Project AMMM: Selecting the best committee

Authors:

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 - Alternative Formulation
 - Fixing to ILP formulation
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Variable	Meaning	Range	Туре
N	Number of members of faculty	Integer	Integer
D	Number of departments in the faculty	Integer	Integer
d_i	Department of professor i	$1 \leq i \leq N$	Integer
n_p	Number of people needed from department p	$1 \le p \le D$	Integer
m _{ij}	Compatibility between professor i and j	$0 \leq m_{ij} \leq 1, \ 1 \leq i, j \leq N$	Real

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- Given $f(S) = \frac{2}{|S| \cdot (|S|-1)} \sum_{i \in S} \sum_{\substack{j \in S \\ i < j}} m_{ij}$, find a solution S^* such

that $f(S^*) \ge f(S)$ for all possible solutions S

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Project AMMM
Problem Formulation
Alternative Formulation

Variable	Meaning	Range	Туре
Xi	Professor <i>i</i> goes to the committee	$1 \le i \le N$	Boolean

Maximize:
$$\frac{2}{n \cdot (n-1)} \sum_{i=1}^{N} \sum_{j=i+1}^{N} m_{ij} \cdot x_i \cdot x_j$$

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Subject to:

Number of participants per department: $\sum_{i \in A_p} x_i = n_p$ for every $1 \le p \le D$

No two professors with 0 compatibility: $\lceil m_{ij} \rceil \geq x_i \cdot x_j$ for every $1 \leq i < j \leq N$

Not enough trust: $\sum_{k \in W_{ij}} x_k \ge x_i \cdot x_j$ for every $(i, j) \in N_{ij}$

Where:

$$A_d = \{i \in \{1, \dots, N\} : d_i = d\}$$

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This is Non-Linear Programming! Can we fix it?

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Уij	Professor i and j go to the committee	$1 \leq i, j \leq N$	Boolean

Maximize:
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Correlation between variables: $\begin{cases} x_i \geq y_{ij} \\ x_j \geq y_{ij} \end{cases}$

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Project AMMM Heuristics Greedy

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- The decisions are based on a greedy function

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- The first element will be the professor with the highest mean compatibility
- The rest of the algorithm is the usual greedy algorithm

```
function GreedySolve(N, D, d, n, m)
    remaining \leftarrow sum(n)
    S \leftarrow \emptyset
    S \leftarrow S \cup \{bestCompat(N, m)\}
    remaining \leftarrow remaining - 1
    while remaining > 0 do
         U \leftarrow feasibleProfs(N, D, d, n, m, S)
        if U = \emptyset then
             return null
         else
             p \leftarrow \arg\max\{q(u)\}
             S \leftarrow S \cup \{p\}
             n_{d_n} \leftarrow n_{d_n} - 1
             remaining \leftarrow remaining - 1
         end if
    end while
    return S
end function
```

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- ullet Given an initial solution and an operator, LS will search in $\mathcal{N}(S)$ for better solutions
- The algorithm stops upon finding S^* such as $f(S^*) \geq f(s) \ \ \forall s \in \mathcal{N}(S^*)$
- We used a Swap Operator with first improvement strategy

```
function LocalSearch(N, D, d, n, m, S)
(i,j) \leftarrow findFeasibleSwap(N, D, d, n, m, S)
while (i,j) is not null do
S \leftarrow (S \setminus \{i\}) \cup \{j\}
(i,j) \leftarrow findFeasibleSwap(N, D, d, n, m, S)
end while
return S
end function
```

```
function FINDFEASIBLESWAP(N,D,d,n,m,S)
    for i = 1, \ldots, N do
        for j = i + 1, \dots, N do
            if validSwap(N, D, d, n, m, S, i, j) then
                outside \leftarrow from i, j the one that is not in S
                inside \leftarrow from i, j the one that is in S
                out \leftarrow 0
                in \leftarrow 0
                for k = 1, \ldots, N do
                    if k \in S and k \neq inside then
                         out \leftarrow out + m_{outside,k}
                        in \leftarrow in + minside k
                    end if
                end for
                if out > in then
                    return (inside, outside)
                end if
            end if
        end for
    end for
    return null
end function
```

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Project AMMM Heuristics GRASP

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- Select an element of the RCL at random
- Execute the whole process (Constructive Greedy + LS) many times to obtain the best solution

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- ullet We tested the optimal lpha value (next section)

```
function GRASP(N, D, d, n, m, \alpha, maxlter)
    S \leftarrow \emptyset
    for i = 1, ..., maxIter do
        U \leftarrow constructiveGreedy(N, D, d, n, m, \alpha)
        if U \neq \emptyset then
             U \leftarrow localSearch(N, D, d, n, m, U)
        end if
        if f(U) > f(S) then

    ▷ Check average compatibility

            S \leftarrow U
        end if
    end for
    return S
end function
```

```
function ConstructiveGreedy(N, D, d, n, m, \alpha)
     remaining \leftarrow sum(n)
     S \leftarrow \emptyset
     while remaining > 0 do
           U \leftarrow feasibleProfs(N, D, d, n, m, S)
           if U = \emptyset then
                return 0
           end if
           q_{max} \leftarrow \max_{u \in U} \{q(u)\}
           q_{min} \leftarrow \min_{u \in U} \{q(u)\}
           \mathsf{rcl} \leftarrow \{ u \in U \mid q(u) \geq q_{\mathsf{max}} - \alpha \cdot (q_{\mathsf{max}} - q_{\mathsf{min}}) \}
           p \leftarrow \text{get random element from rcl}
           S \leftarrow S \cup \{p\}
           n_{d_0} \leftarrow n_{d_0} - 1
           remaining \leftarrow remaining - 1
     end while
     return S
end function
```

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Alpha-tuning

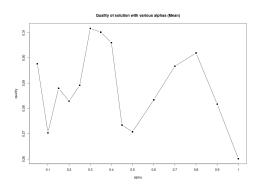


Figure: Mean of objective functions for each alpha

Alpha-tuning

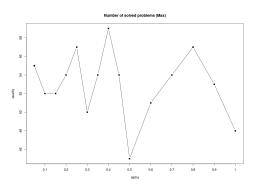


Figure: Number of instances solved by different values of alpha

Successes and Misses

Algorithm	Success	No solution	Fail
CPLEX	86	14	0
Greedy	36	64	50
Local Search	36	64	50
GRASP First Execution	42	58	44
GRASP Second Execution	43	57	43
GRASP Third Execution	35	65	51
GRASP (Max)	52	48	34
GRASP (Mean)	40	60	46

Table: Success and Failures from different methods

Greedy Quality

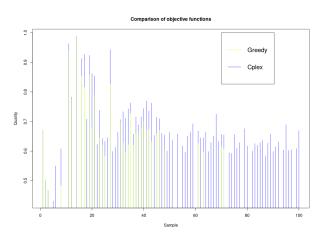


Figure: Greedy Solution

LS Quality

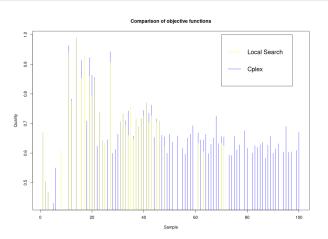


Figure: LS Solution

GRASP Quality

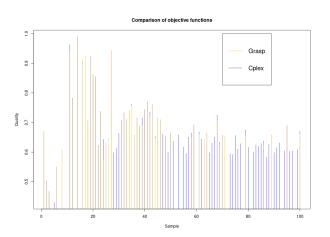


Figure: GRASP Solution

Quality of heuristics: Global

% Close to optimal solution	Greedy	Local Search	GRASP
100%	3	10	20
> 95%	7	20	31
> 90%	16	5	0
> 85%	5	1	1
< 85%	5	0	0

Table: Number of samples that reached certain qualities

Overall Time

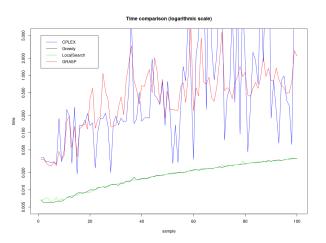


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CPLEX vs GRASP

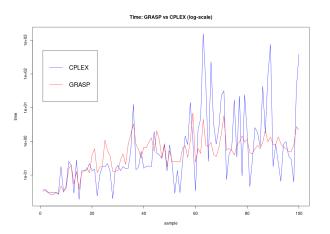


Figure: GRASP vs CPLEX

Greedy vs LS

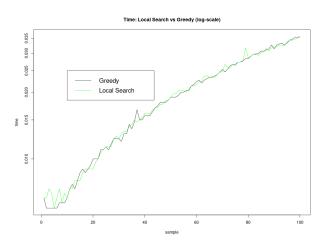


Figure: Greedy vs LS

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- Heuristics gave us very good solutions (most of the cases being > 95% optimal). Unfortunately, it is not guaranteed that they will find a solution when it exists.
- Future improvements to find more solutions, maintaining the quality of them, are very promising!.

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