

GetEvent(task_id, event_mask_ref)

Get a copy of the event mask of task *task_id*. *event_mask_ref* is a pointer to an `EventMaskType` variable where the copy is written. Returns

E_OK	success
E_OS_ID†	task <i>task_id</i> does not exist
E_OS_ACCESS†	task <i>task_id</i> is not an extended task
E_OS_STATE†	task <i>task_id</i> is in <code>SUSPENDED</code> state

WaitEvent(event_mask) ⌘

If the none of the events in *event_mask* is set in the event mask of the caller, the caller is put in the `WAITING` state. Returns:

E_OK	success
E_OS_ACCESS†	the caller isn't an extended task
E_OS_RESOURCE†	the caller hold a resource
E_OS_CALLEVEL†	the caller is not a task

Resources

DeclareResource(rez_id)

Declare the existence of a resource so that it can be referenced.

GetResource(rez_id)

Get resource *rez_id*. The priority of the caller is raised to the priority of the resource if higher. Returns:

E_OK	success
E_OS_ID†	resource <i>rez_id</i> does not exist
E_OS_ACCESS†	the caller try to get a resource already held

ReleaseResource(rez_id) ⌘

Release resource *rez_id*. The priority of the caller returns to the priority it had before. Returns:

E_OK	success
E_OS_ID†	resource <i>rez_id</i> does not exist
E_OS_NOFUNC†	the caller try to release a resource it does not hold

E_OS_ACCESS†	the caller try to release a resource with a priority lower than the caller one
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Messages

DeclareMessage(mess_id)

Declare the existence of a message so that it can be referenced.

SendMessage(mess_id, data_ref) ⌘

Send message *mess_id*. *data_ref* is a pointer to a variable containing the data to send. Returns:

E_OK	success
E_COM_ID†	message <i>mess_id</i> does not exist or has the wrong type

SendZeroMessage(mess_id) ⌘

Send signalization message *mess_id*. Returns:

E_OK	success
E_COM_ID†	message <i>mess_id</i> does not exist or has the wrong type

ReceiveMessage(mess_id, data_ref)

Receive message *mess_id*. *data_ref* is a pointer to a variable where the data are copied.

E_OK	success
E_COM_ID†	message <i>mess_id</i> does not exist or has the wrong type
E_COM_NOMSG	message <i>mess_id</i> is queued and the queue is empty
E_COM_LIMIT	message <i>mess_id</i> is queued and the queue has overflown

GetMessageStatus(mess_id)

Returns the status of a message:

E_COM_ID†	message <i>mess_id</i> does not exist
E_COM_NOMSG	message <i>mess_id</i> is queued and the queue is empty
E_COM_LIMIT	message <i>mess_id</i> is queued and the queue has overflown
E_OK	none of the above

Data types

<code>StatusType</code>	error code returned by a service
<code>AppModeType</code>	an application mode
<code>TaskType</code>	identifier of a task
<code>TaskStateType</code>	state of a task (<code>SUSPENDED</code> , <code>READY</code> , <code>RUNNING</code> or <code>WAITING</code>)
<code>AlarmType</code>	identifier of an alarm
<code>AlarmBaseType</code>	counter attributes
<code>TickType</code>	number of ticks
<code>EventMaskType</code>	a set of events
<code>ResourceType</code>	identifier of a resource
<code>MessageType</code>	identifier of a message

Services

Each service returns an error code except `GetActiveApplicationMode`. If the OS has been compiled in `EXTENDED` configuration additional error codes may be returned and are suffixed by a †. Services suffixed by a ⌘ lead to a rescheduling.

Operating system

StartOS(app_mode)

Start the operating system in application mode *app_mode*. Does not return.

ShutdownOS(error)

Shutdown the operating system with error code *error*. Does not return.

GetActiveApplicationMode()

Returns the application mode used to start the operating system.

Tasks

DeclareTask(*task_id*)

Declare the existence of a task so that it can be forward referenced.

ActivateTask(*task_id*) ⌕

Activate task *task_id*. If task *task_id* has a priority greater than the caller priority, the caller is preempted. Returns:

E_OK	success
E_OS_LIMIT	too many activation of <i>task_id</i>
E_OS_ID†	task <i>task_id</i> does not exist

TerminateTask() ⌕

Terminate the caller. Returns:

E_OK	success
E_OS_RESOURCE†	the caller hold a resource
E_OS_CALLEVEL†	the caller is not a task

ChainTask(*task_id*) ⌕

Terminate the caller and activate *task_id*. Returns:

E_OK	success
E_OS_LIMIT	too many activation of <i>task_id</i>
E_OS_ID†	task <i>task_id</i> does not exist
E_OS_RESOURCE†	the caller hold a resource
E_OS_CALLEVEL†	the caller is not a task

Schedule() ⌕

Call the scheduler. Returns:

E_OK	success
E_OS_RESOURCE†	the caller hold a resource
E_OS_CALLEVEL†	the caller is not a task

GetTaskID(*task_id_ref*)

Get the task identifier of the task which is currently running. *task_id_ref* is a pointer to a **TaskType** variable where the task identifier of the running task is written. Returns:

E_OK	success
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GetTaskState(*task_id*, *task_state_ref*)

Get the task state of task *task_id*. *task_state_ref* is a pointer to a **TaskState** variable where the state is written. Returns:

E_OK	success
E_OS_ID†	task <i>task_id</i> does not exist

Alarms

DeclareAlarm(*alarm_id*)

Declare the existence of an alarm so that it can be referenced.

GetAlarm(*alarm_id*, *tick_ref*)

Get the remaining tick count of alarm *alarm_id* before the alarm reaches the date. *tick_ref* is a pointer to a **TickType** variable where the remaining tick count is written. Returns:

E_OK	success
E_OS_NOFUNC	alarm <i>alarm_id</i> is not started
E_OS_ID†	alarm <i>alarm_id</i> does not exist

GetAlarmBase(*alarm_id*, *info_ref*)

Get the information about the underlying counter of alarm *alarm_id*. *info_ref* is a pointer to a **AlarmBaseType** variable where the information is written. A **AlarmBaseType** is a **struct** with 3 fields: **maxallowedvalue**, **ticksperbase** and **mincycle**. Returns:

E_OK	success
E_OS_ID†	alarm <i>alarm_id</i> does not exist

SetRelAlarm(*alarm_id*, *offset*, *cycle*)

Start alarm *alarm_id*. After *offset* ticks the alarm expire and its action is executed. *offset* shall be > 0. If *cycle* is > 0 the alarm is restarted and expire every *cycle* ticks. Both *offset* and *cycle* shall ∈ [MINCYCLE, MAXALLOWEDVALUE]. Returns:

E_OK	success
E_OS_NOFUNC	alarm <i>alarm_id</i> is already started
E_OS_ID†	alarm <i>alarm_id</i> does not exist
E_OS_VALUE†	<i>offset</i> and/or <i>cycle</i> out of bounds

SetAbsAlarm(*alarm_id*, *date*, *cycle*)

Start alarm *alarm_id*. At next counter *date* the alarm expire and its action is executed. If *cycle* is > 0 the alarm is restarted and expire every *cycle* ticks. *date* shall be ≤ MAXALLOWEDVALUE. *offset* shall ∈ [MINCYCLE, MAXALLOWEDVALUE]. Returns:

E_OK	success
E_OS_NOFUNC	alarm <i>alarm_id</i> is already started
E_OS_ID†	alarm <i>alarm_id</i> does not exist
E_OS_VALUE†	<i>date</i> and/or <i>cycle</i> out of bounds

CancelAlarm(*alarm_id*)

Stop alarm *alarm_id*. Returns:

E_OK	success
E_OS_NOFUNC	alarm <i>alarm_id</i> is not started
E_OS_ID†	alarm <i>alarm_id</i> does not exist

Events

DeclareEvent(*event_id*)

Declare the existence of an event so that it can be referenced.

SetEvent(*task_id*, *event_mask*) ⌕

Set event(s) *event_mask* to task *task_id*. If task *task_id* was waiting for one of the events of *event_mask* and it has a higher priority than the caller, the caller is preempted. Returns:

E_OK	success
E_OS_ID†	task <i>task_id</i> does not exist
E_OS_ACCESS†	task <i>task_id</i> is not an extended task
E_OS_STATE†	task <i>task_id</i> is in SUSPENDED state

ClearEvent(*event_mask*)

Clear the event(s) of the caller according to events set in *event_mask*. Returns:

E_OK	success
E_OS_ACCESS†	the caller is not an extended task
E_OS_CALLEVEL†	the caller is not a task