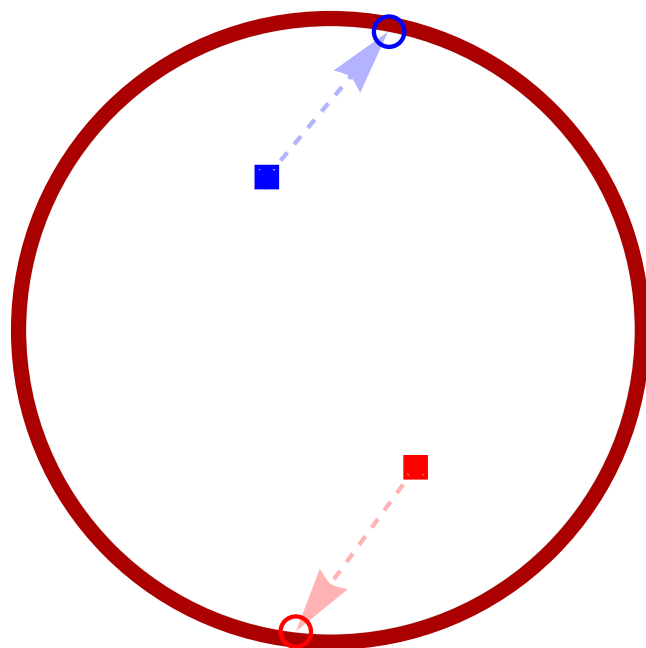


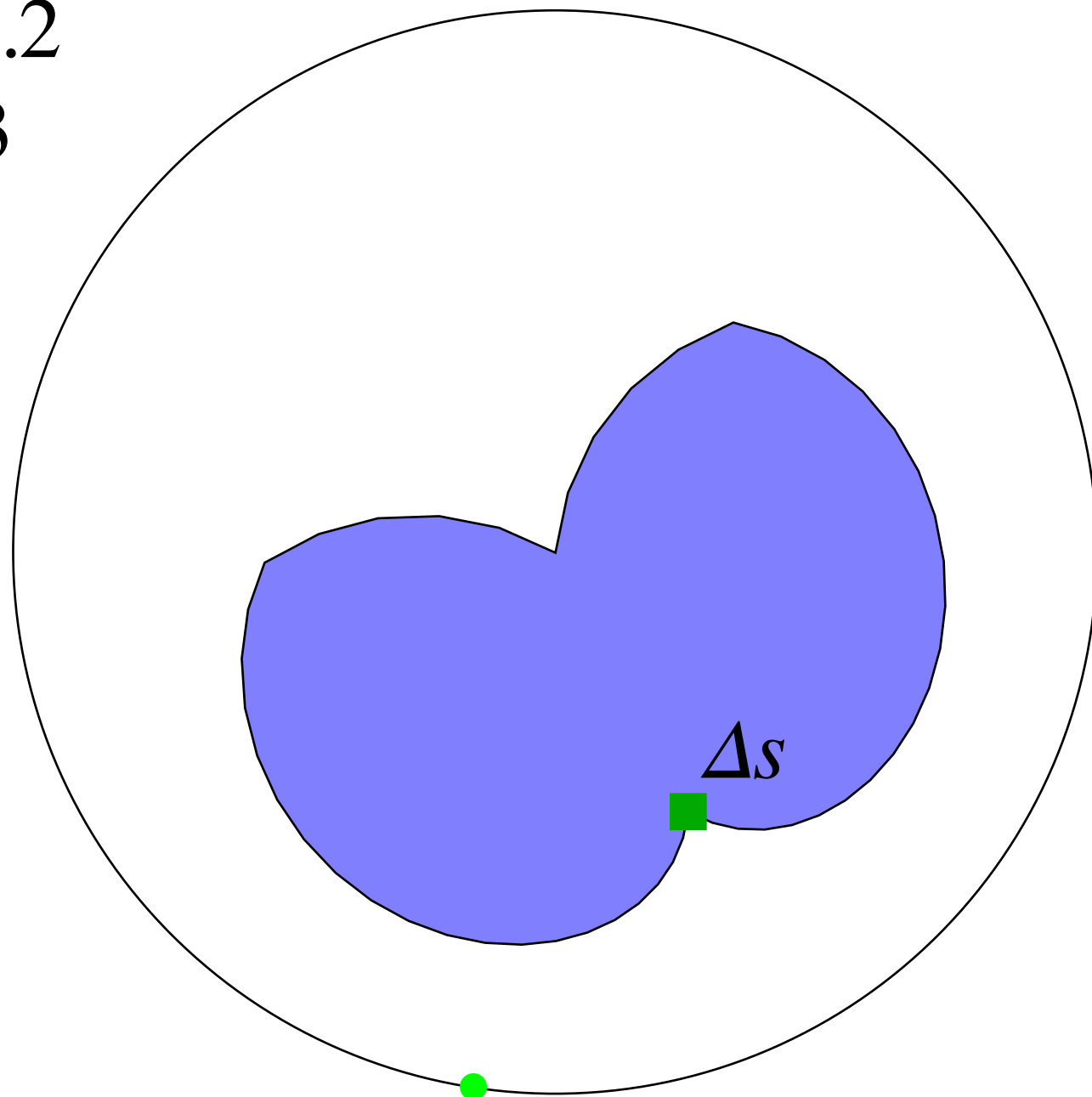
Distance 0 of 14.2
Move 1 of 293

Current ■=□—□

Goal ●=○—○



workspace



Δ configuration space