

Robot



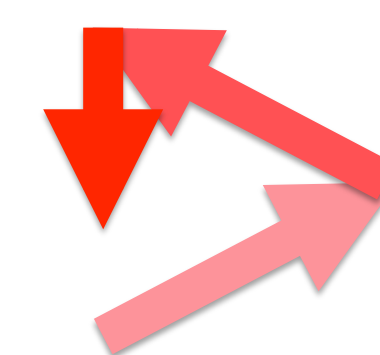
Goal



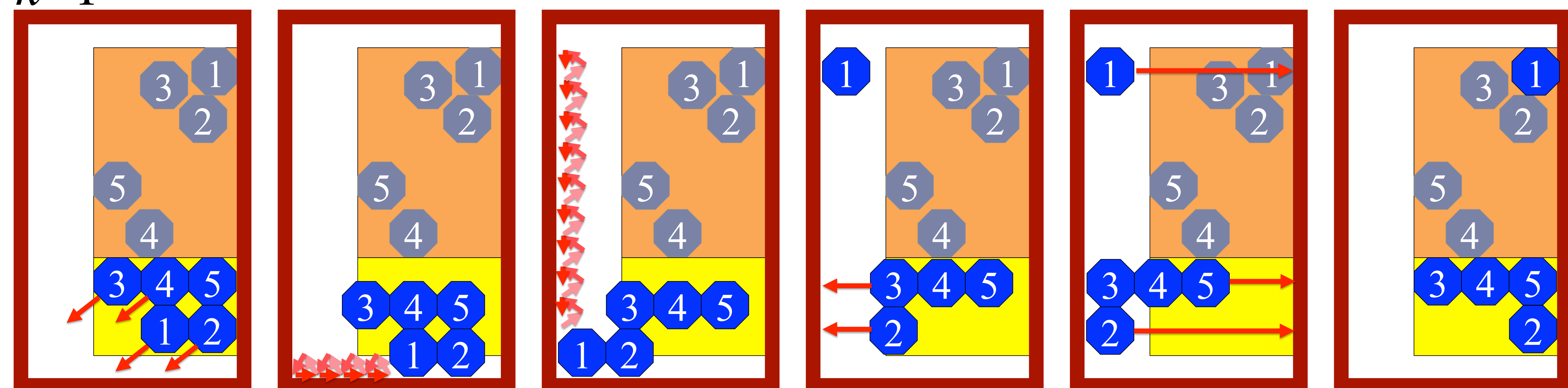
Move



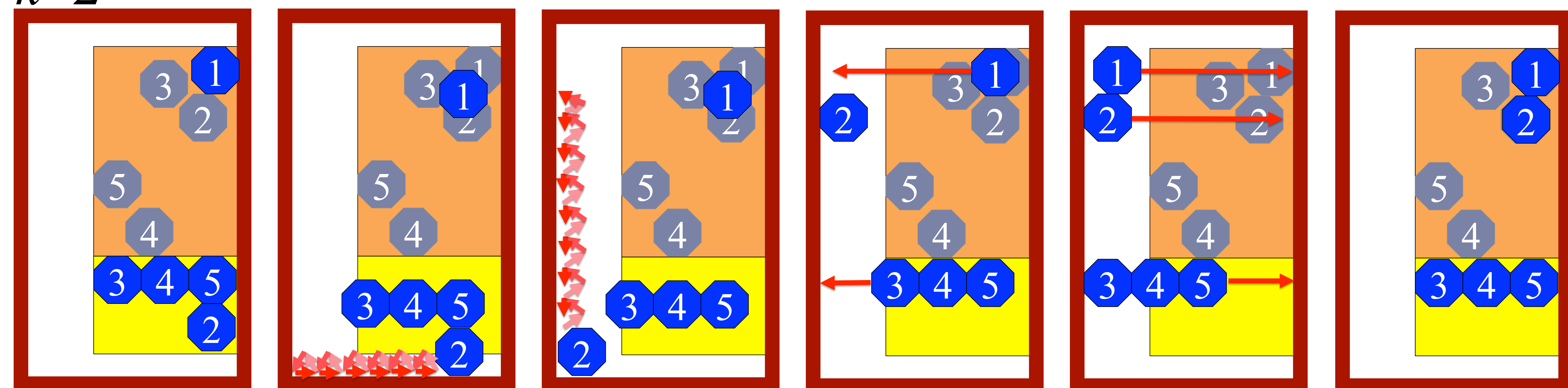
DriftMove



$k=1$



$k=2$



...

$k=5$

