

Term-Indexing for Instantiation-Based First Order Theorem Proving

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References



Alexandre Riazanov and Andrei Voronkov, *Efficient instance retrieval with standard and relational path indexing*, Automated Deduction – CADE-19 (Franz Baader, ed.), Lecture Notes in Computer Science, vol. 2741, Springer Berlin Heidelberg, 2003, pp. 380–396 (English).

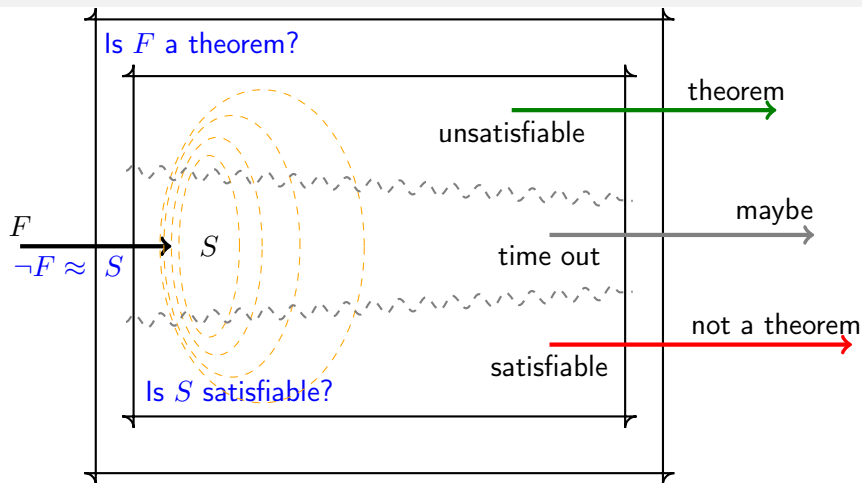


R. Sekar, I. V. Ramakrishnan, and Andrei Voronkov, *Term indexing*, Handbook of Automated Reasoning (Alan Robinson and Andrei Voronkov, eds.), Elsevier Science Publishers B. V., Amsterdam, The Netherlands, The Netherlands, 2001, pp. 1853–1964.

Outline

- 1 Motivation
- 2 path indexing
- 3 discrimination trees

Resolution



Goal

A sound[◊], refutational complete[◊], and effective^{*} procedure.

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A sound[◦], refutational complete[◇], and effective^{*} procedure.

Term retrieval problems

- Find terms that are variants of a given term.
 $\text{variant}(\ell, t) \Leftrightarrow \exists \sigma \ell \sigma = t$ and σ is renaming.
- Find terms that are unifiable with a given term.
 $\text{unifiable}(\ell, t) \Leftrightarrow \exists \sigma \ell \sigma = t \sigma$
- Find terms that are instances of a given term.
 $\text{instance}(\ell, t) \Leftrightarrow \exists \sigma \ell = t \sigma$
- Find terms that are generalizations of a given term.
 $\text{generalization}(\ell, t) \Leftrightarrow \exists \sigma \ell \sigma = t$

Definition

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A position is a sequence of positive integers. The empty sequence ε denotes the root position, pq denotes the concatenation of positions. $\mathcal{Pos}(t)$ denotes the set of positions in term t , and $t|_p$ denotes the subterm of t at position $p \in \mathcal{Pos}(t)$.

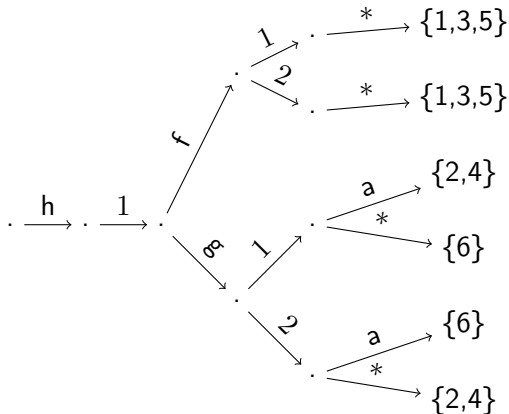
Definition

A position string is a nonempty string of the form $\langle p_1, s_1 \rangle \dots \langle p_n, s_n \rangle$ where p_i are positions and s_i are function or variable symbols and

- 1 if p_i is a proper prefix of p_j then $i < j$
- 2

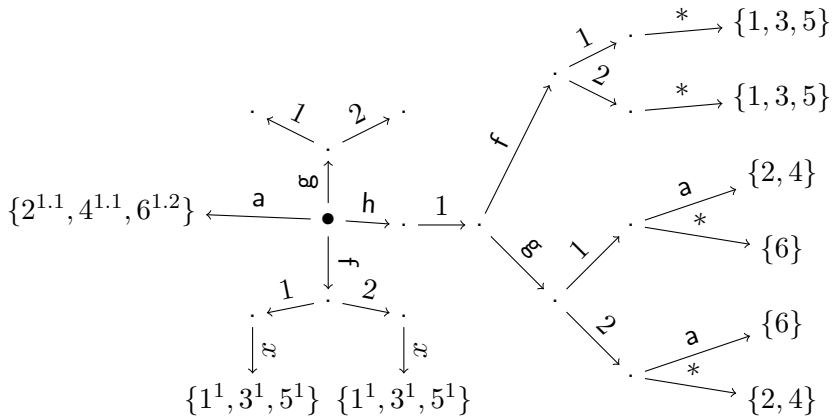
Definition

$$\{^1: h(f(x, x)), ^2: h(g(a, x)), ^3: h(f(y, z)) ^4: h(g(a, y)), ^5: h(f(y, x)), ^6: h(g(y, a))\}$$

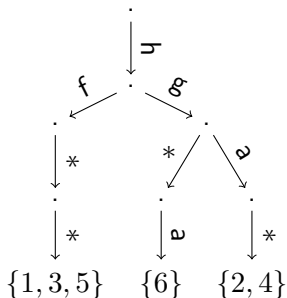


$$h(g(y, x)) \mapsto \{ h.1.g.1.*, h.1.g.2.* \}$$

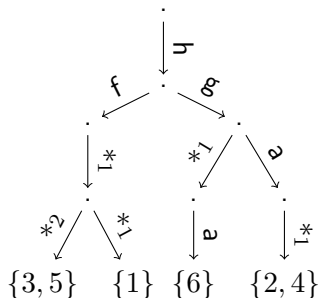
$$\{^1: h(f(x, x)), ^2: h(g(a, x)), ^3: h(f(y, z)) ^4: h(g(a, y)), ^5: h(f(y, x)), ^6: h(g(y, a))\}$$



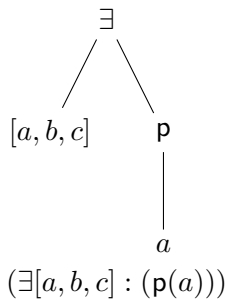
$$\left\{ \begin{array}{lll} {}^1\text{h}(\text{f}(\text{x}, \text{x})), & {}^2\text{h}(\text{g}(\text{a}, \text{x})), & {}^3\text{h}(\text{f}(\text{y}, \text{z})), \\ {}^4\text{h}(\text{g}(\text{a}, \text{y})), & {}^5\text{h}(\text{f}(\text{y}, \text{x})), & {}^6\text{h}(\text{g}(\text{y}, \text{a})) \end{array} \right\}$$



$$\text{h}(\text{f}(\text{y}, \text{x})) \mapsto \text{h.f.*.*}$$



$$\text{h}(\text{f}(\text{y}, \text{x})) \mapsto' \text{h.f.*}_1.*_2$$



$f(a, x)$ f a x $f(a, x) \approx f(x, a)$ \approx f a x f x a