

$$\boxed{3.} \quad y' = \underbrace{\begin{pmatrix} 1 & 3 \\ 3 & 1 \end{pmatrix}}_A y, \quad y(0) = \begin{pmatrix} 5 \\ 1 \end{pmatrix} \quad (*)$$

TEORÍA

$$y(x) = e^{Ax} \cdot \begin{pmatrix} c_1 \\ c_2 \end{pmatrix}$$

$$e^A = I + A + \frac{A^2}{2} + \frac{A^3}{3!} + \dots$$

$$\Rightarrow e^A = \underbrace{P e^D P^{-1}}_{\substack{\text{matriz fun-} \\ \text{damental}}} = P \begin{pmatrix} e^{\lambda_1} & 0 \\ 0 & e^{\lambda_n} \end{pmatrix} P^{-1}$$

↳ también es matriz fundamental

• Si A es diagonalizable: $A = P D P^{-1}$
con $D = \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_n \end{pmatrix}$

• Si A no es diagonalizable:
 $A = P J P^{-1}$ con $J = D + N$
↑
nilpotente

La MATRIZ FUNDAMENTAL: matriz cuyas columnas son soluciones de (*)

La matriz fundamental tal que $\Phi(0) = \text{Id}$ es $\boxed{\Phi(x) = e^{Ax}}$

Si B es una matriz con $\det B \neq 0$, y Φ es matriz fundamental $\Rightarrow \Phi \cdot B$ es matriz fundamental.

$$\begin{vmatrix} 1-\lambda & 3 \\ 3 & 1-\lambda \end{vmatrix} = 0 \Leftrightarrow (1-\lambda)^2 - 9 = 0 \Leftrightarrow 1-\lambda = \pm 3 \Leftrightarrow \lambda = \pm 3 + 1$$

$$\Rightarrow \begin{cases} \lambda_1 = 4 \\ \lambda_2 = -2 \end{cases}$$

Autovectores $v \in \text{Ker}(A - 4I)$

$$\boxed{\lambda=4} \quad \underbrace{(A - 4I)v = 0}_{\text{Autovectores}} \Leftrightarrow \begin{pmatrix} -3 & 3 \\ 3 & -3 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Leftrightarrow -3v_1 + 3v_2 = 0$$

$$\Leftrightarrow v_1 = v_2$$

$$\Rightarrow v = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$w \in \text{Ker}(A + 2I)$

$$\boxed{\lambda=-2} \quad \underbrace{(A + 2I)w = 0}_{\text{Autovectores}} \Leftrightarrow \begin{pmatrix} 3 & 3 \\ 3 & 3 \end{pmatrix} \begin{pmatrix} w_1 \\ w_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Leftrightarrow 3w_1 + 3w_2 = 0$$

$$\Leftrightarrow w_1 = -w_2$$

$$\Rightarrow w = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$P = \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}; \quad e^{Dx} = \begin{pmatrix} e^{4x} & 0 \\ 0 & e^{-2x} \end{pmatrix}$$

$$y = P e^{Dx} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = \begin{pmatrix} e^{4x} & e^{-2x} \\ e^{4x} & -e^{-2x} \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix}$$

$$y(0) = \begin{pmatrix} 3 \\ 1 \end{pmatrix} \Leftrightarrow \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = \begin{pmatrix} 3 \\ 1 \end{pmatrix} \Rightarrow \begin{cases} c_1 = 2 \\ c_2 = 2 \end{cases}$$

$$\Rightarrow Y(x) = \begin{pmatrix} e^{4x} & e^{-2x} \\ e^{-2x} & -e^{-2x} \end{pmatrix} \begin{pmatrix} 3 \\ 2 \end{pmatrix} = \begin{pmatrix} 3e^{4x} + 2e^{-2x} \\ 3e^{4x} - 2e^{-2x} \end{pmatrix}$$

4. Hallar una matriz fundamental tal que $\Phi(0) = Id$ para
 $X' = \begin{pmatrix} 3 & -4 \\ 1 & -1 \end{pmatrix} X$

$$\downarrow \\ e^{AX} = P e^{JX} P^{-1}$$

Autovalores:

$$\begin{vmatrix} 3-\lambda & -4 \\ 1 & -1-\lambda \end{vmatrix} = 0 \Leftrightarrow (3-\lambda)(-1-\lambda) + 4 = -3 - 3\lambda + \lambda + \lambda^2 + 4 = \lambda^2 - 2\lambda + 1 = 0 \Leftrightarrow (\lambda - 1)^2 = 0 \Leftrightarrow \lambda = 1 \text{ (doble)}$$

Autovectores:

$$(A - I)v = 0 \Leftrightarrow \begin{pmatrix} 2 & -4 \\ 1 & -2 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Leftrightarrow 2v_1 - 4v_2 = 0 \Leftrightarrow v_1 = 2v_2$$

$$\Rightarrow v = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$$

Ahora busquemos $w \in \text{Ker}(A - I)^2 \setminus \underbrace{\text{Ker}(A - I)}_{\text{anteriores potencias}}$

e.d., busco w : $(A - I)w = \underbrace{v}_{\text{anterior}}$

$$\begin{pmatrix} 2 & -4 \\ 1 & -2 \end{pmatrix} \begin{pmatrix} w_1 \\ w_2 \end{pmatrix} = \begin{pmatrix} 2 \\ 1 \end{pmatrix} \Rightarrow w_1 - 2w_2 = 1 \Rightarrow w = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$P = \begin{pmatrix} 2 & 1 \\ 1 & 0 \end{pmatrix} \quad J = \underbrace{\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}}_D + \underbrace{\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}}_N$$

$$e^{Jt} = e^{Dt} \cdot e^{Nt}$$

$$e^{Nt} = I + Nt + \frac{N^2 t^2}{2!} + \dots = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} + \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} t = \begin{pmatrix} 1 & t \\ 0 & 1 \end{pmatrix}$$

$$\Rightarrow e^{Jt} = \begin{pmatrix} e^t & 0 \\ 0 & e^t \end{pmatrix} \begin{pmatrix} 1 & t \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} e^t & te^t \\ 0 & e^t \end{pmatrix}$$

dos opciones \rightarrow calcular P^{-1} y multiplicar: $P e^{Jt} P^{-1}$
 $\rightarrow \Phi(0) \cdot \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$

[7.] Encontrar una matriz fundamental para $X' = \begin{pmatrix} 3 & 2 & 1 \\ -1 & 0 & -1 \\ 1 & 1 & 2 \end{pmatrix} X$

$$\begin{vmatrix} 3-\lambda & 2 & 1 \\ -1 & -\lambda & -1 \\ 1 & 1 & 2-\lambda \end{vmatrix} = 0 \Leftrightarrow \begin{cases} \lambda = 2 \text{ (doble)} \\ \lambda = 1 \text{ (simple)} \end{cases}$$

Autovalores & autovectores

$$\boxed{\lambda=2} \quad (A-2I)V = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \Leftrightarrow \begin{pmatrix} 1 & 2 & 1 \\ -1 & -2 & -1 \\ 1 & 1 & 0 \end{pmatrix} \begin{pmatrix} V_1 \\ V_2 \\ V_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \Leftrightarrow \begin{cases} V_1 + 2V_2 + V_3 = 0 \\ V_1 + V_2 = 0 \end{cases} \Leftrightarrow$$

$$\Leftrightarrow \begin{cases} V_3 + V_2 = 0 \\ V_1 = -V_2 \end{cases} \Rightarrow V = \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}$$

Busco $w : (A-2I)w = V \Leftrightarrow \begin{pmatrix} 1 & 2 & 1 \\ -1 & -2 & -1 \\ 1 & 1 & 0 \end{pmatrix} \begin{pmatrix} w_1 \\ w_2 \\ w_3 \end{pmatrix} = \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix} \Leftrightarrow \begin{cases} w_2 = -w_3 \\ w_1 = 1 - w_2 \end{cases}$

$$\Rightarrow w = \begin{pmatrix} 2 \\ -1 \\ 1 \end{pmatrix}$$

$$\boxed{\lambda=1} \quad \begin{pmatrix} 2 & 2 & 1 \\ -1 & -1 & -1 \\ 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \\ u_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \Leftrightarrow \begin{cases} u_3 = 0 \\ u_1 = -u_2 \end{cases} \Leftrightarrow u = \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix}$$

$$\Rightarrow e^{Jt} = e^{Dt} \cdot e^{Nt} = \begin{pmatrix} e^t & 0 & 0 \\ 0 & e^{2t} & 0 \\ 0 & 0 & e^{2t} \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & t \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} e^t & 0 & 0 \\ 0 & e^{2t} & te^{2t} \\ 0 & 0 & e^{2t} \end{pmatrix}$$

$$N = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}$$

$$P = \begin{pmatrix} u & v & w \\ 1 & 1 & 2 \\ -1 & -1 & -1 \\ 0 & 1 & 1 \end{pmatrix}$$

$$\Rightarrow \phi = P e^{Jt}$$

2.1 Hallar la solución general de $y' = \begin{pmatrix} 1 & 2 \\ 3 & 2 \end{pmatrix} y + \begin{pmatrix} x-1 \\ -5x-2 \end{pmatrix}$

homogénea: $y' = \begin{pmatrix} 1 & 2 \\ 3 & 2 \end{pmatrix} y$

$$\begin{vmatrix} 1-\lambda & 2 \\ 3 & 2-\lambda \end{vmatrix} = (1-\lambda)(2-\lambda) - 6 = 2 - 2\lambda + \lambda^2 - \lambda - 6 = \lambda^2 - 3\lambda - 4 \Rightarrow \lambda = \frac{3 \pm \sqrt{9+16}}{2}$$

$$\Rightarrow \lambda_1 = 4, \lambda_2 = -1 \Rightarrow D = \begin{pmatrix} e^{4x} & 0 \\ 0 & e^{-x} \end{pmatrix}$$

Autovector para $\lambda = 4$

$$\begin{pmatrix} -3 & 2 \\ 3 & -2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow -3x + 2y = 0 \quad \text{autovector} \rightarrow \begin{pmatrix} 2 \\ 3 \end{pmatrix}$$

Autovector para $\lambda = -1$

$$\begin{pmatrix} 2 & 2 \\ 3 & 3 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow x + y = 0 \quad \text{autovector} \rightarrow \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

$$P = \begin{pmatrix} 2 & -1 \\ 3 & 1 \end{pmatrix}$$

Solución homogénea: $\underline{y}_h = \begin{pmatrix} 2 & -1 \\ 3 & 1 \end{pmatrix} \begin{pmatrix} e^{4x} & 0 \\ 0 & e^{-x} \end{pmatrix} \begin{pmatrix} C_1 \\ C_2 \end{pmatrix} = \begin{pmatrix} 2e^{4x} & -e^{-x} \\ 3e^{4x} & e^{-x} \end{pmatrix} \begin{pmatrix} C_1 \\ C_2 \end{pmatrix} =$

$$= \underline{C_1 e^{4x} \begin{pmatrix} 2 \\ 3 \end{pmatrix} + C_2 e^{-x} \begin{pmatrix} -1 \\ 1 \end{pmatrix}}$$

↙ expresiones de la solución válidas

$y = y_h + y_p \rightarrow$ busquemos y_p :

• Coeficientes indeterminados: $y' - AY = \begin{pmatrix} x-1 \\ -5x-2 \end{pmatrix} \quad y = \begin{pmatrix} ax+b \\ cx+d \end{pmatrix}$

$$\begin{pmatrix} a \\ c \end{pmatrix} = \begin{pmatrix} 1 & 2 \\ 3 & 2 \end{pmatrix} \begin{pmatrix} ax+b \\ cx+d \end{pmatrix} + \begin{pmatrix} x-1 \\ -5x-2 \end{pmatrix} \Rightarrow$$

$$\Rightarrow \begin{cases} 0x+a = ax+b+2(cx+d)+x-1 \\ 0x+c = 3(ax+b)+2(cx+d)-5x-2 \end{cases}$$

$$\Rightarrow \begin{cases} 0 = a+2c+1 \\ 0 = 3a+2c-5 \\ a = b+2d-1 \\ c = 3b+2d-2 \end{cases} \begin{cases} 3 = b+2d-1 \\ -2 = 3b+2d-2 \end{cases}$$

$$\Rightarrow -2a+6=0 \Rightarrow a=3 \Rightarrow c=-2$$

$$\Rightarrow 5 = -2b+1 \Rightarrow b=-2 \Rightarrow d=3$$

$$\Rightarrow \text{Sol. part.} = \begin{pmatrix} 3x-2 \\ -2x+3 \end{pmatrix} = \underline{y_p}$$

$$\boxed{y = y_h + y_p}$$

$$11. \quad X' = \begin{pmatrix} 2 & -5 \\ 1 & -2 \end{pmatrix} X + \begin{pmatrix} \csc t \\ \sec t \end{pmatrix} \quad (ED)$$

$$X_h :=> X' = \begin{pmatrix} 2 & -5 \\ 1 & -2 \end{pmatrix} X$$

$$\begin{pmatrix} 2-\lambda & -5 \\ 1 & -2-\lambda \end{pmatrix} = (2-\lambda)(-2-\lambda)+5 = -4-2\lambda+2\lambda+\lambda^2+5 = \lambda^2+1 \Rightarrow \lambda = \pm i$$

Autovector para $\lambda = i$

$$\begin{pmatrix} 2-i & -5 \\ 1 & -2-i \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow \begin{cases} (2-i)x_1 - 5x_2 = 0 \\ x_1 - (2+i)x_2 = 0 \end{cases} \Rightarrow (2-i)x_1 - (2+i)(2-i)x_2 = 0$$

$$\Rightarrow (2-i)x_1 - 5x_2 \Rightarrow \begin{pmatrix} 5 \\ 2-i \end{pmatrix} = u$$

Autovector para $\lambda = -i$

$$\begin{pmatrix} 2+i & -5 \\ 1 & -2+i \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow \begin{cases} (2+i)x_1 - 5x_2 = 0 \\ x_1 - (2-i)x_2 = 0 \end{cases} \Rightarrow \begin{pmatrix} 5 \\ 2+i \end{pmatrix} = v$$

$$X_h = \underbrace{C_1 e^{it} \begin{pmatrix} 5 \\ 2-i \end{pmatrix}}_{X_{h1}} + \underbrace{C_2 e^{-it} \begin{pmatrix} 5 \\ 2+i \end{pmatrix}}_{X_{h2}}$$

$$\Rightarrow Z_1 = \frac{X_{h1} + X_{h2}}{2} = \frac{e^{it} \begin{pmatrix} 5 \\ 2-i \end{pmatrix} + e^{-it} \begin{pmatrix} 5 \\ 2+i \end{pmatrix}}{2} = \begin{pmatrix} 5 \frac{e^{it} + e^{-it}}{2} \\ 2 \left(\frac{e^{it} - e^{-it}}{2} \right) - \frac{i(e^{it} - e^{-it})(-i)}{2(-i)} \end{pmatrix}$$

$$= \begin{pmatrix} 5 \cos t \\ 2 \cos t + \sin t \end{pmatrix}$$

$$\Rightarrow Z_2 = \frac{X_{h1} - X_{h2}}{2i} = \frac{e^{it} \begin{pmatrix} 5 \\ 2-i \end{pmatrix} - e^{-it} \begin{pmatrix} 5 \\ 2+i \end{pmatrix}}{2i} = \begin{pmatrix} 5 \frac{e^{it} - e^{-it}}{2i} \\ 2 \frac{e^{it} - e^{-it}}{2i} - \cancel{i} \frac{(e^{it} + e^{-it})}{2i} \end{pmatrix} =$$

$$= \begin{pmatrix} 5 \sin t \\ 2 \sin t - \cos t \end{pmatrix}$$

$$\Rightarrow X_h = \begin{pmatrix} 5 \cos t & 5 \sin t \\ 2 \cos t + \sin t & 2 \sin t - \cos t \end{pmatrix} \begin{pmatrix} C_1 \\ C_2 \end{pmatrix}$$

Buscamos $X_p(t)$ que cumpla $X' = Ax + \begin{pmatrix} \operatorname{cosec} t \\ \operatorname{sect} \end{pmatrix}$

$$X_p(t) = \phi \begin{pmatrix} c_1(t) \\ c_2(t) \end{pmatrix}, \text{ donde } \phi \text{ verifica } \boxed{\phi' = A\phi}$$

$$X_p'(t) \stackrel{\text{R.C.}}{=} \phi'(t) \begin{pmatrix} c_1(t) \\ c_2(t) \end{pmatrix} + \phi \begin{pmatrix} c_1'(t) \\ c_2'(t) \end{pmatrix} = \underbrace{A\phi}_{X_p(t)} \begin{pmatrix} c_1(t) \\ c_2(t) \end{pmatrix} + \phi \begin{pmatrix} c_1'(t) \\ c_2'(t) \end{pmatrix}$$

Por tanto, $X_p(t)$ verifica (ED) si y sdo si

$$\phi \begin{pmatrix} c_1'(t) \\ c_2'(t) \end{pmatrix} = \begin{pmatrix} \frac{1}{\operatorname{sect} t} \\ \frac{1}{\operatorname{cost} t} \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} 5\operatorname{cost} & 5\operatorname{sent} \\ 2\operatorname{cost} + \operatorname{sent} & 2\operatorname{sent} - \operatorname{cost} \end{pmatrix} \begin{pmatrix} c_1'(t) \\ c_2'(t) \end{pmatrix} = \begin{pmatrix} \frac{1}{\operatorname{sect} t} \\ \frac{1}{\operatorname{cost} t} \end{pmatrix}$$

$$W = \begin{vmatrix} \textcircled{*} \end{vmatrix} = -5$$

$$\Rightarrow c_1'(t) = \frac{\begin{vmatrix} \frac{1}{\operatorname{sect} t} & 5\operatorname{sent} \\ \frac{1}{\operatorname{cost} t} & 2\operatorname{sent} - \operatorname{cost} \end{vmatrix}}{W} = \frac{2 - \frac{\operatorname{cost} t}{\operatorname{sect} t} - 5 \frac{\operatorname{sent} t}{\operatorname{cost} t}}{-5}$$

$$\Rightarrow c_1(t) = -\frac{2}{5}t + \frac{1}{5} \log|\operatorname{sent} t| - \log|\operatorname{cost} t|$$

$$\Rightarrow c_2'(t) = \frac{\begin{vmatrix} 5\operatorname{cost} & \frac{1}{\operatorname{sect} t} \\ 2\operatorname{cost} + \operatorname{sent} & \frac{1}{\operatorname{cost} t} \end{vmatrix}}{W} = \frac{-1}{5} \left(5 - \frac{2\operatorname{cost} t}{\operatorname{sent} t} - 1 \right) = \frac{-4}{5} \cdot \frac{-2}{5} \frac{\operatorname{cost} t}{\operatorname{sent} t}$$

$$\Rightarrow c_2(t) = -\frac{4}{5}t - \frac{2}{5} \log|\operatorname{sent} t|$$

$$\Rightarrow \boxed{X = X_h + X_p = \phi \left[\begin{pmatrix} c_1 \\ c_2 \end{pmatrix} + \begin{pmatrix} c_1(t) \\ c_2(t) \end{pmatrix} \right]}$$

$$12. \quad Y' = \begin{pmatrix} 1 & 0 \\ \sin x & -1 \end{pmatrix} Y$$

Escribir la matriz fundamental de la forma $\Phi(x) = B(x) e^{xL}$ donde B es una matriz periódica y L matriz constante.

$$\begin{pmatrix} y_1' \\ y_2' \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ \sin x & -1 \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} \Leftrightarrow \begin{cases} y_1' = y_1 \\ y_2' = \sin x y_1 - y_2 \end{cases} \longrightarrow \boxed{y_1 = ce^x}$$

$$\Rightarrow y_2' = ce^x \sin x - y_2 \quad (**)$$

$$y_{2h}' = -y_2 \Leftrightarrow \boxed{y_{2h} = ke^{-x}}$$

$$\Rightarrow \text{Para la particular probamos con: } y_{2p} = e^x (A \sin x + B \cos x)$$

$$y_{2p}' = e^x (A \cos x - B \sin x) + e^x (A \sin x + B \cos x)$$

Por tanto y_{2p} cumple $(**)$ si y sdo si $y_{2p}' + y_2 = ce^x \sin x$, es decir, $e^x (A \cos x - B \sin x + 2A \sin x + 2B \cos x) = ce^x \sin x$

$$\Rightarrow e^x (A + 2B) \cos x + (2A - B) \sin x = ce^x \sin x$$

$$\Rightarrow \begin{cases} A + 2B = 0 \\ 2A - B = c \end{cases} \Rightarrow -5B = c \Rightarrow B = -\frac{c}{5} \Rightarrow A = -2B = \frac{2c}{5}$$

$$\Rightarrow y_{2p} = e^x (A \sin x + B \cos x) = \frac{2c}{5} e^x \sin x - \frac{c}{5} e^x \cos x$$

$$\Rightarrow \boxed{y_2 = y_{2h} + y_{2p} = ke^{-x} + c \left(\frac{2}{5} e^x \sin x - \frac{e^x}{5} \cos x \right)}$$

$$\Rightarrow Y = \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} = \begin{pmatrix} ce^x \\ ke^{-x} + c \left(\frac{2}{5} e^x \sin x - \frac{e^x}{5} \cos x \right) \end{pmatrix} \rightarrow \text{Hay que expresar esto como nos pide el enunciado}$$

$$\boxed{Y = \begin{pmatrix} 1 & 0 \\ \frac{2}{5} \sin x - \frac{1}{5} \cos x & 1 \end{pmatrix} \begin{pmatrix} e^x & 0 \\ 0 & e^{-x} \end{pmatrix} \begin{pmatrix} c \\ k \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ \frac{2}{5} \sin x - \frac{1}{5} \cos x & 1 \end{pmatrix} \begin{pmatrix} c \\ k \end{pmatrix} e^{\begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} x}}$$

[13.] Sean x_1, x_2 soluciones de $x'' + px' + qx = 0$ (ED)

$$x_1(0) = 1, x_2(0) = 0, x_1'(0) = 0, x_2'(0) = 1$$

a) Demostrar que $x_1''(0) + q = 0, x_2''(0) + p = 0$

$$x_1, x_2 \text{ soluciones} \Rightarrow x_1'' + px_1' + qx_1 = 0 \quad \text{Como } x_1(0) = 1 \wedge x_1'(0) = 0$$

$$\Rightarrow x_1''(0) + q = 0$$

Lo mismo con x_2

$$\boxed{x_1' = -qx_2}^{(*)}, \quad x_2' = x_1 - px_2$$

$$z = x_1' + qx_2 \quad \leftarrow x_1 \text{ sol. de (ED)}$$

$$z' = x_1'' + qx_2' = -px_1' - qx_1 + qx_2' = 0$$

$$z'' = -px_1'' - qx_1' + qx_2'' \stackrel{x_1, x_2 \text{ sol. de (ED)}}{=} p^2x_1' + pqx_1 - qx_1' - qp x_2' - q^2x_2 =$$

$$= -q(x_1' + qx_2) - p(-px_1' - qx_1 + qx_2') = -qz - pz'$$

$$z \text{ es solución de } \begin{cases} z'' + qz + pz' = 0 \\ z(0) = x_1'(0) + qx_2(0) = 0 \\ z'(0) = 0 \end{cases} \quad (\text{P.V.I.})$$

Por unicidad de soluciones y como $z=0$ es solución \Rightarrow
 $\Rightarrow z \equiv 0$.

$$\begin{cases} w = x_2' - x_1 + px_2 \\ w' = x_2'' - x_1' + px_2' = -px_2' - qx_2 - x_1' + px_2' \stackrel{\text{usando } (*)}{=} 0 \end{cases} \quad (\text{P.V.I.})$$

$$w(0) = x_2'(0) - x_1(0) + px_2(0) = 0$$

w cumple $\begin{cases} w' = 0 \\ w(0) = 0 \end{cases} \Rightarrow$ unicidad de soluciones $\Rightarrow w \equiv 0$.

$$b) A_{2 \times 2} \quad e^{tA} = X_1 I + X_2 A$$

$$\xrightarrow{\text{Cayley-Hamilton}} A^2 + pA + q = 0$$

$$e^{tA} \text{ es la \u00fanica soluci\u00f3n de } \begin{cases} X' = AX \\ X(0) = Id \end{cases}$$

$$Z = X_1 I + X_2 A$$

$$\begin{cases} Z' = X_1' I + X_2' A = -qX_2 + A(X_1 - pX_2) \\ AZ = AX_1 + X_2 \overset{\substack{\uparrow \\ \text{C-H}}}{A^2} = AX_1 + X_2(-pA - q) \\ Z(0) = Id \end{cases}$$

\Rightarrow cumple el mismo problema que la exponencial y por unicidad de sol. \Rightarrow
 $\Rightarrow Z = e^{At}$

1. a) $X_1(t)$ y $X_2(t)$ lin. indep. $\Leftrightarrow (aX_1(t) + bX_2(t) = \vec{0} \Rightarrow a=b=0)$
 $a \begin{pmatrix} t \\ t^2 \end{pmatrix} + b \begin{pmatrix} t^2 \\ t^3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Leftrightarrow \begin{pmatrix} at \\ at^2 \end{pmatrix} + \begin{pmatrix} bt^2 \\ bt^3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Leftrightarrow \begin{pmatrix} at + bt^2 \\ at^2 + bt^3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Leftrightarrow$
 $\Leftrightarrow \begin{pmatrix} t(a+bt) \\ t^2(a+bt) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$ se cumple para $t=0$ y para $a=b=0$

b) $W(t) = \begin{bmatrix} \uparrow & \uparrow \\ X_1(t) & X_2(t) \\ \downarrow & \downarrow \end{bmatrix} = \begin{bmatrix} t & t^2 \\ t^2 & t^3 \end{bmatrix}$ está claro que \exists tal que
 $\begin{bmatrix} t_0 & t_0^2 \\ t_0^2 & t_0^3 \end{bmatrix} \neq 0 \Rightarrow W(t) \neq 0 \quad \forall t \in \mathbb{R}$ $\textcircled{?}$ $at=0$? pág 50

2. a) $B = \left\{ \underbrace{\cos x - \text{sen} x}_v, \underbrace{2\text{sen} x}_u \right\}$ base de $y'' + y = 0$?
 \hookrightarrow dimensión de solución de tamaño 2

$v = \cos x - \text{sen} x$ $u = 2\text{sen} x$
 $v' = -\text{sen} x - \cos x$ $u' = 2\cos x$
 $\Rightarrow W(x) = \begin{bmatrix} v & u \\ v' & u' \end{bmatrix} = \begin{bmatrix} \cos x - \text{sen} x & 2\text{sen} x \\ -\text{sen} x - \cos x & 2\cos x \end{bmatrix} =$
 $= 2\cos^2 x - 2\cos x \text{sen} x + (\text{sen} x + \cos x) \cdot 2\text{sen} x =$
 $= 2\cos^2 x - 2\cos x \text{sen} x + 2\text{sen}^2 x + 2\text{sen} x \cos x =$
 $= 2 + 4\text{sen}^2 x \cos^2 x$

$\textcircled{?}$ Para $x=0 \Rightarrow 2 + 4\text{sen}^2 0 \cos^2 0 = 2 \neq 0 \Rightarrow$ lin. indep.
 \hookrightarrow ¿está esto bien?

b) ~~$y(t) = y(1)$~~

$y(x) = C_1 v(x) + C_2 u(x) \rightarrow y(0) = 1 \Leftrightarrow C_1(\cos 0 - \text{sen} 0) + C_2 \cdot 2\text{sen} 0 =$
 $y'(x) = C_1 v'(x) + C_2 u'(x) \rightarrow y'(0) = 1 \Leftrightarrow C_1(-\text{sen} 0 - \cos 0) + C_2 \cdot 2\cos 0 = 1$
 $\Rightarrow \begin{cases} C_1 + C_2 \cdot 0 = 1 \rightarrow C_1 = 1 \\ -C_1 + 2C_2 = 1 \rightarrow C_2 = 1 \end{cases}$

$$\underline{5.7} \quad X' = \overbrace{\begin{pmatrix} 1 & -4 \\ 4 & -7 \end{pmatrix}}^A X \quad X(0) = \begin{pmatrix} 3 \\ 2 \end{pmatrix}$$

$$\begin{vmatrix} 1-\lambda & -4 \\ 4 & -7-\lambda \end{vmatrix} = (1-\lambda)(-7-\lambda) + 16 = -7 - \lambda + 7\lambda + \lambda^2 + 16 = 0 \Leftrightarrow \\ \Leftrightarrow \lambda^2 + 6\lambda + 9 = 0$$

$$\lambda = \frac{-6 \pm \sqrt{36 - 4(\cancel{25})9}}{2} = \frac{-6}{2} \rightarrow \lambda = -3 \text{ (double)}$$

$$\ker(A+3I) : \begin{pmatrix} 4 & -4 \\ 4 & -4 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow 4v_1 - 4v_2 = 0 \Rightarrow v = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

Buscamos $(A+3I)w = v \Rightarrow \begin{pmatrix} 4 & -4 \\ 4 & -4 \end{pmatrix} \begin{pmatrix} w_1 \\ w_2 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \Rightarrow 4w_1 - 4w_2 = 1 \rightarrow$

$\rightarrow w = \left(\frac{1}{4}, 0\right) \rightarrow w = \begin{pmatrix} \frac{1}{4} \\ 0 \end{pmatrix}$

\Rightarrow

$$(5.) \quad X' = \begin{pmatrix} 1 & -4 \\ 4 & -7 \end{pmatrix} X$$

$$\begin{vmatrix} 1-\lambda & -4 \\ 4 & -7-\lambda \end{vmatrix} = (1-\lambda)(-7-\lambda) + 16 = -7 - \lambda + 7\lambda + \lambda^2 + 16$$

$$\Leftrightarrow \lambda^2 + 6\lambda + 9 = 0 \rightarrow \lambda = \frac{-6 \pm \sqrt{36 - 4 \cdot 9}}{2}$$

$$\lambda = -3 \text{ (doble)}$$

$$\begin{pmatrix} 4 & -4 \\ 4 & -4 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \rightarrow v = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} 4 & -4 \\ 4 & -4 \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \rightarrow 4u_1 - 4u_2 = 1 \rightarrow u = \begin{pmatrix} \frac{1}{4} \\ 0 \end{pmatrix}$$

$$\text{Tenemos: } J = D + N = \begin{pmatrix} -3 & 0 \\ 0 & -3 \end{pmatrix} + \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$$

$$e^{Jt} = e^{Dt} \cdot e^{Nt}$$

$$e^{Nt} = I + Nt + \frac{N^2 t^2}{2!} + \dots = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} + \begin{pmatrix} 0 & t \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & t \\ 0 & 1 \end{pmatrix}$$

$$e^{Jt} = \begin{pmatrix} e^{-3t} & 0 \\ 0 & e^{-3t} \end{pmatrix} \begin{pmatrix} 1 & t \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} e^{-3t} & te^{-3t} \\ 0 & e^{-3t} \end{pmatrix}$$

$$\text{Soluci3n general: } \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 1/4 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} e^{-3t} & te^{-3t} \\ 0 & e^{-3t} \end{pmatrix} = \underbrace{\begin{pmatrix} e^{-3t} & te^{-3t} + \frac{e^{-3t}}{4} \\ e^{-3t} & te^{-3t} \end{pmatrix}}_{F(t)}$$

$$X(t) = F(t) \begin{pmatrix} c_1 \\ c_2 \end{pmatrix}$$

$$X(0) = \begin{pmatrix} 3 \\ 2 \end{pmatrix} \Leftrightarrow \begin{pmatrix} 1 & 1/4 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = \begin{pmatrix} 3 \\ 2 \end{pmatrix} \Rightarrow$$

$$\Rightarrow \boxed{c_1 = 2}$$

$$c_1 + \frac{1}{4}c_2 = 3 \Rightarrow \frac{c_2}{4} = 1 \Rightarrow \boxed{c_2 = 4}$$

$$\boxed{X(t) = F(t) \begin{pmatrix} 2 \\ 4 \end{pmatrix}}$$

6. $X' = \underbrace{\begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 6 \\ 0 & -2 & 6 \end{pmatrix}}_A X$

$$\begin{vmatrix} 1-\lambda & 0 & 0 \\ 0 & -1-\lambda & 6 \\ 0 & -2 & 6-\lambda \end{vmatrix} = (1-\lambda)(-1-\lambda)(6-\lambda) - (-2 \cdot 6 \cdot (1-\lambda)) =$$

$$= (-1-\lambda+\lambda+\lambda^2)(6-\lambda) - (-12(1-\lambda)) =$$

$$= -6 + \lambda + 6\lambda^2 - \lambda^3 + 12 - 12\lambda = -\lambda^3 + 6\lambda^2 - 11\lambda + 6 = 0$$

~~$\begin{array}{c|ccc} 1 & 6 & 11 & 6 \\ -2 & -1 & -8 & -6 \\ \hline 3 & 1 & 3 & 0 \end{array}$~~

$$\Leftrightarrow \lambda = \frac{-4 \pm \sqrt{16 - 4 \cdot 3 \cdot (-1)}}{2} = \frac{-4 \pm 2}{2}$$

~~$(\lambda+2)(-\lambda^2+4\lambda+3) = 0$~~

~~$\lambda_1 = -2$~~

~~$\lambda_2 = -1$~~

~~$\lambda_3 = -3$~~

Autovectores

~~$\begin{pmatrix} 3 & 0 & 0 \\ 0 & 1 & 6 \\ 0 & -2 & 4 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \rightarrow$~~

~~$v_1 = 0$~~

~~$v_2 + 6v_3 = 0 \rightarrow v_2 = -6v_3$~~

~~$-2v_2 + 4v_3 = 0$~~

~~$\hookrightarrow -2(-6v_3) + 4v_3 = 0 \rightarrow$~~

~~$\hookrightarrow 12v_3 + 4v_3 = 0$~~

$$(6.) -\lambda^3 + 6\lambda^2 - 11\lambda + 6 = 0$$

$$\begin{array}{r|rrrr} 1 & -1 & +6 & -11 & +6 \\ & & -1 & 5 & -6 \\ \hline 2 & & & & \\ & -1 & 5 & -6 & \boxed{0} \\ \hline 3 & & & & \\ & & -2 & 6 & \\ & -1 & 3 & \boxed{0} \\ \hline & & & & \\ & & -3 & & \\ & -1 & \boxed{0} & & \end{array}$$

$$(\lambda-1)(\lambda-2)(\lambda-3) = 0$$

$$\begin{aligned} \lambda_1 &= 1 \\ \lambda_2 &= 2 \\ \lambda_3 &= 3 \end{aligned}$$

Autovectores

$$\lambda_1 = 1$$

$$\begin{pmatrix} 0 & 0 & 0 \\ 0 & -2 & 6 \\ 0 & -2 & 5 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \Leftrightarrow \begin{cases} v_1 = 0 \\ -2v_2 + 6v_3 = 0 \\ -2v_2 + 5v_3 = 0 \end{cases} \Rightarrow v = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

$$\lambda_2 = 2$$

$$\begin{pmatrix} -1 & 0 & 0 \\ 0 & -3 & 6 \\ 0 & -2 & 4 \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \\ u_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \rightarrow \begin{cases} -u_1 = 0 \\ -3u_2 + 6u_3 = 0 \\ -2u_2 + 4u_3 = 0 \end{cases} \rightarrow u = \begin{pmatrix} 0 \\ 2 \\ 1 \end{pmatrix}$$

$$\lambda_3 = 3$$

$$\begin{pmatrix} -2 & 0 & 0 \\ 0 & -4 & 6 \\ 0 & -2 & 3 \end{pmatrix} \begin{pmatrix} w_1 \\ w_2 \\ w_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \rightarrow \begin{cases} w_1 = 0 \\ -2w_2 + 3w_3 = 0 \end{cases} \rightarrow w = \begin{pmatrix} 0 \\ 3 \\ 2 \end{pmatrix}$$

$$J = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{pmatrix} \quad P = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 2 & 3 \\ 0 & 1 & 2 \end{pmatrix}$$

$$X(t) = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 2 & 3 \\ 0 & 1 & 2 \end{pmatrix} \begin{pmatrix} e^t & 0 & 0 \\ 0 & e^{2t} & 0 \\ 0 & 0 & e^{3t} \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \\ c_3 \end{pmatrix}$$

$$(*) \quad X' = \begin{pmatrix} 3 & 2 & 1 \\ -1 & 0 & -1 \\ 1 & 1 & 2 \end{pmatrix} X$$

$$\begin{vmatrix} 3-\lambda & 2 & 1 \\ -1 & -\lambda & -1 \\ 1 & 1 & 2-\lambda \end{vmatrix} = (3-\lambda)(-\lambda)(2-\lambda) - 1(-2) - (-\lambda(-3+\lambda+2\lambda-4)) =$$

$$= (6-3\lambda-2\lambda+\lambda^2)(-\lambda) - \cancel{2} + \cancel{\lambda} + 3 - \cancel{\lambda} - 2\lambda + 4 =$$

$$= -6\lambda + 3\lambda^2 + 2\lambda^2 - \lambda^3 - 2\lambda + 4 \rightarrow$$

$$\rightarrow -\lambda^3 + 5\lambda^2 - 8\lambda + 4 = 0$$

$$\begin{array}{r|rrrr} & -1 & 5 & -8 & 4 \\ 2 & & -2 & \textcircled{2} & -4 \\ \hline & -1 & 3 & -2 & 0 \\ 1 & & -1 & 2 & \\ \hline & -1 & 2 & 0 & \\ 2 & & -2 & & \\ \hline & -1 & 0 & & \end{array}$$

$$(\lambda-2)^2(\lambda-1) = 0$$

$$\lambda_1 = 1$$

$$\lambda_2 = 2 \text{ (doble)}$$

Autovectores

$$\underline{\lambda_1 = 1}$$

$$\begin{pmatrix} 2 & 2 & 1 \\ -1 & -1 & -1 \\ 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \rightarrow \begin{cases} v_3 = 0 \\ 2v_1 + 2v_2 + v_3 = 0 \end{cases} \rightarrow v = \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix}$$

$$\underline{\lambda_2 = 2}$$

$$\begin{pmatrix} 1 & 2 & 1 \\ -1 & -2 & -1 \\ 1 & 1 & 0 \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \\ u_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \rightarrow \begin{cases} u_1 + 2u_2 + u_3 = 0 \\ u_1 + u_2 = 0 \end{cases} \rightarrow u = \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 2 & 1 \\ -1 & -2 & -1 \\ 1 & 1 & 0 \end{pmatrix} \begin{pmatrix} w_1 \\ w_2 \\ w_3 \end{pmatrix} = \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix} \rightarrow \begin{cases} w_1 + 2w_2 + w_3 = 1 \\ w_1 + w_2 = -1 \end{cases} \rightarrow w = \begin{pmatrix} 2 \\ -1 \\ 1 \end{pmatrix}$$