

Nonlinear Asset Pricing Model

UdeM

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Outline

Introduction

Related literature

Data

Reproducing Kozak et al. results

Nonlinear principal component

- Computation of the NLPCs

- Application of Kozak et al. methodology to the NLPCs

 - 50-k linear PCs + k nonlinear MPs/PCs

Conclusion

- ▶ In modern finance, the price of any asset is obtained by the expected discounted payoffs :

$$p_t^i = \mathbb{E}_t(SDF_{t+1} CF_{t+1}^i)$$

- ▶ The stochastic discount factor SDF_{t+1} is equal to the growth in the marginal value of wealth :

$$SDF_{t+1} = \frac{VW_{t+1}}{VW_t}$$

- ▶ The traditional theories of finance, CAPM, ICAPM, and APT, measure the marginal utility of wealth by the behavior of large portfolios of assets.
 1. **CAPM** : return on the market portfolio.
 2. **Multifactor models** : returns on multiple portfolios.

- ▶ In this paper, we rely on the multi-factor model framework.
- ▶ The SDF_{t+1} is specified as follows :

$$SDF_t = 1 - \lambda'(F_t - \mu)$$

where $\mu = E(F_t)$ and λ is a vector of factor loadings.

- ▶ **IDEA of this paper** : Use the **nonlinear PCs as factors** to estimate the SDF instead of the linear PCs as it is usually done. (See Kozak et al. (2020))
- ▶ **Advantages** :
 1. Factors are truly independent as opposed to linear PCs which are merely uncorrelated. **As a consequence, we capture truly different risk measure.**
 2. We **likely** need less factors when using nonlinear PCs than when using linear counterpart. **As a consequence, we have parsimonious model.**
 3. The increasing number of anomalies is **likely** not a problem anymore.

- ▶ **Nonlinear factors** : Chen et al. (2009), Lawrence (2012), Gunsilius and Schennach (2019), Damianou et al. (2021)
- ▶ **Machine learning asset pricing models** : Feng et al. (2018), Nakagawa et al. (2019), Chen et al. (2020), and Fang and Taylor (2021).
- ▶ **Stochastic discount factor estimation** : Fama and French (1993), Hou et al. (2015), Fama and French (2015), Barillas and Shanken (2018) and Kozak et al. (2018).

- ▶ Anomalies considered : 50 anomaly characteristics (same as Kozak et al.(2020));
- ▶ Daily returns data from November 1973 to December 2019 (2017 for Kozak et al.(2020));
- ▶ Follow the same anomalies definition as Kozak et al.(2020) to construct the anomalies.

Optimization problems

- ▶ Let $r_t = (r_{1,t}, \dots, r_{N,t})'$ be the vector of excess returns of N portfolios, $t=1, \dots, T$
- ▶ Let Z_t be a N -by- k matrix of asset anomaly characteristics ;
- ▶ Let $F_t = Z_{t-1}' r_t$ be a k -by-1 vector of factors (raw characteristic returns or linear PCs or nonlinear PCs) ;
- ▶ Let $\Sigma = \text{Cov}(F)$ be a k -by- k variance-covariance matrix of the factors ;
- ▶ Let $\mu = \mathbb{E}(F)$ be a k -by-1 vector of expected factor returns ;
- ▶ $SDF_t = 1 - \lambda'(F_t - \mathbb{E}F_t)$

Optimization problems

We impose two kind of penalties to estimate the SDF coefficients :

$$L2pen : \hat{\lambda} = \arg \min_{\lambda} (\mu - \Sigma \lambda)' \Sigma^{-1} (\mu - \Sigma \lambda) + \gamma \lambda' \lambda \quad (1)$$

$$L1L2pen : \hat{\lambda} = \arg \min_{\lambda} (\mu - \Sigma \lambda)' \Sigma^{-1} (\mu - \Sigma \lambda) + \gamma_1 \sum_{i=1}^k |\lambda_i| + \gamma_2 \lambda' \lambda \quad (2)$$

- ▶ Estimate the parameter $\hat{\lambda}$ via Ridge or Elastic net using LAR-EN ;
- ▶ choose optimally the tuning parameters γ or (γ_1 and γ_2). Σ is a k-by-k matrix, μ is a k-by-1 vector and λ is a k-by-1 vector.

LARS-EN(1/2)

- ▶ For each γ_2 , the problem (2) is equivalent to a lasso problem (3);
- ▶ So, for each γ_2 we use the modified LARS algorithm to solve the problem (3) equivalently the problem (2).

$$\hat{\lambda} = \arg \min_{\lambda} (\mu^* - \Sigma^* \lambda)' (\mu^* - \Sigma^* \lambda) + \gamma_1 \sum_{i=1}^k |\lambda_i| \quad (3)$$

where $\mu^* = (\Sigma^{-\frac{1}{2}} \mu, 0)'$ and $\Sigma^* = (\Sigma^{\frac{1}{2}}, \sqrt{\gamma_2} I)'$

- ▶ For each γ_2 , we execute the algorithm described in the next slide to estimate $\hat{\lambda}$.

LARS-EN(2/2)

1. Initialize $\hat{\lambda}^{(0)} = 0$, $\mathcal{A} = \operatorname{argmax}_j |\Sigma'_j \mu|$,
 $\nabla \hat{\lambda}_{\mathcal{A}}^{(0)} = -\operatorname{sign}(\Sigma'_{\mathcal{A}} \mu)$, $\nabla \hat{\lambda}_I^{(0)} = 0$, $n = 0$.
2. While $\mathcal{I} \neq \emptyset$ do ;
3. $\delta_j = \min_{j \in \mathcal{A}}^+ -\frac{\hat{\lambda}_j^{(n)}}{\nabla \hat{\lambda}_j^{(n)}}$
4. $\delta_i = \min_{i \in \mathcal{I}}^+ \left\{ \frac{(\Sigma_i + \Sigma_j)'(\mu - X \hat{\lambda}^{(n)})}{(\Sigma_i + \Sigma_j)'(\Sigma \nabla \hat{\lambda}^{(n)})}, \frac{(\Sigma_i - \Sigma_j)'(\mu - \Sigma \hat{\lambda}^{(n)})}{(\Sigma_i - \Sigma_j)'(\Sigma \nabla \hat{\lambda}^{(n)})} \right\}$ where j is any index in \mathcal{A} .
5. $\delta = \min(\delta_j, \delta_i)$
6. if $\delta = \delta_j$ then move j from \mathcal{A} to \mathcal{I} else move i from \mathcal{I} to \mathcal{A} .
7. $\hat{\lambda}^{(n+1)} = \hat{\lambda}^{(n)} + \delta \nabla \hat{\lambda}^{(n)}$
8. $\nabla \hat{\lambda}_{\mathcal{A}}^{(n+1)} = -\frac{1}{2} (\Sigma_{\mathcal{A}} + \gamma_2 I)^{-1} \cdot \operatorname{sign}(\hat{\lambda}_{\mathcal{A}}^{(n+1)})$
9. Update the value of $n=n+1$
10. end while
11. Output the series of coefficients $\Lambda = (\hat{\lambda}^{(0)}, \hat{\lambda}^{(1)}, \dots, \hat{\lambda}^{(k)})$

L2pen : Raw characteristics and linear PCs

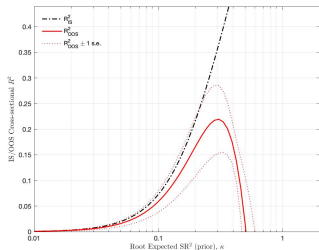


FIGURE – 50 raw characteristics

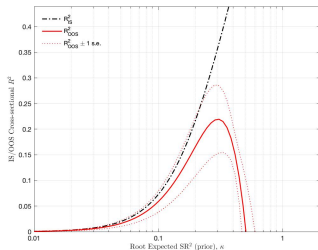
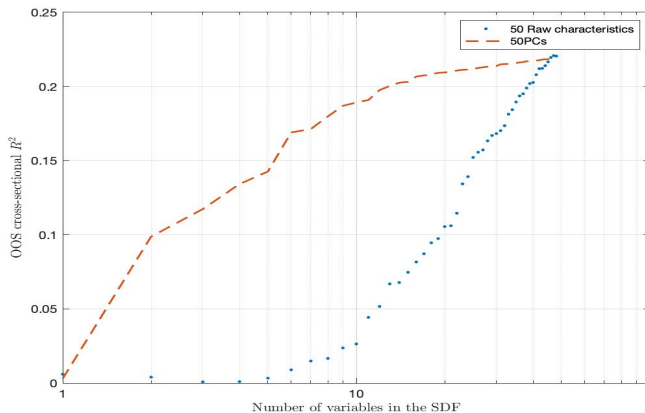


FIGURE – 50 linear PCs

Sparsity



L1L2pen : Raw characteristics and linear PCs

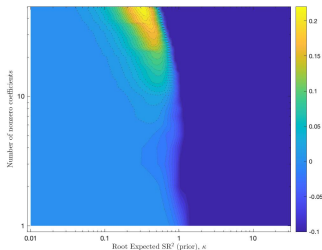


FIGURE – 50 raw characteristics

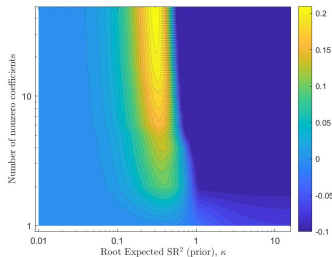


FIGURE – 50 linear PCs

L2pen : With interaction terms

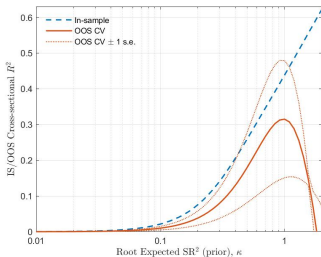


FIGURE – 2600 raw char.

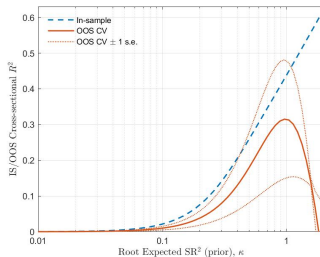


FIGURE – 2600 linear PCs

L1L2pen : With interaction terms

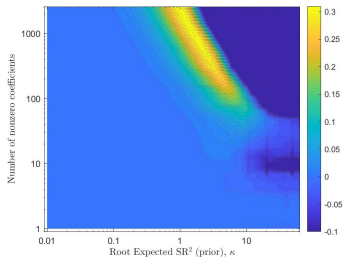


FIGURE – 2600 raw char.

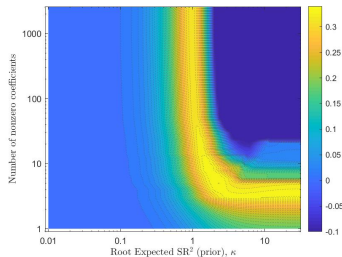


FIGURE – 2600 linear PCs

Takeaway 1

- ▶ From the previous slides, the results are quite similar to the one of Kozak et al. (2020) (replication) ;
- ▶ Let us turn to the second part of our analysis, which consist of integrating nonlinear factors.

- └ Nonlinear principal component
 - └ Computation of the NLPCs

- ▶ Let $r_t = (r_{1,t}, \dots, r_{N,t})$ be the vector of excess returns of N portfolios, $t=1, \dots, T$
- ▶ r_t is orthogonalized with respect to the market and rescaled to have the same standard deviations as the market ;
- ▶ Nonlinear PCs construction : Follows Gunsilius and Schennach (2019)

- ▶ Extract N linear PCs from r denoted by $f_t = (f_t^1, \dots, f_t^N)$;
- ▶ Extract the nonlinear PCs from the first k linear PCs :
 $y_t = (f_t^1, \dots, f_t^k)$;
- ▶ y has a density function g .
- ▶ Find a map T transforming $g(y)$ into a target density $\Phi(x)$ where $x = T(y)$
- ▶ Change of variable formula gives :

$$g(y) = \Phi(T(y)) \det\left(\frac{\partial T(y)}{\partial y'}\right) \quad (4)$$

- ▶ T minimizes $\int \|T(y) - y\|^2 g(y) dy$
- ▶ $T(y) = \frac{\partial C(y)}{\partial y}$, where C is a convex function.
- ▶ C is determined by Gradient descent using equation (4)

- └ Nonlinear principal component
- └ Computation of the NLPCs

► Compute

$$\tilde{J} = - \int g(y) \ln \frac{\partial T(y)}{\partial y'} dy \quad (5)$$

- Extract k eigenvectors $e = (e_1, e_2, \dots, e_k)$ corresponding to the k largest eigenvalues of \tilde{J}
- Therefore, the i^{th} nonlinear principal component is defined by :
 $\tilde{f}_i = T(y)e_i, \quad i = 1, 2, \dots, k.$

50 anomaly characteristics

- ▶ Let $r_t = (r_{1,t}, \dots, r_{50,t})$ be the raw characteristic excess returns;
- ▶ Let y be the first k linear principal components;
- ▶ Set a squared grid y with a size $M \times M \times \dots \times M$ from -4 to 4 each variable;
- ▶ Estimate the Brenier map T for the grid $T(y)$;
- ▶ Calculate \tilde{J} over the grid points, then the eigenvectors $e = (e_1, e_2, \dots, e_k)$;
- ▶ Interpolate the Brenier map to have the full nonlinear transformation of the data : $T(f_1, f_2, \dots, f_k)$;
- ▶ Let $\tilde{f}_t = (\tilde{f}_{1,t}, \dots, \tilde{f}_{k,t})$ be the time series of the k nonlinear PCs;
- ▶ Since the nonlinear factors are not tradable, we construct the corresponding mimicking portfolios.

- Approximation of the NLPCs using a piecewise linear function :

$$\tilde{f}_{j,t} = \beta_{0,j} + \beta_{1,j}r_{mkt,t} + \beta'_{c,j}r_t + \delta_j \max(r_{mkt,t} - k_j, 0) + \epsilon_{j,t} \quad t = 1, \dots, T \quad (6)$$

- If δ is not significant, then a linear mimicking portfolio is sufficient ;

$$MP^1_{j,t} = \hat{\beta}_{0,j} + \hat{\beta}_{1,j}r_{mkt,t} + \hat{\beta}'_{c,j}r_t \quad t = 1, \dots, T \quad (7)$$

- Else, we need a nonlinear mimicking portfolio.

$$MP^2_{j,t} = \hat{\beta}_{0,j} + \hat{\beta}_{1,j}r_{mkt,t} + \hat{\beta}'_{c,j}r_t + \hat{\delta}_j \max(r_{mkt,t} - k_j, 0) \quad t = 1, \dots, T \quad (8)$$

- The third mimicking portfolios we considered :

$$MP^3_{j,t} = \hat{\beta}_{0,j} + \hat{\beta}'_{c,j}r_t \quad t = 1, \dots, T \quad (9)$$

Terminologies

Let f_{-k} be a set of 50-k linear PCs, excluding the first k linear PCs and NMP_k / NPC_k be a set of k nonlinear MPs/PCs. $k = 2, 3, \dots, 6$.

- ▶ **Base case** : Price $[f_{-k}, NMP_k]$ using risk factors derived from $[f_{-k}, NMP_k]$. In formula :
$$\mu = \mathbb{E}([f_{-k}, NMP_k]), \Sigma = \text{Cov}([f_{-k}, NMP_k])$$
- ▶ **Robustness check** : Price $[f_{-k}, NMP_k]$ using risk factors derived from $[f_{-k}, NPC_k]$. In formula :
$$\mu = \mathbb{E}([f_{-k}, NMP_k]), \Sigma = \text{Cov}([f_{-k}, NPC_k])$$

Terminologies

- ▶ **Base case** : Let the LARS-EN algorithm adds the factors starting by the model with all the mimicking portfolios of the NLPCs.
- ▶ **Robustness check** : Let the LARS-EN algorithm adds the factors starting by the model with no risk factors ;

Results do not depend on the mimicking portfolios (MPs), so we present the figures only for MP^2

- Nonlinear principal component

- Application of Kozak et al. methodology to the NLPCs

Base case : 48 PCs + 2NMPs

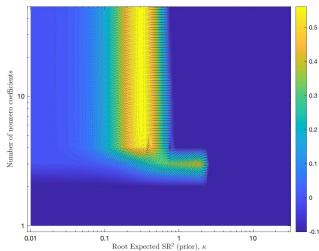


FIGURE – L1L2pen

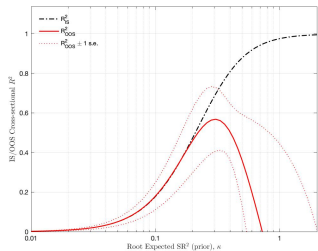


FIGURE – L2pen

Robustness check : 48 PCs + 2NPCs

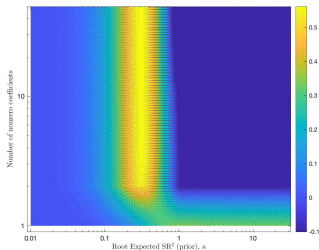


FIGURE – L1L2pen

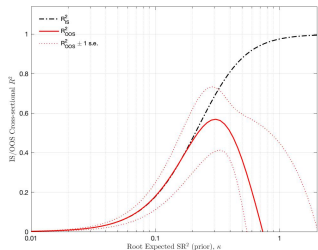


FIGURE – L2pen

- Nonlinear principal component

- Application of Kozak et al. methodology to the NLPCs

Base case : 47 PCs + 3NMPs

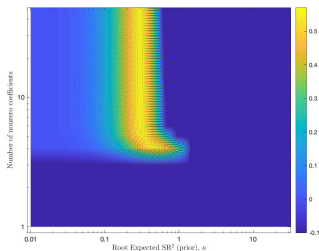


FIGURE – L1L2pen

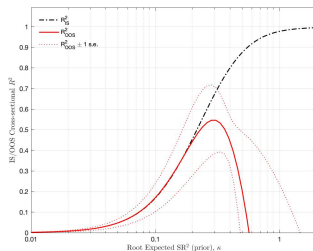


FIGURE – L2pen

Robustness check : 47 PCs + 3NPCs

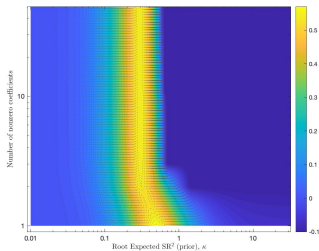


FIGURE – L1L2pen

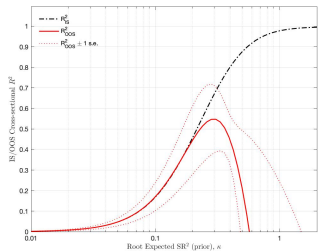


FIGURE – L2pen

- Nonlinear principal component

- Application of Kozak et al. methodology to the NLPCs

Base case : 46 PCs + 4NMPs

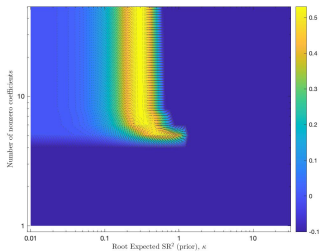


FIGURE – L1L2pen

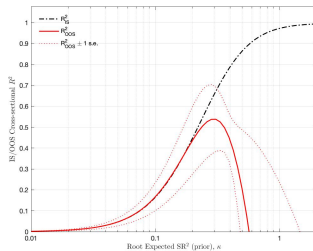


FIGURE – L2pen

- Nonlinear principal component

- Application of Kozak et al. methodology to the NLPCs

Robustness check : 46 PCs + 4NPCs

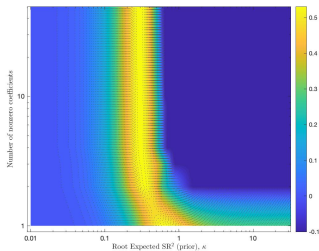


FIGURE – L1L2pen

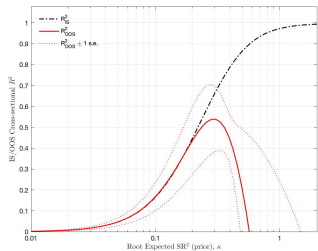


FIGURE – L2pen

- Nonlinear principal component

- Application of Kozak et al. methodology to the NLPCs

Base case : 45 PCs + 5NMPs

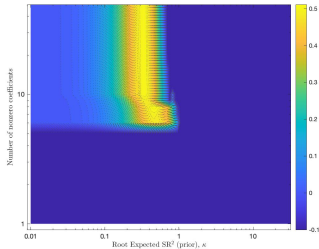


FIGURE – L1L2pen

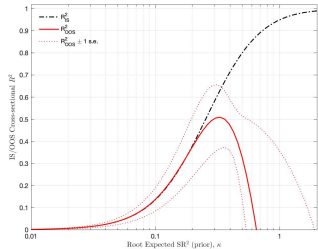


FIGURE – L2pen

Robustness check : 45 PCs + 5NPCs

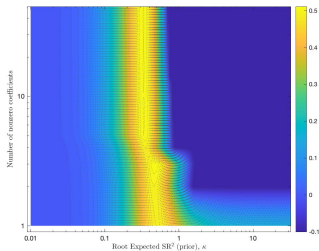


FIGURE – L1L2pen

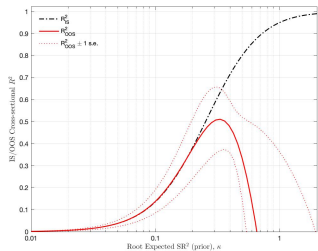


FIGURE – L2pen

- Nonlinear principal component

- Application of Kozak et al. methodology to the NLPCs

Base case : 44 PCs + 6NMPs

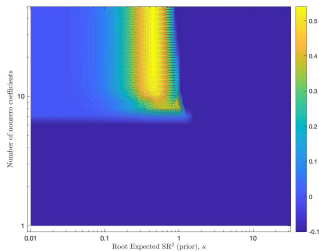


FIGURE – L1L2pen

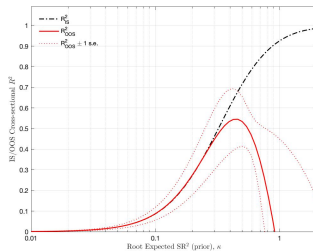


FIGURE – L2pen

- Nonlinear principal component

- Application of Kozak et al. methodology to the NLPCs

Robustness check : 44 PCs + 6NPCs

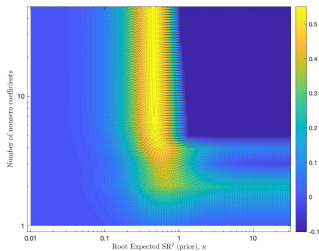


FIGURE – L1L2pen

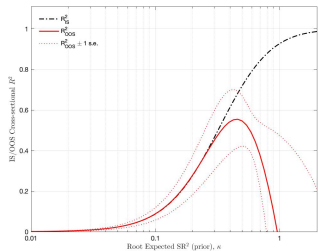


FIGURE – L2pen

Takeaway 2

- ▶ Results do not depend on whether one use the NLPCs or the NMPs;
 - ▶ There is a difference but it is not that much as one can see from previous slides;
 - ▶ One explanation is the quality of the NMPs which perfectly mimic the NLPCs;
- ▶ Our results suggest that one should do supervised Elastic net instead of doing unsupervised Elastic net :
 - ▶ Benchmark analysis is much better than no benchmark analysis.

LF vs NLF

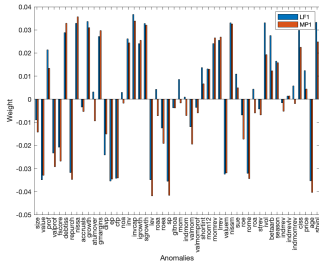


FIGURE – LF1 versus MP1

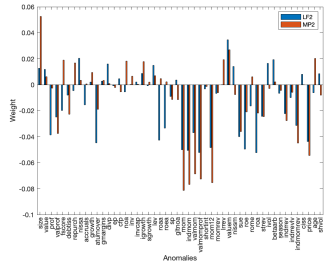


FIGURE – LF2 versus MP2

Conclusion

- ▶ The hybrid model requires less risk factors to achieve the highest out-of-sample performance
- ▶ Weight shifting on some anomalies. The mimicking portfolios (MPs) and the linear factors disagree on the anomalies that are marginal in terms of weights
- ▶ We believe that the nonlinear principal components have good prediction power.
- ▶ Thus, they should be taken into account for the development of future factor model.