

Term-Indexing

Alexander Maringele

January 27th, 2016

References

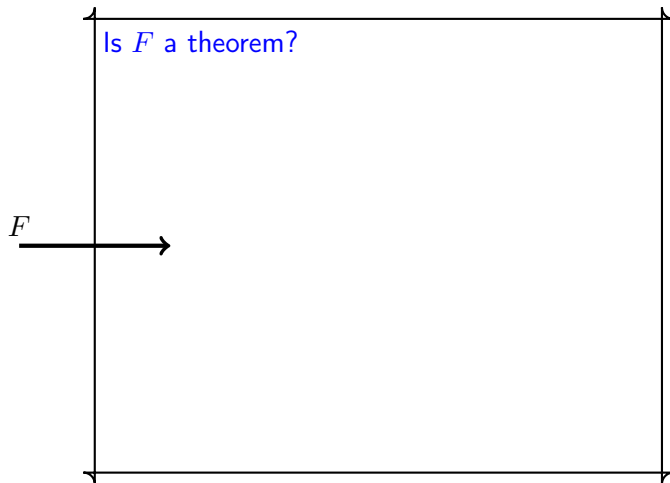


R. Sekar, I. V. Ramakrishnan, and Andrei Voronkov, *Term indexing*, Handbook of Automated Reasoning (Alan Robinson and Andrei Voronkov, eds.), Elsevier Science Publishers B. V., Amsterdam, The Netherlands, 2001, pp. 1853–1964.

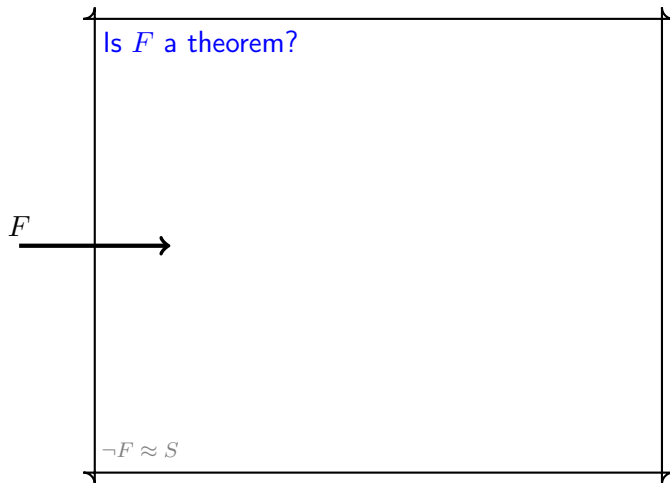
Outline

- 1 Motivation
- 2 Term Structure
- 3 Path Indexing
- 4 Discrimination Trees
- 5 Substitution Trees
- 6 Experiment

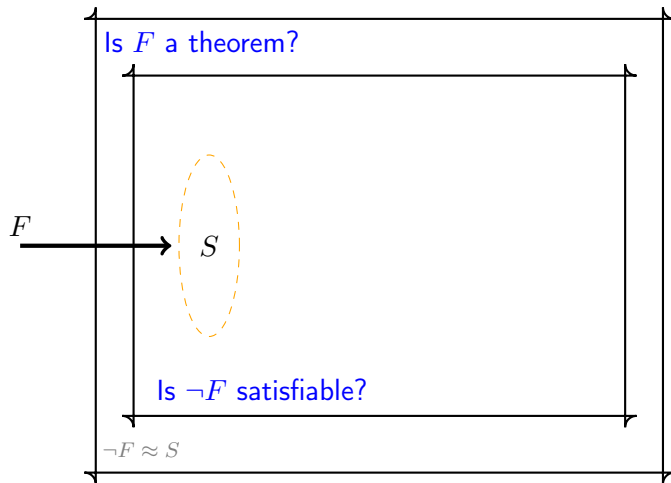
Refutation



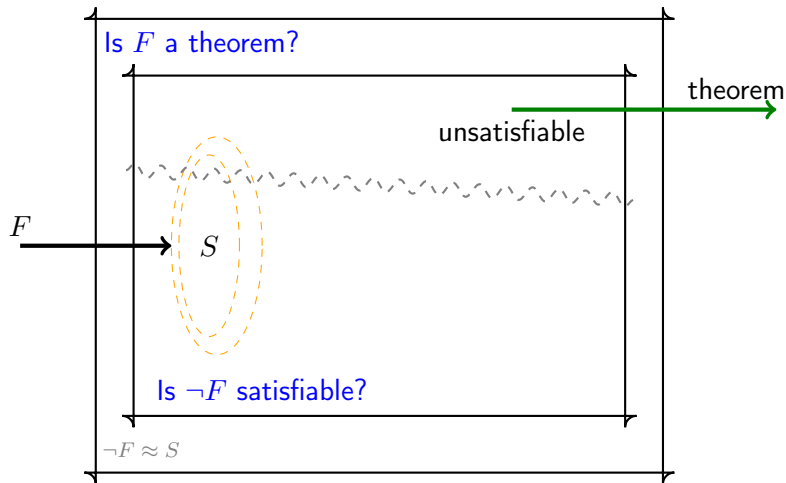
Refutation



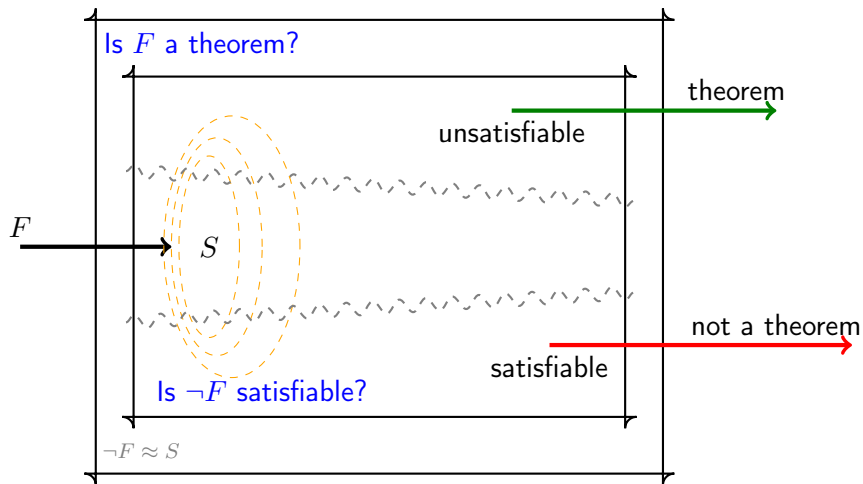
Refutation



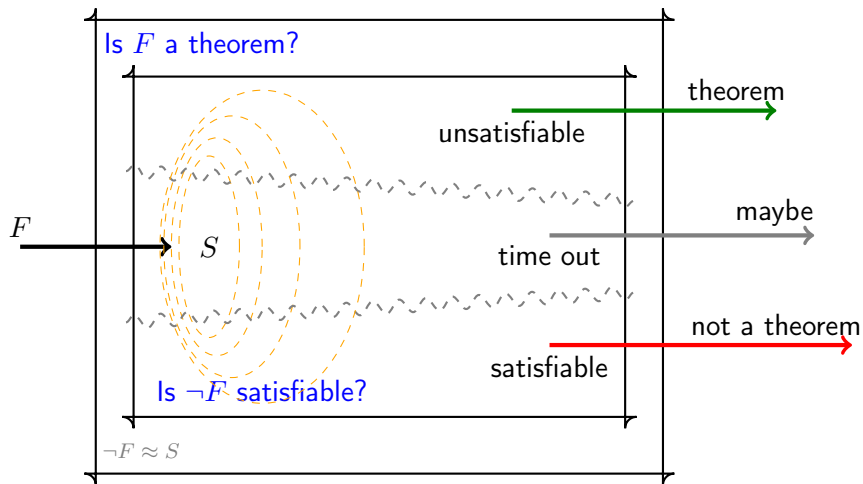
Refutation



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Refutation



Clausal form

$$\{ P(f(x)) \vee f(x) \not\approx a, g(x, y) \approx a \vee \neg Q(x, y), \mathcal{C}_3 \}$$

Clausal form

$$\begin{aligned} & \{ P(f(x)) \vee f(x) \not\approx a, g(x, y) \approx a \vee \neg Q(x, y), \mathcal{C}_3 \} \\ & \equiv \\ & \forall x (P(f(x)) \vee f(x) \not\approx a) \\ & \wedge \\ & \forall xy (g(x, y) \approx a \vee \neg Q(x, y)) \\ & \wedge \\ & \forall \text{Var}(\mathcal{C}_3) (\mathcal{C}_3) \end{aligned}$$

Goal

A sound and refutation complete calculus.

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Resolution (without equality)

Resolve and factor all clauses and literals in an unsatisfiable set

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$$\frac{A \vee C \quad \neg B \vee D}{(C \vee D)\sigma} (\sigma) \text{ resolution} \qquad \frac{A \vee B \vee C}{(A \vee C)\sigma} (\sigma) \text{ factoring}$$

$$\sigma = \text{mgu}(A, B)$$

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$$\sigma = \text{mgu}(A, B)$$

and the empty clause will be derived eventually.

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$$\sigma = \text{mgu}(A, B)$$

and the empty clause will be derived eventually.

Observation

Usually the set grows too fast to obtain a result.

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A sound, refutation complete, and *effective* calculus.

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- 1 *Reduce* search space

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 - Ordered Resolution, Strategies, ...

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- 2 *Reduce* redundancy

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A sound, refutation complete, and *effective* calculus.

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 - ... depending on the calculus

Example (forward subsumption)

$$S = \{^1P(x, y), ^2\neg P(a, z)\} \cup \{^3P(a, z')\}$$

t_1 subsumes t_3

$$\frac{P(x, y) \quad \neg P(a, z)}{\square} \quad \{x \mapsto a, y \mapsto z\}$$

Resolution

$$S \perp = \{P(\perp, \perp), \neg P(a, \perp), P(a, \perp)\}$$

InstGen / SMT

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- 3 Quickly find

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 - *variants*

variant removal

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3 Quickly find

- *variants*
- *instances*

variant removal
backward subsumption

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- *generalizations*

variant removal

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forward subsumption

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- *unifiable terms*

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of a query term in a given set of terms.

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of a query term in a given set of terms.

Observation

Deduction rate drops quickly with sequential search.

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backward subsumption

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Term Indexing

Data structures and algorithms for fast retrieval of matching terms.

Definition (Position Strings)

$$\mathcal{Pos}^{\Sigma}(t) = \left\{ \right.$$

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$$\mathcal{Pos}^{\Sigma}(t) = \begin{cases} \{\langle \epsilon, x \rangle\} & \text{if } t = x \in \mathcal{V} \\ \{\langle \epsilon, f \rangle\} \cup \{\langle ip, s \rangle \mid \langle p, s \rangle \in \mathcal{Pos}^{\Sigma}(t_i)\} & \text{if } t = f(t_1, \dots, t_n) \end{cases}$$

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Term traversals

$$\mathcal{Pos}^{\Sigma}(h(f(a, y))) = \{ \quad \quad \quad \}$$

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$$\mathcal{Pos}^{\Sigma}(h(f(a, y))) = \{\langle \epsilon, h \rangle, \langle \epsilon, f \rangle, \langle 1, a \rangle, \langle 2, y \rangle\}$$

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Term traversals

$$\mathcal{Pos}^{\Sigma}(h(f(a, y))) = \{\langle \epsilon, h \rangle, \langle 1, f \rangle, \langle 11, a \rangle, \quad \}$$

 $\langle \epsilon, h \rangle$
 $\langle 1, f \rangle$
 $\langle 11, a \rangle$

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Term traversals

$$\mathcal{Pos}^{\Sigma}(h(f(a, y))) = \{\langle \epsilon, h \rangle, \langle 1, f \rangle, \langle 11, a \rangle, \langle 12, y \rangle\}$$

$\langle \epsilon, h \rangle$

$\langle 1, f \rangle$

$\langle 11, a \rangle$

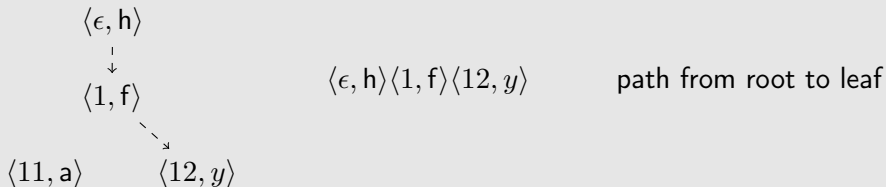
$\langle 12, y \rangle$

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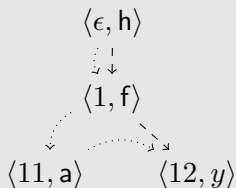


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$\langle \epsilon, h \rangle \langle 1, f \rangle \langle 12, y \rangle$ path from root to leaf
 $\langle \epsilon, h \rangle \langle 1, f \rangle \langle 11, a \rangle \langle 12, y \rangle$ pre-order traversal

Variables

Variants of terms generate the same position strings

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- if variable names are ignored

$$f(y, z) \Rightarrow \langle \epsilon, f \rangle \langle 1, * \rangle \langle 2, * \rangle$$

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- or normalized

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$$f(y, z) \Rightarrow \langle \epsilon, f \rangle \langle 1, x_1 \rangle \langle 2, x_2 \rangle$$

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In the first case even non-variants of terms generate the same strings.

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- path strings $\langle \epsilon, h \rangle \langle 1, f \rangle \langle 12, * \rangle$

$h.1.f.2.*$

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- and traversal strings $\langle \epsilon, h \rangle \langle 1, f \rangle \langle 11, * \rangle \langle 12, * \rangle$ h.f.a.*

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- and traversal strings $\langle \epsilon, h \rangle \langle 1, f \rangle \langle 11, * \rangle \langle 12, * \rangle$ h.f.a.*
when traversal order and arities of symbols are fixed.

Build

$$^{t_1:} h(f(x, y)), ^{t_2:} h(f(x, a)), ^{t_3:} h(f(a, a))$$

$$t_1 \Rightarrow \{h.1.f.1.*, h.1.f.2.*\}$$

$$t_2 \Rightarrow \{h.1.f.1.*, h.1.f.2.a\}$$

$$t_3 \Rightarrow \{h.1.f.1.a, h.1.f.2a\}$$

Build

$$\begin{matrix} \cdot \\ \vdots \\ h \\ \downarrow \\ \cdot \end{matrix}$$

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$$\begin{array}{c} \cdot \\ \vdots \\ h \\ \downarrow \\ \cdot \\ \vdots \\ 1 \\ \downarrow \\ \cdot \end{array}$$

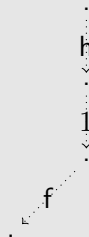
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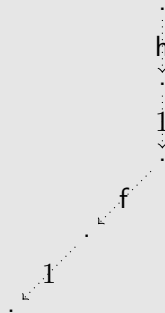
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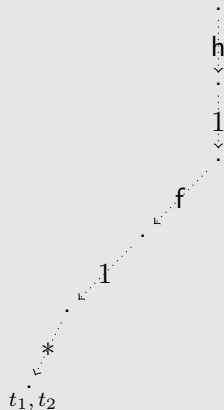
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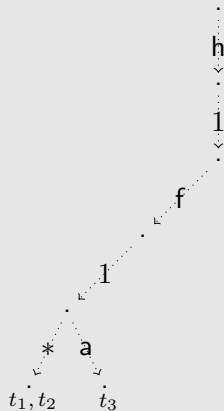
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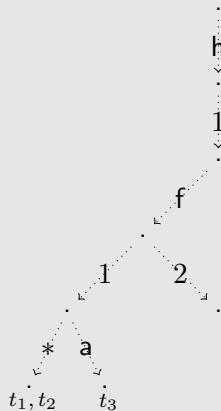
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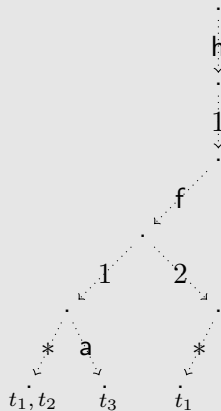
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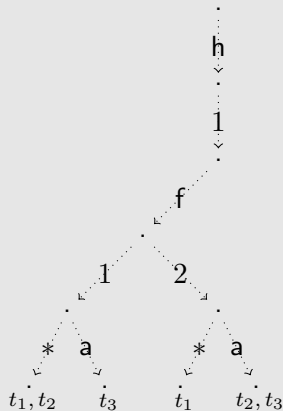


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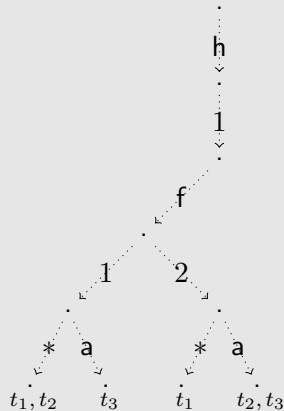
$$t_3 \Rightarrow \{h.1.f.1.a, h.1.f.2.a\}$$


Retrieve

$$^{t_1}h(f(x, y)), ^{t_2}h(f(x, a)), ^{t_3}h(f(a, a))$$

$$h(f(z, b)) \Rightarrow \{h.f.*, h.f.b\}$$

$$u : h(f(\textcolor{blue}{z}, \textcolor{green}{b})) \mapsto$$

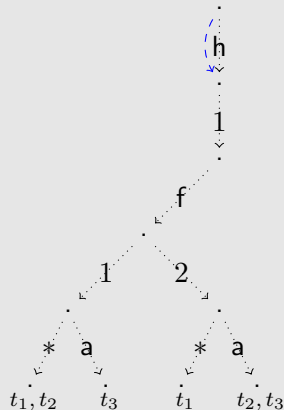


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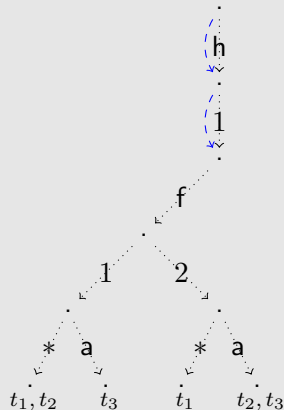


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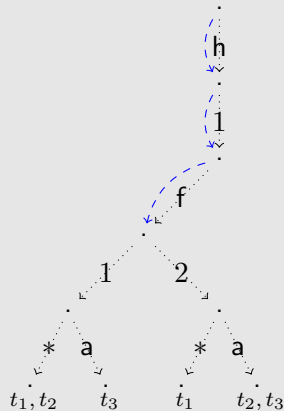


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$$h(f(z, b)) \Rightarrow \{h.f.*, h.f.b\}$$

$$u : h(f(z, b)) \mapsto$$

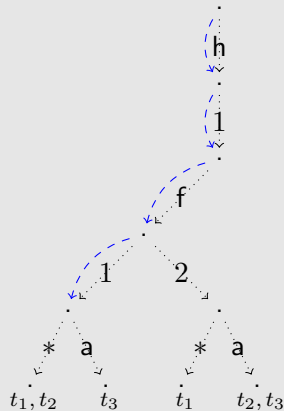


Retrieve

$$^{t_1}h(f(x, y)), ^{t_2}h(f(x, a)), ^{t_3}h(f(a, a))$$

$$h(f(z, b))) \Rightarrow \{h.f.*, h.f.b\}$$

$$u : h(f(z, b)) \mapsto$$

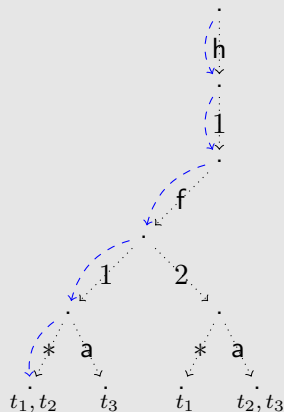


Retrieve

$$^{t_1}h(f(x, y)), ^{t_2}h(f(x, a)), ^{t_3}h(f(a, a))$$

$$h(f(z, b))) \Rightarrow \{h.f.*, h.f.b\}$$

$$u : h(f(z, b)) \mapsto \{t_1, t_2, \quad \}$$

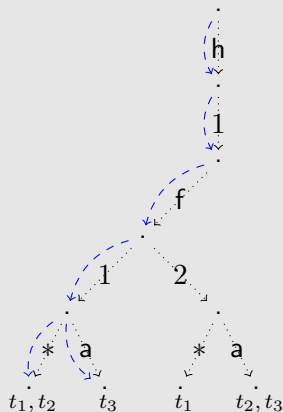


Retrieve

$$^{t_1}h(f(x, y)), ^{t_2}h(f(x, a)), ^{t_3}h(f(a, a))$$

$$h(f(z, b))) \Rightarrow \{h.f.*, h.f.b\}$$

$$u : h(f(\textcolor{blue}{z}, \textcolor{green}{b})) \mapsto \{t_1, t_2, t_3\}$$

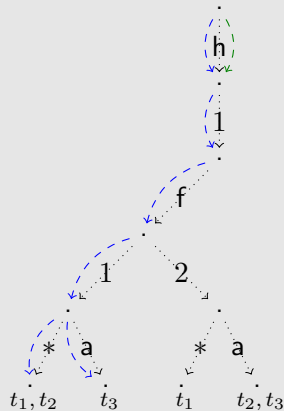


Retrieve

$$^{t_1}h(f(x, y)), ^{t_2}h(f(x, a)), ^{t_3}h(f(a, a))$$

$$h(f(z, b))) \Rightarrow \{h.f.*, h.f.b\}$$

$$u : h(f(z, b)) \mapsto \{t_1, t_2, t_3\}$$

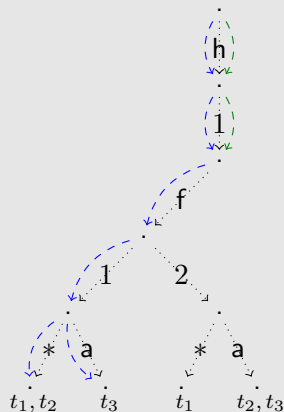


Retrieve

$$^{t_1}h(f(x, y)), ^{t_2}h(f(x, a)), ^{t_3}h(f(a, a))$$

$$h(f(z, b))) \Rightarrow \{h.f.*, h.f.b\}$$

$$u : h(f(z, b)) \mapsto \{t_1, t_2, t_3\}$$

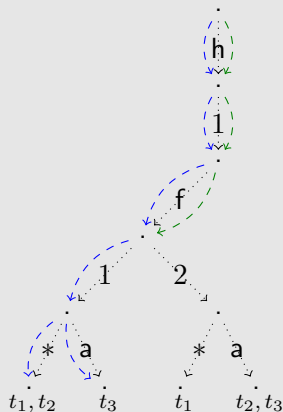


Retrieve

$$^{t_1}h(f(x, y)), ^{t_2}h(f(x, a)), ^{t_3}h(f(a, a))$$

$$h(f(z, b))) \Rightarrow \{h.f.*, h.f.b\}$$

$$u : h(f(z, b)) \mapsto \{t_1, t_2, t_3\}$$

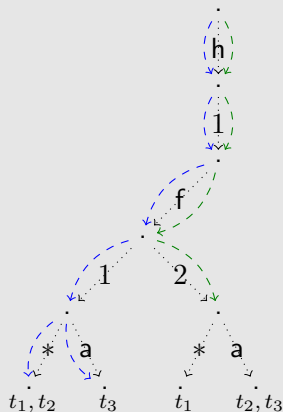


Retrieve

$$^{t_1}h(f(x, y)), ^{t_2}h(f(x, a)), ^{t_3}h(f(a, a))$$

$$h(f(z, b))) \Rightarrow \{h.f.*, h.f.b\}$$

$$u : h(f(\textcolor{blue}{z}, \textcolor{green}{b})) \mapsto \{t_1, t_2, t_3\}$$

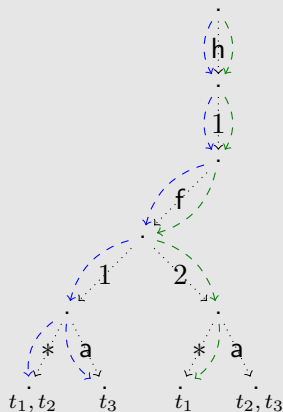


Retrieve

$$^{t_1}h(f(x, y)), ^{t_2}h(f(x, a)), ^{t_3}h(f(a, a))$$

$$h(f(z, b))) \Rightarrow \{h.f.*, h.f.b\}$$

$$u : h(f(z, b)) \mapsto \{t_1, t_2, t_3\} \cap \{t_1\}$$



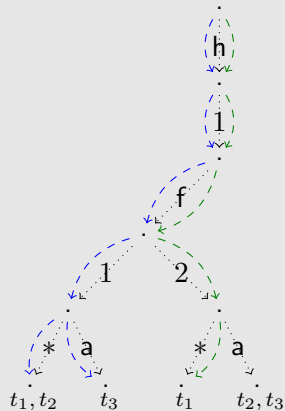
Retrieve

$$^{t_1}h(f(x, y)), ^{t_2}h(f(x, a)), ^{t_3}h(f(a, a))$$

$$h(f(z, b)) \Rightarrow \{h.f.*, h.f.b\}$$

$$u : h(f(z, b)) \mapsto \{t_1, t_2, t_3\} \cap \{t_1\}$$

$$i : h(f(z, b)) \mapsto \{t_1, t_2, t_3\} \cap \{\}$$



Retrieve

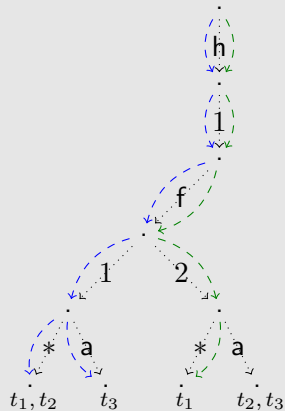
$$^{t_1}h(f(x, y)), ^{t_2}h(f(x, a)), ^{t_3}h(f(a, a))$$

$$h(f(z, b)) \Rightarrow \{h.f.*, h.f.b\}$$

$$u : h(f(z, b)) \mapsto \{t_1, t_2, t_3\} \cap \{t_1\}$$

$$i : h(f(z, b)) \mapsto \{t_1, t_2, t_3\} \cap \{\}$$

$$g : h(f(z, b)) \mapsto \{t_1, t_2\} \cap \{t_1\}$$



Retrieve

$$^{t_1}h(f(x, y)), ^{t_2}h(f(x, a)), ^{t_3}h(f(a, a))$$

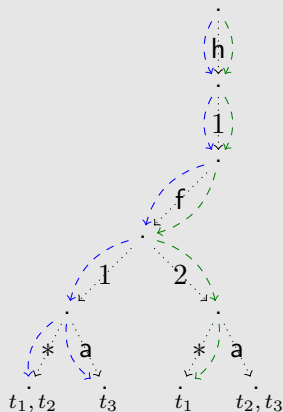
$$h(f(z, b)) \Rightarrow \{h.f.*, h.f.b\}$$

$$u : h(f(z, b)) \mapsto \{t_1, t_2, t_3\} \cap \{t_1\}$$

$$i : h(f(z, b)) \mapsto \{t_1, t_2, t_3\} \cap \{\}$$

$$g : h(f(z, b)) \mapsto \{t_1, t_2\} \cap \{t_1\}$$

$$v : h(f(z, b)) \mapsto \{t_1, t_2\} \cap \{\}$$



Retrieve

$$^{t_1}h(f(x, y)), ^{t_2}h(f(x, a)), ^{t_3}h(f(a, a))$$

$$h(f(z, b))) \Rightarrow \{h.f.*, h.f.b\}$$

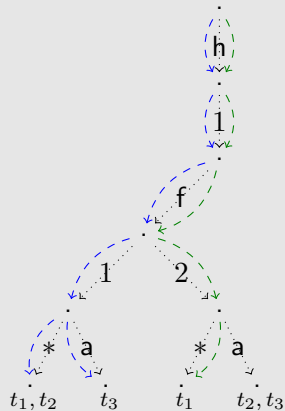
$$u : h(f(z, b)) \mapsto \{t_1, t_2, t_3\} \cap \{t_1\}$$

$$i : h(f(z, b)) \mapsto \{t_1, t_2, t_3\} \cap \{\}$$

$$g : h(f(z, b)) \mapsto \{t_1, t_2\} \cap \{t_1\}$$

$$v : h(f(z, b)) \mapsto \{t_1, t_2\} \cap \{\}$$

$$v : h(f(z, z)) \mapsto \{t_1, t_2\} \cap \{t_1\}$$



Unit Superposition Inference Rules

$$\frac{s \approx t \quad L[s']}{(L[t]) \cdot \sigma} \quad \begin{array}{l} \text{unit} \\ \text{paramodulation} \end{array}$$

where $\sigma = \text{mgu}(s, s')$, $s' \notin \mathcal{V}$, $t\sigma \neq s\sigma$

$$\frac{s \approx t \quad u[s'] \not\approx v}{(u[t] \not\approx v) \cdot \sigma} \quad \begin{array}{l} \text{unit} \\ \text{superposition} \end{array} \quad \frac{s \approx t \quad u[s'] \approx v}{(u[t] \approx v) \cdot \sigma}$$

where $\sigma = \text{mgu}(s, s')$, $s' \notin \mathcal{V}$, $t\sigma \neq s\sigma$, $v\sigma \neq u[s']\sigma$

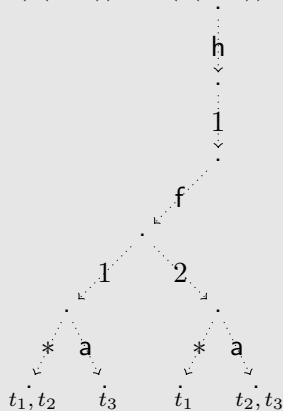
$$\frac{s \not\approx t}{\square} \quad \begin{array}{l} \text{unit equality} \\ \text{resolution} \end{array}$$

$$\frac{A \quad \neg B}{\square} \quad \begin{array}{l} \text{unit} \\ \text{resolution} \end{array}$$

where s and t (A and B respectively) are unifiable

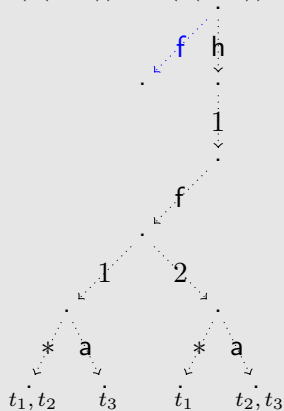
$$^{t_4}f(x, a) \approx x$$

$$^{t_1}h(f(x, y)), ^{t_2}h(f(x, a)), ^{t_3}h(f(a, a))$$



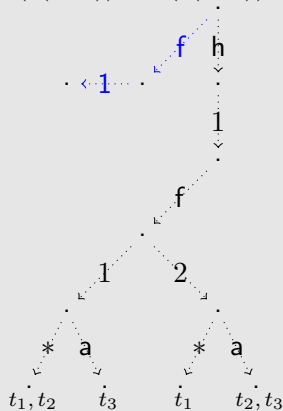
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$${}^{t_1}h(f(x, y)), {}^{t_2}h(f(x, a)), {}^{t_3}h(f(a, a))$$



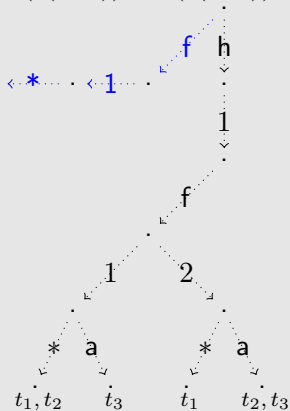
$${}^{t_4}f(x, a) \approx x$$

$${}^{t_1}h(f(x, y)), {}^{t_2}h(f(x, a)), {}^{t_3}h(f(a, a))$$



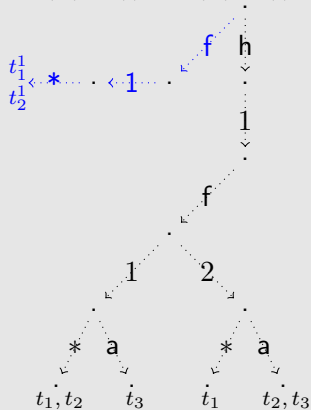
$${}^{t_4}f(x, a) \approx x$$

$${}^{t_1}h(f(x, y)), {}^{t_2}h(f(x, a)), {}^{t_3}h(f(a, a))$$



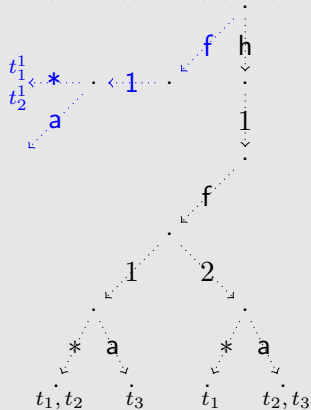
$${}^{t_4}f(x, a) \approx x$$

$${}^{t_1}h(f(x, y)), {}^{t_2}h(f(x, a)), {}^{t_3}h(f(a, a))$$



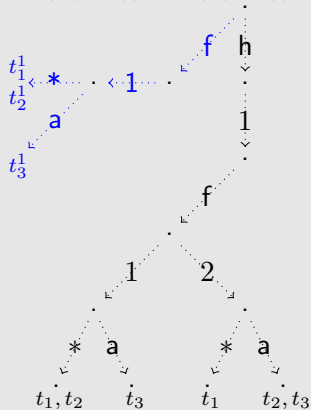
$${}^{t_4}f(x, a) \approx x$$

$${}^{t_1}h(f(x, y)), {}^{t_2}h(f(x, a)), {}^{t_3}h(f(a, a))$$



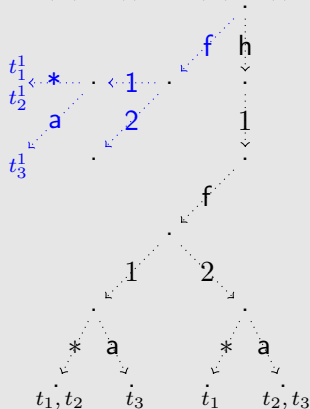
$${}^{t_4}f(x, a) \approx x$$

$${}^{t_1}h(f(x, y)), {}^{t_2}h(f(x, a)), {}^{t_3}h(f(a, a))$$



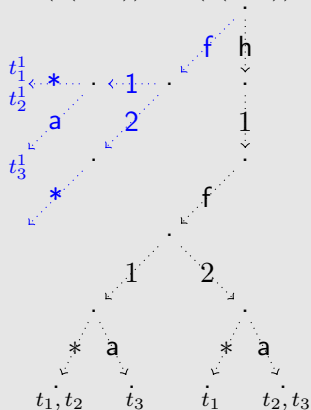
$$t_4: f(x, a) \approx x$$

$$t_1: h(f(x, y)), t_2: h(f(x, a)), t_3: h(f(a, a))$$



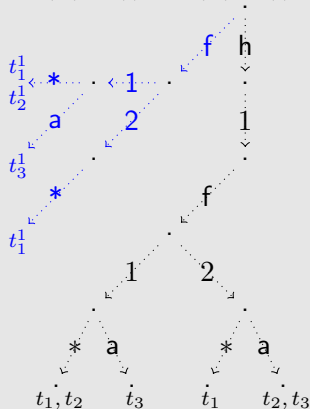
$$^{t_4}f(x, a) \approx x$$

$$^{t_1}h(f(x, y)), ^{t_2}h(f(x, a)), ^{t_3}h(f(a, a))$$



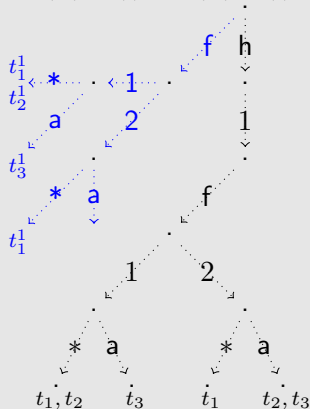
$$t_4: f(x, a) \approx x$$

$$t_1: h(f(x, y)), t_2: h(f(x, a)), t_3: h(f(a, a))$$



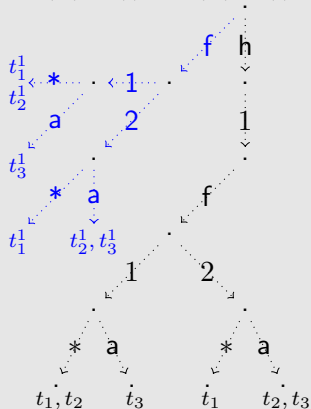
$$t_4: f(x, a) \approx x$$

$$t_1: h(f(x, y)), t_2: h(f(x, a)), t_3: h(f(a, a))$$



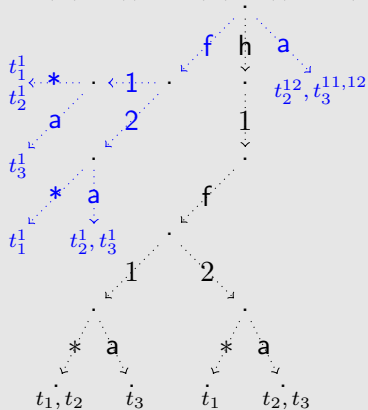
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$${}^{t_1}h(f(x, y)), {}^{t_2}h(f(x, a)), {}^{t_3}h(f(a, a))$$



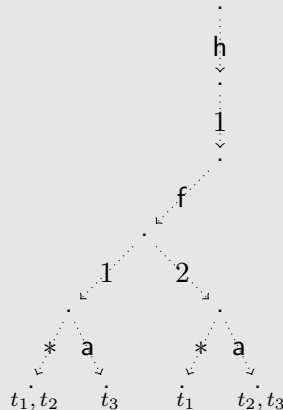
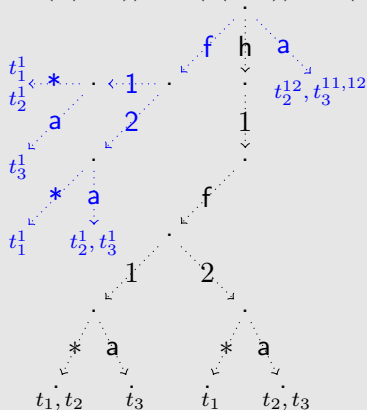
$$t_4: f(x, a) \approx x$$

$$t_1: h(f(x, y)), t_2: h(f(x, a)), t_3: h(f(a, a))$$



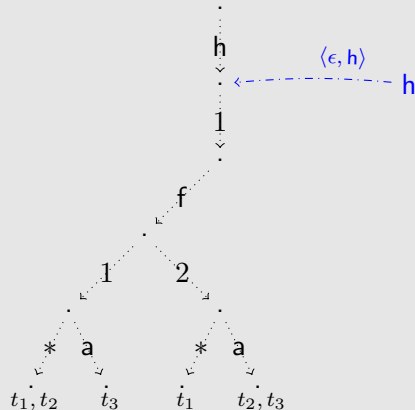
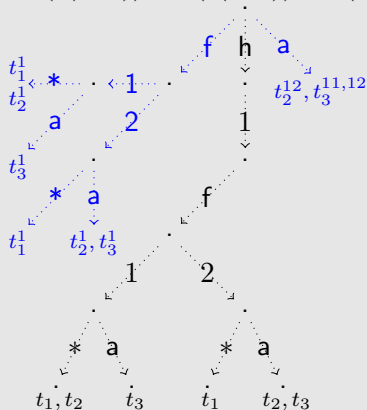
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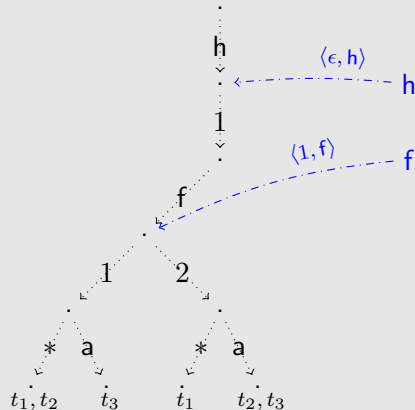
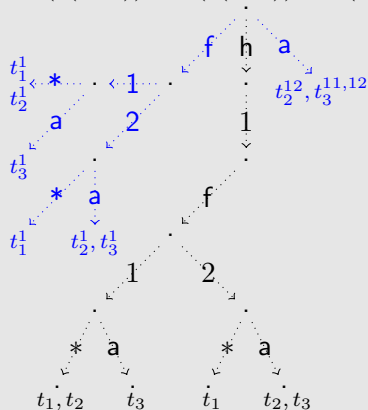
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$${}^{t_1}h(f(x, y)), {}^{t_2}h(f(x, a)), {}^{t_3}h(f(a, a))$$



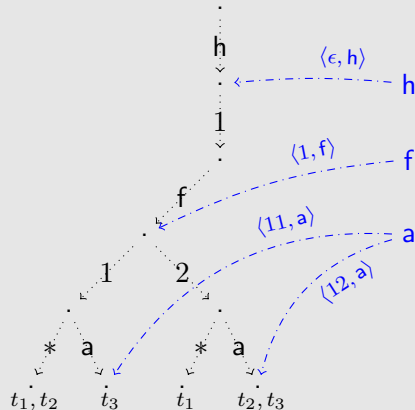
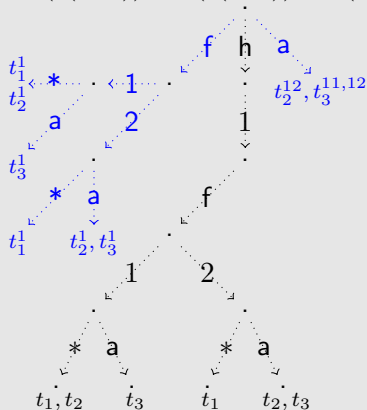
$$t_4: f(x, a) \approx x$$

$$t_1: h(f(x, y)), t_2: h(f(x, a)), t_3: h(f(a, a))$$



$$t_4: f(x, a) \approx x$$

$$t_1: h(f(x, y)), t_2: h(f(x, a)), t_3: h(f(a, a))$$



Insert

$$^{t_1}h(f(x, y)), ^{t_2}h(f(x, h(a))), ^{t_3}h(f(h(a), a))$$

$$t_1 \Rightarrow h.f.*.*$$

$$t_2 \Rightarrow h.f.*.h.a$$

$$t_3 \Rightarrow h.f.h.a.a$$

Insert



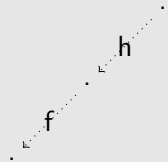
$$t_1: h(f(x, y)), t_2: h(f(x, h(a))), t_3: h(f(h(a), a))$$

$$t_1 \Rightarrow h.f.*.*$$

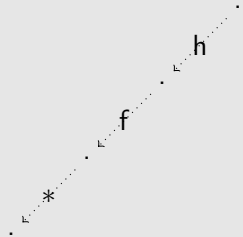
$$t_2 \Rightarrow h.f.*.h.a$$

$$t_3 \Rightarrow h.f.h.a.a$$

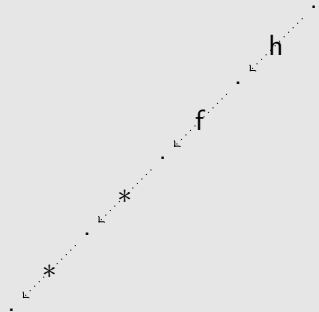
Insert

 $t_1: h(f(x, y)), t_2: h(f(x, h(a))), t_3: h(f(h(a), a))$
 $t_1 \Rightarrow h.f.*.*$
 $t_2 \Rightarrow h.f.*.h.a$
 $t_3 \Rightarrow h.f.h.a.a$


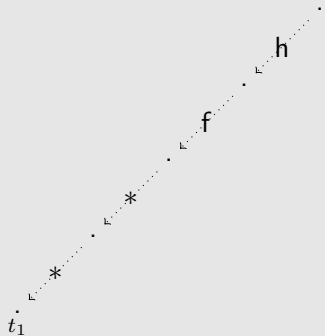
Insert

 $t_1: h(f(x, y)), t_2: h(f(x, h(a))), t_3: h(f(h(a), a))$
 $t_1 \Rightarrow h.f.*.*$
 $t_2 \Rightarrow h.f.*.h.a$
 $t_3 \Rightarrow h.f.h.a.a$


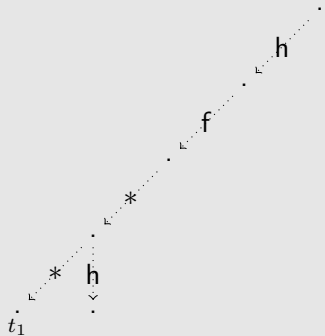
Insert

 $t_1: h(f(x, y)), t_2: h(f(x, h(a))), t_3: h(f(h(a), a))$
 $t_1 \Rightarrow h.f.*.*$
 $t_2 \Rightarrow h.f.*.h.a$
 $t_3 \Rightarrow h.f.h.a.a$


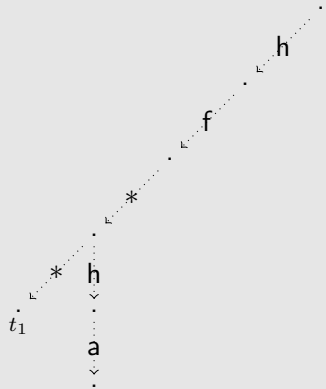
Insert

 $t_1: h(f(x, y)), t_2: h(f(x, h(a))), t_3: h(f(h(a), a))$
 $t_1 \Rightarrow h.f.*.*$
 $t_2 \Rightarrow h.f.*.h.a$
 $t_3 \Rightarrow h.f.h.a.a$


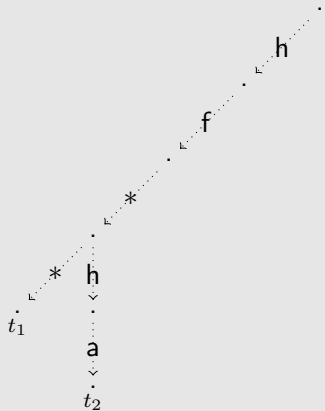
Insert

 $t_1: h(f(x, y)), t_2: h(f(x, h(a))), t_3: h(f(h(a), a))$
 $t_1 \Rightarrow h.f.*.*$
 $t_2 \Rightarrow h.f.*.h.a$
 $t_3 \Rightarrow h.f.h.a.a$


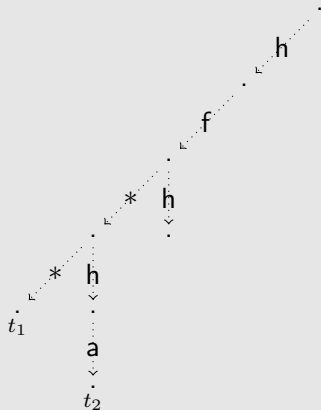
Insert

 $t_1: h(f(x, y)), t_2: h(f(x, h(a))), t_3: h(f(h(a), a))$
 $t_1 \Rightarrow h.f.*.*$
 $t_2 \Rightarrow h.f.*.h.a$
 $t_3 \Rightarrow h.f.h.a.a$


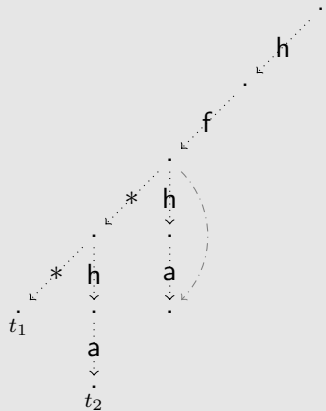
Insert

 $t_1: h(f(x, y)), t_2: h(f(x, h(a))), t_3: h(f(h(a), a))$
 $t_1 \Rightarrow h.f.*.*$
 $t_2 \Rightarrow h.f.*.h.a$
 $t_3 \Rightarrow h.f.h.a.a$


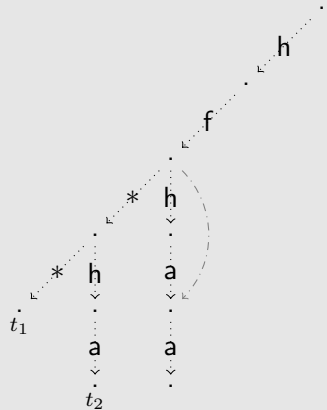
Insert

$$^{t_1}h(f(x, y)), ^{t_2}h(f(x, h(a))), ^{t_3}h(f(h(a), a))$$
$$t_1 \Rightarrow \text{h.f.*.*}$$
$$t_2 \Rightarrow \text{h.f.} * \text{h.a}$$
$$t_3 \Rightarrow \text{h.f.h.a.a}$$


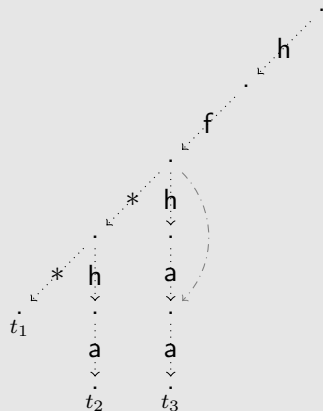
Insert

$$^{t_1}h(f(x, y)), ^{t_2}h(f(x, h(a))), ^{t_3}h(f(h(a), a))$$
$$t_1 \Rightarrow \text{h.f.*.*}$$
$$t_2 \Rightarrow \text{h.f.} * \text{h.a}$$
$$t_3 \Rightarrow \text{h.f.h.a.a}$$


Insert

 $t_1: h(f(x, y)), t_2: h(f(x, h(a))), t_3: h(f(h(a), a))$
 $t_1 \Rightarrow h.f.*.*$
 $t_2 \Rightarrow h.f.*.h.a$
 $t_3 \Rightarrow h.f.h.a.a$


Insert

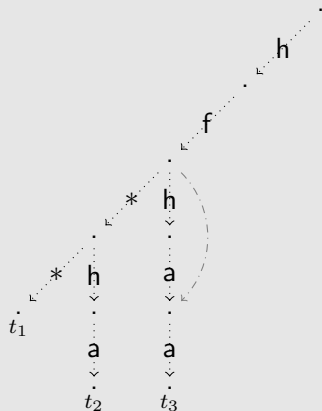
 $t_1: h(f(x, y)), t_2: h(f(x, h(a))), t_3: h(f(h(a), a))$
 $t_1 \Rightarrow h.f.*.*$
 $t_2 \Rightarrow h.f.*.h.a$
 $t_3 \Rightarrow h.f.h.a.a$


Retrieve

$$t_1: h(f(x, y)), t_2: h(f(x, h(a))), t_3: h(f(h(a), a))$$

$$h(f(x', a)) \Rightarrow h.f.*.a$$

$$u : h(f(x', a)) \mapsto \{ \quad \}$$

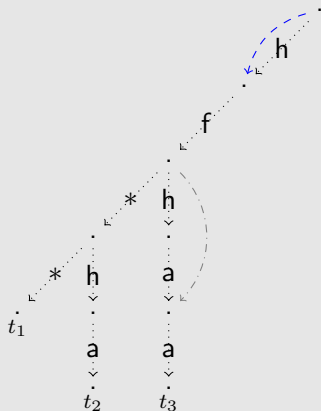


Retrieve

$$t_1: h(f(x, y)), t_2: h(f(x, h(a))), t_3: h(f(h(a), a))$$

$$h(f(x', a)) \Rightarrow h.f.*.a$$

$$u : h(f(x', a)) \mapsto \{ \quad \}$$

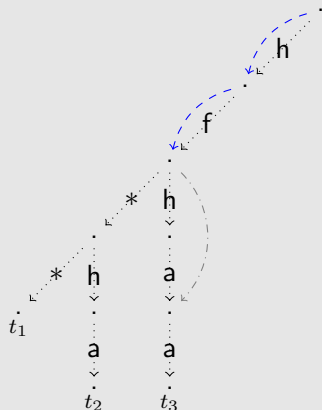


Retrieve

$$^{t_1:}h(f(x, y)), ^{t_2:}h(f(x, h(a))), ^{t_3:}h(f(h(a), a))$$

$$h(f(x', a)) \Rightarrow h.f.*.a$$

$$u : \mathbf{h}(f(x', \mathbf{a})) \mapsto \{ \quad \}$$

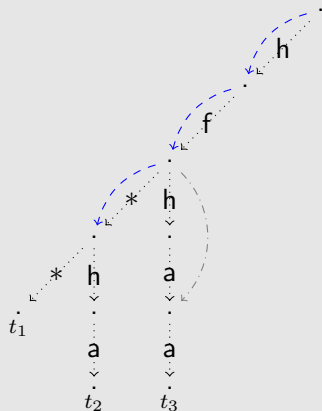


Retrieve

$$t_1: h(f(x, y)), t_2: h(f(x, h(a))), t_3: h(f(h(a), a))$$

$$h(f(x', a)) \Rightarrow h.f.*.a$$

$$u : h(f(x', a)) \mapsto \{ \quad \}$$

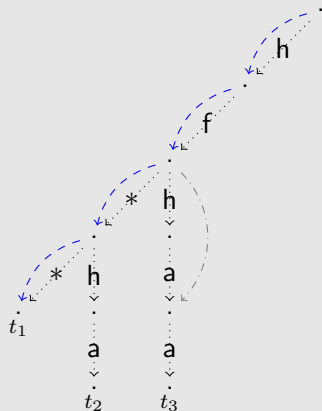


Retrieve

$$t_1: h(f(x, y)), t_2: h(f(x, h(a))), t_3: h(f(h(a), a))$$

$$h(f(x', a)) \Rightarrow h.f.*.a$$

$$u : h(f(x', a)) \mapsto \{t_1, \quad \}$$

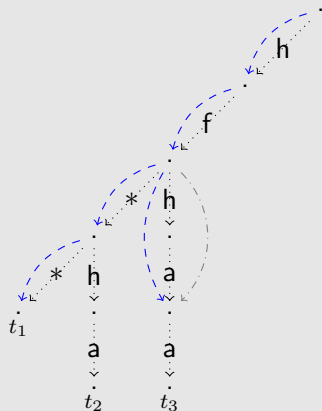


Retrieve

$$t_1: h(f(x, y)), t_2: h(f(x, h(a))), t_3: h(f(h(a), a))$$

$$h(f(x', a)) \Rightarrow h.f.*.a$$

$$u : h(f(x', a)) \mapsto \{t_1, \quad \}$$

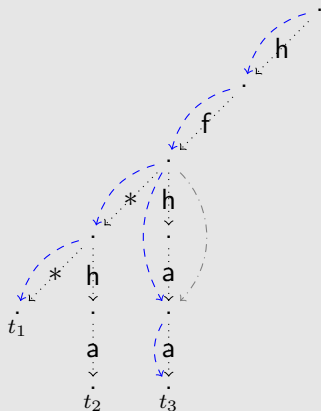


Retrieve

$$t_1: h(f(x, y)), t_2: h(f(x, h(a))), t_3: h(f(h(a), a))$$

$$h(f(x', a)) \Rightarrow h.f.*.a$$

$$u : h(f(x', a)) \mapsto \{t_1, t_3\}$$



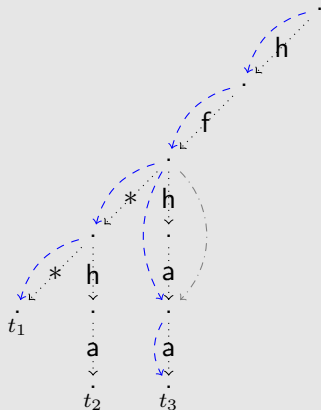
Retrieve

$$^{t_1:}h(f(x, y)), ^{t_2:}h(f(x, h(a))), ^{t_3:}h(f(h(a), a))$$

$$h(f(x', a)) \Rightarrow h.f.*.a$$

$$u : \mathsf{h}(\mathsf{f}(x', \mathbf{a})) \mapsto \{t_1, t_3\}$$

$$i : \mathbf{h}(\mathbf{f}(x', \mathbf{a})) \mapsto \{t_3\}$$



Retrieve

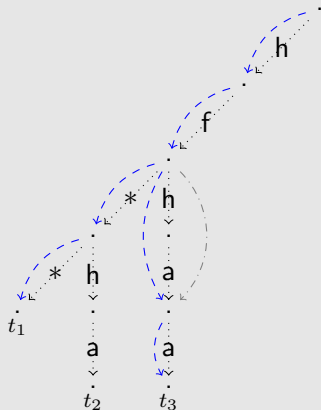
$$^{t_1:}h(f(x, y)), ^{t_2:}h(f(x, h(a))), ^{t_3:}h(f(h(a), a))$$

$$h(f(x', a)) \Rightarrow h.f.*.a$$

$$u : \mathbf{h}(f(x', \mathbf{a})) \mapsto \{t_1, t_3\}$$

$$i : \mathbf{h}(\mathbf{f}(x', \mathbf{a})) \mapsto \{t_3\}$$

$$g : h(f(x', a)) \mapsto \{t_1\}$$



Retrieve

$$^{t_1:}h(f(x, y)), ^{t_2:}h(f(x, h(a))), ^{t_3:}h(f(h(a), a))$$

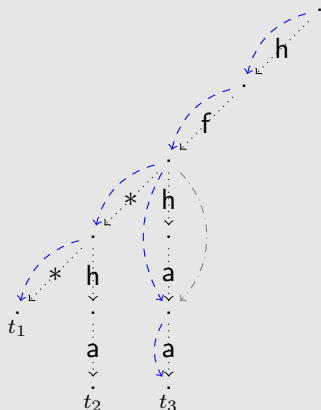
$$h(f(x', a)) \Rightarrow h.f.*.a$$

$$u : \mathbf{h}(f(x', \mathbf{a})) \mapsto \{t_1, t_3\}$$

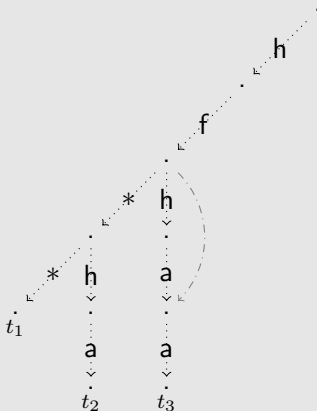
$$i : h(f(x', \mathbf{a})) \mapsto \{t_3\}$$

$$g : h(f(x', a)) \mapsto \{t_1\}$$

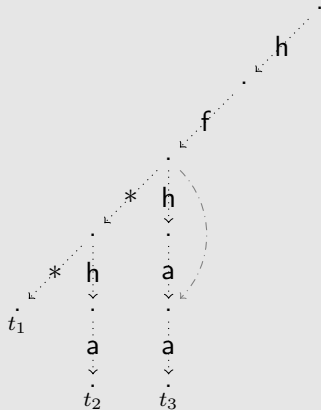
$$v : \mathbf{h}(\mathbf{f}(x', \mathbf{a})) \mapsto \{ \}$$

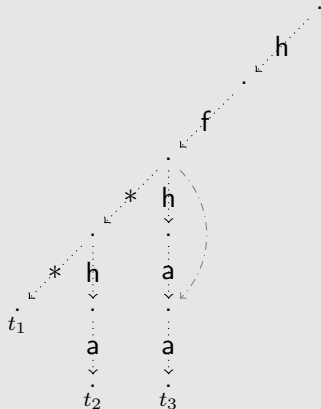


Subterms

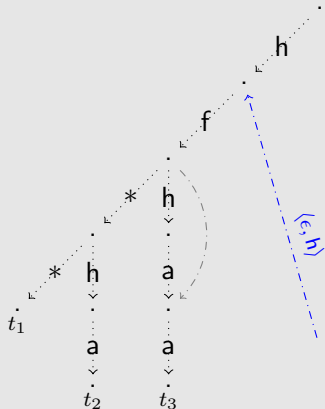
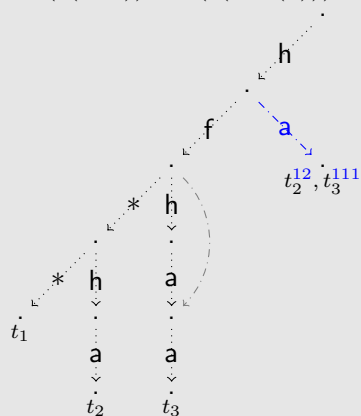
 $t_1: h(f(x, y)), t_2: h(f(x, h(a))), t_3: h(f(h(a), a))$


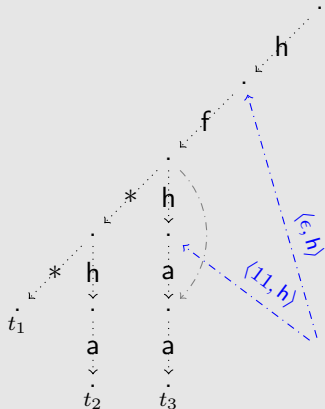
$$^{t_1}h(f(x, y)), ^{t_2}h(f(x, h(a))), ^{t_3}h(f(h(a), a))$$


$$^{t_1}h(f(x, y)), ^{t_2}h(f(x, h(a))), ^{t_3}h(f(h(a), a))$$


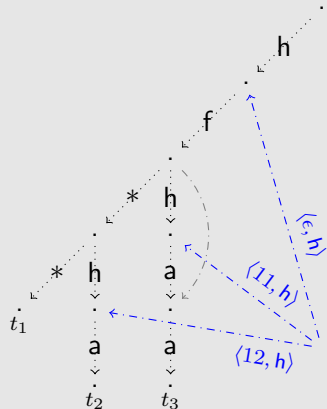
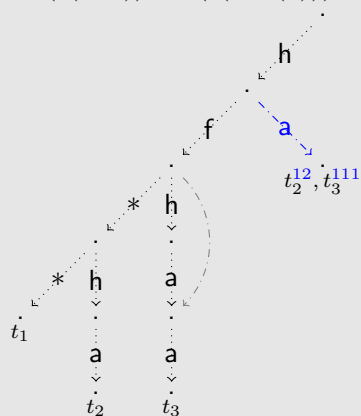
$$^{t_1}h(f(x, y)), ^{t_2}h(f(x, h(a))), ^{t_3}h(f(h(a), a))$$


Subterms

 $t_1: h(f(x, y)), t_2: h(f(x, h(a))), t_3: h(f(h(a), a))$


$$^{t_1:}h(f(x, y)), ^{t_2:}h(f(x, h(a))), ^{t_3:}h(f(h(a), a))$$


Subterms

 $t_1: h(f(x, y)), t_2: h(f(x, h(a))), t_3: h(f(h(a), a))$


Build

$$^{t_1}h(f(x, y)), ^{t_2}h(f(x, h(a))), ^{t_3}h(f(h(a), a)), ^{t_4}h(f(a, a)))$$

Build

$$^{t_1}h(f(x, y)), ^{t_2}h(f(x, h(a))), ^{t_3}h(f(h(a), a)), ^{t_4}h(f(a, a))$$

$$*_0 \mapsto h(*_1)$$

Build

$$^{t_1}h(f(x, y)), ^{t_2}h(f(x, h(a))), ^{t_3}h(f(h(a), a)), ^{t_4}h(f(a, a)))$$

$$\downarrow$$

$$*_0 \mapsto h(*_1)$$

$$\downarrow$$

$$*_1 \mapsto f(*_2, *_3)$$

Build

$$^{t_1}h(f(x, y)), ^{t_2}h(f(x, h(a))), ^{t_3}h(f(h(a), a)), ^{t_4}h(f(a, a)))$$

$$\downarrow$$

$$*_0 \mapsto h(*_1)$$

$$\downarrow$$

$$*_1 \mapsto f(*_2, *_3)$$

$$\swarrow$$

$$*_2 \mapsto x$$

Build

$$^{t_1}h(f(x, y)), ^{t_2}h(f(x, h(a))), ^{t_3}h(f(h(a), a)), ^{t_4}h(f(a, a)))$$

$$\downarrow$$

$$*_0 \mapsto h(*_1)$$

$$\downarrow$$

$$*_1 \mapsto f(*_2, *_3)$$

$$\swarrow$$

$$*_2 \mapsto x$$

$$\swarrow$$

$$*_3 \mapsto y$$

$$t_1$$

Build

$$^{t_1}h(f(x, y)), ^{t_2}h(f(x, h(a))), ^{t_3}h(f(h(a), a)), ^{t_4}h(f(a, a)))$$

$$\downarrow$$

$$*_0 \mapsto h(*_1)$$

$$\downarrow$$

$$*_1 \mapsto f(*_2, *_3)$$

$$\swarrow$$

$$*_2 \mapsto x$$

$$\swarrow$$

$$*_3 \mapsto y$$

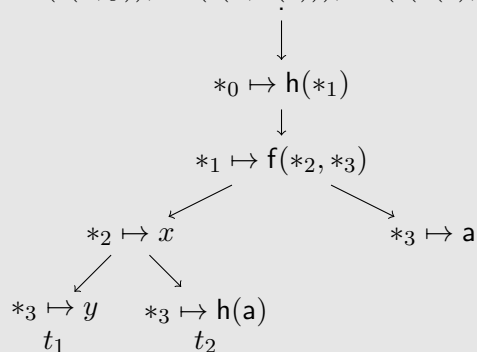
$$t_1$$

$$\searrow$$

$$*_3 \mapsto h(a)$$

$$t_2$$

Build

$$^{t_1}h(f(x, y)), ^{t_2}h(f(x, h(a))), ^{t_3}h(f(h(a), a)), ^{t_4}h(f(a, a)))$$


Build

$$^{t_1}h(f(x, y)), ^{t_2}h(f(x, h(a))), ^{t_3}h(f(h(a), a)), ^{t_4}h(f(a, a)))$$

$$\downarrow$$

$$*_0 \mapsto h(*_1)$$

$$\downarrow$$

$$*_1 \mapsto f(*_2, *_3)$$

$$\swarrow$$

$$*_2 \mapsto x$$

$$\searrow$$

$$*_3 \mapsto a$$

$$\swarrow$$

$$*_3 \mapsto y$$

$$t_1$$

$$\searrow$$

$$*_3 \mapsto h(a)$$

$$t_2$$

$$\swarrow$$

$$*_2 \mapsto h(a)$$

$$t_3$$

Build

$$^{t_1}h(f(x, y)), ^{t_2}h(f(x, h(a))), ^{t_3}h(f(h(a), a)), ^{t_4}h(f(a, a)))$$

$$\downarrow$$

$$*_0 \mapsto h(*_1)$$

$$\downarrow$$

$$*_1 \mapsto f(*_2, *_3)$$

$$\swarrow \quad \searrow$$

$$*_2 \mapsto x \qquad *_3 \mapsto a$$

$$\begin{array}{cc} \swarrow \quad \searrow & \swarrow \quad \searrow \\ *_3 \mapsto y & *_3 \mapsto h(a) & *_2 \mapsto h(a) & *_2 \mapsto a \\ t_1 & t_2 & t_3 & t_4 \end{array}$$

TPTP/Problems/HWV/HWV134-1.p

2 332 428 formulae, 6 570 884 literals

TPTP/Problems/HWV/HWV134-1.p

2 332 428 formulae, 6 570 884 literals

checking 1000 new literals	sequential	path	speed
afterwards	search	index	up
(ℓ_1, ℓ_2)			
$A, \neg B$			

TPTP/Problems/HWV/HWV134-1.p

2 332 428 formulae, 6 570 884 literals

checking 1000 new literals	sequential	path	speed
afterwards (ℓ_1, ℓ_2) $A, \neg B$	search	index	up
1 000 500 000 761	726ms	70ms	10

TPTP/Problems/HWV/HWV134-1.p

2 332 428 formulae, 6 570 884 literals

checking afterwards	1000 new literals (ℓ_1, ℓ_2)	$A, \neg B$	sequential search	path index	speed up
1 000	500 000	761	726ms	70ms	10
2 000	1 500 000	812	2s	69ms	29

TPTP/Problems/HWV/HWV134-1.p

2 332 428 formulae, 6 570 884 literals

checking afterwards	1000 new literals (ℓ_1, ℓ_2)	$A, \neg B$	sequential search	path index	speed up
1 000	500 000	761	726ms	70ms	10
2 000	1 500 000	812	2s	69ms	29
4 000	3 500 000	723	4s	75ms	53

TPTP/Problems/HWV/HWV134-1.p

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checking 1000 new literals afterwards	(ℓ_1, ℓ_2)	$A, \neg B$	sequential search	path index	speed up
1 000	500 000	761	726ms	70ms	10
2 000	1 500 000	812	2s	69ms	29
4 000	3 500 000	723	4s	75ms	53
8 000	7 500 000	433	9s	125ms	72

TPTP/Problems/HWV/HWV134-1.p

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2 000	1 500 000	812	2s	69ms	29
4 000	3 500 000	723	4s	75ms	53
8 000	7 500 000	433	9s	125ms	72
16 000	15 500 000	742	21s	221ms	95

TPTP/Problems/HWV/HWV134-1.p

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2 000	1 500 000	812	2s	69ms	29
4 000	3 500 000	723	4s	75ms	53
8 000	7 500 000	433	9s	125ms	72
16 000	15 500 000	742	21s	221ms	95
32 000	31 500 000	592	40s	489ms	82

TPTP/Problems/HWV/HWV134-1.p

2 332 428 formulae, 6 570 884 literals

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2 000	1 500 000	812	2s	69ms	29
4 000	3 500 000	723	4s	75ms	53
8 000	7 500 000	433	9s	125ms	72
16 000	15 500 000	742	21s	221ms	95
32 000	31 500 000	592	40s	489ms	82
64 000	63 500 000	1 167	80s	697ms	115

TPTP/Problems/HWV/HWV134-1.p

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1 000	500 000	761	726ms	70ms	10
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8 000	7 500 000	433	9s	125ms	72
16 000	15 500 000	742	21s	221ms	95
32 000	31 500 000	592	40s	489ms	82
64 000	63 500 000	1 167	80s	697ms	115
128 000	127 500 000	1 479	160s	13s	12

TPTP/Problems/HWV/HWV134-1.p

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4 000	3 500 000	723	4s	75ms	53
8 000	7 500 000	433	9s	125ms	72
16 000	15 500 000	742	21s	221ms	95
32 000	31 500 000	592	40s	489ms	82
64 000	63 500 000	1 167	80s	697ms	115
128 000	127 500 000	1 479	160s	13s	12
256 000	255 500 000	1 097	320s	440s	1

TPTP/Problems/HWV/HWV134-1.p

2 332 428 formulae, 6 570 884 literals

checking afterwards	1000 new literals (ℓ_1, ℓ_2)	$A, \neg B$	sequential search	path index	speed up
1 000	500 000	761	726ms	70ms	10
2 000	1 500 000	812	2s	69ms	29
4 000	3 500 000	723	4s	75ms	53
8 000	7 500 000	433	9s	125ms	72
16 000	15 500 000	742	21s	221ms	95
32 000	31 500 000	592	40s	489ms	82
64 000	63 500 000	1 167	80s	697ms	115
128 000	127 500 000	1 479	160s	13s	12
256 000	255 500 000	1 097	320s	440s	1
512 000	511 500 000	1 440	640s	348s	2

TPTP/Problems/HWV/HWV134-1.p

2 332 428 formulae, 6 570 884 literals

checking afterwards	1000 new literals (ℓ_1, ℓ_2)	$A, \neg B$	sequential search	path index	speed up
1 000	500 000	761	726ms	70ms	10
2 000	1 500 000	812	2s	69ms	29
4 000	3 500 000	723	4s	75ms	53
8 000	7 500 000	433	9s	125ms	72
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64 000	63 500 000	1 167	80s	697ms	115
128 000	127 500 000	1 479	160s	13s	12
256 000	255 500 000	1 097	320s	440s	1
512 000	511 500 000	1 440	640s	348s	2
1 024 000	1023 500 000	1 534	1280s	330s	4