

Air Quality Forecasting

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- Our goal is to predict future PM values.
- Our dataset collects values of PM 2.5, PM 1, PM 4 once per hour from different sensors in Milan, called Arianna.
- Other variables of our dataset are
 - latitude and longitude of sensors
 - temperature
 - humidity
 - wind
 - rain
- We start from an **univariate analysis** considering only data from one sensor in the period from 01-09-2020 to 27-10-2020.

$$y_t = \phi_0 + \phi_1 y_{t-1} + \phi_2 y_{t-2} + \epsilon_t \quad \epsilon_t | \sigma^2 \stackrel{i.i.d.}{\sim} \mathcal{N}(0, \sigma^2)$$

$$y_t | y_{t-1}, \dots, y_{t-p}, \mathbf{X}, \beta, \sigma^2 \sim \mathcal{N}(y_t | \mathbf{f}_t^T \beta, \sigma^2) \quad \epsilon_t | \sigma^2 \stackrel{i.i.d.}{\sim} \mathcal{N}(0, \sigma^2)$$

$$\Rightarrow p(\mathbf{Y} | y_{t-1}, \dots, y_{t-p}, \mathbf{X}, \beta, \sigma^2) = \prod_{t=p_{\max}}^{n+p_{\max}} \mathcal{N}(y_t | \mathbf{f}_t^T \beta, \sigma^2) = \mathcal{N}_n(\mathbf{Y} | \mathbf{F}^T \beta, \sigma^2)$$

$$\begin{cases} \mathbf{Y} | y_{t-1}, \dots, y_{t-p}, \mathbf{X}, \beta, \sigma^2 \sim \mathcal{N}_n(\mathbf{Y} | \mathbf{F}^T \beta, \sigma^2) \\ \beta | \sigma^2 \sim \mathcal{N}_k(\boldsymbol{\mu}_0, \sigma^2 B_0) \\ \sigma^2 \sim \text{inverse-gamma}(\frac{\nu_0}{2}, \frac{\nu_0 \sigma_0^2}{2}) \end{cases}$$

- $\mathbf{Y} = [y_{p_{\max}}, \dots, y_{p_{\max}+n}]$, where $p_{\max} = \max(p, p_1, p_2, p_3, p_4)$
- $\mathbf{X} = [\mathbf{x}_1, \mathbf{x}_2, \mathbf{x}_3, \mathbf{x}_4]$ is the vector of covariates: temperature, humidity, rain, wind, where $\mathbf{x}_i = [x_{t-1}^i, \dots, x_{t-p_i}^i]$
- $\mathbf{f}_t^T = [1, y_{t-1}, \dots, y_{t-p}, \mathbf{X}]$ is the autoregressive part together with the vector of covariates
- $\mathbf{F} = [\mathbf{f}_{p_{\max}}, \dots, \mathbf{f}_{p_{\max}+n}]$

$$p = p_1 = p_2 = p_3 = p_4 = 7$$

↓

$$y_t = \beta_0 + \beta_1 y_{t-1} + \dots + \beta_7 y_{t-7} + \beta_8 x_{t-1}^1 + \dots + \beta_{14} x_{t-7}^1 + \dots + \beta_{29} x_{t-1}^4 + \dots + \beta_{35} x_{t-7}^4 + \epsilon_t$$

$$\left\{ \begin{array}{l} \mathbf{Y} | \mathbf{y}_{t-1}, \dots, \mathbf{y}_{t-p}, \mathbf{X}, \beta, \sigma^2 \stackrel{i.i.d.}{\sim} \mathcal{N}_n(\mathbf{Y} | \mathbf{F}^T \beta, \sigma^2) \\ \beta_j | \lambda \stackrel{i.i.d.}{\sim} \mathcal{N}(0, \frac{1}{\lambda}) \\ \lambda \sim \text{gamma}(a_\lambda, b_\lambda) \\ \sigma^2 \sim \text{inverse-gamma}(a_{\sigma^2}, b_{\sigma^2}) \end{array} \right. \quad j = 1, \dots, k$$

$$y_t = \beta_1 + \beta_1 y_{t-1} + \beta_2 y_{t-2} + \beta_9 x_{t-1}^1 + \beta_7 x_{t-1}^2 + \beta_{18} x_{t-2}^2 + \beta_{19} x_{t-3}^2 + \beta_{23} x_{t-1}^4 + \beta_{24} x_{t-7}^3 + \epsilon_t$$

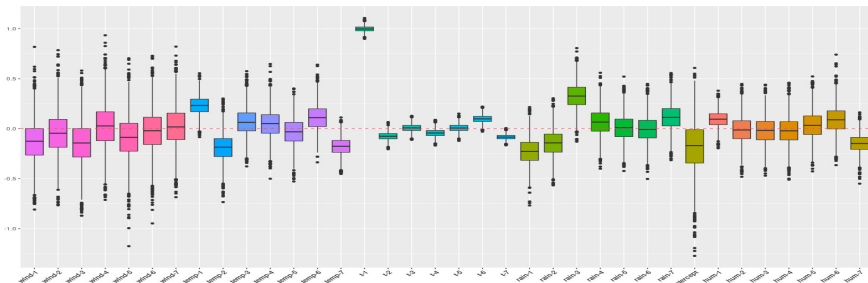


Figure: Boxplots from Ridge regression

Significant covariates (considering 90% credible intervals) from Ridge are:

- lag 1-2 for the autoregressive part $\Rightarrow y_{t-1}, y_{t-2}$
- lag 1 for humidity $\Rightarrow x_{t-1}^1$
- lag 1-2-3 for rain $\Rightarrow x_{t-1}^2, x_{t-2}^2, x_{t-3}^2$
- lag 1-2 for temperature $\Rightarrow x_{t-1}^3, x_{t-2}^3$
- the covariate wind seems to be not significant

Traceplots and posterior density plots of significant parameters

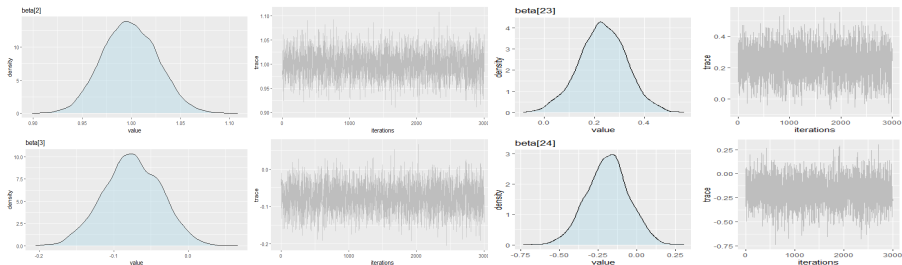


Figure: lag 1-2 autoregressive

Figure: lag 1-2 temperature

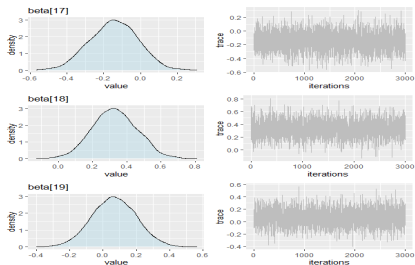


Figure: lag 1-2-3 rain

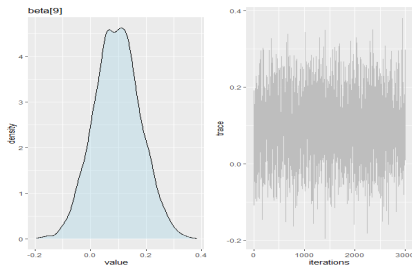


Figure: lag 1 humidity

Hourly SARX: ARX with hourly seasonal effect

$$y_t = \mu_t + \epsilon_t, \quad \epsilon_t \stackrel{i.i.d.}{\sim} \mathcal{N}(0, \sigma^2) \quad t = p_{\max} : n, \quad p_{\max} = \max(p, p_1, p_2, p_3)$$

$$\mu_t = \mathbf{f}_t^T \boldsymbol{\alpha} + \mathbf{x}_t^T \boldsymbol{\beta} + S_t$$

$$S_t = \sum_{i=0}^{T-1} \gamma_i \delta_t^i \quad T = 24$$

$$\delta_t^i = \begin{cases} 1 & \text{if at time } t \text{ is hour } i \\ 0 & \text{otherwise} \end{cases}$$

- $\mathbf{f}_t^T = (1, y_{t-1}, \dots, y_{t-p})$ is the autoregressive term
- $\mathbf{x}_t^T = (X_{t-1}^1, \dots, X_{t-p_1}^1, \dots, X_{t-1}^3, \dots, X_{t-p_3}^3)$ is the regressive term

$$\mu = \mathbf{F}^T \alpha + \mathbf{X}^T \beta + \Delta \gamma$$

Δ is a $24 \times n$ matrix having for each row t , 1 in position j if $\delta_t^j = 1$, 0 otherwise

$$\left\{ \begin{array}{ll} \mathbf{Y} | \mathbf{F}, \alpha, \mathbf{X}, \beta, \Delta, \gamma, \sigma^2 \sim \mathcal{N}_n(\mathbf{Y} | \mu, \sigma^2) \\ \sigma^2 \sim \text{inverse} - \text{gamma}(a_\sigma^2, b_\sigma^2) \\ \alpha_i \stackrel{i.i.d.}{\sim} \mathcal{N}(a_0, \sigma_\alpha^2) & i = 0, \dots, p \\ \beta_j \stackrel{i.i.d.}{\sim} \mathcal{N}(b_0, \sigma_\beta^2) & j = 1, \dots, k, \\ & k = p_1 + p_2 + p_3 \\ \gamma_h | \sigma_\gamma \stackrel{i.i.d.}{\sim} \mathcal{N}(0, \sigma_\gamma) & h = 0, \dots, 23 \\ \sigma_\gamma \sim \text{inverse} - \text{gamma}(a_\gamma, b_\gamma) \end{array} \right.$$

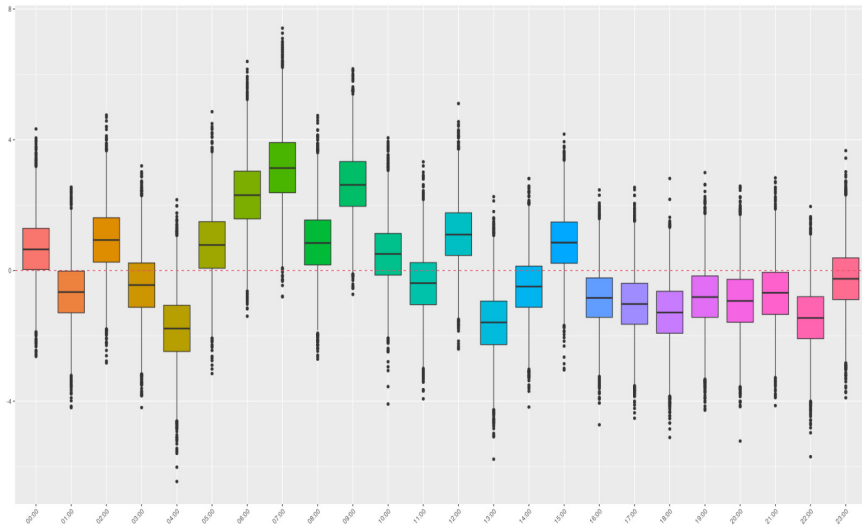


Figure: Boxplots of gamma

Daily SARX: ARX with daily seasonal effect

$$y_t = \mu_t + \epsilon_t, \quad \epsilon_t \stackrel{i.i.d.}{\sim} \mathcal{N}(0, \sigma^2)$$

$$\mu_t = \mathbf{f}_t^T \boldsymbol{\alpha} + \mathbf{x}_t^T \boldsymbol{\beta} + S_t$$

$$S_t = \sum_{i=0}^{T-1} \gamma_i \delta_t^i \quad T = 7$$

$$\delta_t^i = \begin{cases} 1 & \text{if at time } t \text{ is day } i \\ 0 & \text{otherwise} \end{cases}$$

$$\Rightarrow \mathbf{Y} | \mathbf{F}, \boldsymbol{\alpha}, \mathbf{X}, \boldsymbol{\beta}, \boldsymbol{\Delta}, \boldsymbol{\gamma}, \sigma^2 \sim \mathcal{N}_n(\mathbf{y} | \boldsymbol{\mu}, \sigma^2)$$

priors as in the hourly case

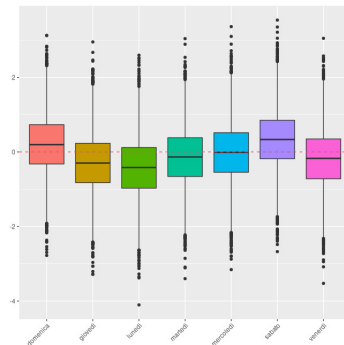


Figure: boxplots of gamma

We compared models on the base of both WAIC and BIC indexes

$$WAIC = \sum_{i=1}^n \log \left[\frac{1}{M} \sum_{j=1}^M f_i(y_i | \theta^{(m)}) \right] - p_{WAIC}$$

$$BIC = 2 \log f(\mathbf{x} | \tilde{\theta}) - r \log n \quad \tilde{\theta} : \text{MCMC estimate of the posterior mean of } \theta, \quad r = \dim(\theta)$$

model	WAIC	BIC
AR(2)	8948.05	-18405.63
ARX(7)	8830.286	-18175.14
regularized ARX(7)	20150.2	-23111.88
SARX(2,2,1,3)	8820.29	-18122.96

⇒ According to both WAIC and BIC, SARX(2,2,1,3) is the best model

$$y_t = \phi_0 + \phi_1 y_{t-1} + \phi_2 y_{t-2} + \epsilon_t$$

$$y_t = \mathbf{f}_t^T \boldsymbol{\alpha} + \mathbf{x}_t^T \boldsymbol{\beta} + \sum_{i=0}^{23} \gamma_i \delta_t^i + \epsilon_t$$

Why so bad results?

- All the models seen so far are static, in the sense that parameters are kept fixed once the model is fitted.
- Static models are not able to adapt to **big changes in the time series dynamics** (peaks).
- Dynamic parameter models allow to better track the time series as new information is collected, in a sort of **feedback loop** style.

Next models to investigate:

- TVAR (Time Varing AR)
- Exponential smoothing
- Generic DLM models
- Multivariate analysis

- Time Series Modeling, Computation, and Inference. West Mike, Prado Raquel
- Bayesian Forecasting and Dynamic Models. Mike West, Jeff Harrison