

# APP INVENTOR

## Conexão com mini Drone Tello DJI

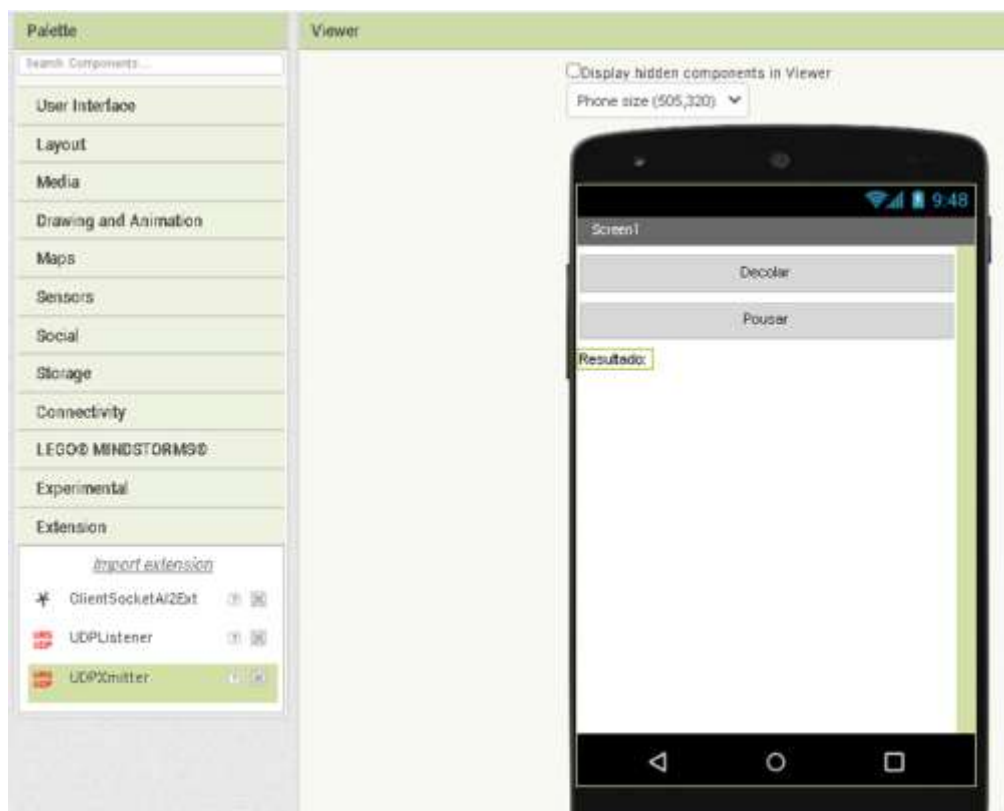


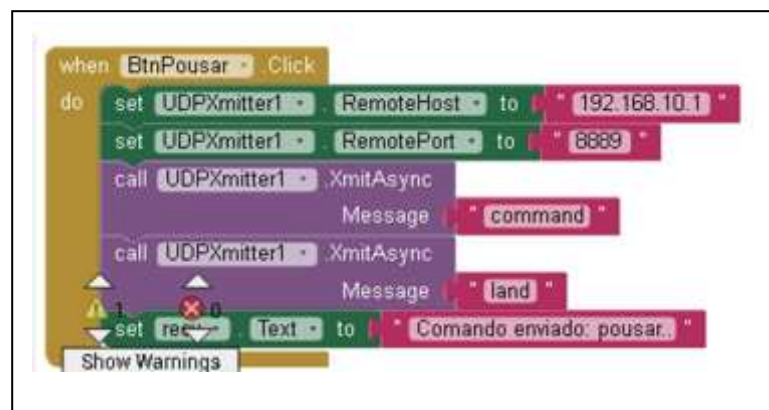
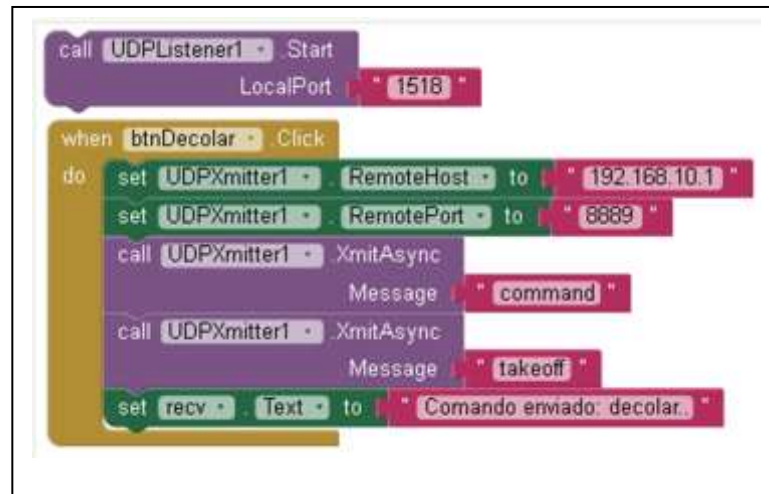
**Baixar a extensão para o App Inventor:**

<https://ullisroboterseite.de/android-AI2-UDP.html>

## Download

Das ZIP-Archiv [Urs42UDP zum Download](#) Das Archiv enthält den Quellcode, das kompilierte Binary zum Upload in den App Inventor und eine Beispiel Anwendung.





Exemplo com código Python

util.py

import threading

import socket

import sys

import time

import platform

host = "

port = 9000

locaddr = (host,port)

# Create a UDP socket

sock = socket.socket(socket.AF\_INET, socket.SOCK\_DGRAM)

```
tello_address = ('192.168.10.1', 8889)
```

```
sock.bind(locaddr) #ligar
```

```
def recv():
```

```
    count = 0
```

```
    while True:
```

```
        try:
```

```
            data, server = sock.recvfrom(1518)
```

```
            #print(data.decode(encoding="utf-8"))
```

```
        except Exception:
```

```
            #print ("\nExit . . .\n')
```

```
            break
```

```
#recvThread create
```

```
recvThread = threading.Thread(target=recv)
```

```
recvThread.start()
```

```
def sendData(cmd):
```

```
    # Send data
```

```
    msg = cmd.encode(encoding="utf-8")
```

```
    sent = sock.sendto(msg, tello_address)
```

```
def sendStop():
```

```
    sock.close()
```

---

```
menu.py
```

```
import sys
```

```
import subprocess as sp
```

```
from utilTello import sendData,sendStop
```

```
def get_menu_choice():
```

```
    def print_menu():
```

```
        print(30 * "-", "DRONE MENU", 30 * "-")
```

```
        print("1. Decolar ")
```

```
        print("2. Pousar")
```

```
        print("3. Vire a direita ")
```

```
        print("4. Vire a esquerda ")
```

```
        print("5. Sair Menu ")
```

```
        print(73 * "-")
```

```
loop = True
```

```
while loop:
```

```
    sp.call('cls', shell=True)
```

```
    print_menu()
```

```
    choice = input("Enter your choice [1-5]: ")
```

```
    if choice == '1': # Decolar
```

```
        sendData("command")
```

```
        sendData("takeoff")
```

```
    elif choice == '2': # Pousar
```

```
        sendData("command")
```

```
        sendData("land")
```

```
    elif choice == '3': # Vire a direita
```

```
        sendData("command")
```

```
        sendData("up 33")
```

```
    elif choice == '4': # Vire a esquerda
```

```
        sendData("command")
```

```
sendData("down 33")
```

```
elif choice == '5':
```

```
sendStop()
```

```
loop = False
```

```
return [choice]
```

```
get_menu_choice()
```

---

Bom estudo.

Prof º Aldriano