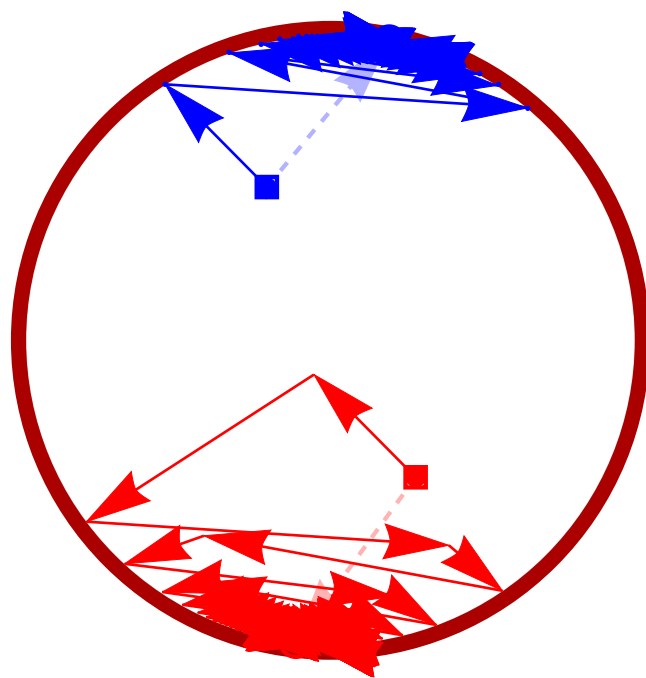


Distance 14.2 of 14.2

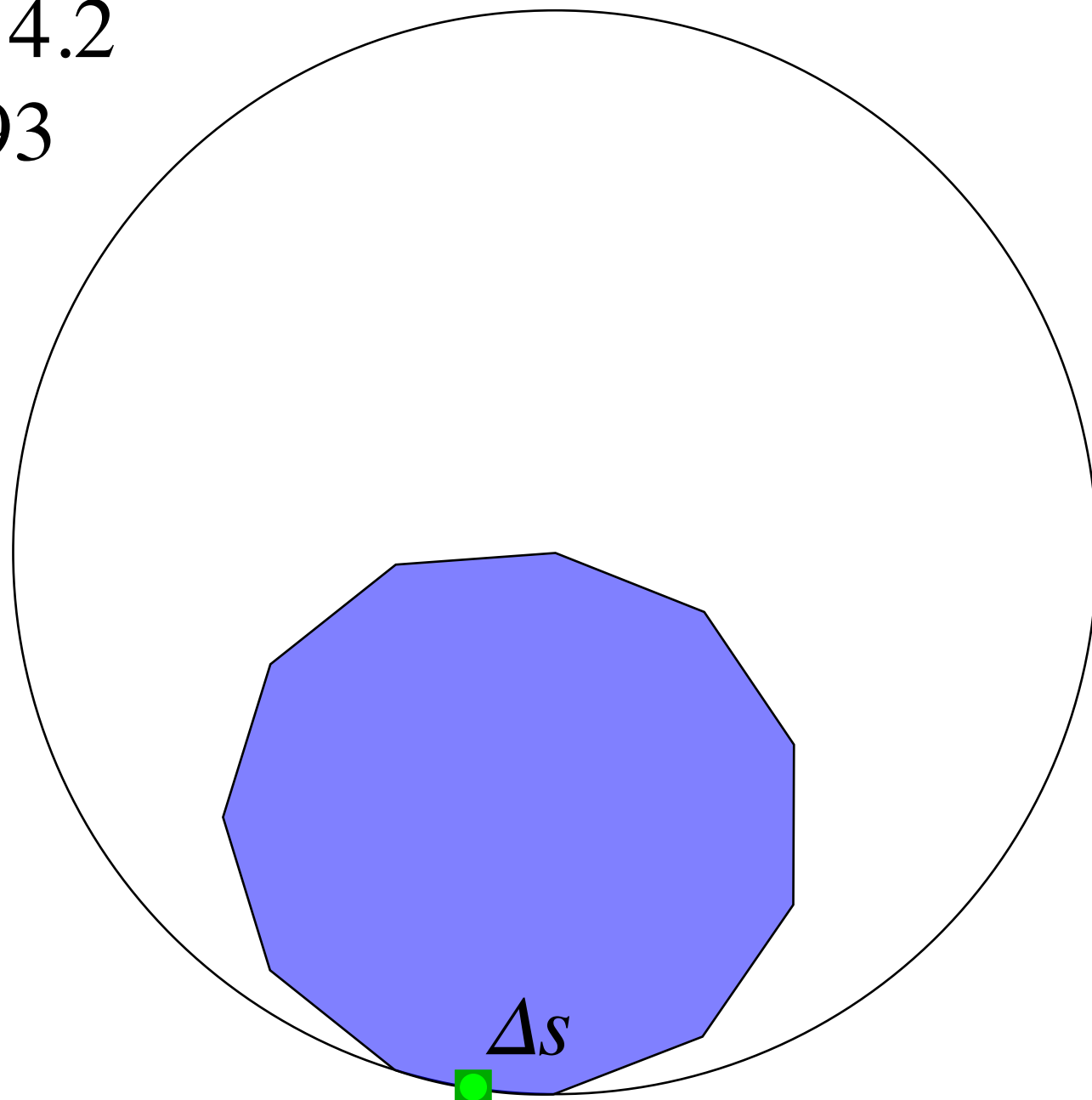
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Current ■=□—□

Goal ●=○—○



workspace



$\Delta$  configuration space