```
Index.html
          onClick="sendRequest('http://192.168.4.1/Button?val=1')"
                          function sendRequest(url) {
                            var xhr = new XMLHttpRequest();
                            xhr.open("GET", url, true);
                            xhr.send();
                            xhr.timeout = 100;
ESP8266
                                                                       56
                              void loop() {
          2
                                                                       55
                                handle_client();
          3
                                                                       54
                                                                       53
                                                                       52
                                                                       51
          server.on("/Button", HTTP GET, handleButtonRequest);
                                                                       50
                                                                       49
          9
                                                                       48
                void handleButtonRequest(void) {
          10
                                                                       47
          11
                                                                       46
                  int id = server.arg("val").toInt();
          12
                                                                       45
                  //Avanzar
          13
                                                                       44
                  if (id == 1) {
          14
                                                                       43
                    motor FWBW(true);
          15
                                                                       42
                    server.send(200, "text/plain", "OK");}
          16
                                                                       41
          17
                                                                       40
          18
                                                                       39
                    void motor FWBW(bool dir1)
          19
                                                                       38
          20
                                                                       37
          21
                                                                       36
                      if (dir1) {
          22
                                                                       35
                        digitalWrite(motor A1, LOW);
          23
                                                                       34
                        digitalWrite(motor A2, HIGH);
          24
                                                                       33
                        analogWrite(pin_vel_A, SPEED_A);
          25
                                                                       32
                        digitalWrite(motor B1, LOW);
          26
                                                                       31
                        digitalWrite(motor B2, HIGH);
          27
                                                                       30
                        analogWrite(pin_vel_B, SPEED_B);
          28
                                                                       29
                      }
```