[48.]
$$\Omega = \{x \in \mathbb{R}^3 : x_1 + x_2 + x_3 \neq -1 \}$$

$$f: \Omega \subset \mathbb{R}^3 \longrightarrow \mathbb{R}^3$$
 augas componentes son:

$$f_1(x) = \frac{x_i}{1 + x_1 + x_2 + x_3} \qquad x \in \Omega$$

$$f(x) = f(y) = 0 \frac{x_1}{1 + x_1 + x_2 + x_3} = \frac{y_i}{1 + y_1 + y_2 + y_3}$$
 $i = 4, 2, 3$

Sumo en i:
$$\frac{X_1+X_2+X_3}{1+X_1+X_2+X_3} = \frac{Y_1+Y_2+Y_3}{1+Y_1+Y_2+Y_3}$$

$$\underbrace{\Lambda - \left(\begin{array}{c} 11 \\ \end{array}\right)}_{11} = \underbrace{\Lambda - \left(\begin{array}{c} 11 \\ \end{array}\right)}_{11}$$

$$\frac{1}{1+X_1+X_2+X_3} = \frac{1}{1+y_1+y_2+y_3} = \frac{1}{1+X_1+X_2+X_3=1+y_1+y_2+y_3}$$

Como
$$\frac{x_1}{1+X_1+X_2+X_3} = \frac{y_1}{1+y_1+y_2+y_3} = 0 \quad x_1 = y_1$$
son iguales por (x)

2)
$$\int f(x) = \frac{\partial x_i}{\partial x_j} = 1$$
 cuando $i=j$ of 0 cuando $i\neq j$

$$\frac{\partial f}{\partial x_{i}} = \frac{\int_{ij}^{i} (1 + X_{1} + X_{2} + X_{3}) - X_{1} \cdot 1}{(1 + X_{1} + X_{2} + X_{3})^{2}}$$

$$\int f(x) = \begin{cases} \frac{1+x_2+x_3}{(1+x_1+x_2+x_3)^2} & \frac{-x_1}{(1)^2} & \frac{-x_1}{(1)^2} \\ \frac{-x_2}{(1)^2} & \frac{1+x_1+x_3}{(1)^2} & \frac{-x_2}{(1)^2} \\ \frac{-x_3}{(1)^2} & \frac{-x_3}{(1)^2} & \frac{1+x_1+x_2}{(1)^2} \end{cases}$$

Supongamos
$$(y_1, y_2, y_3) \in f(\Omega)$$

$$y_i = \frac{x_i}{1 + \sum_{j=1}^{3} x_j}$$

$$\int_{1}^{3} \frac{1}{1} + y_{2} + y_{3} = \frac{\int_{1}^{3} x_{j}}{1 + \int_{1}^{3} x_{j}}$$

$$1 + \int_{1}^{3} x_{j}$$

$$f(\Omega)$$
 no contiene puntos (y_1, y_2, y_3) con $y_1 + y_2 + y_3 = 1$

Parece que
$$f(\Omega) = \mathbb{R}^3 \setminus \{y_1 + y_2 + y_3 = 1\}$$

$$-P \quad 1 - \frac{3}{4}y_j = 1 - \frac{\sum x_j}{1 + \sum x_j} = \frac{1 + \sum x_j - \sum x_j}{1 + \sum x_j} = \frac{1}{1 + \sum x_j} = \frac{1}{1 + \sum x_j}$$

$$\Rightarrow 1 + \sum_{j=1}^{3} x_{j} = \frac{1}{1 + \sum_{j=1}^{3} y_{j}} \Rightarrow 0$$

$$X_{1} = \frac{y_{1}}{1 - \sum y_{j}}$$

$$X_{2} = \frac{y_{2}}{1 - \sum y_{j}}$$

$$X_{3} = \frac{y_{3}}{1 - \sum y_{j}}$$

Lo demuestro:

$$f(x_1, x_2, x_3) = f(\frac{y_1}{1-\Sigma}, \dots, \dots) = (y_1, y_2, y_3)$$

$$f^{-1}(y_1,...,y_3) = \left(\frac{y_1}{1-\Sigma},...,\frac{y_3}{1-\Sigma}\right) \rightarrow Down f^{-1} = f(\Omega)$$

49.1 (oordenadas polares $C = \{(r, \theta) \mid r > 0, \theta \in (-\pi, \pi)\}$ $\Omega = \mathbb{R}^2 \setminus \{(x_{1,0}) \mid x_1 \in 0\}$ $f: C \longrightarrow SZ$, $f(r_1\theta) = (rcos\theta, rsen\theta)$ 1. f biyectiva de f en sz. 1.1. Inyectiva $r^2 = (r\cos\theta)^2 + (r\sin\theta)^2 = (\bar{r}\cos\bar{\theta})^2 + (\bar{r}\sin\bar{\theta})^2 = \bar{r}^2 \implies r = \pm \bar{r}$ pero como en C ry $\overline{r} > 0 \Rightarrow \overline{r} = \overline{r}$ ya que r=r>0 $rcos\theta = \overline{r}cos\overline{\theta}$ $cos\theta = cos\overline{\theta}$ $rsen\theta = \overline{r}sen\overline{\theta}$ $sen\theta = sen\overline{\theta}$ Pero $-\Pi < \theta, \bar{\theta} < \Pi$ como el intervalo es de longitud $< 2\Pi$, un angulo quedo deferminado de forma unívoca por su coseno y su seno $\Rightarrow \theta = \overline{\theta}$. 1.2. Sobreyective $x_1 = r\cos\theta$ Sea $(x_1, x_2) \in \Omega$. Necesito $r_1\theta$ tal que Xz = (seu 0

Con r>0, - π < θ < Π.

= Necenito $r = \sqrt{X_1^2 + X_2^2}$, y además r > 0 y como $(X_1, X_2) \in \Omega$ y (0,0) \$ \$2 => r>0.

Ahora necesito O.

 $\left(\frac{X_{1}}{r}\right)^{2} + \left(\frac{X_{2}}{r}\right)^{2} = 1 \implies \exists \theta \in (-\Pi, \Pi) \text{ fal que } \cos\theta = \frac{X_{1}}{r}, \text{ sen}\theta = \frac{X_{2}}{r}$

Si $\theta = \pi$, $\mathcal{L} = \cos \theta = -1$ $\Rightarrow x_1 < 0$ $\Rightarrow D(x_1 x_2) \notin \Omega$ $\Rightarrow D(x_1 x_2) \notin \Omega$ $\frac{X_2}{r} = \operatorname{Sen}\theta = 0 \implies X_2 = 0$ → 0 ≠ 17 siempre

 $\Rightarrow \theta \in (-\pi, \pi)$

2.
$$g: \Omega \rightarrow C$$
, $g = f$ ($f: C \rightarrow \Omega$ biyertiva)

2.1. g es differenciable

 f es C^{∞}
 $Df(r, \theta) = \begin{vmatrix} \cos \theta & -r \cos \theta \\ \sin \theta & r \cos \theta \end{vmatrix}$
 $Df(r, \theta) = \begin{vmatrix} \cot \theta & -r \cos \theta \\ \cos \theta & r \cos \theta \end{vmatrix}$
 $Df(r, \theta) = \begin{vmatrix} \cot \theta & -r \cos \theta \\ \cos \theta & r \cos \theta \end{vmatrix}$
 $Df(r, \theta) = \begin{vmatrix} \cot \theta & -r \cos \theta \\ \cos \theta & r \cos \theta \end{vmatrix}$
 $Df(r, \theta) = \begin{vmatrix} \cot \theta & -r \cos \theta \\ \cos \theta & r \cos \theta \end{vmatrix}$
 $Df(r, \theta) = \begin{vmatrix} \cot \theta & -r \cos \theta \\ \cos \theta & r \cos \theta \end{vmatrix}$
 $Df(r, \theta) = \begin{vmatrix} \cot \theta & -r \cos \theta \\ \cos \theta & r \cos \theta \end{vmatrix}$
 $Df(r, \theta) = \begin{vmatrix} \cot \theta & -r \cos \theta \\ \cos \theta & r \cos \theta \end{vmatrix}$
 $Df(r, \theta) = \begin{vmatrix} \cot \theta & -r \cos \theta \\ \cos \theta & r \cos \theta \end{vmatrix}$
 $Df(r, \theta) = \begin{vmatrix} \cot \theta & -r \cos \theta \\ \cos \theta & r \cos \theta \end{vmatrix}$
 $Df(r, \theta) = \begin{vmatrix} \cot \theta & -r \cos \theta \\ \cos \theta & r \cos \theta \end{vmatrix}$
 $Df(r, \theta) = \begin{vmatrix} \cot \theta & r \cos \theta \\ \cos \theta & r \cos \theta \end{vmatrix}$
 $Df(r, \theta) = \begin{vmatrix} \cot \theta & r \cos \theta \\ \cos \theta & r \cos \theta \end{vmatrix}$
 $Df(r, \theta) = \begin{vmatrix} \cot \theta & r \cos \theta \\ \cos \theta & r \cos \theta \end{vmatrix}$
 $Df(r, \theta) = \begin{vmatrix} \cot \theta & r \cos \theta \\ \cos \theta & r \cos \theta \end{vmatrix}$
 $Df(r, \theta) = \begin{vmatrix} \cot \theta & r \cos \theta \\ \cos \theta & r \cos \theta \end{vmatrix}$
 $Df(r, \theta) = \begin{vmatrix} \cot \theta & r \cos \theta \\ \cos \theta & r \cos \theta \end{vmatrix}$
 $Df(r, \theta) = \begin{vmatrix} \cot \theta & r \cos \theta \\ \cos \theta & r \cos \theta \end{vmatrix}$
 $Df(r, \theta) = \begin{vmatrix} \cot \theta & r \cos \theta \\ \cos \theta & r \cos \theta \end{vmatrix}$
 $Df(r, \theta) = \begin{vmatrix} \cot \theta & r \cos \theta \\ \cos \theta & r \cos \theta \end{vmatrix}$
 $Df(r, \theta) = \begin{vmatrix} \cot \theta & r \cos \theta \\ \cos \theta & r \cos \theta \end{vmatrix}$
 $Df(r, \theta) = \begin{vmatrix} \cot \theta & r \cos \theta \\ \cos \theta & r \cos \theta \end{vmatrix}$
 $Df(r, \theta) = \begin{vmatrix} \cot \theta & r \cos \theta \\ \cos \theta & r \cos \theta \end{vmatrix}$
 $Df(r, \theta) = \begin{vmatrix} \cot \theta & r \cos \theta \\ \cos \theta & r \cos \theta \end{vmatrix}$
 $Df(r, \theta) = \begin{vmatrix} \cot \theta & r \cos \theta \\ \cos \theta & r \cos \theta \end{vmatrix}$
 $Df(r, \theta) = \begin{vmatrix} \cot \theta & r \cos \theta \\ \cos \theta & r \cos \theta \end{vmatrix}$
 $Df(r, \theta) = \begin{vmatrix} \cot \theta & r \cos \theta \\ \cos \theta & r \cos \theta \end{vmatrix}$
 $Df(r, \theta) = \begin{vmatrix} \cot \theta & r \cos \theta \\ \cos \theta & r \cos \theta \end{vmatrix}$
 $Df(r, \theta) = \begin{vmatrix} \cot \theta & r \cos \theta \\ \cos \theta & r \cos \theta \end{vmatrix}$
 $Df(r, \theta) = \begin{vmatrix} \cot \theta & r \cos \theta \\ \cos \theta & r \cos \theta \end{vmatrix}$
 $Df(r, \theta) = \begin{vmatrix} \cot \theta & r \cos \theta \\ \cos \theta & r \cos \theta \end{vmatrix}$
 $Df(r, \theta) = \begin{vmatrix} \cot \theta & r \cos \theta \\ \cos \theta & r \cos \theta \end{vmatrix}$
 $Df(r, \theta) = \begin{vmatrix} \cot \theta & r \cos \theta \\ \cos \theta & r \cos \theta \end{vmatrix}$
 $Df(r, \theta) = \begin{vmatrix} \cot \theta & r \cos \theta \\ \cos \theta & r \cos \theta \end{vmatrix}$
 $Df(r, \theta) = \begin{vmatrix} \cot \theta & r \cos \theta \\ \cos \theta & r \cos \theta \end{vmatrix}$
 $Df(r, \theta) = \begin{vmatrix} \cot \theta & r \cos \theta \\ \cos \theta & r \cos \theta \end{vmatrix}$
 $Df(r, \theta) = \begin{vmatrix} \cot \theta & r \cos \theta \\ \cos \theta & r \cos \theta \end{vmatrix}$
 $Df(r, \theta) = \begin{vmatrix} \cot \theta & r \cos \theta \\ \cos \theta & r \cos \theta \end{vmatrix}$
 $Df(r, \theta) = \begin{vmatrix} \cot \theta & r \cos \theta \\ \cos \theta & r \cos \theta \end{vmatrix}$
 $Df(r, \theta) = \begin{vmatrix} \cot \theta & r \cos \theta \\ \cos \theta & r \cos \theta \end{vmatrix}$
 $Df(r, \theta) = \begin{vmatrix} \cot \theta & r \cos \theta \\ \cos \theta & r \cos \theta \end{vmatrix}$
 $Df(r, \theta) = \begin{vmatrix} \cot \theta & r \cos \theta \\ \cos \theta & r \cos \theta \end{vmatrix}$
 $Df(r, \theta) = \begin{vmatrix} \cot \theta & r \cos \theta \\ \cos \theta & r \cos \theta \end{vmatrix}$
 $Df(r, \theta) = \begin{vmatrix} \cot \theta & r \cos \theta \\ \cos \theta & r \cos \theta \end{vmatrix}$
 $Df(r,$

3.
$$g(x) = (||x||, 2 \arctan \frac{x_2}{||x|| + x_1})$$

$$g(x_1, x_2) = (r_1\theta) \quad \text{fal} \quad x_1 = r \cos \theta$$

$$x_2 = r \sec \theta$$

$$r > 0, \quad \theta \in (-\pi, \pi)$$

$$\frac{1}{\sqrt{x_1^2 + x_2^2}} = ||x|| > 0$$

$$Q = 2 \arctan\left(\frac{x_2}{||x|| + x_1}\right) \in \left(-\frac{\pi}{2}, \frac{\pi}{2}\right)$$

$$Q = -\frac{x_2}{||x|| + x_1} \in \left(-\pi, \pi\right)$$

$$Q = -\frac{x_2}{||x|| + x_1} \in \left(-\pi, \pi\right)$$

$$F(x,y) = \left(\frac{-y}{x^2 + y^2}, \frac{x}{x^2 + y^2}\right)$$

$$\frac{\partial}{\partial x_1} F_2 = \frac{\partial}{\partial x_2} F_1?$$

$$C: c(t) = (cost, sent) \quad t \in [0, 2\pi]$$

$$\int_{C} Fds = \int_{0}^{2\pi} F(c(t)) \cdot c'(t) dt = \int_{0}^{2\pi} \langle F(c(t)), c'(t) \rangle dt =$$

$$= \int_0^{2\pi} 1 dt = 2\pi$$

Supongamos que si
$$F = \nabla U = (\frac{\partial U}{\partial x}, \frac{\partial U}{\partial y})$$

$$\int_{C} F ds = \int_{C} \nabla U = \int_{0}^{2\pi} \nabla U(cCt) \cdot c'(t) dt = \int_{0}^{2\pi} \frac{d}{dt} \left(U(cCt) \right) =$$

$$= \bigcup (C(2\pi)) - \bigcup (C(0)) = \bigcup ((1,0)) - \bigcup (1,0) = 0 \quad (anter = 2\pi)$$

$$= \underbrace{\bigcup (C(2\pi)) - \bigcup (C(0))}_{\text{contradicción}} = \underbrace{\bigcup ((1,0)) - \bigcup ((1,0))}_{\text{contradicción}}$$

F:
$$\Omega = |R^2| \gamma(x_{1,0})$$
, $x_1 \leq 0$ θ es C^1 en Ω

$$C = \{r>0, -\pi < \theta < \pi\}$$
 $f > (rcos\theta, rsen \theta)$

$$(r(x,y), \theta(x,y))$$
 $= g$ $(x,y) \in \Omega$

Ver que
$$F(x) = \nabla \beta(x)$$

$$\left(\frac{\partial \theta}{\partial x_1}, \frac{\partial \theta}{\partial x_2}\right)$$

problème 49

 $\theta = \arctan\left(\frac{x_2}{\|x\| + x_4}\right)$

Ver que
$$F(x) = \nabla \beta(x)$$

[51]
$$f: \mathbb{R}^2 \longrightarrow \mathbb{R}^2$$
 $f(x_1, x_2) = (x_1^2 - x_2^2, 2x_1x_2)$

a. f no es inyectiva en \mathbb{R}^2 .

 $f(a_1, a) = f(a_1, a) \implies$ no es inyectiva

 f es inyectiva en $\Omega = \frac{1}{2}x_1 > 0$
 $f(x_1, x_2) = f(y_1, y_2)$ con $x_1, y_1 > 0$
 $x_1^2 - x_2^2 = y_1^2 - y_2^2$
 $f(x_1, x_2) = f(y_1, y_2)$
 $f(x_1, x_2) = f(x_1, y_2)$
 $f(x$

| VEI que | 2 | 0 | $x + \sqrt{x^2 + y^2} > 0$ | $x + \sqrt{x^2 + y^2} > 0$ | $x + \sqrt{x^2 + y^2} = x + |x| = 0$ | $x + \sqrt{x^2 + y^2} = x + |x| = 0$ | $x + \sqrt{x^2 + y^2} = x + |x| = 0$ | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 | x = 0 |

$$(y_1, y_2) = \left(\frac{\operatorname{sen} x_1}{\cos x_2}, \frac{\operatorname{sen} x_2}{\cos x_1}\right)$$

$$y_1 = \frac{\text{Sen } X_1}{\cos X_2}$$

Sen
$$x_1 = y_1 \cos x_2$$

 $x_1 = \operatorname{arcseu}(y_1, \cos x_2)$

Sen
$$X_1 = Y_1 \cdot \cos\left(\arccos\left(\frac{to!}{pesca}\right)\right)$$

$$(1 = \arcsin \left(y_1 \cdot \sqrt{\frac{y_2^2 - 1}{y_2^2 y_4^2 - 1}} \right)$$

$$y_2 = \frac{\operatorname{sen} X_2}{\cos X_1} = \frac{\operatorname{sen} X_2}{\sqrt{1 - \operatorname{sen}^2 X_1}}$$

$$\sqrt{1-\text{Sen}^2(\text{arcseu}(y_1,\cos x_2))}$$

$$= y_2^2 = \frac{\sin^2 X_2}{1 - y_1^2 \cos^2 X_2}$$

$$y_2^2 = \frac{1 - \cos^2 x_2}{1 - y_1^2 \cos^2 x_2}$$

$$y_2^2 - y_2^2 y_1^2 \cos^2 X_2 = 1 - \cos^2 X_2$$

$$y_2^2 - 1 = \cos^2 \chi_2 (y_2^2 y_1^2 - 1)$$

$$\cos^2 \chi_2 = \frac{y_2^2 - 1}{y_2^2 y_1^2 - 1}$$

$$\cos^{2} X_{2} = \frac{y_{2}^{2} - 1}{y_{2}^{2} y_{4}^{2} - 1}$$

$$= P X_{2} = \arccos \left(\frac{y_{2}^{2} - 1}{y_{2}^{2} y_{4}^{2} - 1} \right)$$

