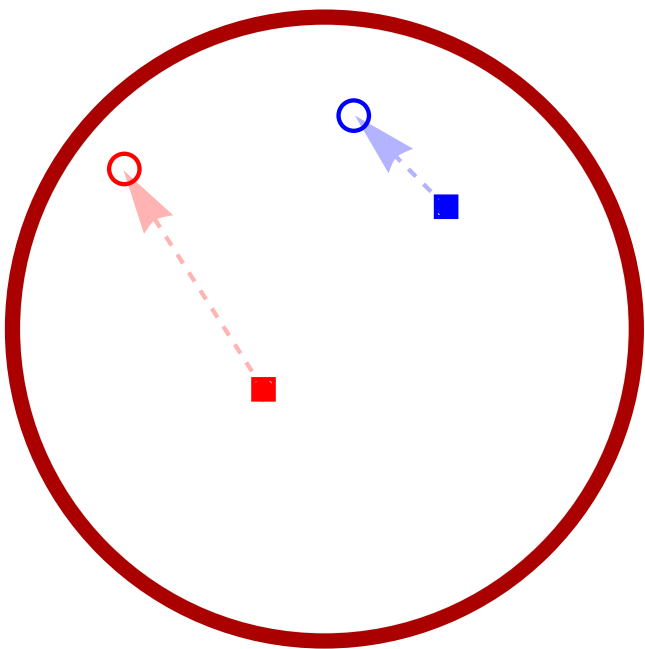


Distance 0 of 0.944

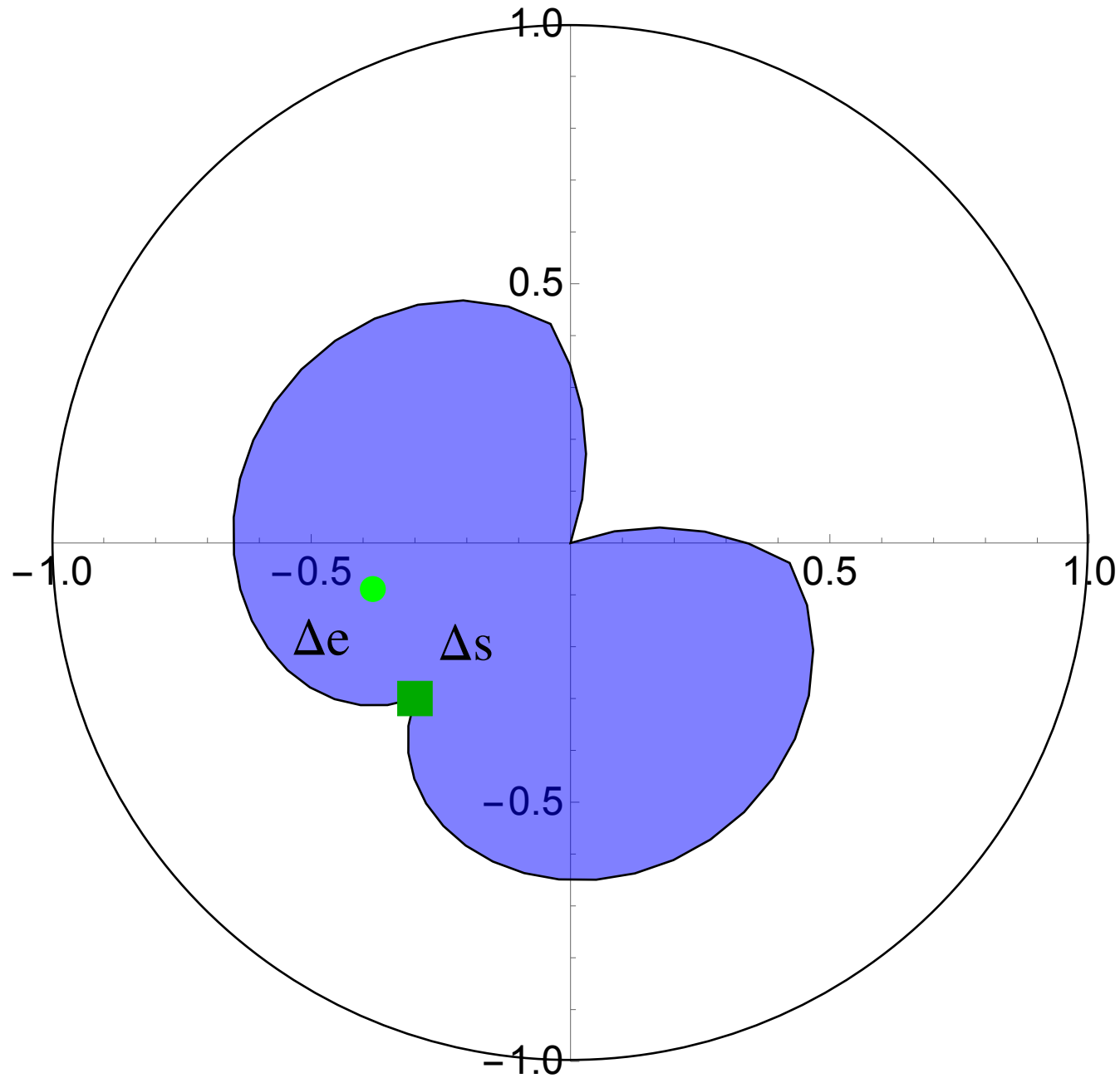
Move 1 of 3

Current ■ = □ - □

Goal ● = ○ - ○



workspace



Δ configuration space