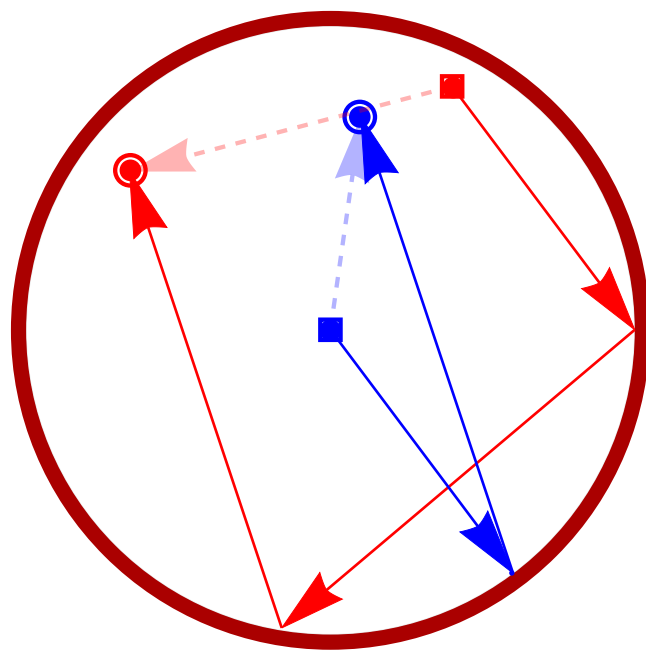


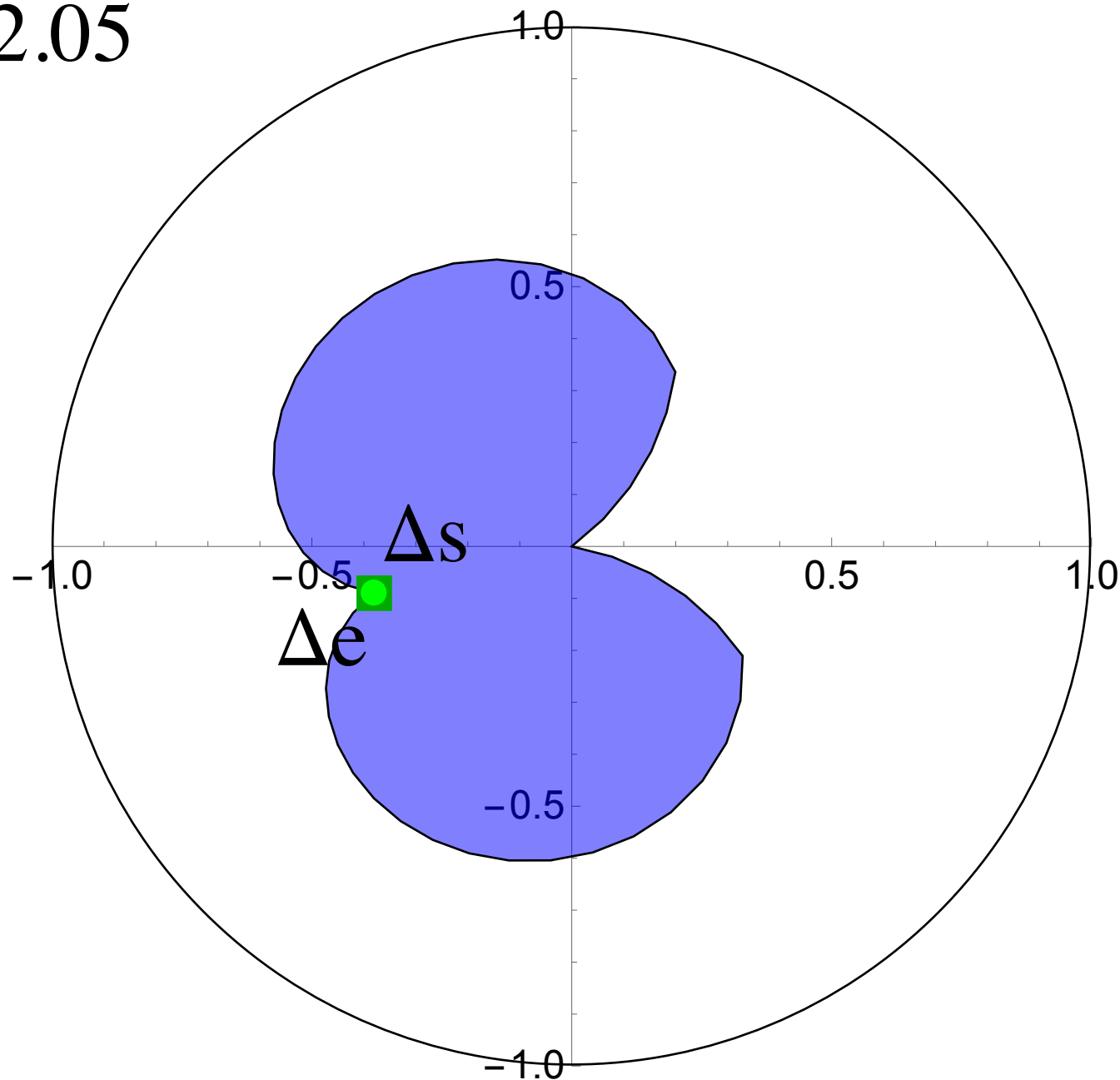
Distance 2.05 of 2.05  
Move 3 of 3

Current ■=□—□

Goal ●=○—○



workspace



$\Delta$  configuration space