**Main**

Initialisation

Thread angle

**Thread**

**angle**

**Thread**

**regulation**

Uniquement calibrations & initialisations

Compute angle

Regulation

Esquive

**Thread**

**proximité**

Get angle

Get slope

Initialisation

Thread regulation

Initialisation

Thread proximité

Get\_prox\_alert

Mode selection

Search for proximity

Alerte proximité ?

Fin esquive ?

get\_prox\_alert

regulator

motors\_set\_speed

escape

regulator

motors\_set\_speed

Non

Non

Oui

Oui