

Robot



Goal



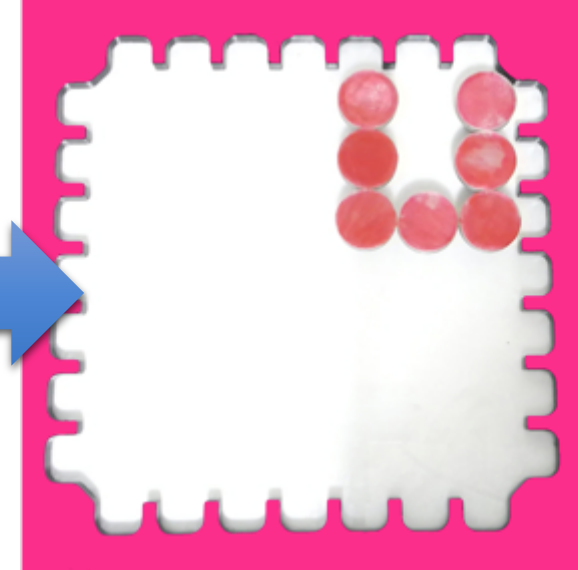
Move



Drift Move

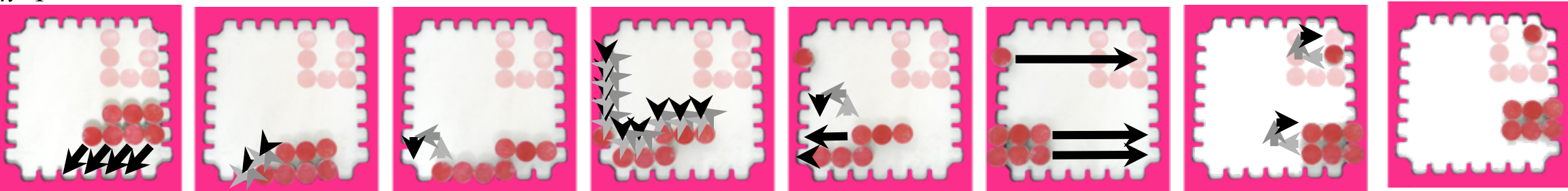


start

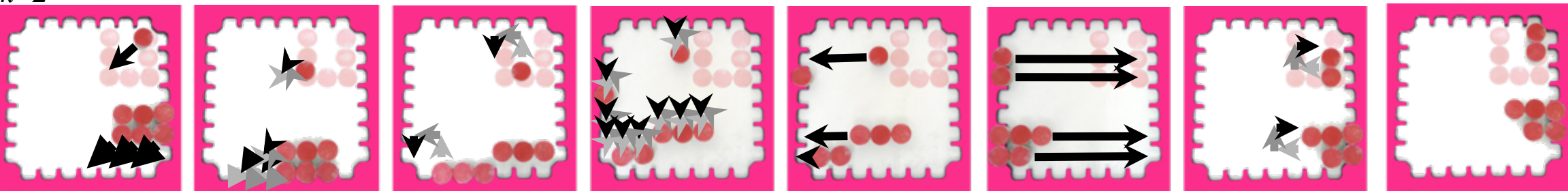


final

$k=1$



$k=2$



...

$k=7$

