

Hoja 9

1. Sea S una superficie regular y sea $p \in S$. Demuestra que la curvatura gaussiana en p (con respecto a la primera forma fundamental) verifica:

$$K(p) = \lim_{r \rightarrow 0} \frac{12 \pi r^2 - A}{\pi r^4}$$

donde A es el área del disco geodésico centrado en p y de radio r .

2. Sea S una superficie regular con métrica de Riemann Q y sea $c > 0$ una constante.

- (a) Demuestra que las geodésicas para cQ son las mismas que para Q .
 (b) Halla la relación entre la curvatura gaussiana de Q y de cQ .

3. A una superficie S , con parametrización regular $\mathbf{X}(u, v)$, $u > 0, v > 1$, le damos la siguiente métrica de Riemann:

$$Q = (du)^2 + \frac{2}{v} (du)(dv) + e^u (dv)^2.$$

- (a) Comprueba que las curvas $\alpha(t) = \mathbf{X}(t, \text{cte})$ son geodésicas unitarias para Q .
 (b) Halla la trayectoria Q -ortogonal, pasando por el punto $\mathbf{X}(1, e)$, de esas geodésicas. Parametrízala como $\mathbf{X}(h(v), v)$ para cierta función $h(v)$. \rightarrow curva $u + \log v = 2$
 (c) Utiliza lo obtenido en los apartados (a) y (b) para construir coordenadas (\tilde{u}, \tilde{v}) en las cuales tengamos:

$$Q = (d\tilde{u})^2 + C(\tilde{u}, \tilde{v}) (d\tilde{v})^2,$$

y calcula explícitamente la función $C(\tilde{u}, \tilde{v})$.

4. Consideremos el plano hiperbólico: $\mathbb{H} = \{(u, v) : v > 0\}$ con $Q = \frac{(du)^2 + (dv)^2}{v^2}$

Sea $C(c, R)$ el círculo de centro $c = (u_0, v_0)$ y radio R en \mathbb{H} , es decir,

$$C(c, R) := \{(u, v) \in \mathbb{H} : d_{\mathbb{H}}((u, v), c_0) = R\}$$

- (a) Comprueba que $C(c, R)$ es un círculo euclídeo de centro $(u_0, v_0 \cosh R)$ y radio $v_0 \sinh R$.
 (b) Demuestra que $C(c, R)$ tiene curvatura geodésica $\coth R$.
 5. Sea S una superficie regular con parametrización $\mathbf{X}(u, v)$ y con métrica de Riemann Q . Demuestra:

$$Q = (du)^2 + h(u, v)^2 (dv)^2 \implies K = \frac{-h_{uu}}{h}.$$

$$Q = a^2 (du)^2 + b^2 (dv)^2 \implies K = \frac{-1}{ab} \left[\left(\frac{a_v}{b} \right)_v + \left(\frac{b_u}{a} \right)_u \right].$$

$$Q = e^{2h(u, v)} [(du)^2 + (dv)^2] \implies K = \frac{-h_{uu} - h_{vv}}{e^{2h}}.$$

$$Q = (du)^2 + 2 \cos \theta (du)(dv) + (dv)^2 \implies K = \frac{-\theta_{uv}}{\sin \theta}.$$

- 6. Una superficie S tiene primera forma fundamental

$$I = (du)^2 + 2u(du)(dv) + (dv)^2, \quad \text{con } |u| < 1$$

Demuestra que S es localmente isométrica al plano euclídeo.

7. En el plano xy consideramos la fórmula:

$$\frac{(dx)^2 + (dy)^2}{(x^2 + y^2 + c)^2} \quad \text{con } c = cte \in \mathbb{R}$$

Describe, según el valor de c , el dominio del plano donde esta fórmula define una métrica y calcula la curvatura gaussiana de dicha métrica.

- 8. Sea Σ con parametrización $\mathbf{X}(u, v)$ y métrica de Riemann

$$Q = \frac{(du)^2}{1 - u^2} + u^2 (dv)^2.$$

Demuestra que (Σ, Q) es isométrica a una esfera (con primera forma fundamental). Calcula el radio de la esfera y determina la isometría.

9. Sea S el helicoido, parametrizado por $\Phi(u, v) \equiv (u \cos v, u \sin v, v)$. Halla todas las isometrías del helicoido consigo mismo respecto de la primera forma fundamental.
- 10. Tenemos dos parametrizaciones de las mismas variables: $\Phi(u, v)$ y $\Psi(u, v)$, con $u > 0$. Sean S_1 y S_2 las superficies definidas por ellas. Sabiendo que:

$$I_\Phi \equiv \frac{1}{2u} (du)^2 + u^2 (dv)^2,$$

$$I_\Psi \equiv \frac{1}{2u} (du)^2 + \frac{1}{2u} (dv)^2,$$

demuestra que no hay ninguna isometría $S_1 \rightarrow S_2$.

OTRO (CREO QUE EL 8)

1 TEOREMA DE MINDING

↓
misma curvatura
de Gauss const
⇒ son localm.
isométricas

$$E = \frac{1}{1-u^2} \quad F = 0 \quad G = u^2 \quad 0 < u < 1$$

$$E = \lambda^2 \quad G = \mu^2 \quad F = 0$$

$$K = \frac{-1}{\lambda\mu} \left(\left(\frac{\lambda_v}{\mu} \right)_v + \left(\frac{\mu_u}{\lambda} \right)_u \right) = \frac{-1}{\lambda\mu} (-\lambda\mu) = 1$$

$$\lambda = (1-u^2)^{-1/2}$$

$$\mu = u$$

$$\lambda_v = 0$$

$$\mu_u = 1$$

$$\frac{\mu_u}{\lambda} = (1-u^2)^{1/2}$$

$$\left(\frac{\mu_u}{\lambda} \right)_u = \frac{1}{2} (1-u^2)^{-1/2} (-2u) = \frac{-u}{\sqrt{1-u^2}} = -u\lambda = -\mu\lambda$$

$$d\bar{u} = \lambda du = \frac{1}{\sqrt{1-u^2}} du$$

$$\bar{v} = v$$

$$\bar{u} = \arcsen u$$

$$u = \sen \bar{u}$$

$$\bar{v} = v$$

$$0 < \bar{u} < \pi/2$$

$$\frac{1}{1-u^2} du^2 + dv^2 = d\bar{u}^2 + \sen^2 \bar{u} d\bar{v}^2$$

Otro ejercicio : HOJA 9 - EJ. 8

$$\lambda = \mu = \frac{E}{x^2 + y^2 + c}$$

$$E(x^2 + y^2 + c) = |x^2 + y^2 + c|$$

$$E = \lambda^2 \quad F = 0 \quad G = \mu^2$$

Sabemos: $K = \frac{-1}{\lambda \mu} \left(\left(\frac{\lambda_v}{\mu} \right)_v + \left(\frac{\mu_u}{\lambda} \right)_u \right)$ Laplaciano

Si $\lambda = \mu$: $K = \frac{-1}{\lambda^2} \Delta(\log \lambda) = \frac{-1}{\lambda^2} ((\log \lambda)_{uu} + (\log \lambda)_{vv})$

$$\log \lambda = -\log |x^2 + y^2 + c|$$

$$(\log \lambda)_x = \frac{2x}{x^2 + y^2 + c}$$

$$\begin{aligned} (\log \lambda)_{xx} &= \frac{2}{x^2 + y^2 + c} - \frac{2x \cdot 2x}{(x^2 + y^2 + c)^2} = \frac{2}{(x^2 + y^2 + c)^2} \cdot (x^2 + y^2 + c - 2x^2) = \\ &= \frac{2}{(x^2 + y^2 + c)^2} \cdot (-x^2 + y^2 + c) \end{aligned}$$

$$\begin{aligned} \Rightarrow K &= \frac{-1}{\lambda^2} \Delta(\log \lambda) = \frac{-1}{\lambda^2} ((\log \lambda)_{uu} + (\log \lambda)_{vv}) = \\ &= \frac{-1}{\frac{1}{(x^2 + y^2 + c)^2}} \cdot \frac{4c}{(x^2 + y^2 + c)^2} = -4c \end{aligned}$$

$$u > 0 \quad v > 1$$

$$E=1 \quad F = \frac{1}{v} \quad G = e^u$$

Demonstrar:

$\alpha(t) = X(t, \text{cte.})$ são geodésicas unitárias.

$$\left. \begin{aligned} u(t) &= t & v(t) &= v_0 \\ u'(t) &= 1 & v'(t) &= 0 \end{aligned} \right\} \Rightarrow \|\alpha'(t)\|^2 = 1 \Rightarrow \|\alpha'(t)\| = 1$$

$$\Gamma = \frac{1}{e^u - \frac{1}{v^2}} \begin{pmatrix} e^u & -\frac{1}{v} \\ -\frac{1}{v} & 1 \end{pmatrix} \begin{pmatrix} 0 & 0 & -\frac{1}{v^2} \cdot \left(-\frac{1}{2} e^4\right) \\ 0 & \frac{1}{2} e^u & 0 \end{pmatrix} =$$

$$= \frac{1}{e^u - \frac{1}{v^2}} \begin{pmatrix} 0 & -\frac{1}{2} e^u & -e^u \left(e^u + \frac{1}{v^2}\right) \\ 0 & \frac{1}{2} e^u & \frac{1}{v} \left(e^u + \frac{1}{v^2}\right) \end{pmatrix}$$

$$\begin{cases} u'' + \Gamma_{uu}^u u'^2 + 2\Gamma_{uv}^u u'v' + \Gamma_{vv}^u v'^2 = 0 \\ v'' + \Gamma_{uu}^v u'^2 + 2\Gamma_{uv}^v u'v' + \Gamma_{vv}^v v'^2 = 0 \end{cases}$$

$$\Gamma_{uu}^u = 0 \quad \Gamma_{uu}^v = 0$$

$$\beta(t) = X(u(t), v(t))$$

$$\langle \beta'(t), X_u(\beta(t)) \rangle = 0 = \langle u' X_u + v' X_v, X_u \rangle = u' + \frac{v'}{v} = 0$$

$$(u + \log v)' = 0 \quad u + \log v = -c$$

$$u = c + \log v = h(v)$$

$$(1, e) \quad h(e) = 1 = c + \log e = c + 1 \Rightarrow c = 0$$

$$u = \log v$$

19- EJ. 10/ $\Phi(u,v)$, $\Psi(u,v)$

S_1 y S_2 sup. def. por ellas, sabiendo que:

$$I_{\Phi} = \frac{1}{2u}(du)^2 + u^2(dv)^2$$

$$I_{\Psi} = \frac{1}{2u}(du)^2 + \frac{1}{2u}(dv)^2$$

demostrar que no hay ninguna isometría $S_1 \rightarrow S_2$.

De I_{Φ} sacamos $\lambda = (2u)^{-1/2}$ $\mu = u$

$$\lambda_v = 0 \quad \mu_u = 1 \quad \frac{\mu_u}{\lambda} = (2u)^{1/2}$$

$$\left(\frac{\mu_u}{\lambda}\right)_u = \frac{1}{2}(2u)^{1/2} \cdot 2 = (2u)^{-1/2} = \lambda$$

$$\Rightarrow K_1(u,v) = \frac{-1}{\lambda} \cdot \frac{1}{u} (\lambda) = \frac{-1}{u}$$

De I_{Ψ} sacamos $\lambda = (2u)^{-1/2}$ $\mu = (2u)^{-1/2} = \lambda$

$$\log \lambda = \frac{-1}{2} \log(2u) \quad (\log \lambda)_v = 0$$

$$(\log \lambda)_u = \frac{-1}{2} \cdot \frac{2}{2u} = \frac{-1}{2u} \quad (\log \lambda)_{uu} = \frac{1}{2u^2}$$

$$\Rightarrow K_2(\bar{u}, \bar{v}) = \frac{-1}{\lambda^2} \Delta \log \lambda = -2\bar{u} \left(\frac{1}{2\bar{u}^2} \right) = \frac{-1}{\bar{u}}$$

$$\left. \begin{array}{l} u = u(\bar{u}, \bar{v}) \\ v = v(\bar{u}, \bar{v}) \end{array} \right\} \Rightarrow \frac{-1}{u} = \frac{-1}{\bar{u}} \Rightarrow u = \bar{u} \Rightarrow u_u = 1; u_v = 0$$

$$\frac{1}{2u} du + u^2 dv^2 = \frac{1}{2\bar{u}} \underbrace{(d\bar{u})^2}_{\substack{\uparrow \\ \text{porque } u=\bar{u} \\ \Rightarrow du=d\bar{u}}} + \bar{u}^2 \underbrace{(v_{\bar{u}} d\bar{u} + v_{\bar{v}} d\bar{v})^2}_{d\bar{v} \text{ derivando } v=v(\bar{u}, \bar{v})} =$$

$$= \frac{1}{2\bar{u}} (d\bar{u})^2 + \bar{u}^2 (v_{\bar{u}}^2 d\bar{u}^2 + 2v_{\bar{u}} v_{\bar{v}} d\bar{u} d\bar{v} + v_{\bar{v}}^2 d\bar{v}^2) =$$

$$= \left(\frac{1}{2\bar{u}} + \bar{u}^2 v_{\bar{u}}^2 \right) d\bar{u}^2 + 2\bar{u} v_{\bar{u}} v_{\bar{v}} d\bar{u} d\bar{v} + \bar{u}^2 v_{\bar{v}}^2 d\bar{v}^2 =$$

$$= \frac{1}{2\bar{u}} d\bar{u}^2 + \frac{1}{2\bar{u}} d\bar{v}^2$$

$$2\bar{u} v_{\bar{u}} v_{\bar{v}} = 0 \quad \frac{1}{2\bar{u}} + \bar{u}^2 v_{\bar{u}}^2 = \frac{1}{2\bar{u}} \Rightarrow v_{\bar{u}} = 0 \Rightarrow v = v(\bar{v}) \Rightarrow v_{\bar{v}}(\bar{v}) = v'(\bar{v}) \text{ sólo depende de } \bar{v}$$

$$\bar{u}^2 v_{\bar{v}}^2 = \frac{1}{2\bar{u}} \Rightarrow v_{\bar{v}}^2 = 2\bar{u}^3$$

contradicción \Rightarrow no pueden ser isométricas

$$X(u,v) \quad u > 0 \quad I_X \equiv \frac{1}{2u} (du)^2 + u^2 (dv)^2$$

$$Y(\bar{u}, \bar{v}) \quad \bar{u} > 0 \quad I_Y \equiv \frac{1}{2\bar{u}} (d\bar{u})^2 + \frac{1}{2\bar{u}} (d\bar{v})^2$$

$f(X(u,v)) = Y(h(u,v))$ es una isometría (suponemos esto)

$$Y^{-1} \circ f \circ X = h: \bar{u} \longrightarrow u$$

$$h(u,v) = (\bar{u}(u,v), \bar{v}(u,v))$$

$$K_X(u,v) = K_Y(h(u,v))$$

$$X: \quad \lambda = \frac{1}{\sqrt{2u}} \quad \mu = u \quad E = \lambda^2 \quad F = 0 \quad G = \mu^2$$

$$K_X = \frac{-1}{\lambda \mu} \left(\left(\frac{\lambda_v}{\mu} \right)_v + \left(\frac{\lambda_u}{\lambda} \right)_u \right)$$

$$\lambda \mu = \frac{1}{\sqrt{2u}} \quad u = \sqrt{\frac{u}{2}}$$

$$\lambda = \frac{1}{\sqrt{2}} u^{-1/2} \longrightarrow \lambda_u = \frac{1}{\sqrt{2}} \cdot \frac{-1}{2} u^{-3/2} = \frac{-1}{2\sqrt{2} u \sqrt{2}} \quad \lambda_v = 0$$

$$\Rightarrow \mu = u \longrightarrow \mu_u = 1 \quad \mu_v = 0$$

$$\frac{\mu_u}{\lambda} = \sqrt{2u} = \sqrt{2} \sqrt{u} \Rightarrow \left(\frac{\mu_u}{\lambda} \right)_u = \frac{\sqrt{2}}{2\sqrt{u}} = \frac{1}{\sqrt{2u}}$$

$$K_X = -\sqrt{\frac{u}{2}} \cdot \frac{1}{\sqrt{2u}} = \frac{-1}{2}$$

$$Y: \quad \lambda = \mu = \frac{1}{\sqrt{2\bar{u}}} \quad \log \lambda = \frac{-1}{2} \log(2\bar{u}) \quad (\log \lambda)_{\bar{u}} = \frac{-1}{2} \frac{2}{2\bar{u}} = \frac{-1}{2\bar{u}}$$

$$(\log \lambda)_{\bar{v}} = 0$$

$$(\log \lambda)_{\bar{u}\bar{u}} = \frac{1}{2\bar{u}^2}$$

$$K_Y = \frac{-1}{2} \Delta \log \lambda = -2\bar{u}^2 \cdot \frac{1}{2\bar{u}^2} = -1.$$

HOJA 9- EJ. 6

$$E=1, F=u, G=1 \quad |u| < 1$$

Demostrar que es localmente isométrico al plano euclídeo.

$$D_t W = \left((a_u + \Gamma_{uu}^u a + \Gamma_{uv}^u b) u' + (a_v + \Gamma_{uv}^u a + \Gamma_w^u b) v' \right) X_u \\ + \left((b_u + \Gamma_{uu}^v a + \Gamma_{uv}^v b) u' + (b_v + \Gamma_{uv}^v a + \Gamma_{vv}^v b) v' \right) X_v$$

$$K = \frac{\langle [D_v, D_u] X_u, X_v \rangle}{EG - F^2}$$

$$W = aX_u + bX_v$$

$$\begin{pmatrix} \Gamma_{uu}^u & \Gamma_{uv}^u & \Gamma_{vv}^u \\ \Gamma_{uu}^v & \Gamma_{uv}^v & \Gamma_{vv}^v \end{pmatrix} = \begin{pmatrix} \frac{1}{2} E_u & \frac{1}{2} E_v & F_v - \frac{1}{2} G_u \\ F_u - \frac{1}{2} E_v & \frac{1}{2} G_u & \frac{1}{2} G_v \end{pmatrix} = \\ = \frac{1}{1-u^2} \begin{pmatrix} 1 & -u \\ -u & 1 \end{pmatrix} \begin{pmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix} = \begin{pmatrix} \frac{-u}{1-u^2} & 0 & 0 \\ \frac{1}{1-u^2} & 0 & 0 \end{pmatrix}$$

$$W = aX_u + bX_v$$

$$D_u W = \left(a_u - \frac{u}{1-u^2} a \right) X_u + \left(b_u + \frac{1}{1+u^2} a \right) X_v$$

$$D_v W = a_v X_u + b_v X_v$$

$$D_u X_u = \frac{-u}{1-u^2} X_u$$

$$D_v D_u X_u = 0$$

$$D_v X_u = 0 \Rightarrow [D_v, D_u] X_u = D_v D_u X_u - D_u D_v X_u = 0 \Rightarrow K = 0$$

TEOREMA DE MINDING

$$\exp_p u = 0 \quad (1)$$

$$\begin{cases} \gamma^u(0) = p \\ \dot{\gamma}^u(0) = u \end{cases} \quad \text{geodésica}$$

$f: S_1 \rightarrow S_2$ es isometría local.

γ geodésica a $S_1 \Rightarrow f \circ \gamma$ es geodésica en S_2

$$\exp_{f(p)} T_p f u = (f \circ \gamma^u)(1)$$

$$\exp_{g(u)} T_p g(u) = g(\exp_p u)$$

$$\exp_{f(p)} T_p f u = f \exp_p u$$

$f, g: S_1 \rightarrow S_2$ isometrías locales
conexas

$$\left. \begin{aligned} f(p) &= g(p) \\ T_p f &= T_p g \end{aligned} \right\} \Rightarrow f = g$$

Isometrías del helicóide sobre si mismo:

$$X(u,v) = (v \cos u, v \sin u, u)$$

$$E = 1 + v^2$$

$$F = 0$$

$$G = 1$$

$$\mu = 1 = \sqrt{G}$$

$$\lambda = \sqrt{1+v^2}$$

$$\lambda_v = \frac{v}{\sqrt{1+v^2}}$$

$$\frac{\lambda_v}{\mu} = \lambda_v$$

$$\begin{aligned} \lambda_w &= (1+v^2)^{-1/2} + v \left(-\frac{1}{2} (1+v^2)^{-3/2} \cdot 2v \right) = \\ &= \frac{1+v^2 - v^2}{(1+v^2)^{3/2}} = \frac{1}{(1+v^2)^{3/2}} \end{aligned}$$

$$EG - F^2 = 1 + v^2$$

$$\frac{1}{1+v^2} \begin{pmatrix} 1 & 0 \\ 0 & 1+v^2 \end{pmatrix} \begin{pmatrix} 0 & v & 0 \\ -v & 0 & 0 \end{pmatrix}$$

$$K = \frac{-\lambda_{vv}}{\lambda} = \frac{-1}{(1+v^2)^{3/2}} \cdot \frac{1}{(1+v^2)^{1/2}} = \frac{-1}{(1+v^2)^2}$$

Utilizamos que K se conserva para sacar información:

$$K(\bar{u}, \bar{v}) = \frac{-1}{(1+\bar{v}^2)^2} = K(u,v) = \frac{-1}{(1+v^2)^2} \Rightarrow \bar{v} = \varepsilon v \text{ con } \varepsilon = \pm 1$$

$$\begin{cases} u = u(\bar{u}, \bar{v}) \\ v = \varepsilon \bar{v} \end{cases}$$

Deben conservar la 1ª FF.
y tratamos de sacar u .

$$X(\bar{u}, \bar{v}) = X(u(\bar{u}, \bar{v}), v(\bar{u}, \bar{v}))$$

$$X_{\bar{u}} = \frac{\partial u}{\partial \bar{u}} X_u + \frac{\partial v}{\partial \bar{u}} X_v \Rightarrow \|X_{\bar{u}}\|^2 = \left| \frac{\partial u}{\partial \bar{u}} \right|^2 \|X_u\|^2 = \left| \frac{\partial u}{\partial \bar{u}} \right|^2 (1+v^2)$$

\parallel
 $1+\bar{v}^2$

$$\frac{\partial u}{\partial \bar{u}} = \delta = \pm 1$$

$$u = \delta \bar{u} + a(\bar{v}) \rightarrow \frac{\partial u}{\partial \bar{v}} = a'(\bar{v})$$

$$X_{\bar{v}} = \frac{\partial u}{\partial \bar{v}} X_u + \frac{\partial v}{\partial \bar{v}} X_v = \frac{\partial u}{\partial \bar{v}} X_u + \varepsilon X_v = a'(\bar{v}) X_u + \varepsilon X_v$$

$$\langle X_{\bar{u}}, X_{\bar{v}} \rangle = \langle \delta X_u, a'(\bar{v}) X_u + \varepsilon X_v \rangle = \delta a'(\bar{v}) (1+v^2) = 0$$

$$a'(\bar{v}) = 0 \Rightarrow a(\bar{v}) = a$$

$$\begin{cases} u = \delta \bar{u} + a \\ v = \epsilon \bar{v} \end{cases}$$

simetría helicoidal en si mismo

$$\begin{aligned} (v \cos u, v \sin u, u) &= (\epsilon \bar{v} \cos(\delta \bar{u} + a), \epsilon \bar{v} \sin(\delta \bar{u} + a), \delta \bar{u} + a) = \\ &= \begin{pmatrix} 0 \\ 0 \\ a \end{pmatrix} + \begin{pmatrix} \cos a & -\sin a & 0 \\ \sin a & \cos a & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \epsilon \bar{v} \cos(\delta \bar{u}) \\ \epsilon \bar{v} \sin(\delta \bar{u}) \\ \delta \bar{u} \end{pmatrix} \end{aligned}$$

Movimientos
rigidos de
 \mathbb{R}^3
(giros, simetrías
y traslaciones)

Recordo: las isometrías de la esfera son las
aplicaciones ortogonales → giros y simetrías.

H9 - #EJ1

$$K(p) = \lim_{r \rightarrow 0} \frac{12\pi r - A}{\pi r^4}$$

$$\lambda(\theta, r) d\theta^2 + dr^2$$

$$\sqrt{EG - F^2} = \lambda$$

$$\lambda(\theta, 0) = 0 \quad \lambda_r(\theta, 0) = 1 \quad \lambda_{rr}(\theta, 0) = 0$$

$$\lambda_{rr}(\theta, r) = -K(\theta, r) \lambda(\theta, r)$$

$$\lambda_{rrr}(\theta, r) = -K_r(\theta, r) \lambda(\theta, r) - K(\theta, r) \lambda_r(\theta, r)$$

$$\lambda_{rrr}(\theta, r) = -K(\theta, r) = -K(p)$$

$$\lambda(\theta, r) = r - \frac{K(p)r^3}{6} + \psi(\theta, r) \quad \frac{\psi(\theta, r)}{r^3} \xrightarrow{r \rightarrow 0} 0$$

$$A_r = \iint_{D_r} \lambda d\theta dr = \int_0^r \int_0^{2\pi} \lambda(\theta, r) d\theta dr = \int_0^r \int_0^{2\pi} r - \frac{K(p)r^3}{6} + \psi(\theta, r) d\theta dr =$$

$$= 2\pi \left(\frac{r^2}{2} - \frac{K(p)r^4}{24} \right) + \psi(\theta, r) = \frac{\psi(\theta, r)}{r^4} \xrightarrow{r \rightarrow 0} 0$$

$$= \pi r^2 - \frac{K(p)r^4}{12} \pi + \psi$$

$$\pi K(p) \frac{r^4}{12} = \pi r^2 - A_r + \psi \Rightarrow K(p) = \frac{12}{\pi} \frac{(\pi r^2 - A_r)}{r^4} + \frac{12\psi}{\pi r^4}$$

$$\xrightarrow{r \rightarrow 0} \frac{12}{\pi} \left(\frac{\pi r^2 - A_r}{r^4} \right) = K(p)$$

$$u > 0 \quad v > 1$$

$$ds^2 = (du)^2 + \frac{2}{v} du dv + e^u (dv)^2$$

a) $\alpha(t) = X(t, v_0) \quad \|\alpha'(t)\| = 1$ geodésicas

b) $X(1, e) \quad X(h(v), v) = \beta(v)$

c) $(\bar{u}, \bar{v}) \quad d\bar{s}^2 = (d\bar{u})^2 + c(\bar{u}, \bar{v})(d\bar{v})^2$

$$\begin{cases} u(t) = t & v(t) = v_0 \\ u' = 1 & v' = 0 \\ u'' = 0 & v'' = 0 \end{cases}$$

$$\begin{cases} u''(t) + \Gamma_{uu}^u u'(t)^2 + 2\Gamma_{uv}^u u'(t)v'(t) + \Gamma_{vv}^u v'(t)^2 = 0 \\ v''(t) + \Gamma_{uu}^v u'(t)^2 + 2\Gamma_{uv}^v u'(t)v'(t) + \Gamma_{vv}^v v'(t)^2 = 0 \end{cases} \quad \begin{matrix} \text{Ecuaciones} \\ \text{geodésicas} \end{matrix}$$

$$\Gamma_{uu}^u = 0$$

$$\Gamma_{uu}^v = 0$$

$$\begin{pmatrix} \Gamma_{uu}^u & \Gamma_{uv}^u & \Gamma_{vv}^u \\ \Gamma_{uu}^v & \Gamma_{uv}^v & \Gamma_{vv}^v \end{pmatrix} = \begin{pmatrix} E & F \\ F & G \end{pmatrix}^{-1} \begin{pmatrix} \frac{1}{2} E_u & \frac{1}{2} E_v & F_v - \frac{1}{2} G_u \\ F_u - \frac{1}{2} E_v & \frac{1}{2} G_u & \frac{1}{2} G_v \end{pmatrix}$$

$$E = 1 \Rightarrow E_u = 0 \quad E_v = 0$$

$$F = \frac{2}{v} \Rightarrow F_v = 0$$

$$\alpha'(t) = X_u(t, v_0) \quad \|\alpha'(t)\| = \sqrt{E} = 1$$

$$\beta(t) = X(u(t), v(t)) \quad \beta'(t) = X(u(t), v(t)) \quad \beta(0) = X(1, e)$$

$$u(0) = 1 \quad v(0) = e$$

$$\beta'(t) = u' X_u + v' X_v \quad \langle \beta'(t), X_u(\beta(t)) \rangle = 0 = E u' + F v' = u' + \frac{v'}{v} = 0$$

$$u + \ln v = \text{cte.}$$

$$u = 2 - \log v = \log \frac{e^2}{v} = h(v)$$

$$\Rightarrow 1 + \log e = c$$

$$c = 2$$

4. Demostrar que no existe una superficie $X(u,v)$ tal que $E=G=1$, $F=0$ y $e=1$, $f=0$, $g=-1$

$$\bar{K} = \frac{-1}{2\sqrt{EG}} \left[\left(\frac{E_v}{\sqrt{EG}} \right)_v + \left(\frac{G_u}{\sqrt{EG}} \right)_u \right] = 0 \quad \left(\text{usando esta fórmula de } F=0 \right)$$

$$\bar{K} = \frac{eg-f^2}{EG-F^2} = \frac{-1}{1} = -1 \quad \leftarrow \text{contradicción}$$

5. Decidir si existe una superficie $X(u,v)$ tal que $E=1$, $F=0$, $G=\cos^2 u$ y $e=\cos^2 u$, $f=0$, $g=1$.

$$K = (1^{\text{a}} \text{ fórmula}) = 1$$

$$K = \frac{eg-f^2}{EG-F^2} = 1 \quad \leftarrow \text{no hemos encontrado}$$

Opción 1: se han equivocado y $g=-1$ (fácil llegar a una contr.)

Opción 2: utilizar las ecuaciones de compatibilidad
 \rightarrow que solo sabemos que existen.

FÓRMULA IMPORTANTE:

$$\bar{K} = \frac{1}{EG-F^2} \left[F_{uv} - \frac{1}{2} E_w - \frac{1}{2} G_{uu} - \begin{pmatrix} \frac{1}{2} E_u & F_u - \frac{1}{2} E_v \end{pmatrix} \begin{pmatrix} E & F \\ F & G \end{pmatrix}^{-1} \begin{pmatrix} F_v - \frac{1}{2} G_v \\ \frac{1}{2} G_v \end{pmatrix} + \begin{pmatrix} \frac{1}{2} E_v & \frac{1}{2} G_u \end{pmatrix} \begin{pmatrix} E & F \\ F & G \end{pmatrix}^{-1} \begin{pmatrix} \frac{1}{2} E_v \\ \frac{1}{2} G_u \end{pmatrix} \right]$$

#9-E3

$$\bar{F}_\Phi = \frac{1}{2u} \quad G_\Phi = u^2 \quad a = \frac{1}{\sqrt{2u}} \quad b = u$$

$$b_u = 1 \quad (\sqrt{2u})_u = \frac{1}{\sqrt{2u}} = \frac{1}{\sqrt{2u}}$$

$$K_\Phi = \frac{-1}{\frac{1}{\sqrt{2u}} \cdot u} \left[\left(\frac{a_v}{b} \right)_v + \left(\frac{b_u}{a} \right)_u \right] =$$

$$= \frac{-1}{\frac{1}{\sqrt{2u}} \cdot u} \left(\frac{1}{\sqrt{2u}} \right) = \frac{-1}{u}$$

$$\bar{F}_\Psi = \frac{1}{2u} \quad G_\Psi = \frac{1}{2u} \quad a = \frac{1}{\sqrt{2u}} \quad b = \frac{1}{\sqrt{2u}}$$

$$a_v = 0$$

$$b_u = -\frac{2}{2\sqrt{2u}} = \frac{-1}{\sqrt{2u}} = \frac{-1}{2u\sqrt{2u}}$$

$$\frac{b_u}{a} = \frac{\frac{-1}{2u\sqrt{2u}}}{\frac{1}{\sqrt{2u}}} = \frac{-1}{2u} \xrightarrow{du} \frac{+1 \cdot 2}{4u^2} = \frac{1}{2u^2}$$

$$K_\Psi = \frac{-1}{\frac{1}{2u}} \left[\frac{1}{2u^2} \right] = \frac{-2u}{2u^2} = \frac{-1}{u}$$

$$u = u(\bar{u}, \bar{v})$$

$$v = v(\bar{u}, \bar{v})$$

$$\rightarrow \boxed{u = \bar{u}}$$

$$\frac{1}{2u} (du)^2 + u^2 (dv)^2$$

$$dv = V_{\bar{u}} \bar{u}' + V_{\bar{v}} \bar{v}'$$

$$\frac{1}{2\bar{u}} (d\bar{u})^2 + \bar{u}^2 \left(V_{\bar{u}} \bar{u}' + V_{\bar{v}} \bar{v}' \right)^2 = \frac{1}{2\bar{u}} (d\bar{u})^2 + \bar{u}^2 \left(V_{\bar{u}}^2 \bar{u}'^2 + V_{\bar{v}}^2 \bar{v}'^2 + 2V_{\bar{u}} \bar{u}' V_{\bar{v}} \bar{v}' \right)$$

$$= \frac{1}{2\bar{u}} (d\bar{u})^2 + \bar{u}^2 V_{\bar{u}}^2 d\bar{u}^2 + \bar{u}^2 V_{\bar{v}}^2 d\bar{v}^2 + 2V_{\bar{u}} V_{\bar{v}} d\bar{u} d\bar{v}$$

$$+ 2V_{\bar{u}} V_{\bar{v}} d\bar{u} d\bar{v} + \bar{u}^2 V_{\bar{v}}^2 d\bar{v}^2 = \left(\frac{1}{2\bar{u}} + \bar{u}^2 V_{\bar{u}}^2 \right) d\bar{u}^2 + 2V_{\bar{u}} V_{\bar{v}} d\bar{u} d\bar{v} + \bar{u}^2 V_{\bar{v}}^2 d\bar{v}^2$$

$$= \frac{1}{2\bar{u}} d\bar{u}^2 + \frac{1}{2\bar{u}} d\bar{v}^2$$

$$\bar{u}^2 V_{\bar{u}}^2 = 0 \rightarrow V_{\bar{u}}^2 = 0 \rightarrow V \text{ no depende de } \bar{u}$$

Contradiction

$$\bar{u}^2 V_{\bar{v}}^2 = \frac{1}{2\bar{u}} \Rightarrow V_{\bar{v}}^2 = \frac{1}{2\bar{u}^3} \Rightarrow V_{\bar{v}} = \sqrt{\frac{1}{2\bar{u}^3}} \Rightarrow V \text{ depende de } \bar{u}$$

