Energy efficiency assessment in the context of multimodal passenger transport: From 'well' to 'wheels'

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Impact assessment of multimodal routes in relation to the MOVESMART project

Aim

To support the mobility of individuals by assisting the traveler to **combine** various **means of transportation in an energy-efficient way**

Methodological approach

"Well-to-wheels" analysis of energy consumption/emissions over the operational phase of the life cycle









Challenges in relation to MOVESMART objectives

- Scientific:
 - Consideration of traffic conditions
 - Inclusion of electric vehicles in mobility chains
- Technological:
 - Low response time



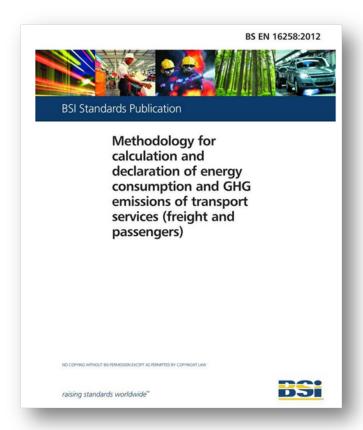






Transport services and standardisation in EU

"The assessment of energy consumption and GHG emissions of a transport service shall include both vehicle operational processes and energy operational processes that occur during the operational phase of the lifecycle."

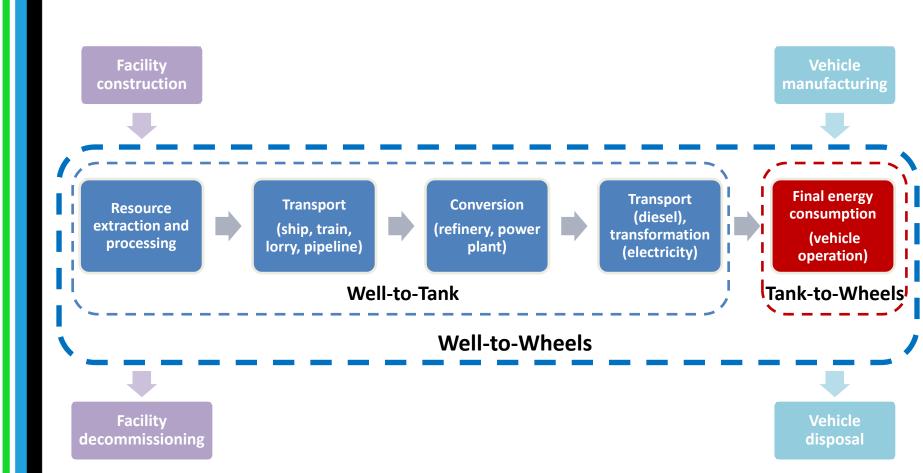








Scope of the analysis



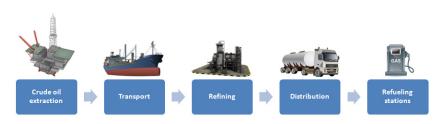




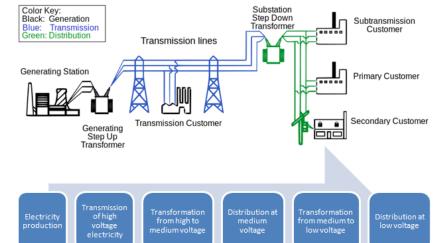


From "well" to "tank": Energy operational processes (1)

- Modeling of upstream stages of the life cycle for:
 - Transport fuels
 - Electricity
- Tool/Database: SimaPro v8/Ecoinvent v3
- Methods and impact categories:
 - Global warming potential (GWP 100a, IPCC 2013)
 - Cumulative energy demand (CED v1.08)
- Determination of upstream energy and emission factors as part of the life cycle analysis, by:
 - fuel type
 - electricity generation technology (composition of electricity mix)



Example of well-to-tank (WTT) stages of petroleum-based transport fuels

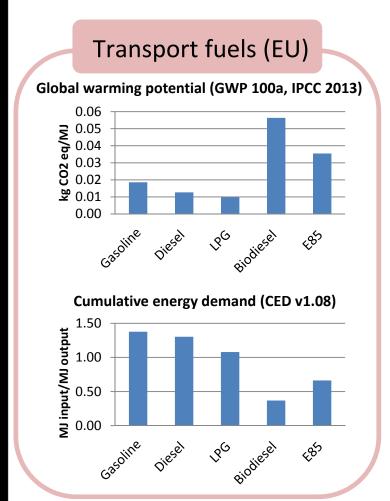


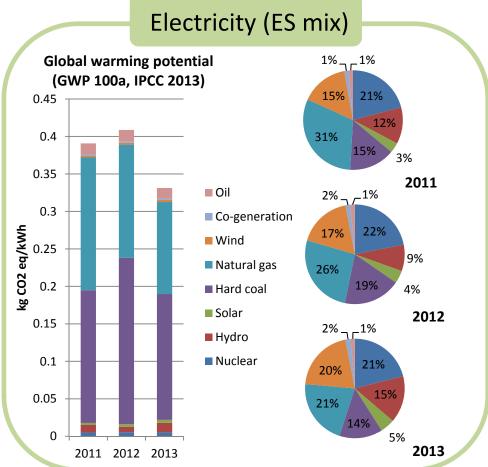
Electricity generation, transmission, transformation and distribution to end users





From "well" to "tank": Energy operational processes (2)











From "tank" to "wheels": Vehicle operational processes for passenger cars (PCs)

- Dynamic emission factors from Handbook Emission Factors for Road Transport (HBEFA)
- Integrated in a MongoDB:
 - Inputs:
 - Traffic situation: <area type, road type, speed limit, level of service>
 - Road gradient: 0%, ±2%, ±4%, and ±6%
 - Car engine technology: Diesel, Petrol (4-stroke), Petrol (2-stroke), LPG, Bifuel CNG/Petrol, Flex-fuel E85
 - Engine size class: Small (<1.4 L), Medium (>=1.4 L and <2 L), Large (>=2 L)
 - Emission class: Up to Euro 6
 - Fuel type (for bifuel vehicles)
 - Outputs:
 - Emission factors for CO₂, CH₄, N₂O
 - Fuel consumption







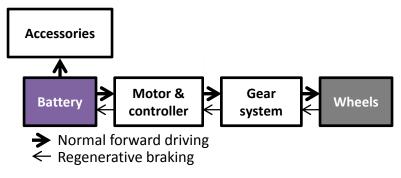


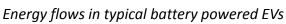
From "tank" to "wheels": Vehicle operational processes for electric vehicles (EVs) (1)

Physics-based vehicle model → Estimation of traction power, i.e.
power required to overcome the forces opposing to the movement of
the vehicle and drive it at speed u

$$P_{ts} = F_{ts} * u = (F_{ad} + F_{rr} + F_{hc} + F_{la} + F_{\omega \alpha}) * u$$

 EV components model → Transformation of traction power requirements (at wheels) into EV battery power requirements







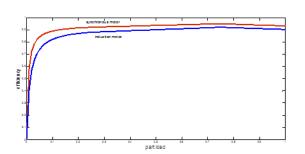


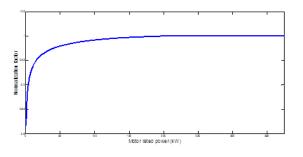


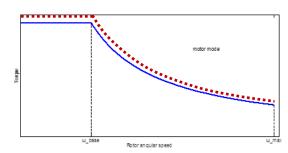
From "tank" to "wheels": Vehicle operational processes for electric vehicles (EVs) (2)

- What's new in modeling of motor operation?
 - Efficiency-load curves based on motor type:
 - Synchronous
 - Induction
 - Normalisation of efficiency based on motor size

- Modeling of "overtorque" conditions







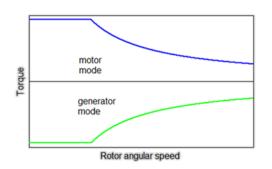


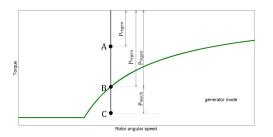


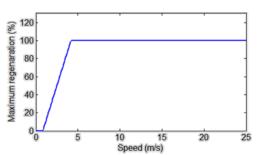


From "tank" to "wheels": Vehicle operational processes for electric vehicles (EVs) (3)

- What's new in modeling of energy recuperation?
 - Symmetric torque-speed curve:
 - Motor mode
 - Generator mode
 - Maximum torque limitation on energy recuperation
 - Maximum regeneration capability (%) as function of vehicle speed
 - No energy recuperation at low vehicle speeds
 - Maximum energy recuperation for vehicle speeds above a minimum threshold













From "tank" to "wheels": Vehicle operational processes for electric cars (1)

 Definition of 3 "average" models based on available electric cars in the market

Low power model

Based on:

- Citroen C-Zero
- Peugeot Ion
- Mitsubishi i-Miev
- VW e-Up!



Medium power model

Based on:

- Renault Zoe
- Renault Fluence ZE
- Nissan Leaf
- KIA Soul



High power model

Based on:

- Ford Focus Electric
- BMW i3
- MercedesBenz Class b Electric

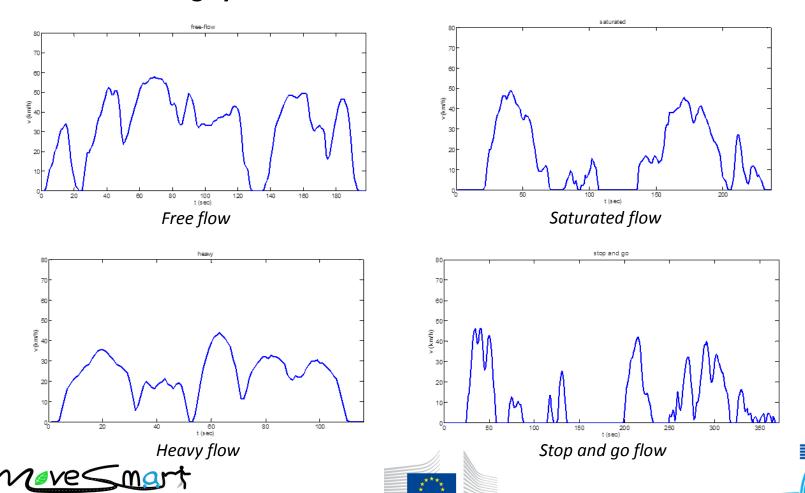






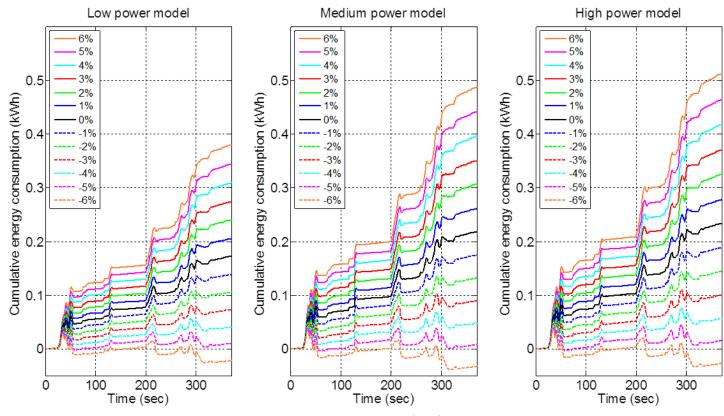
From "tank" to "wheels": Vehicle operational processes for electric cars (2)

• Realistic driving cycles for urban traffic conditions



From "tank" to "wheels": Vehicle operational processes for electric cars (3)

 Extraction of energy consumption factors: Indicative simulation results for stop and go flow and various road gradients





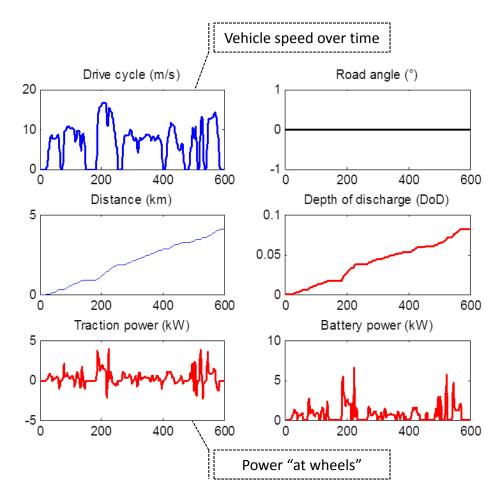




From "tank" to "wheels": Vehicle operational processes for electric scooter

- Model: The Core (GG)
- Regenerative braking: No
- Driving cycle: World Motorcycle Test Cycle (WMTC) – part 1
- Road gradient: 0%



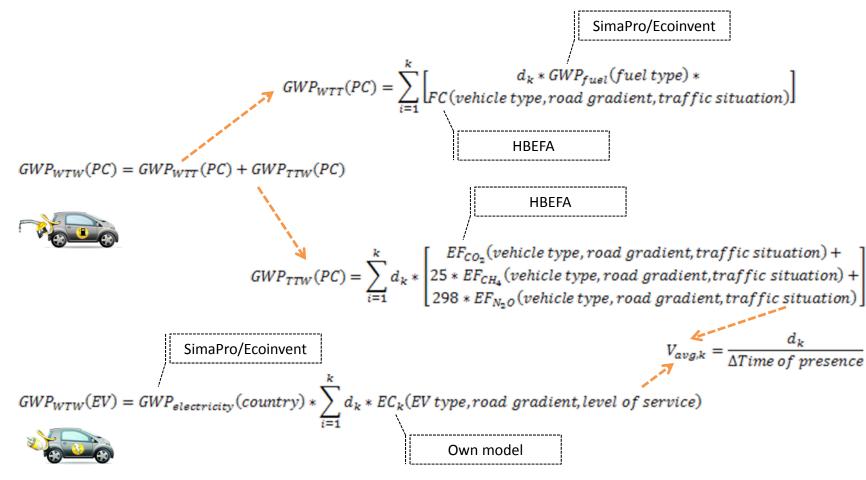








From "well" to "wheels": Full energy/vehicle pathway for PCs and EVs

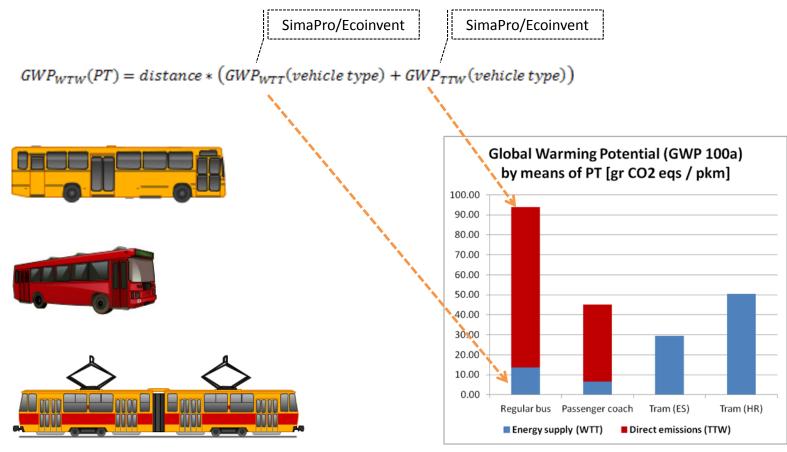








From "well" to "wheels": Full energy/vehicle pathway for public transport (PT)





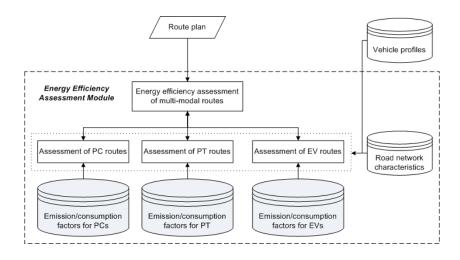


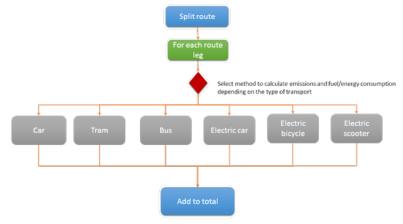


Energy Efficiency Assessment Module as a MOVESMART web-service

 Purpose: Integration of components for energy efficiency assessment of multimodal routes

• **Challenge**: Low response time





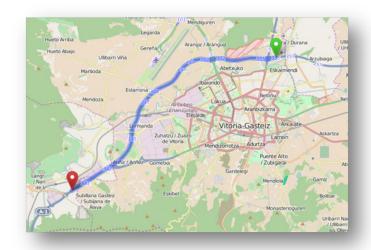






Concluding remarks

- Worst case scenario:
 - 15 km route with PC in Vitoria-Gasteiz
 - 136 road segments
- Achievement: Response time < 0.6 sec
 with Intel Core i5 and 4GB RAM
- Potential improvements:
 - Current implementation is built with Jersey and runs on Grizzly: Test other frameworks, e.g. Vert.x and Akka
 - Load road network characteristics and energy/consumption databases in memory









Questions?

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