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Snake-Like Robots for Minimally Invasive Spine Surgery

Project: Snake-Like Robots for Minimally Invasive Spine Surgery

Date:

Student Engineer:

Student ID:

Supervisor:

Version	Date	Author	Changes/Comments

General Objective

Key Finding from the Literature

Resource	Purpose	Access

Project Methodology

Deliverables

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Risks, Requirements & Constraints

Regulatory, safety and ethical concerns to consider:

Risks, likelihood, consequence, risk monitoring and mitigation:

Quality & Sustainability

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Timeline & Deliverables

No.	Focus	Deliverable	Dependency	Release Date/ Milestone

Management of Project Changes

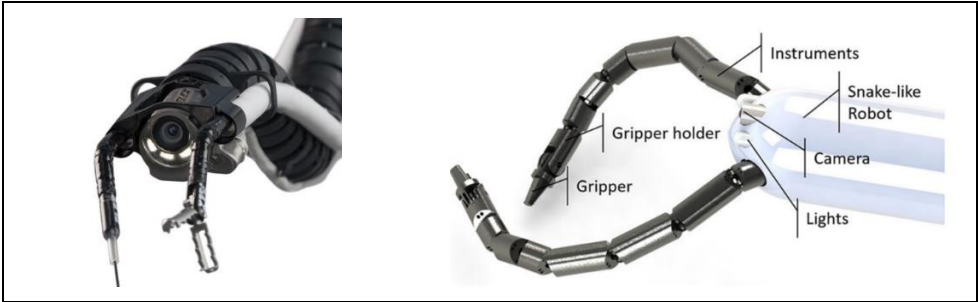
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Sign off

	SIGNATURE	DATE
STUDENT ENGINEER		

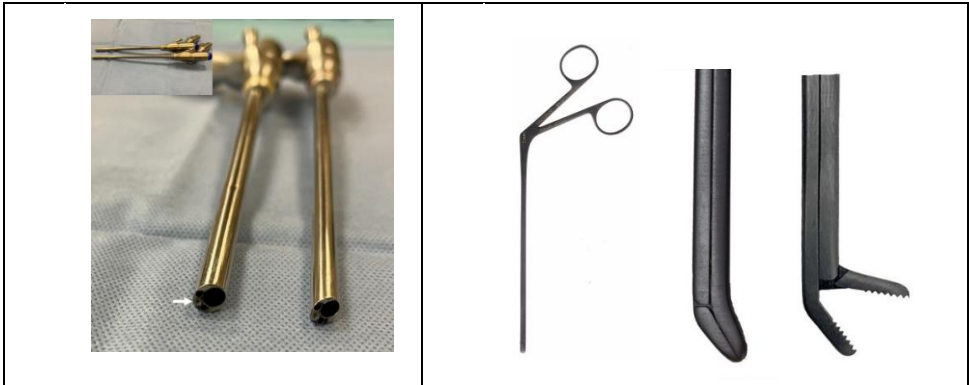
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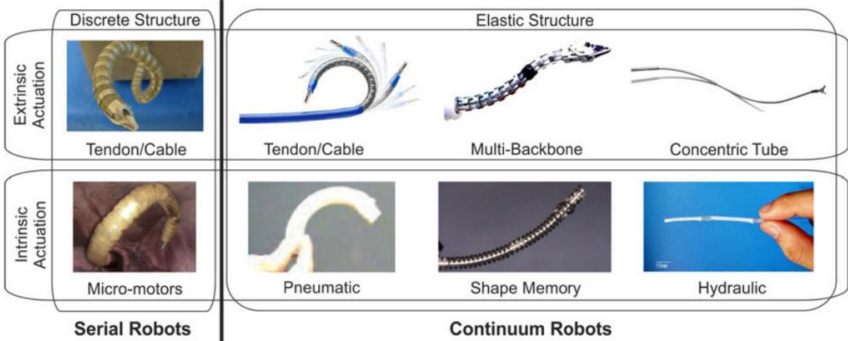


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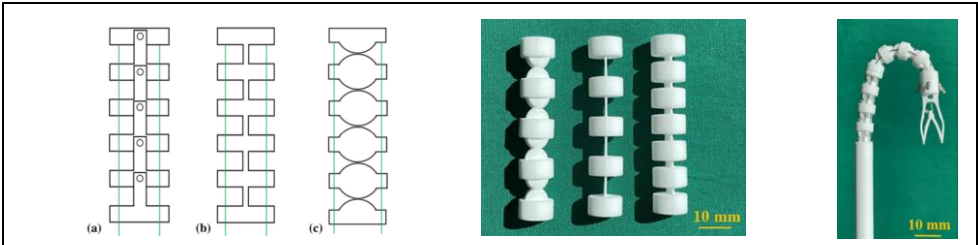
Macro Surgical Robot Platforms & Macro-Micro Teleoperation

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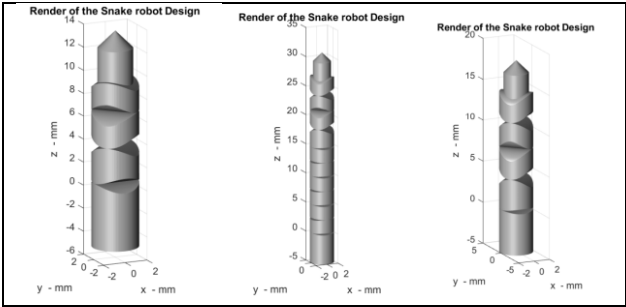
Defining the surgical site

Design Metrics: Measurement of reachable workspace and dexterity.

Design and Optimisation approaches.



Modelling and Fabrication



References