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Assignment

The mean of the function
$$f(x, \delta) = \frac{x}{\delta^2} e^{-x^2/(2\delta^2)}$$
can be calculated as integral using matlab.

$$M1 = \frac{\int x f(x, \delta) dx}{\int f(x, \delta) dx} = \frac{\int x^2 e^{-x^2/(2(0.5)^2)}}{\int f(x, \delta) dx}$$

$$= \int_{0}^{\infty} \frac{x^{2}e^{-x^{2}/(z\cdot(o_{1}s)^{2})}}{(o_{1}s)^{2}} = \frac{0.6267}{(o_{1}s)^{2}}$$

$$\int_{0}^{\infty} x e^{-x^{2}/(2(0.5)^{2})} dx = 1$$

$$\int_{0}^{\infty} x e^{-x^{2}/(2(0.5)^{2})} dx = 0.6264$$

(2) The variance of 
$$f(x,\sigma)$$
 can be defined as

$$A = M_2 - M_1^2$$

$$M_2 = \int_0^\infty x^2 f(x, 0) dx$$

Using matlab

$$M_2 = \int x^2 \sqrt{2 \cdot 2c} e^{-x^2/(2 \cdot (0.5)^2)} dx$$

$$= \int_{0}^{\infty} \frac{3c^{3}}{(0.5)^{2}} e^{-\frac{\chi^{2}}{(2.(0.5)^{2})}} dx$$

$$S_0, G^2 = M2 - M1 = (0.500 - (0.6264)^2)$$

$$= 0.1073$$

or 
$$V = \sqrt{6^2} = 0.3276$$

(3) 
$$f(x, 0) = \frac{3c}{(0.5)^2} e^{-\frac{3c^2}{2(0.5)^2}}$$

2 (1) Expression for covavience matrix

$$V = \begin{pmatrix} 6^{2} & 0 & 0 \\ 0 & 6^{2} & 0 \\ 0 & 0 & 6^{2} \\ 0 & 0 & 5^{2} \end{pmatrix}$$

$$V = 10^{-6} \begin{pmatrix} 2^{2} & 0 & 6 \\ 0 & (0.3)^{2} & 6 \\ 0 & 0 & (0.4)^{2} \end{pmatrix}$$

$$V = 10^{-6} / 4 0 0 0$$

$$0.09 0$$

$$0.09 0$$

$$0.16$$

Because Ti and Tz are Independant variables.

(2) 2)
$$g_{1} = \frac{4\pi^{2}L}{T^{2}}$$

$$g_{2} = \frac{4\pi^{2}L}{T_{1}^{2}} \quad j \quad g_{2} = \frac{4\pi^{2}L}{T_{2}^{2}}$$

$$G = \begin{pmatrix} \frac{\partial g_1}{\partial L} & \frac{\partial g_1}{\partial T_1} & \frac{\partial g}{\partial T_2} \\ \frac{\partial g_2}{\partial L} & \frac{\partial g_2}{\partial T_1} & \frac{\partial g_2}{\partial T_2} \end{pmatrix} = \begin{pmatrix} \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} \\ \frac{\partial g_2}{\partial L} & \frac{\partial g_2}{\partial T_1} & \frac{\partial g_2}{\partial T_2} \end{pmatrix} = \begin{pmatrix} \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} \\ \frac{\partial g_2}{\partial L} & \frac{\partial g_2}{\partial T_1} & \frac{\partial g_2}{\partial T_2} \end{pmatrix} = \begin{pmatrix} \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} \\ \frac{\partial g_2}{\partial L} & \frac{\partial g_2}{\partial T_1} & \frac{\partial g_2}{\partial T_2} \end{pmatrix} = \begin{pmatrix} \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} \\ \frac{\partial g_2}{\partial L} & \frac{\partial g_2}{\partial T_1} & \frac{\partial g_2}{\partial T_2} \end{pmatrix} = \begin{pmatrix} \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} \\ \frac{\partial g_2}{\partial L} & \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} \end{pmatrix} = \begin{pmatrix} \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} \\ \frac{\partial g_2}{\partial L} & \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} \end{pmatrix} = \begin{pmatrix} \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} \\ \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} \end{pmatrix} = \begin{pmatrix} \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} \\ \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} \end{pmatrix} = \begin{pmatrix} \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} \\ \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} \end{pmatrix} = \begin{pmatrix} \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} \\ \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} \end{pmatrix} = \begin{pmatrix} \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} \\ \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} \end{pmatrix} = \begin{pmatrix} \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} \\ \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} \end{pmatrix} = \begin{pmatrix} \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} \\ \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} \end{pmatrix} = \begin{pmatrix} \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} \\ \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} \end{pmatrix} = \begin{pmatrix} \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} \\ \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} \end{pmatrix} = \begin{pmatrix} \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} \\ \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} \end{pmatrix} = \begin{pmatrix} \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} \\ \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} \end{pmatrix} = \begin{pmatrix} \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} \\ \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} \end{pmatrix} = \begin{pmatrix} \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} \\ \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} \end{pmatrix} = \begin{pmatrix} \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} \\ \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} \end{pmatrix} = \begin{pmatrix} \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} \\ \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} \end{pmatrix} = \begin{pmatrix} \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} \\ \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} \end{pmatrix} = \begin{pmatrix} \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} \\ \frac{\partial g_2}{\partial T_2} & \frac{\partial g_2}{\partial T_2} \end{pmatrix} = \begin{pmatrix} \frac{\partial g_2}{\partial T_2}$$

$$T_1 = 1.1433$$
 $T_2 = 1.1446$ 
 $L = 0.1325$ 

$$G = \begin{pmatrix} 30.196 & -17.167 & 0 \\ 30.127 & 0 & -17.109 \end{pmatrix}$$

$$\hat{\zeta} = \begin{pmatrix} 30.127 & 30.196 \\ 0 & -17.167 \\ -17.109 & 0 \end{pmatrix}$$

$$\begin{vmatrix}
30.196 - 17.164 & 0 \\
30.127 & 0 - 17.109
\end{vmatrix} \times 10 \begin{vmatrix}
9 & 0 & 0 \\
0 & 0.09 & 0
\end{vmatrix} \times \begin{vmatrix}
30.127 \\
0 & -17.161 \\
-17.109 & 0
\end{vmatrix}$$

## Results from matlab

$$V_f = GVG = \begin{pmatrix} 3.6374 & 3.6747 \\ 3.6267 & 3.6843 \end{pmatrix} \cdot 10^{-6}$$

$$V = GV_{f} \tilde{G}$$

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$$V = \left(\frac{\partial g}{\partial L} - \frac{\partial g}{\partial T}\right) \left(\frac{\partial g}{\partial L}\right) \left(\frac{\partial g}{\partial T}\right)$$

$$\left(\frac{\partial g}{\partial L} \frac{\partial g}{\partial T}\right) = \left(\frac{4\pi^2}{T^2} \frac{\partial -2x4\pi^2 L}{T^3}\right)$$

$$= (30.1196 j -17.167)$$

$$\begin{vmatrix} \frac{\partial g}{\partial L} \\ \frac{\partial g}{\partial T} \end{vmatrix} = \begin{pmatrix} 30.1196 \\ -17.167 \end{pmatrix}$$

$$V = \begin{pmatrix} 30.1196 \\ -17.167 \end{pmatrix} \begin{pmatrix} 3.6374 \\ 3.667 \\ 3.667 \end{pmatrix} \begin{pmatrix} 30.1196 \\ -17.167 \end{pmatrix} =$$

$$= 10^{-6} \times 620.3 = 6.203.10^{-4}$$

$$\int V = \int 6.203.10^{-4} = 2.45 \times 10^{-2}$$

$$g = \frac{g_1 + g_2}{z} = g.8040$$

$$g = \hat{g} \pm JV$$

$$g = 9.8040 \pm 0.0245$$

$$g = 9.804 \pm 0.025$$