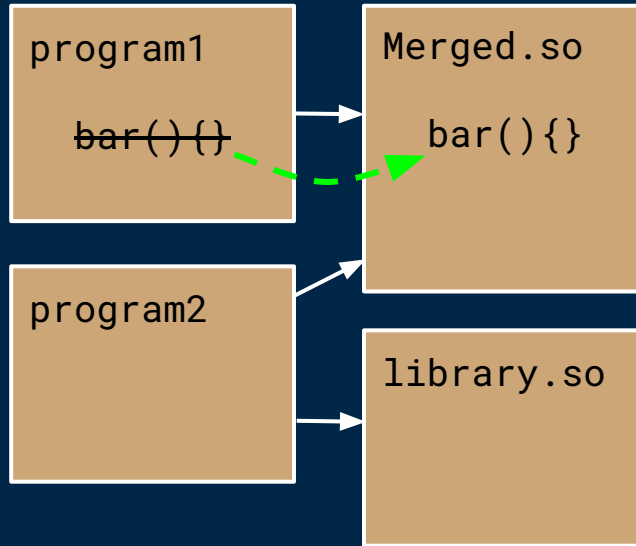
# Without the Constraint

Unsafe with other defs



# With the Constraint

Safe with **NoWeak**





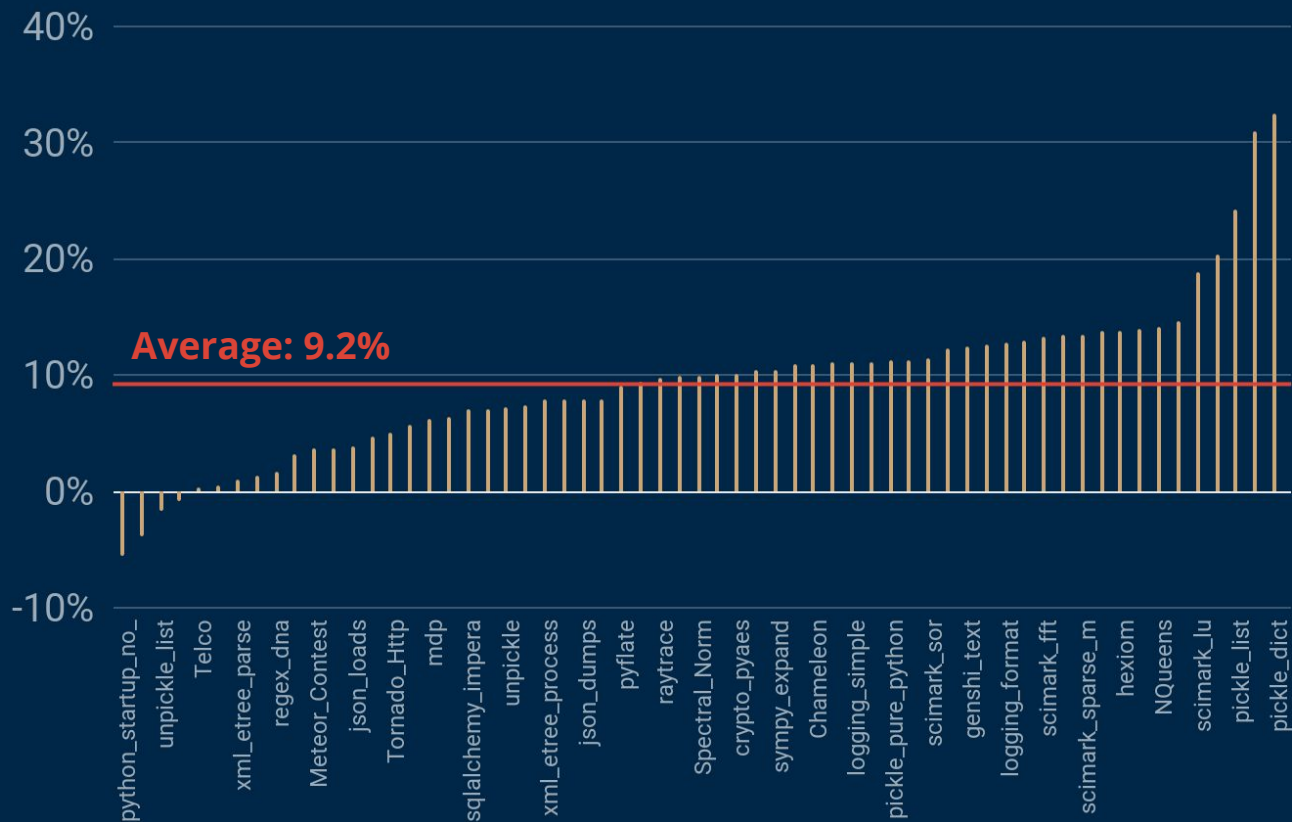
# Results

# Python

- Optimized set: Python, plus plugin modules
- Constraints: **NoOverride+NoUse+NoPlugin+NoWeak**
  - **NoPlugin** exceptions for plugins & their deps
  - **NoUse** exceptions for functions loaded with dlsym()
- Baseline: O3+LTO+PGO
- Benchmarks: pyperformance suite

# Python

Speedup w/ Guided Linking



# Python Example 1

```
// _pickle.so
int save(...) {
    ...
    while (_PyDict_Next(...))
        ...
    ...
}
```

```
// libpython3.7m.so
int _PyDict_Next(...) { ... }
```

Guided Linking enables inlining here.

# Python Example 2

```
// libpython3.7m.so
PyTypeObject PyFrame_Type = {
    ...
    (destructor)frame_dealloc,
    ...
};
```

- Guided Linking internalizes this variable
- LLVM determines it's never modified
- `frame_dealloc()` can be inlined.

# Boost and Protobuf

- Optimized set: multiple versions of the same library
- Constraint: **NoPlugin**
- Function deduplication
  - Normalize functions
  - Merge bodies of identical functions
- Baseline: `clang -Oz -flto`

# Size reductions

57%

11 versions of Boost

31%

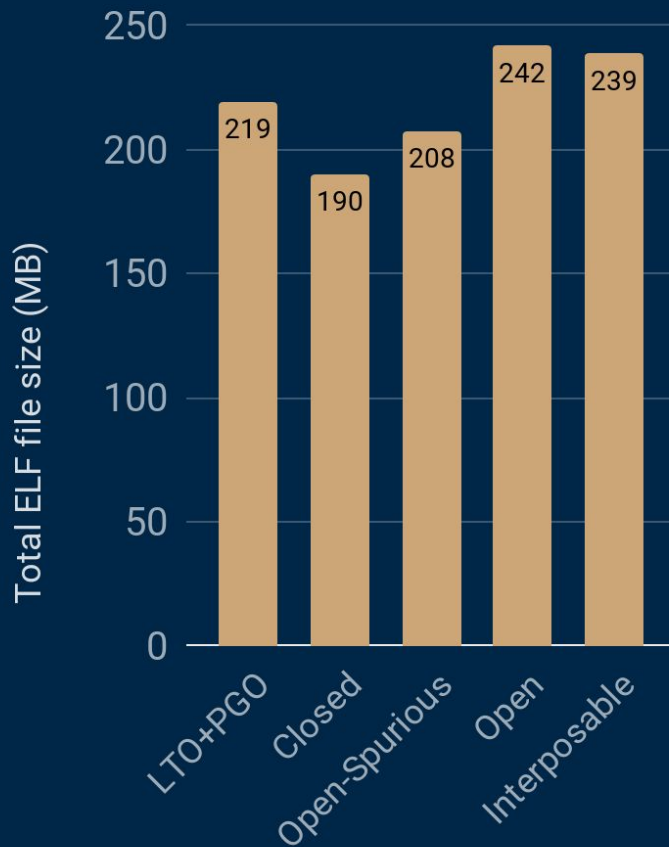
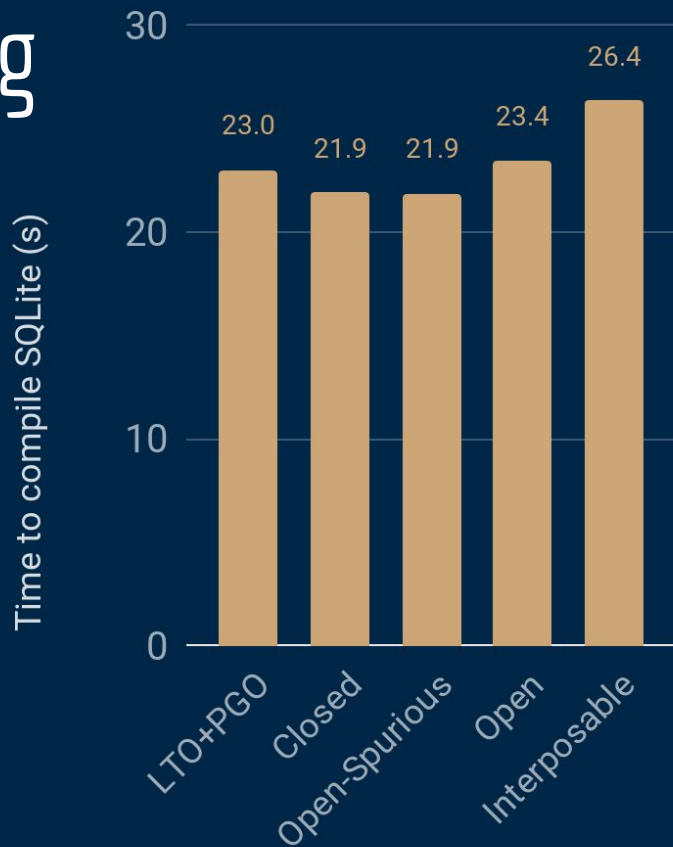
8 versions of Protobuf

# Clang

- Optimized set: all of LLVM and Clang
  - Built with BUILD\_SHARED\_LIBS (94 programs, 227 libs)
  - Caveat: LLVM already has better options
- Constraints: 4 different levels
  - Closed: **NoPlugin+NoOverride+NoWeak+NoUse**
  - Open-Spurious: **NoPlugin+NoOverride+NoWeak**
  - Open: **NoPlugin+NoOverride**
  - Interposable: **NoPlugin**
- Baseline: O3+LTO+PGO
- Benchmark: compile SQLite



# Clang



# Future Work

# Automatic Multicall

- Automatically make a program like Busybox
- Get rid of dynamic linker entirely
- Will Dietz' Allmux did this in limited cases
  - No libraries left out
  - No plugins or dlsym
  - No multiply-defined symbols

# Conclusion

- Guided Linking can optimize dynamically linked code
- Use an **optimized set** and **constraints**
- Speed up Python by **9%**
- Combine Boost/Protobuf versions and shrink by **31-57%**
- Speed up Clang+LLVM by **5%** and shrink by **13%**

# Conclusion

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Questions? Ideas? [smbarte2@illinois.edu](mailto:smbarte2@illinois.edu)