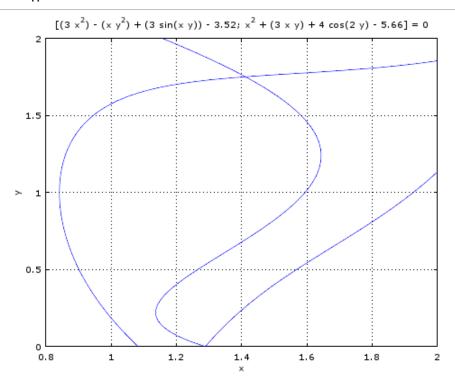
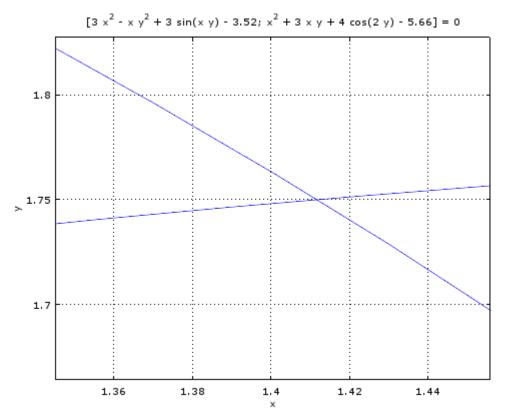
Giuseppe Ragusa. CI:28.224.758 Michael Wu. CI:25.847.074 Isabella Guzmán. CI:27.942.264

1.





Intervalo seleccionado:  $X^{(0)} = [1.4, 1.7]$ 

Iteraciones	Jac	F0	dx	Error
1	1.8189 -7.8000 7.9001 6.2451	0.38422 -0.42719	0.012779 0.052239	0.052239
2	1.2732 -8.2838 8.0824 7.0789	-0.016190 0.023018	-0.0010013 -0.0021083	0.0021083
3	1.2949 -8.2596 8.0740 7.0443	-3.7105e-005 4.2274e-005	-1.1581e-006 -4.6739e-006	4.6739e-006
4	1.2950 -8.2595 8.0740 7.0442	-1.6395e-009 3.7981e-009	-2.6146e-010 -2.3950e-010	2.6146e-010
5	1.2950 -8.2595 8.0740 7.0442	-7.6383e-014 2.0428e-013	-1.5159e-014 -1.1625e-014	1.5159e-014

ans =

1.4118

1.7501

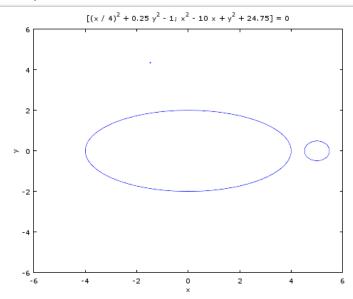
Este es el resultado final luego de las 5 iteraciones

### 2.a)

Se define la función para a=4 y se gráfica en el intervalo [6,-6]

```
>> F= @(x,y)[(x/4).^2+0.25*y.^2-1;x.^2-10*x+y.^2+24.75]
F =
@(x, y) [(x / 4) .^ 2 + 0.25 * y .^ 2 - 1; x .^ 2 - 10 * x + y .^ 2 + 24.75]
>> ezplot(F,[-6,6])
```

## Gráfica para a=4



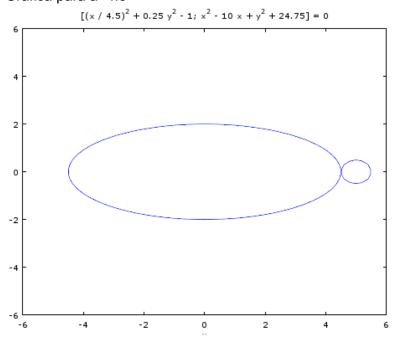
## Se define la función para a=4.5 y se gráfica en el intervalo [6,-6]

>> F=  $\emptyset$  (x,y) [(x/4.5).^2+0.25\*y.^2-1;x.^2-10\*x+y.^2+24.75] F =

@(x, y) [(x / 4.5) .^ 2 + 0.25 \* y .^ 2 - 1; x .^ 2 - 10 \* x + y .^ 2 + 24.75]

>> ezplot(F,[-6,6])

### Gráfica para a=4.5

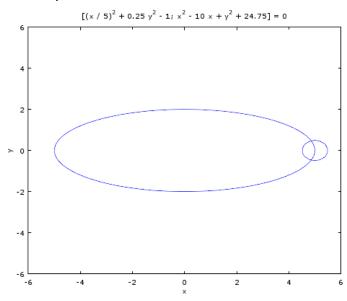


## Se define la función para a=5 y se gráfica en el intervalo [6,-6]

```
>> F= @(x,y)[(x/5).^2+0.25*y.^2-1;x.^2-10*x+y.^2+24.75]
F =

@(x, y) [(x / 5) .^ 2 + 0.25 * y .^ 2 - 1; x .^ 2 - 10 * x + y .^ 2 + 24.75]
>> ezplot(F,[-6,6])
```

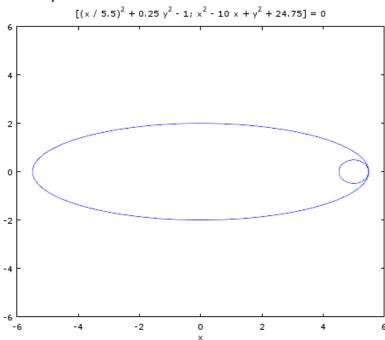
#### Gráfica para a=5



## Se define la función para a=5.5 y se gráfica en el intervalo [6,-6]

```
>> F= @(x,y)[(x/5.5).^2+0.25*y.^2-1;x.^2-10*x+y.^2+24.75]
F =
@(x, y) [(x / 5.5) .^ 2 + 0.25 * y .^ 2 - 1; x .^ 2 - 10 * x + y .^ 2 + 24.75]
>> ezplot(F,[-6,6])
```

### Gráfica para a=5.5

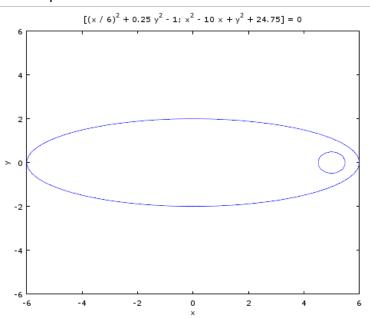


# Se define la función para a=6 y se gráfica en el intervalo [6,-6]

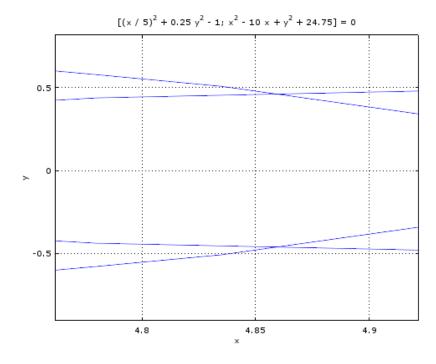
```
>> F= @(x,y)[(x/6).^2+0.25*y.^2-1;x.^2-10*x+y.^2+24.75]
F =

@(x, y) [(x / 6).^2 + 0.25 * y .^2 - 1; x .^2 - 10 * x + y .^2 + 24.75]
```

## Gráfica para a=6



Se tomó la gráfica para la cual a=5 ya que es la única que da 2 soluciones Raíz 1 (4.86,0.49) Raíz 2 (4.86,-0.49)



# Iteraciones de la primera raíz (4.86,0.49)

```
raiz =

4.85482
0.47846

niter = 4
```

#### Iteración 1

```
jac =
    0.38880    0.24502
    -0.27990    0.98010

f0 =
    0.0048090
    0.0097000

dx =
    -0.0051964
    -0.0113810

x =
    4.85480
    0.47862
error = 0.011381
```

```
jac =
    0.38839    0.23933
    -0.29029    0.95734

f0 =
    3.3767e-005
    1.5819e-004

dx =
    1.2538e-005
    -1.6143e-004

x =
    4.85482
    0.47846
error = 1.6143e-004
```

### Iteración 3

```
jac =
    0.38839    0.23925
    -0.29027    0.95702

f0 =
    1.0507e-008
    4.1108e-008

dx =
    -4.9959e-010
    -4.3105e-008

x =
    4.85482
    0.47846

error = 4.3105e-008
```

```
jac =
    0.38839    0.23925
    -0.29027    0.95702

f0 =
    1.0800e-012
    4.3663e-012

dx =
    2.5049e-014
    -4.5548e-012

x =
    4.85482
    0.47846

error = 4.5548e-012
```

# Iteraciones de la segunda raíz (4.86,-0.49)

```
raiz =

4.85482
-0.47846

niter = 3
```

#### Iteración 1

```
jac =
    0.38880   -0.24498
    -0.27990   -0.97990

f0 =
    0.0048090
    0.0097000

dx =
    -0.0051964
    0.0113833

x =
    4.85480
    -0.47862
error = 0.011383
```

```
jac =
    0.38839    -0.23928
    -0.29029    -0.95713

f0 =
    3.3211e-005
    1.5596e-004

dx =
    1.2538e-005
    1.5915e-004

x =
    4.85482
    -0.47846
error = 1.5915e-004
```

```
jac =
    0.38839    -0.23920
    -0.29027    -0.95682

f0 =
    2.3093e-009
    8.3160e-009

dx =
    -4.9959e-010
    8.8429e-009

x =
    4.85482
    -0.47846
error = 8.8429e-009
```

```
3) X^{(0)} = (1,1,1)^T
```

#### Iteración #1:

```
>> g
 \theta \left( \textbf{x}, \ \textbf{y}, \ \textbf{z} \right) \ \left[ \ \left( \textbf{x} \ .^{^{\wedge}} \ 2 \right) \ - \ \left( 2 \ ^{\times} \ \exp \left( \textbf{y} \right) \right) \ - \ \left( 5 \ ^{\times} \ \textbf{z} \right) ; \ \left( \textbf{x} \ .^{\times} \ \textbf{y} \right) \ + \ \left( \textbf{z} \ .^{^{\wedge}} \ 2 \right) \ + \ \sin \left( \textbf{y} \ .^{^{\wedge}} \ 2 \right) \ - \ 1; \ \left( 2 \ ^{\times} \ \textbf{x} \right) \ + \ \left( \textbf{y} \ .^{^{\wedge}} \ 2 \right) \ - \ \textbf{z} 
>> newtonRaphson3x3(g,[1;1;1],(10^-10))
iac =

    2.00009999998849
    -5.436835494165848
    -5.000000000006111

    0.99999999997669
    2.080490323730366
    2.000099999994731

    1.9999999999999
    2.000099999999172
    -0.9999999999999

f0 =
     -9.43656365691809
     1.84147098480790
     -1.000000000000000
      1.030964098861995
     -0.821655612538239
     -0.581465192913353
      2.030964098861995
       0.178344387461761
      0.418534807086647
error = 1.03096409886200
```

#### Iteración #2:

```
jac =
   4.062028197733270 -2.390593277588060 -5.000000000001670
                        2.387572210712507 0.837169614172906
0.356788774924510 -1.000000000002110
   0.178344387461449
   2.000000000004221
f0 =
  -0.358332614481580
  -0.430816209248950
   0.675200111176454
dx =
  -1.152529057834209
   0.744837514433040
  -1.364108340201569
x =
   0.878435041027786
   0.923181901894801
  -0.945573533114922
error = 1.36410834020157
```

#### Iteración #3:

```
jac =
    4.062028197733270 -2.390593277588060 -5.000000000001670
                          2.387572210712507 0.837169614172906
    0.178344387461449
    2.00000000004221 0.356788774924510 -1.000000000002110
f0 =
  -0.358332614481580
  -0.430816209248950
    0.675200111176454
dx =
  -1.152529057834209
   0.744837514433040
  -1.364108340201569
x =
   0.878435041027786
    0.923181901894801
  -0.945573533114922
error = 1.36410834020157
Iteración #4:
jac =
   2.376174513467610 -3.581171357884827 -5.000000000001670
0.582492760861086 2.286677032625750 -0.801361659628075
2.000000000004221 1.165085521721565 -1.000000000002110
f0 =
  -0.165905629846542
   0.185433322809900
   0.116103159734301
dx =
  -0.00707226307358878
  -0.07361892768221953
  0.01618628681983812
x =
   1.180964993658859
   0.508873833178063
  -0.384544542994932
```

error = 0.0736189276822195

#### Iteración #5:

```
jac =
  2.362029987317271 -3.327000056949636 -4.999999999997229
  0.508873833178214 2.164863049538557 -0.768989085990768
  1.99999999999780 1.017847666355820 -0.99999999997669
f0 =
 -0.00943267850002316
  0.00490488174265069
  0.00542710840598559
dx =
 -0.00230962129361424
 -0.00224891471396646
 -0.00148118677468987
x =
  1.178655372365245
  0.506624918464096
 -0.386025729769622
error = 0.00230962129361424
Iteración #6:
jac =
  2.357410744731059 -3.319526324609967 -4.999999999999449
  0.506624918465981 2.158795845437211 -0.771951459538345
  1.9999999999780 1.013349836926913 -1.000000000002110
f0 =
 -3.21541098080580e-006
  1.19468668624556e-005
 5.28250886455695e-006
dx =
 1.31159264735086e-006
 -4.72819180979423e-006
 3.11438175983766e-006
x =
  1.178656683957892
  0.506620190272287
 -0.386022615387862
error = 4.72819180979423e-006
```

#### Iteración #7:

```
jac =
    2.357413367917172    -3.319510629293809    -4.99999999999449
    0.506620190272589    2.158789243318360    -0.771945230775284
    1.999999999999339    1.013340380540129    -1.000000000002110

f0 =
    -9.51296819096115e-010
    1.06464170812615e-010
    4.95175456194374e-010

dx =
    -3.65804453189836e-010
    -7.53000086470254e-011
    -3.12737989599984e-010

x =
    1.178656683592088
    0.506620190196987
    -0.386022615700600

error = 3.65804453189836e-010
```

```
X^{(0)} = [-1, -1, -1]^T
```

Error menor a 0,01% = 0,0001

error = 1.09506063455859

```
Iteración #1:
```

```
jac =
 -1.99989999995947 -0.735795671511497 -4.999999999997229
 -1.000000000002110 -2.080718851669161 -1.999900000004828
  1.99999999999780 -1.99990000000387 -0.99999999997669
f0 =
  5.26424111765712
  1.84147098480790
  -3.000000000000000
dx =
  1.449257335625956
 -0.310167284489561
  0.518818223503594
x =
  0.449257335625956
 -1.310167284489561
 -0.481181776496406
error = 1.44925733562596
Iteración #2:
jac =
  0.898614671251963 -0.539576825291377 -5.000000000001670
 1.9999999995339 -2.620234568979640 -1.000000000002110
f0 =
  2.0681911891969476
 -0.3676679393625730
  0.0962347610950673
dx =
 -1.095060634558591
 -0.919754636204389
  0.316086384744355
 -0.645803298932636
 -2.229921920693950
 -0.165095391752051
```

#### Iteración #3:

```
jac =
  -1.291506597866920 \quad -0.215084406460786 \quad -5.000000000001670
  -2.229921920693378 -1.792057263078073 -0.330090783504655
   1.99999999999780 -4.459743841405128 -0.999999999997669
f0 =
   1.027465207254976
  -0.499000693546390
   0.846040566278174
dx =
 -0.27005713382418900
   0.00694567344317222
   0.27495037426789826
x =
  -0.915860432756825
  -2.222976247250778
   0.109854982515848
error = 0.274950374267898
Iteración #4:
jac =
 -1.831620865513361 -0.216583512633317 -5.000000000000560
 -2.222976247252539 -1.925138072147448 0.219809965029683
  1.9999999999780 -4.445852494514568 -1.000000000002110
f0 =
 7.29527360725343e-002
  7.41634592846896e-002
 4.75478116537253e-005
dx =
  0.02505306139915991
  0.01016247624326228
  0.00497280025340489
x =
 -0.890807371357665
 -2.212813771007515
  0.114827782769253
```

error = 0.0250530613991599

#### Iteración #5:

-2.212597357353623 0.114794647307749

error = 1.07730672756005e-007

```
jac =
  -1.781514742713597 -0.218795759348023 -5.000000000000560
  -2.212813771007571 -1.700232540280400 0.229755565539502
   1.99999999995339 -4.425527542029073 -1.000000000002110
f0 =
  6.14039276765954e-004
  1.28505120644573e-003
  1.02259675918592e-004
dx =
 4.11054393851829e-004
  2.16355684827412e-004
 -3.31195784578675e-005
x =
  -0.890396316963813
  -2.212597415322688
   0.114794663190795
error = 4.11054393851829e-004
Iteración #6:
jac =
  -1.780692633926995 -0.218843102176569 -5.000000000000560
  -2.212597415323092 -1.695576671968402 0.229689326380900
   1.9999999995339 -4.425094830660115 -1.000000000002110
f0 =
  1.25106116466434e-007
  3.40303768719963e-007
  2.51742191537119e-008
dx =
 1.07730672756005e-007
  5.79690651346996e-008
  -1.58830458005057e-008
x =
  -0.890396209233140
```