

Exercise 8

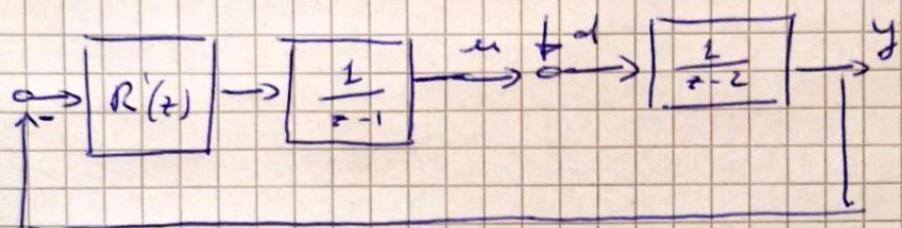
See the notes pp. 54 - 57, 153 - 163

Exercise 7

$$y(l) = \frac{1}{z-2} (u(l) + d)$$

[pole placement + integral action]

solution with transfer functions



$$R'(z) = \frac{f_1 z + f_0}{g_1 z + g_0}, \quad R(z) = R'(z) \frac{1}{z-1}$$

$$P(z) = (z-0.5)^3 = z^3 + P_2 z^2 + P_1 z + P_0$$

$$G'(z) = \frac{1}{z-1} \cdot \frac{1}{z-2} = \frac{1}{z^2 - 3z + 2}$$

$$\begin{vmatrix} 1 & 0 & 0 & 0 \\ -3 & 1 & 0 & 0 \\ 2 & -3 & 1 & 0 \\ 0 & 2 & 0 & 1 \end{vmatrix} \begin{pmatrix} y_1 \\ y_0 \\ p_1 \\ p_0 \end{pmatrix} = \begin{pmatrix} 1 \\ p_2 \\ p_1 \\ p_0 \end{pmatrix}$$

Solution with state space ($y^0 = d = 0$ for simplicity)

$$\begin{cases} x(l+1) = 2x(l) + u(l) \\ y(l) = x(l) \end{cases}$$

Integration

$$v(h+1) = v(h) + e(h) = v(h) - y(h) = v(h) - x(h)$$

$$\begin{vmatrix} x(h+1) \\ v(h+1) \end{vmatrix} = \underbrace{\begin{vmatrix} 2 & 0 \\ -1 & 2 \end{vmatrix}}_A \begin{vmatrix} x(h) \\ v(h) \end{vmatrix} + \underbrace{\begin{vmatrix} 1 \\ 0 \end{vmatrix}}_B u(h)$$

$$u(h) = -K \begin{vmatrix} x(h) \\ v(h) \end{vmatrix}, \quad K = |h_1 \ h_2|$$

~~$$\det A \text{ def } (2I - (A - BK)) = (\varepsilon - 0.5)^2$$~~

Reduced order observer

$$d(h+1) = d(h)$$

$$\underbrace{y(h+1) - 2y(h) - u(h)}_{y(h+1)} = d(h)$$

$$\hat{d}(h+1|h) = \hat{d}(h|h-1) + L [y(h+1) - \hat{d}(h|h-1)]$$

Compensator

