

$$A = \begin{pmatrix} 3 & -1 & 1 & -7 \\ 9 & -3 & -7 & -1 \\ 0 & 0 & 4 & -8 \\ 0 & 0 & 2 & -4 \end{pmatrix}$$

$$p_A(\lambda) = \det(\lambda I - A) \\ = \lambda^4$$

0 é o único autovalor
autovetores (em \mathbb{R}^4)

$$\begin{pmatrix} 3 & -1 & 1 & -7 \\ 9 & -3 & -7 & -1 \\ 0 & 0 & 4 & -8 \\ 0 & 0 & 2 & -4 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \\ w \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$$z + 2w = 0$$

$$\text{Aut}_A(0) = \left[\begin{pmatrix} 5 \\ 0 \\ 6 \\ 3 \end{pmatrix}, \begin{pmatrix} 1 \\ 3 \\ 0 \\ 0 \end{pmatrix} \right] \xrightarrow{\dim} 2 \Rightarrow \text{há dois blocos de}$$

$$A_1 = \left(\begin{array}{c|cc} 0 & 0 & 0 \\ 1 & 0 & 0 \\ \hline 0 & 1 & 0 \\ 0 & 0 & 0 \end{array} \right) \text{ ou } A_2 = \left(\begin{array}{c|cc} 0 & 0 & 0 \\ 0 & 1 & 0 \\ \hline 0 & 0 & 0 \end{array} \right) \text{ Jordan}$$

$$v_4 = \begin{pmatrix} 1 \\ 3 \\ 0 \\ 0 \end{pmatrix} \quad \uparrow \quad \text{Existe } v_3 \text{ tq } Av_3 = v_4?$$

$$v_3 = \begin{pmatrix} x \\ y \\ z \\ w \end{pmatrix} \begin{pmatrix} 3 & -1 & 1 & -7 \\ 9 & -3 & -7 & -1 \\ 0 & 0 & 4 & -8 \\ 0 & 0 & 2 & -4 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \\ w \end{pmatrix} = \begin{pmatrix} 1 \\ 3 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 3 & -1 & 1 & -7 & 1 \\ 9 & -3 & -7 & -1 & 3 \\ 0 & 0 & 4 & -8 & 0 \\ 0 & 0 & 2 & -4 & 0 \end{pmatrix} \rightarrow \begin{pmatrix} 3 & -1 & 1 & -7 & 1 \\ 0 & 0 & -10 & 20 & 0 \\ & & 0 & 0 & - \\ & & 0 & 0 & - \end{pmatrix}$$

$$z = 2w$$

$$3x - y + z - 7w = 1$$

$$3x - y + 2w - 7w = 1$$

$$3x - y - 5w = 1 \quad y = 3x - 5w - 1$$

$$S = \left\{ \begin{pmatrix} x \\ 3x - 5w - 1 \\ 2w \\ w \end{pmatrix} ; x, w \in \mathbb{R} \right\}$$

$$x=1, w=0, \quad v_3 = \begin{pmatrix} 1 \\ 2 \\ 0 \\ 0 \end{pmatrix}.$$

$$\text{Como } \begin{pmatrix} 3 & -1 & 1 & -7 \\ 9 & -3 & -7 & -1 \\ 0 & 0 & 4 & -8 \\ 0 & 0 & 2 & -4 \end{pmatrix}^2 = 0$$

$\Rightarrow m_A(x) = x^2 \Rightarrow$ o maior dos blocos de Jordan é de ordem 2

$$\Rightarrow J(A) = \begin{pmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}$$

$$v_3, v_4; \quad v_2 = \begin{pmatrix} 5 \\ 0 \\ 6 \\ 3 \end{pmatrix}; \quad v_1 \text{ é solução de}$$

$$(A - 0I)v_1 = v_2.$$

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$$(6) \quad p_1(x) = (x-3)^5(x-2)^4, \quad m_\tau(x) = (x-3)^3(x-2)^2$$

$$\begin{aligned} \text{Um bloco } 5 \times 5 &\leftrightarrow \lambda_1 = 3 \\ 4 \times 4 &\leftrightarrow \lambda_2 = 2 \end{aligned}$$

do bloco $5 \times 5 \leftrightarrow \lambda_1 = 3$, o maior dos blocos de Jordan é 3×3 ($m_\tau(x) = (x-3)^3(x-2)^2$)

\Rightarrow há exatamente duas possibilidades

$$\left(\begin{array}{ccc|ccc} 3 & & & & & \\ & 3 & & & & \\ 1 & & & & & \\ & 1 & 3 & & & \\ \hline & & & 3 & & \\ & & & & 3 & \\ & & & & 1 & 3 \end{array} \right) \text{ ou } \left(\begin{array}{ccc|cc} 3 & & & & \\ & 3 & & & \\ 1 & & & & \\ & 1 & 3 & & \\ \hline & & & 3 & 0 \\ & & & 0 & 3 \end{array} \right)$$

$$\dim \text{Aut}_\tau(3) = 2$$

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Para o bloco $4 \times 4 \leftrightarrow 2$, o maior dos blocos de Jordan é 2×2 . Então, as possibilidades são

$$\left(\begin{array}{cc|cc} 2 & 2 & & \\ 1 & & & \\ \hline & & 2 & \\ & & 1 & 2 \end{array} \right) \sim \left(\begin{array}{cc|cc} 2 & 2 & & \\ 1 & & & \\ \hline & & 2 & \\ & & & 2 \end{array} \right)$$

$$\dim \ker_{\tau}(2) = 2$$

$$= 3$$

$$9 \times 9: \left(\begin{array}{cc|cc} 5 \times 5 & & & \\ \hline & & 4 \times 4 & \end{array} \right)$$

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$$5 - A = \left(\begin{array}{cc|cc} 0 & -9 & 0 & 0 \\ 1 & -6 & 0 & 0 \\ \hline 0 & 0 & 3 & 0 \\ 0 & 0 & 0 & 3 \end{array} \right)$$

$$p_A(x) = \det(xI - A)$$

$$= \left(\det \begin{pmatrix} x+9 & \\ -1 & x-6 \end{pmatrix} \right) (x-3)^2$$

$$(x(x-6)+9)(x-3)^2 =$$

$$(x^2 - 6x + 9)(x-3)^2 = (x-3)^4$$

$$\begin{pmatrix} 3 & 9 \\ -1 & -3 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 3 & 9 & & \\ -1 & -3 & & \\ & & 0 & \\ & & & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \\ w \end{pmatrix} = 0$$

z, w livres

$$x = -3y$$

$$\ker_A(3) = S = \left\{ \begin{pmatrix} -3y \\ y \\ z \\ w \end{pmatrix} \right\}, \dim S = 3 \Rightarrow \text{nos é}$$

diagonalizável e o nº de blocos de Jordan é 3

$$\Rightarrow J(A) = \left(\begin{array}{cc|cc} 3 & 1 & 1 & 1 \\ -1 & 3 & 1 & 1 \\ \hline & & 3 & 1 \\ & & 1 & 3 \end{array} \right)$$

$$3I - A' = \begin{pmatrix} 3 & 9 \\ -1 & -3 \end{pmatrix} ; \quad (3I - A') \begin{pmatrix} x \\ y \end{pmatrix} = 0$$

$$S = \left\{ \begin{pmatrix} -3y \\ y \end{pmatrix} \right\}$$

$$v_2 = \begin{pmatrix} -3 \\ 1 \end{pmatrix} \quad v_1 \text{ é solução de}$$

$$\begin{pmatrix} 3 & 9 \\ -1 & -3 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} -3 \\ -1 \end{pmatrix}$$

$$x + 3y = 1 \quad x = 1 - 3y$$

$$S = \left\{ \begin{pmatrix} 1-3y \\ y \end{pmatrix} \right\}, \text{ escolha } v_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$v_1 : (3I - A)v_1 = v_2$$

$$3v_1 - Av_1 = v_2$$

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$$T ; \text{ Nuc } T, \quad v \in \text{Nuc } T \Rightarrow Tv = 0$$

$$\Rightarrow T(Tv) = T(0) = 0 \Rightarrow v \in \text{Nuc } T^2$$

$$\Rightarrow \text{Nuc } T \subset \text{Nuc } T^2$$

$$\Rightarrow \text{Nuc } T \subset \text{Nuc } T^2 \subset \dots \subset \text{Nuc } T^m \subset \text{Nuc } T^{m+1} \subset \dots$$

$$\dim V < \infty \Rightarrow \exists m \text{ (o menor) tq}$$

$$\text{Nuc } T^{m+i} = \text{Nuc } T^m, \forall i$$

$$\Rightarrow T = T_1 \oplus T_2, \text{ onde}$$

$$T_1 = T|_{U_1}; \quad U_1 = \text{Nuc } T^m$$

$$T_2 = T|_{U_2}; \quad U_2 = \text{Im } T^m.$$

$$(8) \quad T: \mathcal{P}_n(\mathbb{R}) \rightarrow \mathcal{P}_n(\mathbb{R}), \quad T(p(x)) = p(x+1)$$

(a) Forma de Jordan de T

(b) Uma base p/ $n=4$

$$\mathcal{B}_0 = \{1, x, \dots, x^n\}.$$

$$T(1) = 1, \quad T(x) = x+1, \quad T(x^2) = (x+1)^2 \\ = x^2 + 2x + 1$$

$$T(x^3) = x^3 + 3x^2 + 3x + 1, \dots$$

$$T_{B_0} = \begin{bmatrix} 1 & 1 & 1 & 1 & \dots \\ 0 & 1 & 2 & 3 & \dots \\ 0 & 0 & 1 & 3 & \dots \\ \vdots & \vdots & 0 & 1 & \dots \\ 0 & 0 & 0 & \dots & \dots \end{bmatrix}$$

$$\det(\lambda I - T) = (\lambda - 1)^n$$

$$(T - I)X = 0 \quad \begin{bmatrix} 0 & 1 & 1 & 1 & \dots \\ 0 & 0 & 2 & 3 & \dots \\ 0 & \vdots & 0 & 3 & \dots \\ \vdots & \vdots & \vdots & 0 & \dots \\ 0 & 0 & 0 & 0 & \dots \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_n \\ 0 \end{bmatrix} = \vec{0}$$

$\rightarrow \begin{pmatrix} n \\ 1 \end{pmatrix}$

x_1 é livre; da penúltima linha
da antepenúltima

$$\begin{aligned} x_n &= 0 \\ x_{n-1} &= 0 \\ &\vdots \\ x_2 &= 0 \end{aligned}$$

$$v = \begin{pmatrix} 1 \\ 0 \\ 0 \\ \vdots \\ 0 \end{pmatrix} \quad (\dim \ker(T - I) = 1)$$

\Rightarrow um bloco de Jordan (em particular

$$m_T(\lambda) = p_T(\lambda)$$

$$J(T) = \begin{pmatrix} 1 & & & & 0 \\ 1 & 1 & & & \\ & 1 & 1 & & \\ 0 & & 1 & 1 & \dots & 1 & 1 \\ & & & 1 & \dots & 1 & 1 \end{pmatrix}_{n \times n}$$

$$\text{Ex } n = \cancel{4} 3 \quad T_0 = \begin{pmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$T - I = \begin{pmatrix} 0 & 1 & 1 & 1 \\ 0 & 0 & 2 & 3 \\ 0 & 0 & 0 & 3 \\ 0 & 0 & 0 & 0 \end{pmatrix} \quad \text{e} \quad v = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} \text{ gera}$$

$$\text{Aut}_T(1) ; \text{ chama-se } v_4 = v = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$$v_3 \text{ é sol de } (T - I)x = v_4$$

$$v_2 \quad \quad \quad v_3$$

$$v_1 \quad \quad \quad v_2$$

$$P_3(\mathbb{R}) = [v_1, Tv_1, T^2v_1, \underset{\substack{\uparrow \\ \text{autovetor}}}{T^3v_1}]$$

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$$A \in M_6(\mathbb{R}) : A^4 - 8A^2 + 16I = 0$$

$$\begin{aligned} q(x) &= x^4 - 8x^2 + 16 \\ &= (x^2 - 4)^2 \end{aligned}$$

$$q(\lambda) = (\lambda+2)^2(\lambda-2)^2$$

$$m_A(\lambda) \mid q(\lambda) \quad \text{pois} \quad q(A) \equiv 0 \in L(\mathbb{R}^6, \mathbb{R}^6)$$

Os possíveis $m_A(\lambda)$:

$$\begin{cases} (\lambda+2)(\lambda-2) \leftarrow \text{diag} \\ (\lambda+2)^2(\lambda-2) \\ (\lambda+2)(\lambda-2)^2 \\ (\lambda+2)^2(\lambda-2)^2 \\ \vdots \\ (\lambda+2) \leftarrow \text{diag} \\ (\lambda+2)^2 \\ (\lambda-2) \leftarrow \text{diag} \\ (\lambda-2)^2 \end{cases}$$

Suponha que

$$p_A(\lambda) = (\lambda-2)^m (\lambda+2)^l, \quad m+l=6$$

$$m_A(\lambda) = (\lambda-2)^2 (\lambda+2)$$

\uparrow
 Um bloco $J(2)_{2 \times 2}$

$J(-2)$ só 1×1

$$m=2, \quad l=4$$

$$\begin{pmatrix} 2 & & & & \\ 1 & 2 & & & \\ & -2 & -2 & & \\ & & -2 & -2 & \\ & & & -2 & -2 \end{pmatrix},$$

$$m=3, \quad l=3$$

$$\begin{pmatrix} 2 & & & & \\ 1 & 2 & & & \\ & 2 & -2 & & \\ & & -2 & -2 & \\ & & & -2 & -2 \end{pmatrix}$$

$$m=4, \quad l=2 \quad \begin{pmatrix} 2 & & & & \\ 1 & 2 & & & \\ & 2 & 2 & & \\ & 1 & 2 & & \\ & & -2 & -2 & \\ & & & -2 & -2 \end{pmatrix} \text{ ou}$$

$$\begin{pmatrix} 2 & & & & & \\ & 1 & 2 & & & \\ & & 2 & & & \\ & & & 2 & & \\ & & & & -2 & \\ & & & & & -2 \end{pmatrix}$$

\vdots

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$$P_T(\lambda) = (\lambda - \lambda_1)^{m_1} \cdots (\lambda - \lambda_t)^{m_t}$$

$$\exists U_i, \dim U_i = m_i, \quad i = 1, \dots, t,$$

T - invariantes

$$T|_{U_i} = \begin{bmatrix} J_1(\lambda_i) & & \\ & \ddots & \\ & & J_k(\lambda_i) \end{bmatrix}$$

$$\text{ordem } J_{l+1} \leq \text{ordem } J_l \quad ; \quad \text{ordem } J_1 = \text{grau de } \lambda_i \text{ em } m_T(\lambda)$$

e, para cada l , $\exists \gamma$ e um ciclo que "gera" o bloco correspondente.

$$k = \dim \text{Aut}(\lambda_i)$$

$$\underbrace{\lambda \cdot \lambda}_{\in \mathbb{C}}, \quad \lambda \in \mathbb{C}$$

$$T \in L(V, V), \mathbb{R}$$

$$P_T(x) = (x - \lambda_1)^{m_1} \cdots (x - \lambda_t)^{m_t} \cdot \prod_{j=1}^s p_j(x)^{n_j} \quad P_T(x) \sim P_S(x)$$

$p_j(x)$ irredutível de grau 2.

$$l, m_1, m_2, \dots, m_t \begin{matrix} \xleftrightarrow{T} \\ \xleftarrow{S} \end{matrix} \Rightarrow \exists \text{ isomorphism}$$

$$\varphi: V \rightarrow W$$

$$\varphi T \varphi^{-1} = S$$

$$\varphi T = S \varphi$$

$$\begin{array}{ccc} V & \xrightarrow{T} & V \\ \varphi \downarrow & \swarrow & \downarrow \varphi \\ W & \xrightarrow{S} & W \end{array}$$

$$v_1, T v_1, \dots, T^{m_1-1} v_1, v_2, \dots$$

$$\downarrow \varphi$$

$$\uparrow T$$

$$\varphi v_1, \varphi T v_1, \dots, \varphi T^{m_1-1} v_1, \varphi v_2$$

$$w_1, w_2$$

$$w_{m_1}, \dots$$

$$S w_1 = S \varphi v_1$$

$$= \varphi T v_1 = w_2$$

$$\left. \begin{array}{l} S^2 w_1 = S^2 \varphi v_1 = S(S \varphi v_1) = S(\varphi T v_1) \\ \vdots \\ S^{m_1-1} w_1 = \varphi T^{m_1-1} v_1 \end{array} \right\} \text{LI}$$

$$m_1 \hookrightarrow T$$

$$l_1 \hookrightarrow S$$

$$S^{m_1-1} w_1 = \varphi T^{m_1-1} v_1 \uparrow$$

$$S^{m_1} w_1 = \varphi T^{m_1} v_1 = 0 \quad \nwarrow$$

$$\left[\begin{array}{l} l_1 \leq m_1 \\ l_1 \geq m_1 \end{array} \right]$$

$$v_1, Tv_1, T^2v_1, v_2, Tv_2$$

$$\downarrow \varphi$$

$$\varphi v_1 = w_1$$

$$S w_1 = S \varphi v_1 = \varphi T v_1 \Rightarrow$$

$$S^2 w_1 = S^2 \varphi v_1 = \varphi T^2 v_1$$

$$S^3 w_1 = \varphi T^3 v_1 = 0$$

$$\{ w_1, S w_1, S^2 w_1 \} \text{ LI}$$

$$e \\ S^3 w_1 = 0$$

$$l_1 = m_1$$

Se fosse $l_1 = 2$, $S^2 w_1 = 0$ e φ ~~nao~~ não
pode ser iso

$$P_T(x), m_T(x)$$

$$(x - \lambda_1)^{m_1}, (x - \lambda_1)^{d_1}$$

Em $U_1 (\leftrightarrow \lambda_1)$, existe subesp T -inv

de dim d_1 :

$$U_1 = W_1^{d_1} \oplus W_2 \quad e \quad \exists v_1 :$$

$$V = U_1^{m_1} \oplus W_1 \quad T\text{-inv}$$

$$\exists v_1 : U_1 = [v_1, T v_1, \dots, T^{m_1-1} v_1]$$

$$T|_{W_1} \text{ is } m_2\text{-nilp} \quad (m_2 \leq m_1)$$

$$\Rightarrow W_1 = U_2^{m_2} \oplus W_2, \quad \exists v_2 : [v_2, \dots, T^{m_2-1} v_2]$$

$$\vdots$$

$$T|_{W_2} \text{ is } m_3\text{-nilp}, \quad m_3 \leq m_2$$

$$\vdots$$