

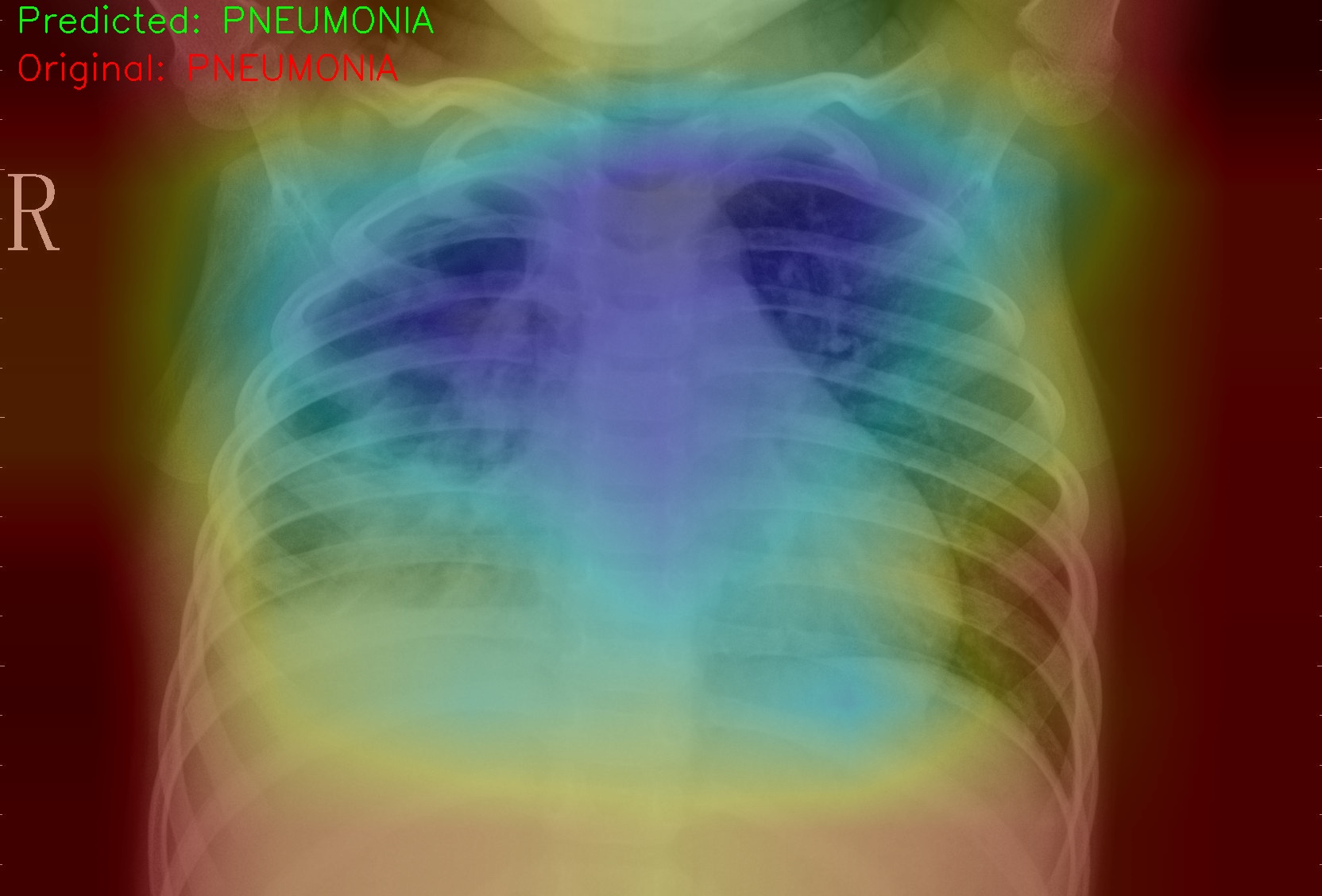


**CAP 5516 – PNEUMONIA CLASSIFICATION**

*Deep Learning-based Pneumonia Detection Using Chest X-Ray Images*

In this report, we present results of applying deep learning models and techniques to detect pneumonia by using the provided pediatric chest X-rays, downloaded from kaggle. The deep learning architecture we selected is ResNet18 and the best accuracy achieved on the test set is 94.71% by leveraging ImageNet pre-training, data augmentation and hyper-parameter fine-tuning.

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**Programming Assignment 01:**

**Report:**

1. **Implementation Details**

In this section, we share the implementation details of our experiments. All the code is implemented using the PyTorch framework.

* 1. Network Architecture

The deep learning architecture we selected for our experiments is a very basic ResNet18 model. The detailed structure of the ResNet18 model is presented in Appendix A. The total number of training parameters were 11,177,538.

* 1. Hyperparameters
     1. Learning Rate

We used the following values of learning rates in our experiments:

0.01, 0.001, 0.0001

* + 1. Batch Size

We used a batch size of 64 for all our experiments.

* + 1. Training Epochs

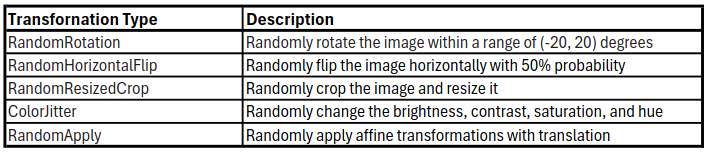
The number of training epochs varied between 15 and 40.

* 1. Pretraining

For Task 1.2 (a) and Task 1.2 (b), we used the ImageNet pretrained weights directly downloaded through PyTorch.

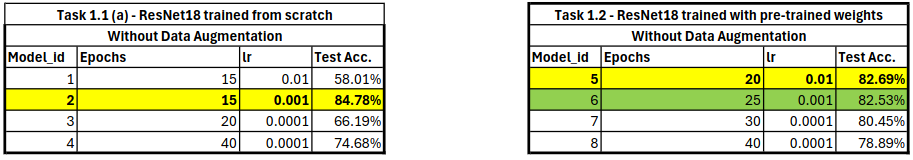
* 1. Data Augmentation

For Task 1.1 (b) and Task 1.2 (b), we used a series of transformations to leverage data augmentation and gain improvement in terms of model accuracy. Following table describes the transformations we used:

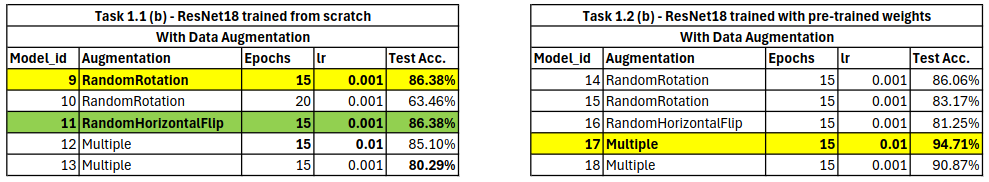


1. Results
   1. Quantitative
      1. Tabular Results

First, we present the results of Task 1.1 (a) and Task 1.2 (a), side by side to make the comparison easier. In Task 1.1 (a), the ResNet18 model was trained from scratch while in Task 1.2 (a) we used the pretrained weights. We used different combinations of hyper-parameters to get the best combination possible (best highlighted in yellow; second best highlighted in green). It is to be noted that both the tasks are performed without any data augmentation. Model 2 and model 5 are the winners here.



Next, we present the results of Task 1.1 (b) and Task 1.2 (b). These are performed with data augmentation. Model 9 and model 17 are the winners in this case.

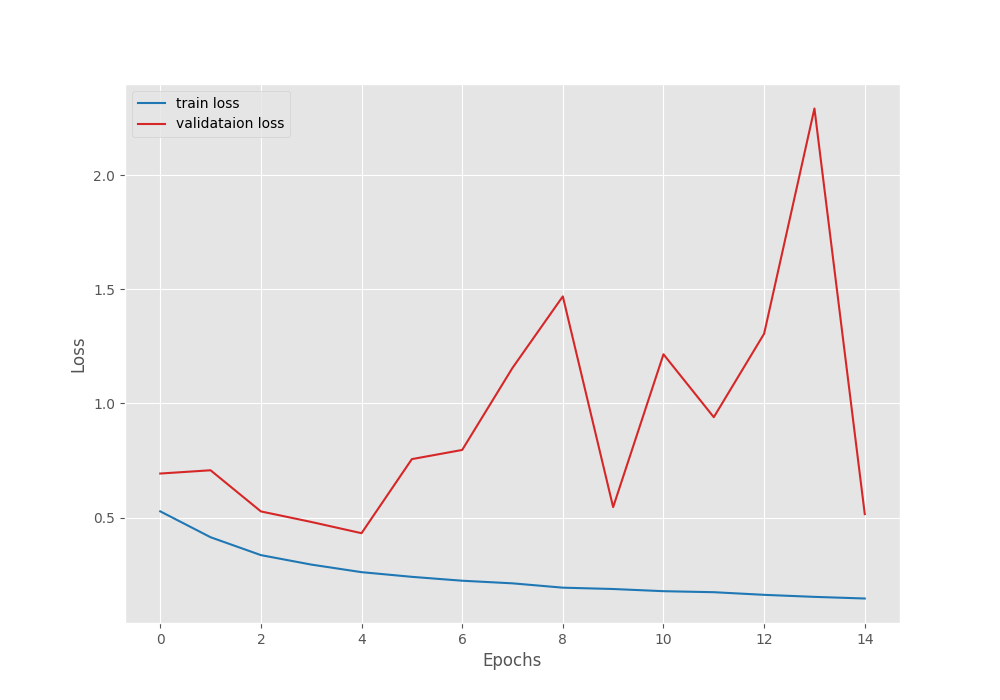
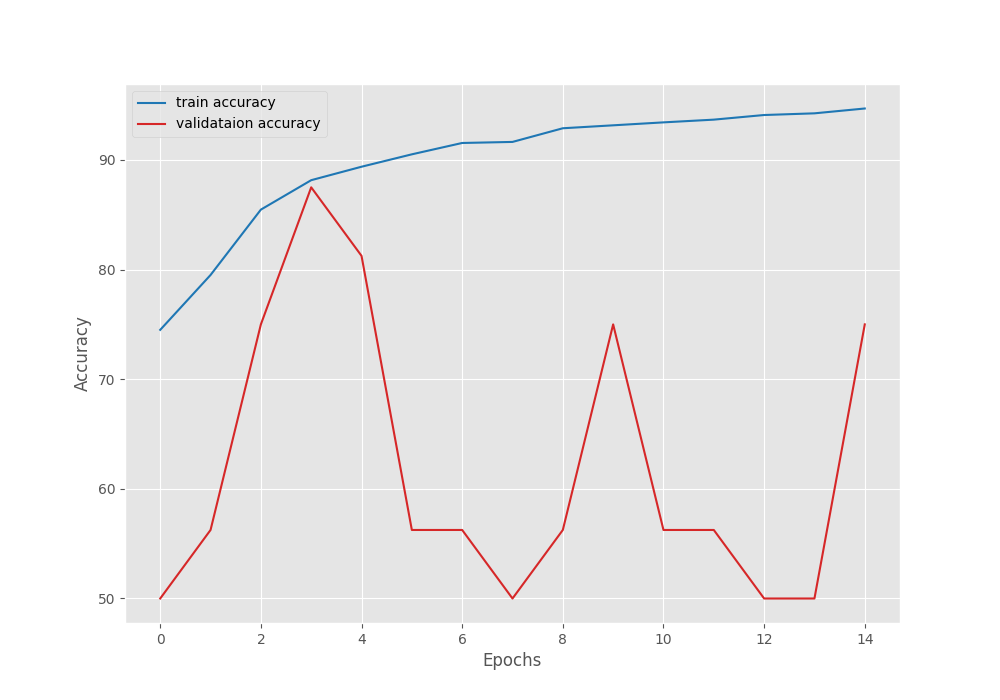


* + 1. Graphical Results

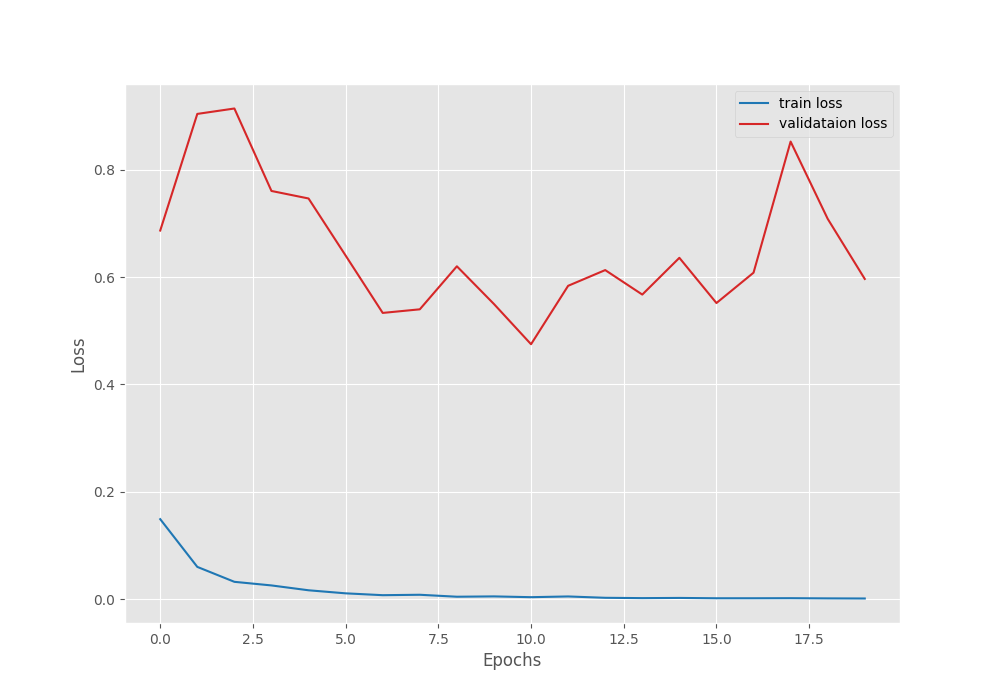
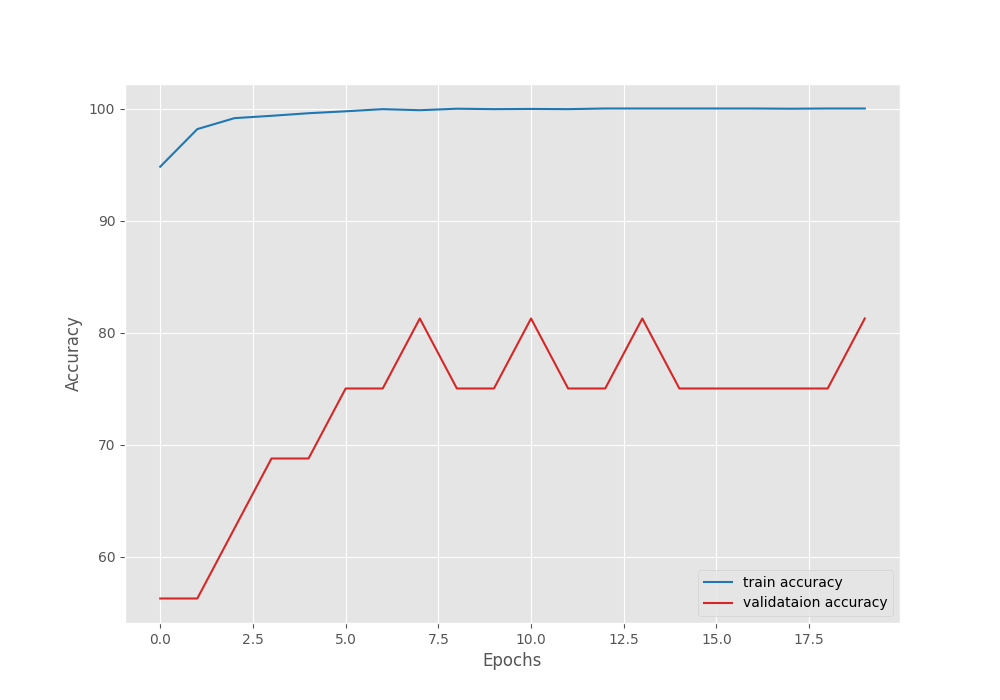
In this section, we present the loss and accuracy curves for both training and validation for the best models i.e. model 2, model 5, model 9 and model 17. The rest of the charts are presented in the attached folder at path: Pneumonia/outputs

Please note that the validation set provided is very small i.e. 8 images per class which impacts the behavior of both validation loss and validation accuracy.

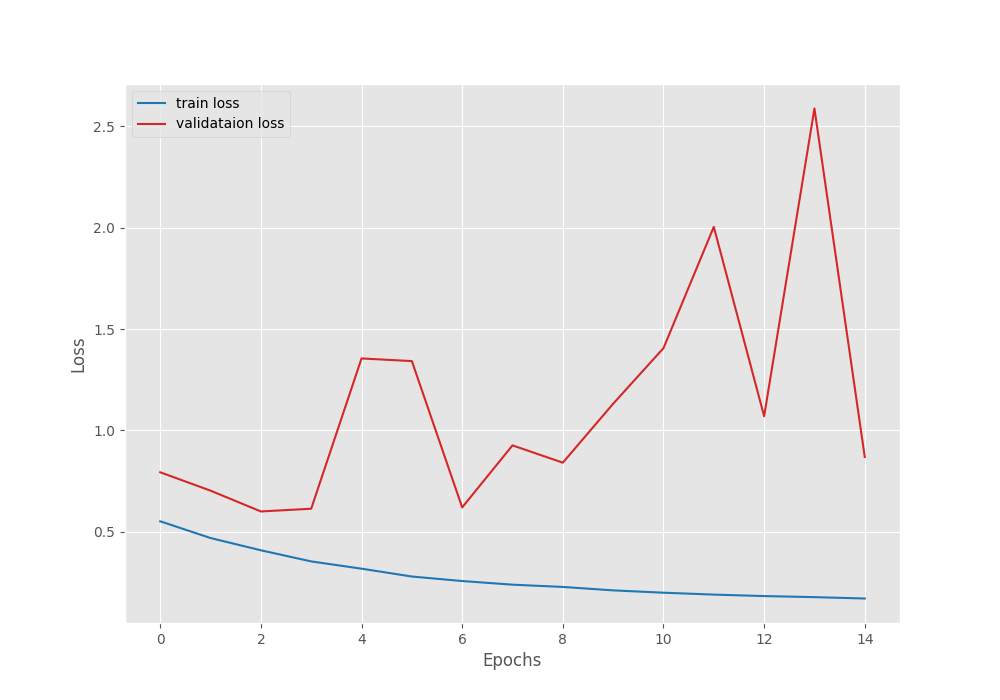
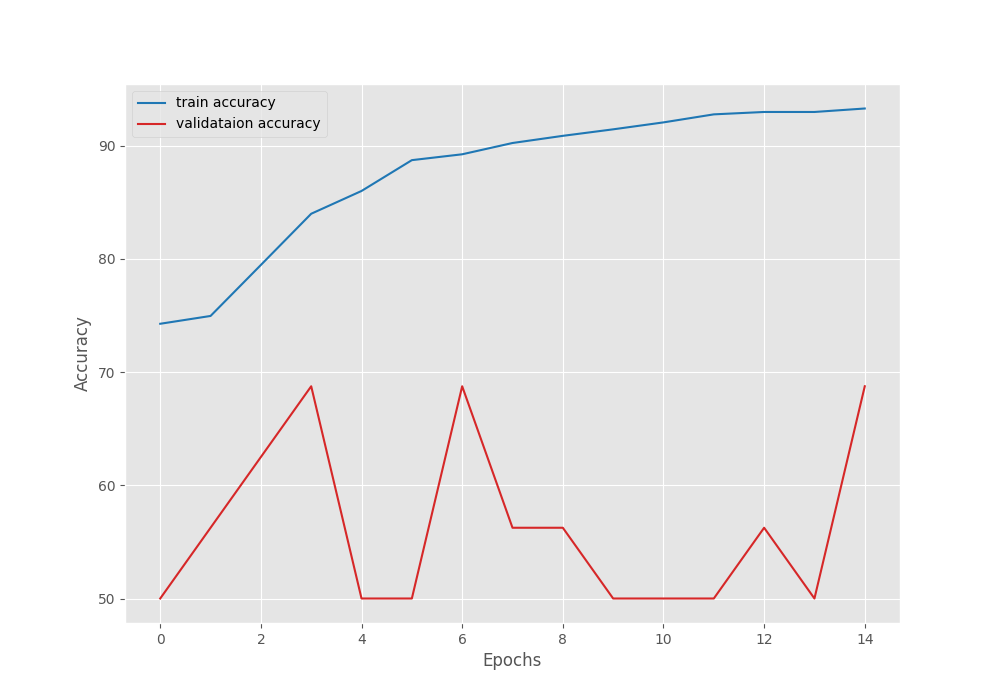
**Model 02 – Accuracy** **Model 02 – Loss Curve**



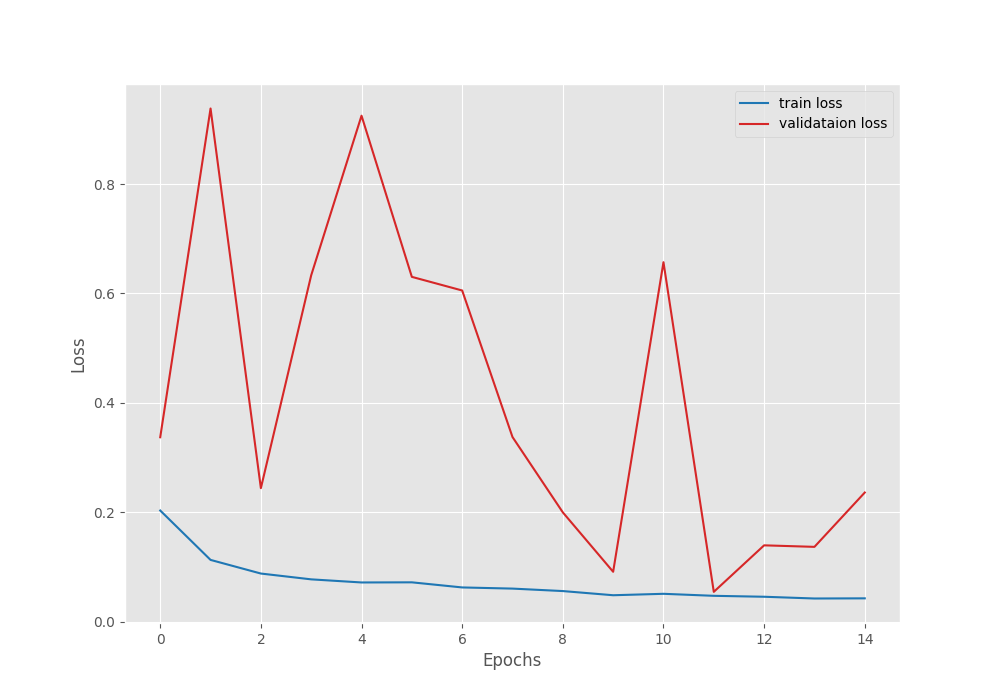
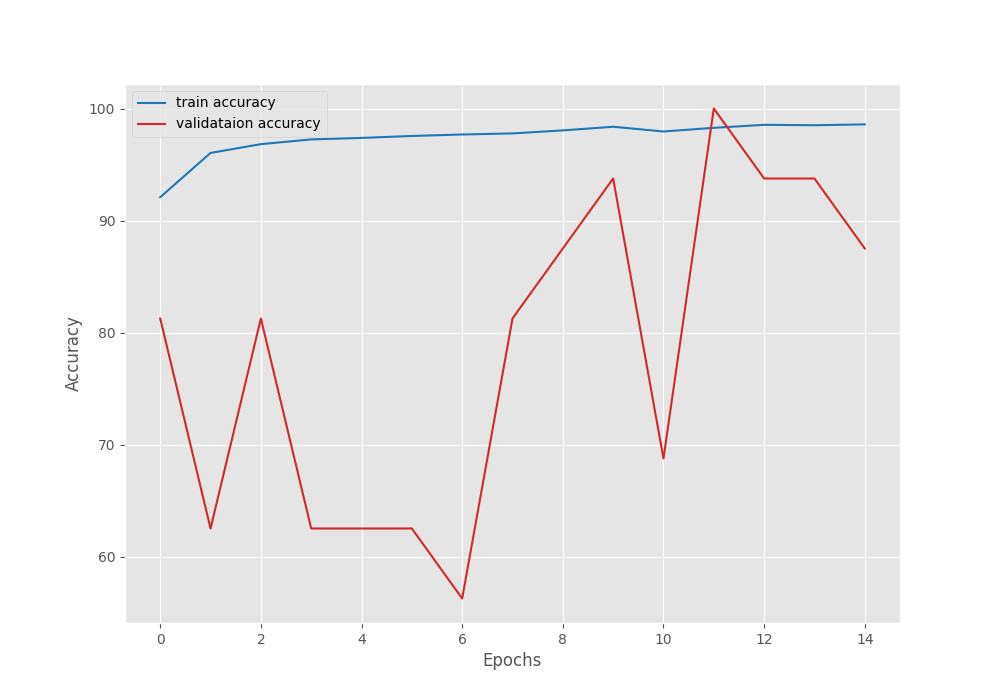
**Model 05 - Accuracy Curve** **Model 05 - Loss Curve**



**Model 09 – Accuracy Curve** **Model 09 – Loss Curve**



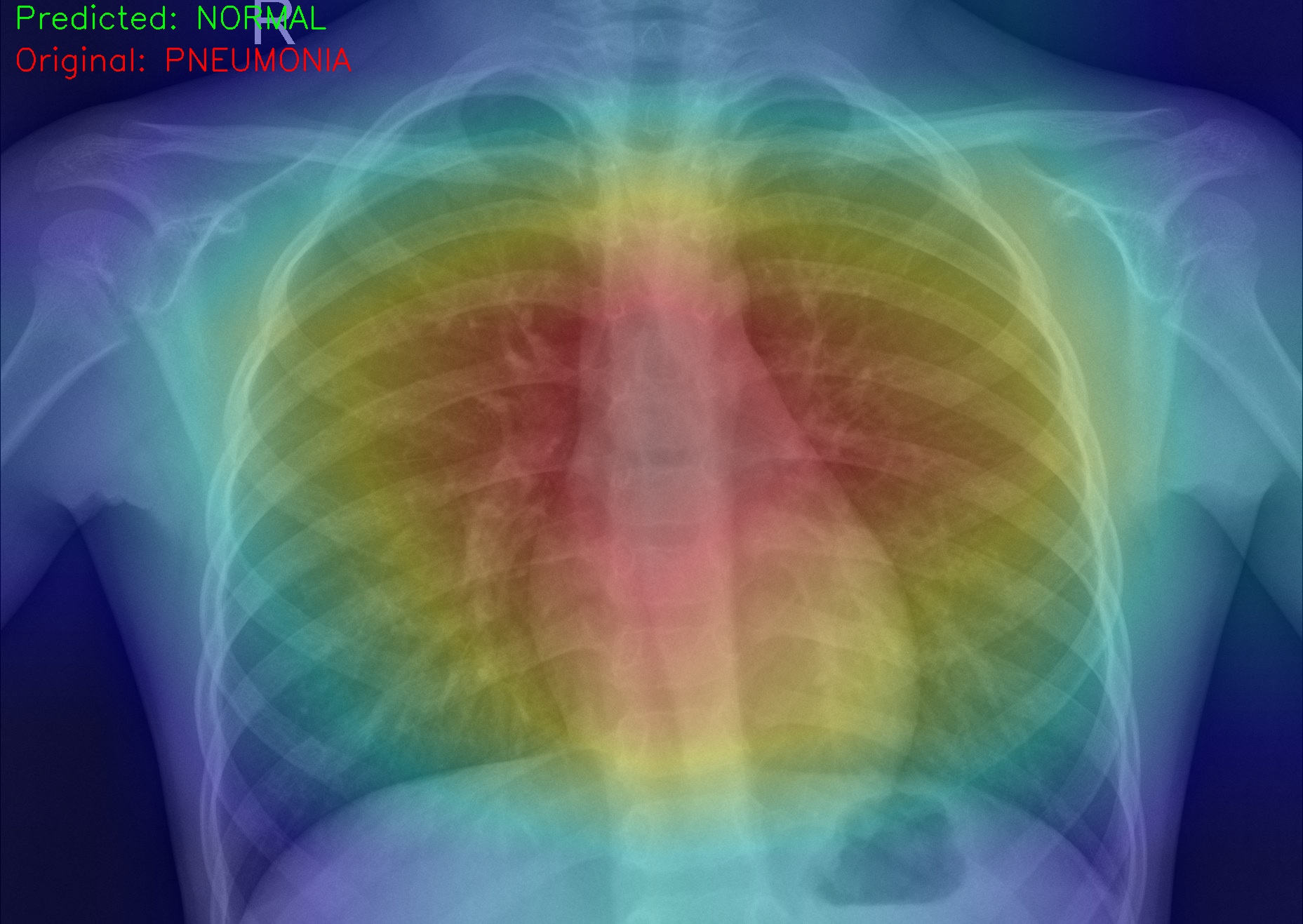
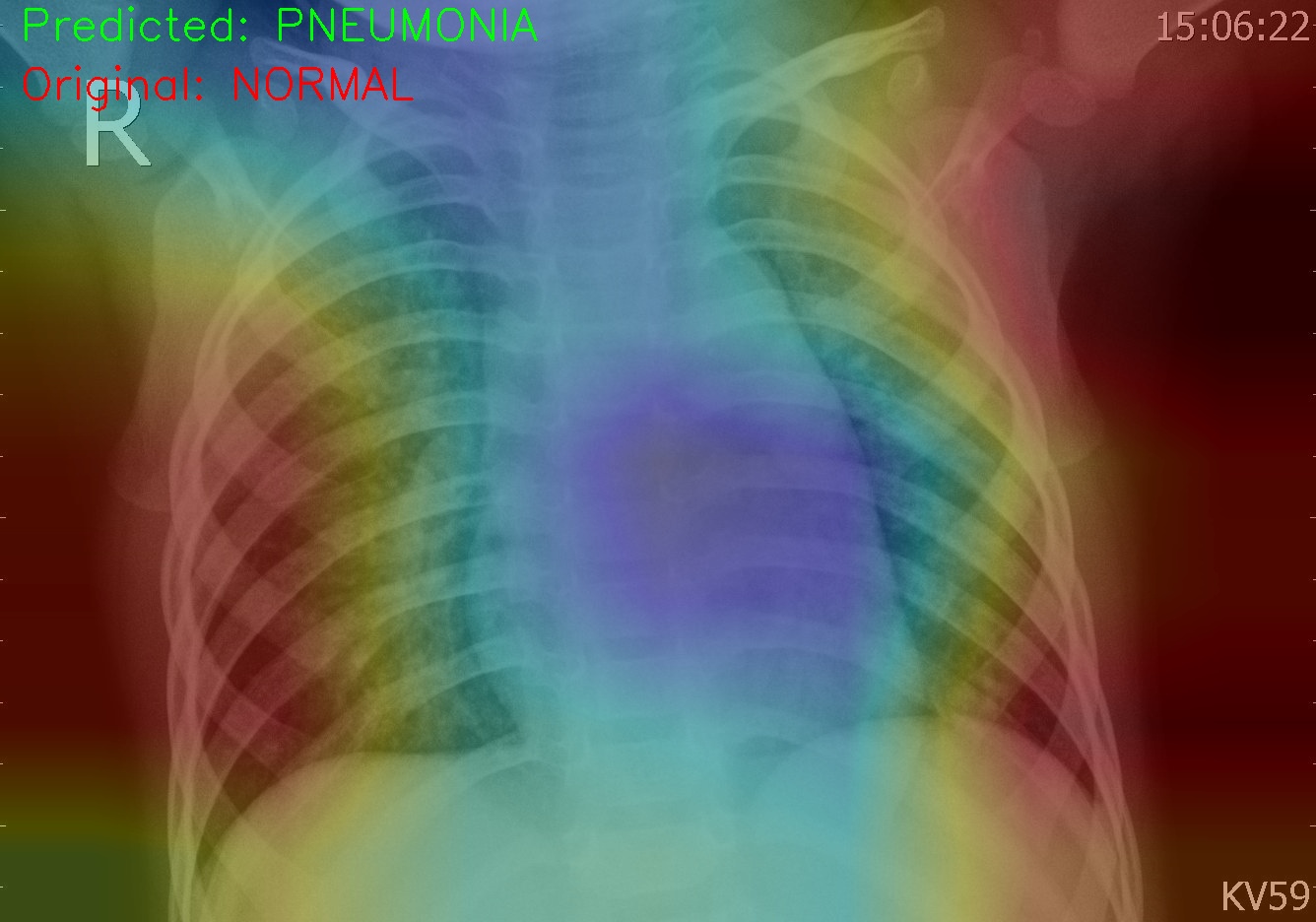
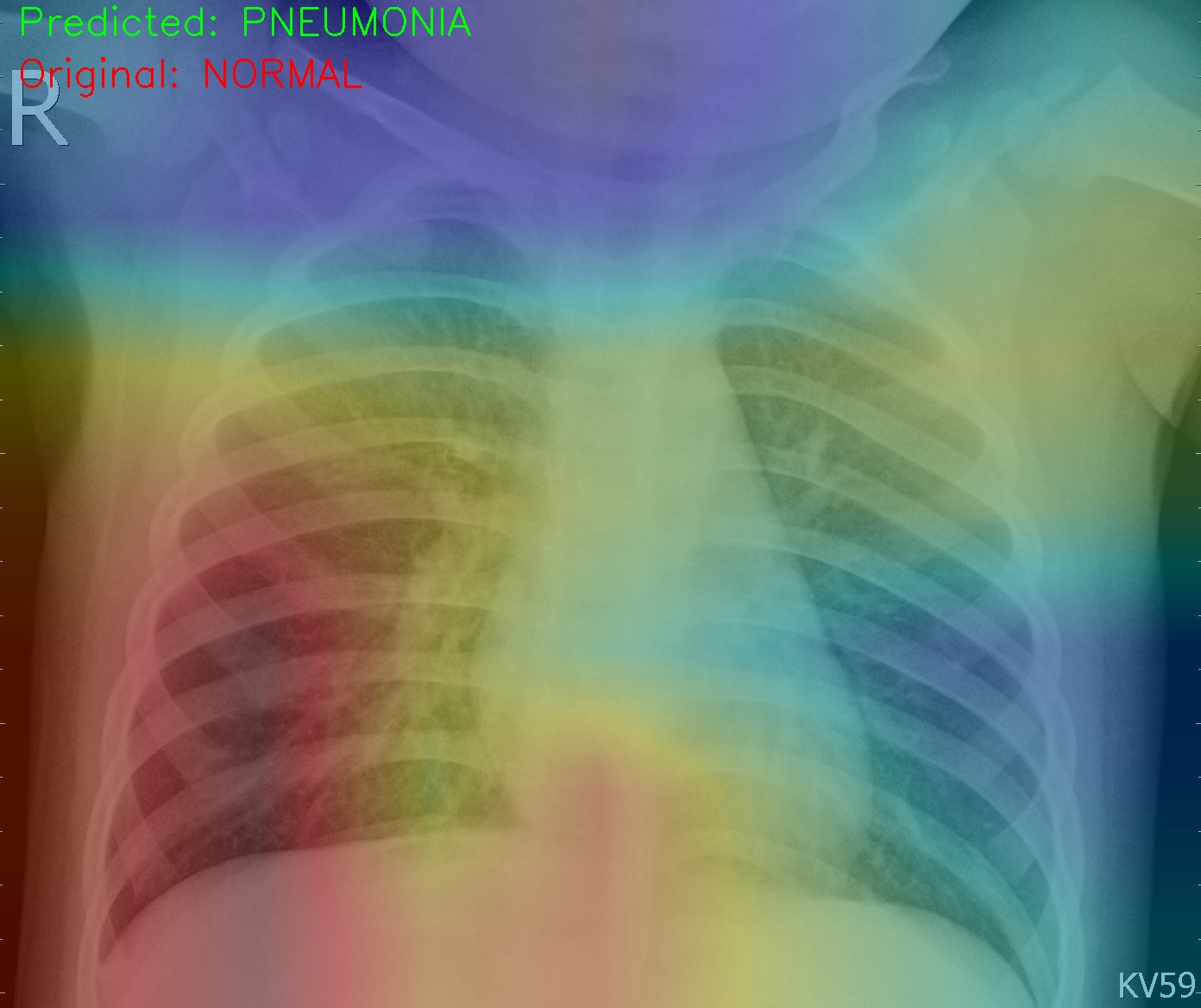
**Model 17 – Accuracy Curve** **Model 17 – Loss Curve**



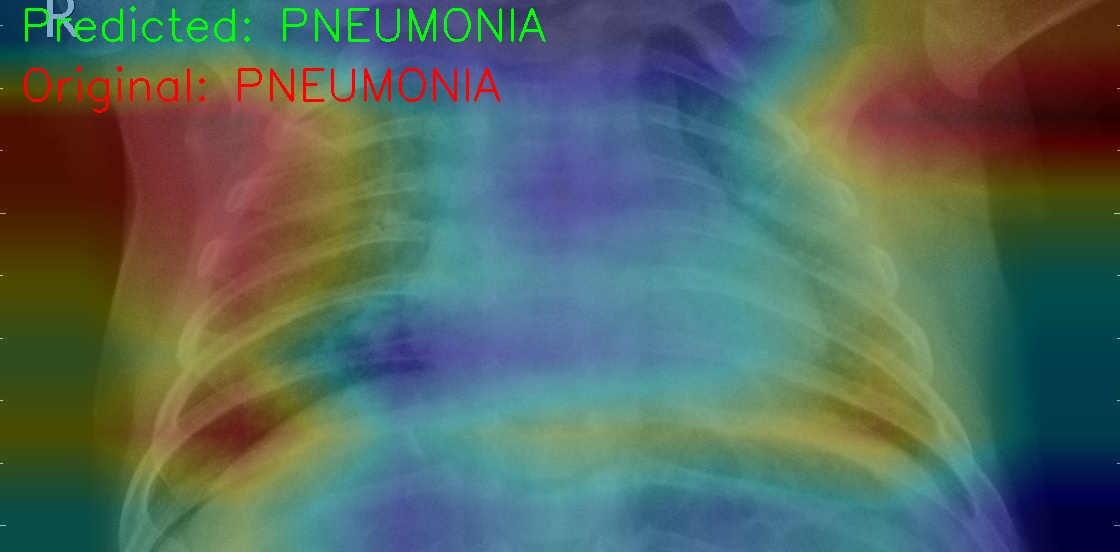
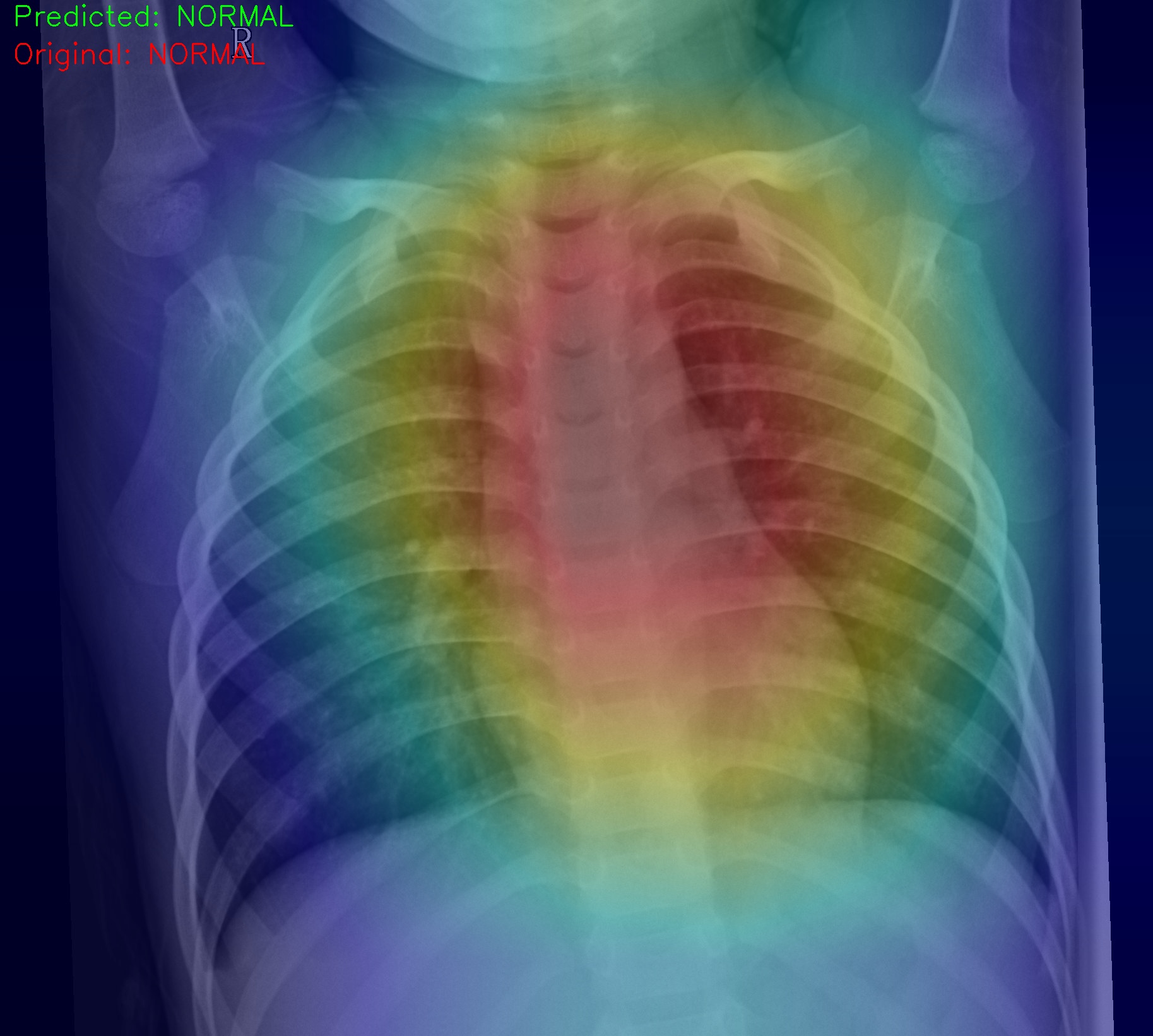
* 1. Qualitative Results
     1. Visualization using CAM

In this section, we present a few examples of both failure and success cases using our overall best model, Model 17. We have provided visualization with CAM for all examples of the test set and the validation set, All other CAM images can be found at Pneumonia/CAM\_visualization/cam\_outputs with their corresponding inpput images at Pneumonia/CAM\_visualization/cam\_inputs.

* + - 1. Failure Cases



* + - 1. Success Cases



1. Conclusion

Our best model, Model 17 is trained using ImageNet pre-trained weights and data augmentation using a combination of Random Rotation, Random Horizontal Flip, Random Resized Crop, Color Jitter, and Random Affine with a learning rate of 0.01 for only 15 epochs and achieves a 94.7% accuracy.

Appendix A

ResNet(  
 (conv1): Conv2d(3, 64, kernel\_size=(7, 7), stride=(2, 2), padding=(3, 3), bias=False)  
 (bn1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track\_running\_stats=True)  
 (relu): ReLU(inplace=True)  
 (maxpool): MaxPool2d(kernel\_size=3, stride=2, padding=1, dilation=1, ceil\_mode=False)  
 (layer1): Sequential(  
 (0): BasicBlock(  
 (conv1): Conv2d(64, 64, kernel\_size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False)  
 (bn1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track\_running\_stats=True)  
 (relu): ReLU(inplace=True)  
 (conv2): Conv2d(64, 64, kernel\_size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False)  
 (bn2): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track\_running\_stats=True)  
 )  
 (1): BasicBlock(  
 (conv1): Conv2d(64, 64, kernel\_size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False)  
 (bn1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track\_running\_stats=True)  
 (relu): ReLU(inplace=True)  
 (conv2): Conv2d(64, 64, kernel\_size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False)  
 (bn2): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track\_running\_stats=True)  
 )  
 )  
 (layer2): Sequential(  
 (0): BasicBlock(  
 (conv1): Conv2d(64, 128, kernel\_size=(3, 3), stride=(2, 2), padding=(1, 1), bias=False)  
 (bn1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track\_running\_stats=True)  
 (relu): ReLU(inplace=True)  
 (conv2): Conv2d(128, 128, kernel\_size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False)  
 (bn2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track\_running\_stats=True)  
 (downsample): Sequential(  
 (0): Conv2d(64, 128, kernel\_size=(1, 1), stride=(2, 2), bias=False)  
 (1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track\_running\_stats=True)  
 )  
 )  
 (1): BasicBlock(  
 (conv1): Conv2d(128, 128, kernel\_size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False)  
 (bn1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track\_running\_stats=True)  
 (relu): ReLU(inplace=True)  
 (conv2): Conv2d(128, 128, kernel\_size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False)  
 (bn2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track\_running\_stats=True)  
 )  
 )  
 (layer3): Sequential(  
 (0): BasicBlock(  
 (conv1): Conv2d(128, 256, kernel\_size=(3, 3), stride=(2, 2), padding=(1, 1), bias=False)  
 (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track\_running\_stats=True)  
 (relu): ReLU(inplace=True)  
 (conv2): Conv2d(256, 256, kernel\_size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False)  
 (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track\_running\_stats=True)  
 (downsample): Sequential(  
 (0): Conv2d(128, 256, kernel\_size=(1, 1), stride=(2, 2), bias=False)  
 (1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track\_running\_stats=True)  
 )  
 )  
 (1): BasicBlock(  
 (conv1): Conv2d(256, 256, kernel\_size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False)  
 (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track\_running\_stats=True)  
 (relu): ReLU(inplace=True)  
 (conv2): Conv2d(256, 256, kernel\_size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False)  
 (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track\_running\_stats=True)  
 )  
 )  
 (layer4): Sequential(  
 (0): BasicBlock(  
 (conv1): Conv2d(256, 512, kernel\_size=(3, 3), stride=(2, 2), padding=(1, 1), bias=False)  
 (bn1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track\_running\_stats=True)  
 (relu): ReLU(inplace=True)  
 (conv2): Conv2d(512, 512, kernel\_size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False)  
 (bn2): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track\_running\_stats=True)  
 (downsample): Sequential(  
 (0): Conv2d(256, 512, kernel\_size=(1, 1), stride=(2, 2), bias=False)  
 (1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track\_running\_stats=True)  
 )  
 )  
 (1): BasicBlock(  
 (conv1): Conv2d(512, 512, kernel\_size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False)  
 (bn1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track\_running\_stats=True)  
 (relu): ReLU(inplace=True)  
 (conv2): Conv2d(512, 512, kernel\_size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False)  
 (bn2): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track\_running\_stats=True)  
 )  
 )  
 (avgpool): AdaptiveAvgPool2d(output\_size=(1, 1))  
 (fc): Linear(in\_features=512, out\_features=2, bias=True)  
)