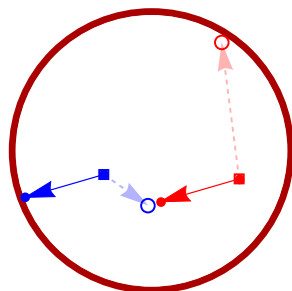
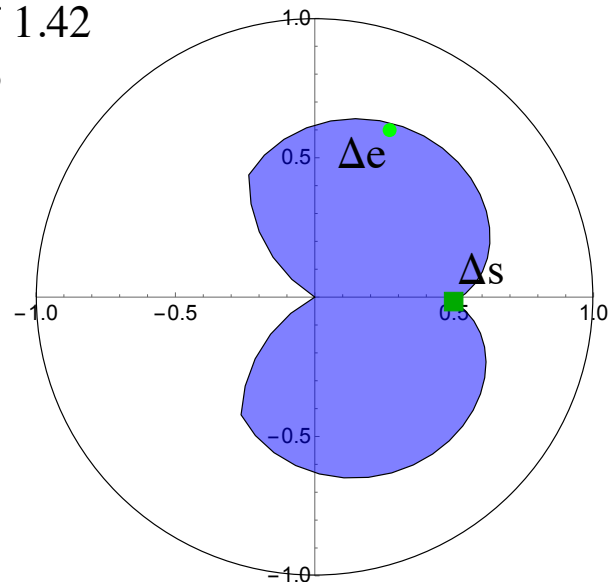


Distance 0.301 of 1.42  
Move 1 of 3

Current ■ □ — □  
Goal ● ○ — ○



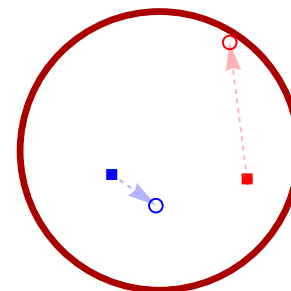
workspace



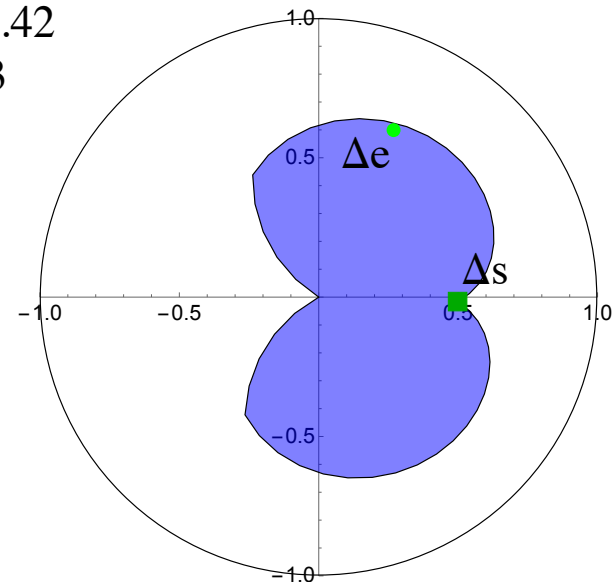
$\Delta$  configuration space

Distance 0 of 1.42  
Move 1 of 3

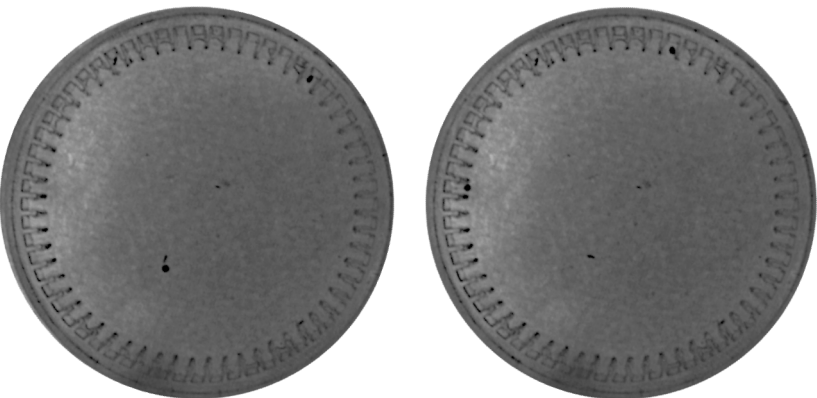
Current ■ □ — □  
Goal ● ○ — ○



workspace

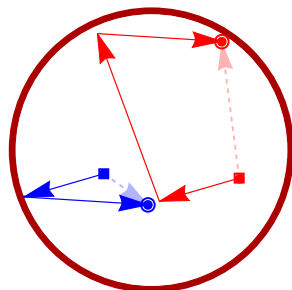


$\Delta$  configuration space

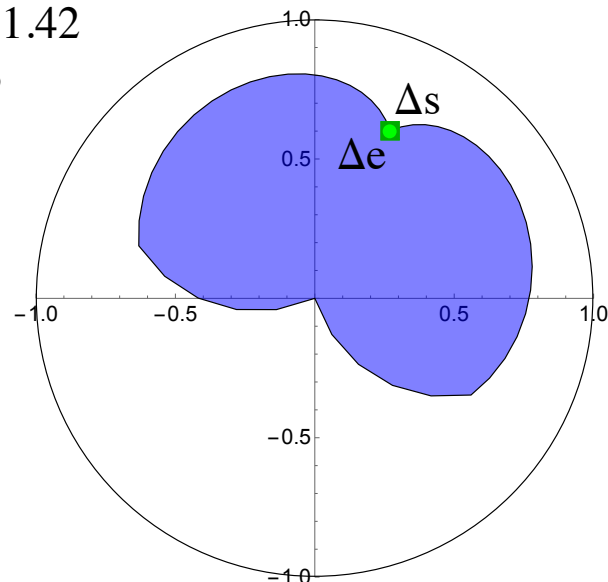


Distance 1.42 of 1.42  
Move 3 of 3

Current ■ □ — □  
Goal ● ○ — ○



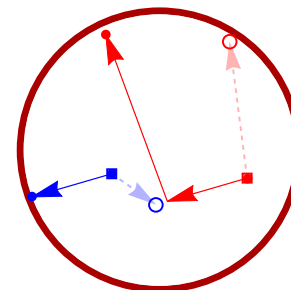
workspace



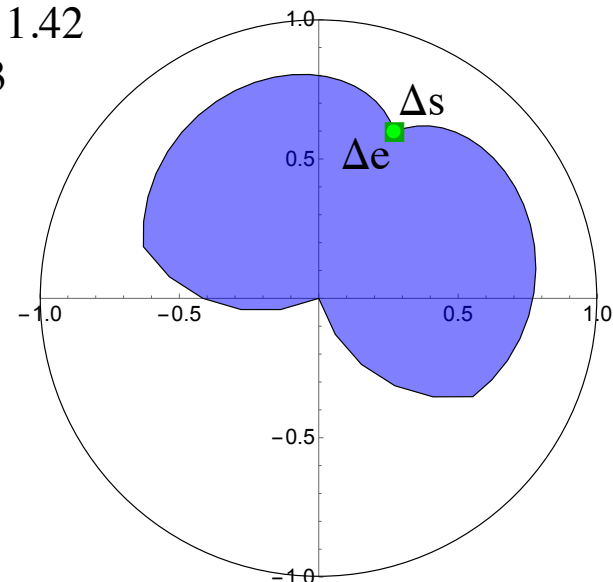
$\Delta$  configuration space

Distance 1.01 of 1.42  
Move 2 of 3

Current ■ □ — □  
Goal ● ○ — ○



workspace



$\Delta$  configuration space