

Linear DC-Servomotors

with Analog Hall Sensors QUICKSHAFT® Technology

3,6 N

For combination with Drive Electronics:
Motion Controller

Series LM 1247 ... 11

	LM 1247-	020-11	040-11	060–11	080-11	100–11	120–11	
1 Continuous force 1)	Fe max.	3,6						N
2 Peak force 1) 2)	Fp max.	10,7						N
3 Continuous current 1)	le max.	0,55						Α
4 Peak current 1) 2)	lp max.	1,66						Α
5 Back-EMF constant	kε	5,25						V/m/s
6 Force constant ³⁾	k F	6,43						N/A
7 Terminal resistance, phase-phase	R	13,17						Ω
8 Terminal inductance, phase-phase	L	820						μH
					1		1	
9 Stroke length	Smax.	20	40	60	80	100	120	mm
10 Repeatability ⁴⁾		40	40	40	40	40	40	μm
11 Precision ⁴⁾		120	140	160	180	200	220	μm
42							00.0	, 2
12 Acceleration 5)	a e max.	198,0	148,5	127,3	101,8	91,4	82,9	m/s ²
13 Speed ^{5) 6)}	Ve max.	2,0	2,4	2,8	2,9	3,0	3,2	m/s
14 Thermal resistance	Rth1 / Rth2	2 2 / 20 0						K/W
15 Thermal time constant	Tw1 / Tw2	3,2 / 20,0 11 / 624						-
15 Thermal time constant	lw1 / lw2	11/624						S
16 Operating temperature range		- 20 +125						°C
To Operating temperature range		- 20 TIZJ						
17 Rod weight 7)	m m	18	24	28	35	39	43	g
18 Total weight ⁷⁾	mt	57	63	67	74	78	82	g
10 Total Weight	7770	3,	03	07	174	70	02	9
19 Magnetic pitch	τm	18						mm
	*							111111
20 Rod bearings		polymer sleeves						
21 Housing material		metal, non-magnetic						
22 Direction of movement		electronically reversible						

¹⁾ thermal resistance Rth 2 by 55% reduced

Notes: These motors are for operation with DC-voltage < 75 V DC.

The given values are for free standing motors.

The mounting with magnetic conductive metal can influence the characteristics of the motor.

Caution: Presence of strong magnetic fields. Static sensitive device.



Trapezoidal motion profile (t1 = t2 = t3)

Displacement distance: 20 mm
Friction coefficient: 0,2
Slope angle: 0°
Rest time: 0,1 s

Load: The max. permissible load at a given speed with an

a given speed with an external force of 0 N

External force: The max. permissible external force at a given speed with a load of:

²⁾ for max. 1 second with a duty cycle of 10%

³⁾ with sine wave commutation

⁴⁾ typical values with integrated linear Hall sensors and Motion Controller.

The values depend on conditions of use 5) theorical value, referring only to the motor

⁶⁾ with a triangular speed profile and the max. stroke

⁷⁾ rounded value, for reference only







