This notebook will classify fruits from the fruit 360 dataset. The dataset can be found at https://www.kaggle.com/datasets/moltean/fruits.

This dataset originally contained 131 classes of fruits and vegetables but I selected 16 of them for this notebook.

It is important to note that the data was already split into train and test and had the same image size.

The model should be able to classify the fruits into the correct category.

Importing packages

```
import numpy as np
import os
import cv2
import tensorflow as tf
from tqdm import tqdm

from sklearn.metrics import confusion_matrix
import seaborn as sn; sn.set(font_scale=1.4)
from sklearn.utils import shuffle
import pandas as pd
```

Loading the data

```
In [ ]: #names of classes/folders in the file
   names = ['Apple Braeburn', 'Banana', 'Blueberry', 'Cherry', 'Grape White', 'Kiv
   #labels for each class/folder
   namesLabel = {names:i for i, names in enumerate(names)}
   #set size to (100,100)
   SIZE = (100, 100)

In [ ]: %capture
   #load data from drive
   from google.colab import drive
   drive.mount('/content/gdrive')
   !unzip gdrive/MyDrive/fruit.zip;
   #!cp '/content/drive/MyDrive/fruit 360 2.zip' <data>
```

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e Blue/. 146 100.jpg
```

In []: #confirm that the classes got labelled correctly
 namesLabel

```
{'Apple Braeburn': 0,
Out[]:
         'Banana': 1,
         'Blueberry': 2,
         'Cherry': 3,
         'Grape White': 4,
         'Kiwi': 5,
         'Lemon': 6,
         'Mango': 7,
         'Orange': 8,
         'Pear': 9,
         'Pineapple': 10,
         'Plum': 11,
         'Pomegranate': 12,
         'Strawberry': 13,
         'Tomato': 14,
         'Watermelon': 15}
In [ ]: # Define a function to load the data
        def load_data():
            train_dir = "/content/fruit 360/fruits-360_dataset/fruits-360/Train/"
            test dir = "/content/fruit 360/fruits-360_dataset/fruits-360/Test/"
            image_size = 64
            output = []
            # Iterate through training and test sets
             for data in [train_dir, test_dir]:
                 images = []
                imageLabels = []
                print("Loading {}".format(data))
                # Iterate through each folder corresponding to a category
                for folder in os.listdir(data):
                    Label = namesLabel[folder]
                     # Iterate through each image in our folder
                     for file in tqdm(os.listdir(os.path.join(data, folder))):
                         # Get the path name of the image
                         image path = os.path.join(os.path.join(data, folder), file)
                         # Open the img
                         image = cv2.imread(image path)
                         # Check if image is valid
                         if image is None or image.size == 0:
                             continue
                         # Resize and convert the img
                         image = cv2.resize(image, (image size, image size))
                         image = cv2.cvtColor(image, cv2.COLOR BGR2RGB) # convert BGR
                         # Append the image and its corresponding label to the output
                         images.append(image)
                         imageLabels.append(Label)
                # Convert images and imageLabels
```

```
images = np.array(images, dtype = 'float32')
imageLabels = np.array(imageLabels, dtype = 'int32')

output.append((images, imageLabels))

return output
```

This is an extra step that I had to perform becasue I was getting an error called DS_Store which means that there are hidden files that are not useful for python programs and can cause them to crash.

```
In [ ]:
        !find /content/fruit\ 360/fruits-360 dataset/fruits-360/Train -name .DS Store
        !find /content/fruit\ 360/fruits-360 dataset/fruits-360/Test -name .DS Store
        #Loading training and testing images and their corresponding labels.
In [ ]:
        (ImagesForTraining, ImageLabelsForTraining), (ImagesForTesting, ImageLabelsForT
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                          475/475 [00:00<00:00, 4152.39it/s]
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                          490/490 [00:00<00:00, 4224.32it/s]
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                          492/492 [00:00<00:00, 2491.38it/s]
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                          462/462 [00:00<00:00, 2817.68it/s]
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                          479/479 [00:00<00:00, 2774.64it/s]
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                         447/447 [00:00<00:00, 2845.59it/s]
                         492/492 [00:00<00:00, 2901.13it/s]
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In [ ]: #lets check the size of train and test
        numTrain = ImageLabelsForTraining.shape[0]
        numTest = ImageLabelsForTesting.shape[0]
        print ("There are {} training images".format(numTrain))
```

```
print ("There are {} testing images".format(numTest))
print ("The size of each image is: {}".format(SIZE))
```

There are 7979 training images
There are 2672 testing images
The size of each image is: (100, 100)

I also normalized the data since I read that it was good practice

```
In []: # Normalize the data
    ImagesForTraining = ImagesForTraining / 255.0
    ImagesForTesting = ImagesForTesting / 255.0

ImagesForTraining
    ImagesForTesting
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           , 1.
                        , 1.
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                                    ]],
 ...,
 [[0.9882353 , 1. , 0.99215686],
                   , 0.99607843],
 [1. , 1.
            , 0.99215686, 0.99215686],
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  [1.
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```

```
, 1.
                            , 1.
[[1.
                                          ],
              , 1.
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 . . . ,
 [1.
              , 1.
                            , 1.
                                          ],
               1.
                             1.
 [1.
                                          ],
 [1.
              , 1.
                            , 1.
                                          ]]]], dtype=float32)
```

Data visualization

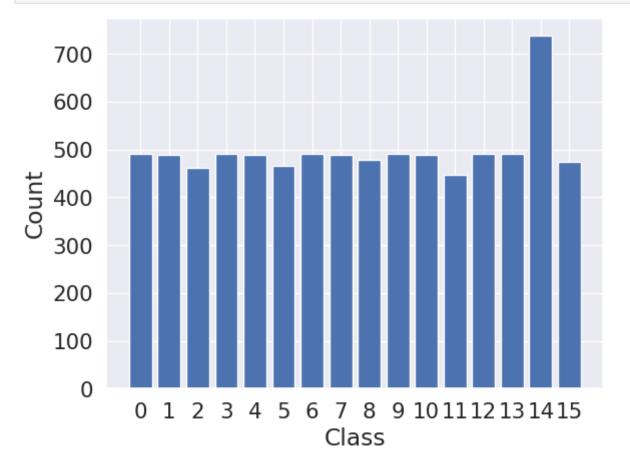
Next we create graphs showing the distribution of target classes. I had to do this twice because I felt that the first graph didn't give enough information. The second graph shows us that 15 of the fruits had a count between 450 and 500 however tomatoes had a significantly higher count of about 750.

```
In []: import matplotlib.pyplot as plt

# Count the number of images for each class in the training set
class_counts = np.bincount(ImageLabelsForTraining)

# Create a bar chart

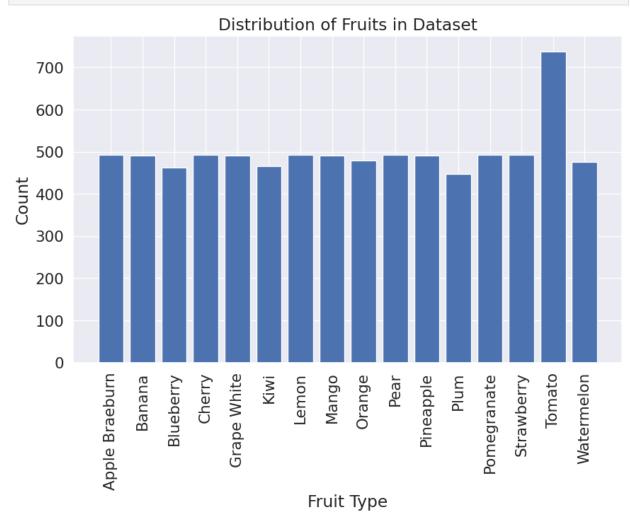
x = np.arange(len(class_counts))
plt.bar(x, class_counts)
plt.xticks(x)
plt.xticks(x)
plt.ylabel('Class')
plt.ylabel('Count')
plt.show()
```



```
In []: # Create a graph showing the distribution of the target classes
fig, ax = plt.subplots(figsize=(10, 6))
ax.bar(names, class_counts)
ax.set_xlabel("Fruit Type")
ax.set_ylabel("Count")
ax.set_title("Distribution of Fruits in Dataset")

# Rotate the x-axis labels vertically
plt.xticks(rotation='vertical')

plt.show()
```



Sequential model

I will now create a sequential model.

```
In []: num_classes=len(names)

model = tf.keras.models.Sequential([
    tf.keras.layers.Flatten(input_shape=(64, 64, 3)),
    tf.keras.layers.Dense(512, activation='relu'),
    tf.keras.layers.Dropout(0.2),
    tf.keras.layers.Dense(512, activation='relu'),
    tf.keras.layers.Dropout(0.2),
```

```
tf.keras.layers.Dense(num_classes, activation='softmax'),
])
```

In []: model.summary()

Model: "sequential"

Layer (type)	Output	Shape	Param #
flatten (Flatten)	(None,	12288)	0
dense (Dense)	(None,	512)	6291968
dropout (Dropout)	(None,	512)	0
dense_1 (Dense)	(None,	512)	262656
dropout_1 (Dropout)	(None,	512)	0
dense_2 (Dense)	(None,	16)	8208
			=======
Total params: 6,562,832 Trainable params: 6,562,832 Non-trainable params: 0			

```
Epoch 1/20
63/63 [============= ] - 6s 16ms/step - loss: 3.5711 - accurac
y: 0.3819 - val_loss: 0.9658 - val_accuracy: 0.6680
Epoch 2/20
63/63 [============= ] - 1s 10ms/step - loss: 0.8544 - accurac
y: 0.7011 - val_loss: 0.8006 - val_accuracy: 0.7231
Epoch 3/20
63/63 [===============] - 1s 11ms/step - loss: 0.5580 - accurac
y: 0.8175 - val_loss: 1.6763 - val_accuracy: 0.5902
Epoch 4/20
63/63 [============= ] - 1s 14ms/step - loss: 0.4623 - accurac
y: 0.8695 - val_loss: 0.1984 - val_accuracy: 0.9184
Epoch 5/20
63/63 [============== ] - 1s 12ms/step - loss: 0.3437 - accurac
y: 0.9110 - val loss: 0.8611 - val accuracy: 0.8192
Epoch 6/20
63/63 [============== ] - 1s 12ms/step - loss: 0.3098 - accurac
y: 0.9183 - val_loss: 0.0827 - val_accuracy: 0.9671
Epoch 7/20
63/63 [============== ] - 1s 13ms/step - loss: 0.2843 - accurac
y: 0.9301 - val_loss: 0.1452 - val_accuracy: 0.9547
63/63 [===============] - 1s 12ms/step - loss: 0.2460 - accurac
y: 0.9408 - val_loss: 0.1219 - val_accuracy: 0.9701
Epoch 9/20
63/63 [===============] - 1s 11ms/step - loss: 0.2102 - accurac
y: 0.9515 - val_loss: 0.2877 - val_accuracy: 0.9334
Epoch 10/20
63/63 [=============== ] - 1s 9ms/step - loss: 0.1816 - accurac
y: 0.9581 - val loss: 0.1206 - val accuracy: 0.9607
Epoch 11/20
63/63 [============] - 1s 10ms/step - loss: 0.1665 - accurac
y: 0.9611 - val loss: 0.4632 - val accuracy: 0.8930
Epoch 12/20
63/63 [============] - 1s 10ms/step - loss: 0.1688 - accurac
y: 0.9560 - val loss: 0.1496 - val accuracy: 0.9644
Epoch 13/20
63/63 [============= ] - 1s 10ms/step - loss: 0.1333 - accurac
y: 0.9665 - val loss: 0.0959 - val accuracy: 0.9783
Epoch 14/20
63/63 [============== ] - 1s 10ms/step - loss: 0.1715 - accurac
y: 0.9593 - val loss: 0.2463 - val accuracy: 0.9281
Epoch 15/20
63/63 [=============] - 1s 15ms/step - loss: 0.0842 - accurac
y: 0.9784 - val_loss: 0.1389 - val_accuracy: 0.9476
Epoch 16/20
63/63 [============] - 1s 10ms/step - loss: 0.0834 - accurac
y: 0.9756 - val_loss: 0.2033 - val_accuracy: 0.9558
Epoch 17/20
63/63 [============ ] - 1s 9ms/step - loss: 0.1209 - accurac
y: 0.9708 - val loss: 0.2448 - val accuracy: 0.9506
Epoch 18/20
63/63 [============= ] - 1s 10ms/step - loss: 0.0499 - accurac
y: 0.9848 - val loss: 0.1525 - val accuracy: 0.9506
Epoch 19/20
63/63 [=============] - 1s 10ms/step - loss: 0.0850 - accurac
y: 0.9782 - val loss: 0.3193 - val accuracy: 0.9311
Epoch 20/20
63/63 [============== ] - 1s 10ms/step - loss: 0.0818 - accurac
y: 0.9799 - val loss: 0.1240 - val accuracy: 0.9648
```

```
In []: history.history.keys()
Out[]: dict_keys(['loss', 'accuracy', 'val_loss', 'val_accuracy'])
In []: import matplotlib.pyplot as plt

# Plot training & validation accuracy values
plt.plot(history.history['val_accuracy'])
plt.plot(history.history['accuracy'])
plt.title('Model accuracy')
plt.ylabel('Accuracy')
plt.ylabel('Epoch')
plt.legend(['Train', 'Test'], loc='upper left')
plt.show()
```



```
In []: score = model.evaluate(ImagesForTesting, y_test, verbose=0)
    print('Test loss:', score[0])
    print('Test accuracy:', score[1])

Test loss: 0.12395673990249634
    Test accuracy: 0.964820384979248
```

CNN

```
In []: batch_size = 128
num_classes = 16
epochs = 20
```

```
In [ ]:
        #Loading training and testing images and their corresponding labels.
         (ImagesForTraining, ImageLabelsForTraining), (ImagesForTesting, ImageLabelsForT
        Loading /content/fruit 360/fruits-360 dataset/fruits-360/Train/
                          492/492 [00:00<00:00, 2723.33it/s]
        100%
        100%
                          475/475 [00:00<00:00, 2758.61it/s]
        100%
                          466/466 [00:00<00:00, 2587.19it/s]
                          490/490 [00:00<00:00, 2765.42it/s]
        100%
                          492/492 [00:00<00:00, 2828.66it/s]
        100%
        100%
                          492/492 [00:00<00:00, 3013.37it/s]
                          492/492 [00:00<00:00, 2748.89it/s]
        100%
                          462/462 [00:00<00:00, 3103.15it/s]
        100%
        100%
                          479/479 [00:00<00:00, 2639.95it/s]
        100%
                          738/738 [00:00<00:00, 2931.69it/s]
                          447/447 [00:00<00:00, 2819.33it/s]
        100%
                          492/492 [00:00<00:00, 1859.28it/s]
        100%
        100%
                          490/490 [00:00<00:00, 1458.71it/s]
                          490/490 [00:00<00:00, 1972.48it/s]
        100%
        100%
                          490/490 [00:00<00:00, 2636.56it/s]
                          492/492 [00:00<00:00, 4516.08it/s]
        100%
        Loading /content/fruit 360/fruits-360_dataset/fruits-360/Test/
                          164/164 [00:00<00:00, 4297.68it/s]
        100%
        100%
                          157/157 [00:00<00:00, 4284.13it/s]
        100%
                          156/156 [00:00<00:00, 4692.96it/s]
                          166/166 [00:00<00:00, 5084.30it/s]
        100%
        100%
                          164/164 [00:00<00:00, 4672.02it/s]
                          165/165 [00:00<00:00, 4946.75it/s]
        100%
        100%
                          164/164 [00:00<00:00, 3520.31it/s]
                          154/154 [00:00<00:00, 1205.81it/s]
        100%
        100%
                          160/160 [00:00<00:00, 873.57it/s]
                          246/246 [00:00<00:00, 1316.27it/s]
        100%
                          151/151 [00:00<00:00, 4586.53it/s]
        100%
                          164/164 [00:00<00:00, 5185.18it/s]
        100%
        100%
                          166/166 [00:00<00:00, 4448.68it/s]
                          166/166 [00:00<00:00, 5124.15it/s]
        100%
                          166/166 [00:00<00:00, 5827.27it/s]
        100%
                          164/164 [00:00<00:00, 4327.72it/s]
        100%
In [ ]:
       model = tf.keras.models.Sequential(
                tf.keras.Input(shape=(64, 64, 3)),
                tf.keras.layers.Conv2D(32, kernel size=(3, 3), activation="relu"),
                tf.keras.layers.MaxPooling2D(pool size=(2, 2)),
                tf.keras.layers.Conv2D(64, kernel size=(3, 3), activation="relu"),
                tf.keras.layers.MaxPooling2D(pool size=(2, 2)),
                tf.keras.layers.Flatten(),
                tf.keras.layers.Dropout(0.5),
                tf.keras.layers.Dense(16, activation="softmax"),
            ]
In [ ]:
        model.summary()
```

Model: "sequential 1"

```
Layer (type)
                                    Output Shape
                                                             Param #
        _____
                                 ______
                                    (None, 62, 62, 32)
                                                              896
         conv2d (Conv2D)
         max pooling2d (MaxPooling2D (None, 31, 31, 32)
                                    (None, 29, 29, 64)
         conv2d_1 (Conv2D)
                                                             18496
         max pooling2d 1 (MaxPooling (None, 14, 14, 64)
         2D)
         flatten 1 (Flatten)
                                    (None, 12544)
         dropout 2 (Dropout)
                                    (None, 12544)
         dense_3 (Dense)
                                                              200720
                                    (None, 16)
        Total params: 220,112
        Trainable params: 220,112
        Non-trainable params: 0
In [ ]: model.compile(loss = 'sparse_categorical_crossentropy', optimizer = 'adam', met
In []:
        history = model.fit(
            ImagesForTraining, ImageLabelsForTraining,
            batch size=128,
            epochs=20,
            verbose=1,
            validation data=(ImagesForTesting, ImageLabelsForTesting)
```

```
Epoch 1/20
63/63 [============= ] - 7s 25ms/step - loss: 14.4420 - accura
cy: 0.6561 - val_loss: 0.2019 - val_accuracy: 0.9315
Epoch 2/20
63/63 [============= ] - 1s 17ms/step - loss: 0.0502 - accurac
y: 0.9840 - val_loss: 0.0309 - val_accuracy: 0.9921
Epoch 3/20
63/63 [============== ] - 1s 16ms/step - loss: 0.0256 - accurac
y: 0.9922 - val_loss: 0.0359 - val_accuracy: 0.9888
Epoch 4/20
63/63 [============== ] - 1s 20ms/step - loss: 0.0072 - accurac
y: 0.9979 - val_loss: 0.0195 - val_accuracy: 0.9925
Epoch 5/20
63/63 [============== ] - 1s 17ms/step - loss: 0.0214 - accurac
y: 0.9935 - val loss: 0.0204 - val accuracy: 0.9921
Epoch 6/20
63/63 [============= ] - 1s 15ms/step - loss: 0.0124 - accurac
y: 0.9960 - val_loss: 0.0222 - val_accuracy: 0.9925
Epoch 7/20
63/63 [============== ] - 1s 15ms/step - loss: 0.0126 - accurac
y: 0.9961 - val_loss: 0.0083 - val_accuracy: 0.9970
63/63 [===============] - 1s 15ms/step - loss: 0.0081 - accurac
y: 0.9981 - val_loss: 0.0207 - val_accuracy: 0.9944
Epoch 9/20
63/63 [===============] - 1s 16ms/step - loss: 0.0111 - accurac
y: 0.9964 - val_loss: 0.2288 - val_accuracy: 0.9719
Epoch 10/20
63/63 [============] - 1s 16ms/step - loss: 0.0030 - accurac
y: 0.9990 - val loss: 0.0109 - val accuracy: 0.9944
Epoch 11/20
63/63 [============] - 1s 16ms/step - loss: 0.0035 - accurac
y: 0.9992 - val loss: 0.0087 - val accuracy: 0.9963
Epoch 12/20
63/63 [===========] - 1s 15ms/step - loss: 0.0014 - accurac
y: 0.9994 - val loss: 0.0153 - val accuracy: 0.9959
Epoch 13/20
63/63 [============= ] - 1s 16ms/step - loss: 0.0017 - accurac
y: 0.9996 - val loss: 0.0120 - val accuracy: 0.9955
Epoch 14/20
63/63 [============== ] - 1s 15ms/step - loss: 0.0051 - accurac
y: 0.9981 - val loss: 0.0204 - val accuracy: 0.9933
Epoch 15/20
63/63 [=============] - 1s 16ms/step - loss: 0.0238 - accurac
y: 0.9934 - val_loss: 0.1523 - val_accuracy: 0.9611
63/63 [============] - 1s 17ms/step - loss: 0.0356 - accurac
y: 0.9891 - val_loss: 0.2192 - val_accuracy: 0.9734
Epoch 17/20
63/63 [============] - 1s 18ms/step - loss: 0.0698 - accurac
y: 0.9837 - val loss: 0.1992 - val accuracy: 0.9798
Epoch 18/20
63/63 [============ ] - 1s 17ms/step - loss: 0.0203 - accurac
y: 0.9944 - val loss: 0.0229 - val accuracy: 0.9906
Epoch 19/20
63/63 [=============] - 1s 16ms/step - loss: 0.0198 - accurac
y: 0.9960 - val loss: 0.0812 - val accuracy: 0.9805
Epoch 20/20
63/63 [============== ] - 1s 15ms/step - loss: 0.0302 - accurac
y: 0.9947 - val loss: 0.2466 - val accuracy: 0.9749
```

```
In []: history.history.keys()
Out[]: dict_keys(['loss', 'accuracy', 'val_loss', 'val_accuracy'])
In []: import matplotlib.pyplot as plt

# Plot training & validation accuracy values
plt.plot(history.history['val_accuracy'])
plt.plot(history.history['accuracy'])
plt.title('Model accuracy')
plt.ylabel('Accuracy')
plt.ylabel('Accuracy')
plt.xlabel('Epoch')
plt.legend(['Train', 'Test'], loc='upper left')
plt.show()
```

1.00 Train 0.95 Test 0.90 0.85 0.80 0.75

Model accuracy

10

Epoch

15

```
In []: score = model.evaluate(ImagesForTesting, ImageLabelsForTesting, verbose=0)
    print('Test loss:', score[0])
    print('Test accuracy:', score[1])

Test loss: 0.24655233323574066
Test accuracy: 0.97492516040802
```

5

Performance analysis of different approaches

In this project, I classified different types of fruits. As mentioned previously in the notebook the dataset originally contained 131 classes but i narrowed this down to 16. I used

0.70

0.65

0

TensorFlow and Keras to perform deep learning. I used a sequential model and CNN. 99%

The sequential model had a few layers. The input shape was 64 by 64 by 3(the 3 refers to 3 color channels) and the dense layers had 512 nodes each. The outer layer has a softmax activation function. The hidden layers have a relu activation function. It also uses the categorical_crossentropy loss function to compile the model.

The Convolutional Neural Network also uses the same input layer of 64x64x3 and the 3 refers to the 3 color channels. The first convolutional layer has 32 filters and uses the relu activation function. It extracts 32 different 3x3 features from the input image. The first max pooling layer reduces the spatial dimensions of the output from the convolutional layer by taking the maximum value within a 2x2 window. The second convolutional layer has 64 filters. The second max pooling layer further reduces the spatial dimensions. The flatten layer flattens the output from the second max pooling layer into a 1D vector, which is then passed to a fully connected layer.

The two neural networks had different accuracies. The first model had an accuracy of 96% and the second had an accuracy of 98%. I consider these accuracies to be quite high.

There are several reasons why CNNs can perform better than sequential models. CNNs are designed to take into account the spatial structure of input data. Also, it is able to detect local features like edges and textures. They are also able to detect pattens in an image regardless of position. They are also able to learn a small number of parameters and apply them across the entire image. This is called parameter sharing and reduces the risk of overfitting.