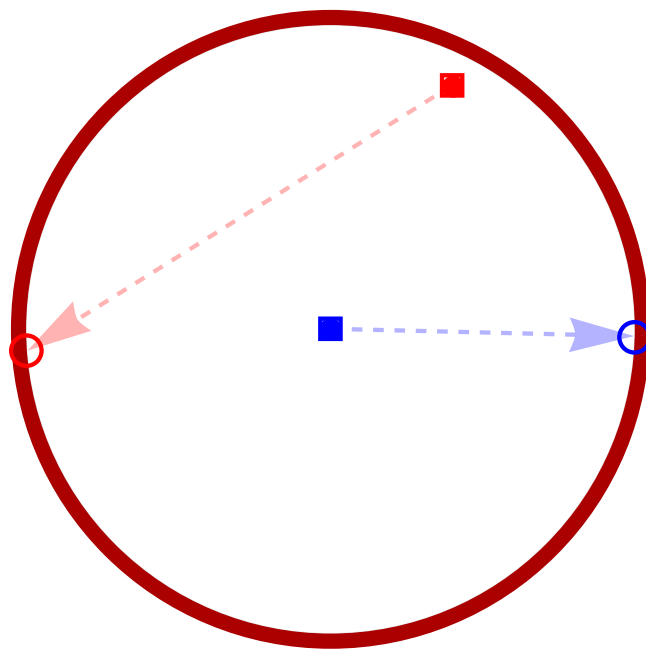


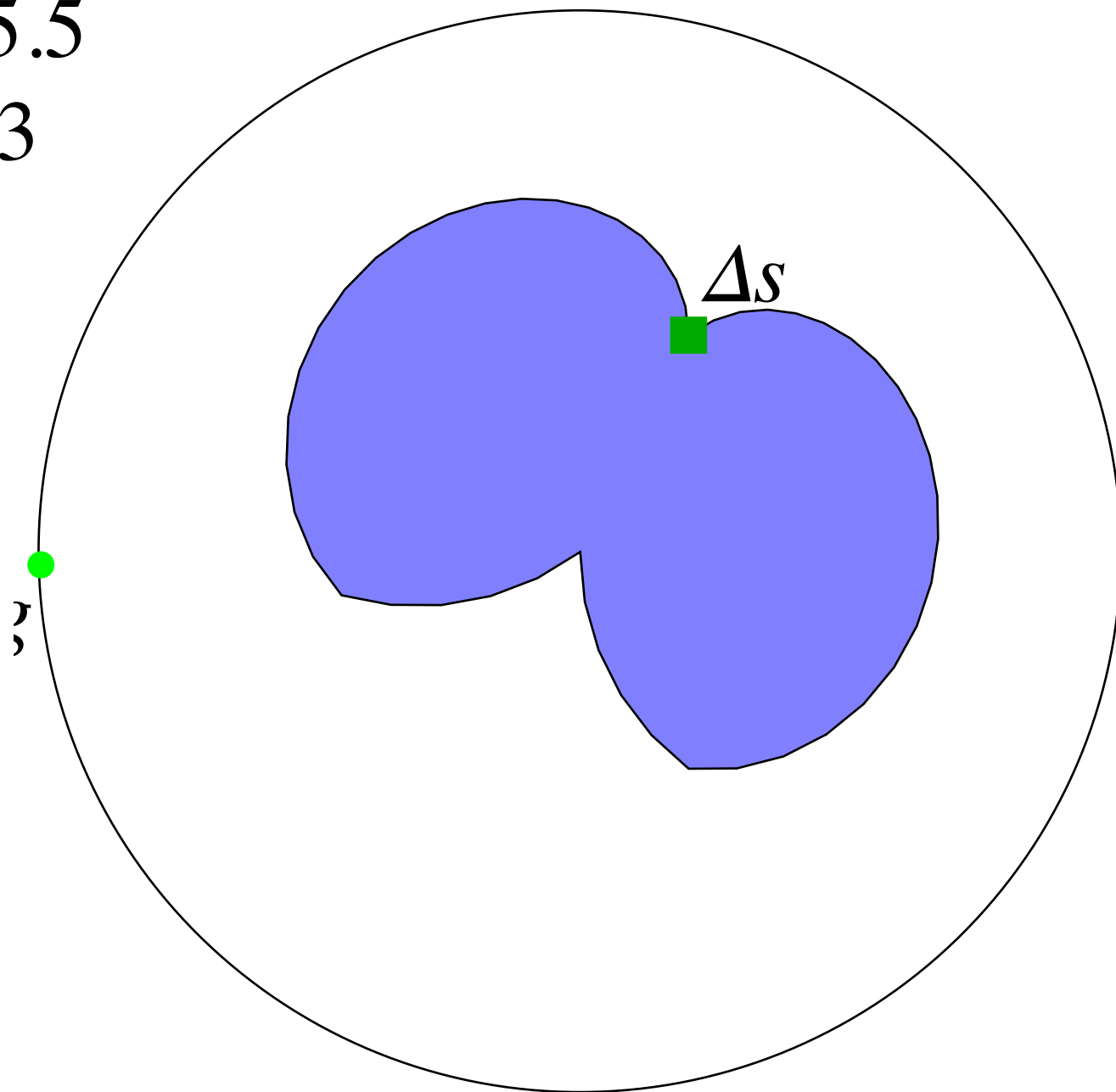
Distance 0 of 15.5
Move 1 of 283

Current ■=□—□

Goal ●=○—○



workspace



Δ configuration space