

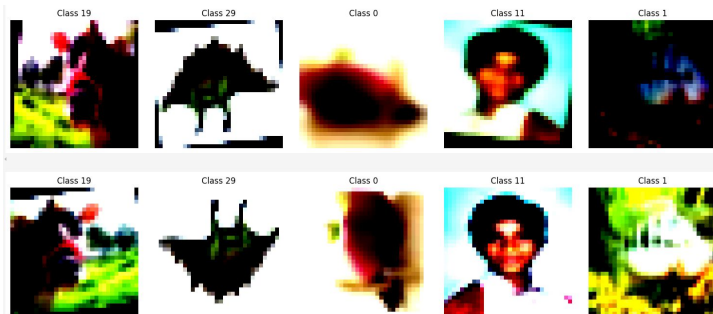
Research task

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Работа с датасетом

Аугментации из библиотеки Albumentations:

- геометрические
- цвет/контраст
- размытие
- нормализация



```
class alb_transform:
    def __init__(self, transform):
        self.transform = transform

    def __call__(self, img):
        img = np.array(img)
        return self.transform(image = img)['image']

train_transform = A.Compose([
    A.RandomRotate90(p = 0.3),
    A.HorizontalFlip(p=0.5),
    A.ShiftScaleRotate(shift_limit=0.05, scale_limit=0.1, rotate_limit=10, p=0.7),
    A.RandomBrightnessContrast(p=0.5),
    A.RGBShift(p=0.2),
    A.GaussianBlur(p=0.3),
    A.Normalize(mean=[0.5071, 0.4867, 0.4408], std=[0.2675, 0.2565, 0.2761]),
    ToTensorV2(),
])

test_transform = A.Compose([
    A.Normalize(mean=[0.5071, 0.4867, 0.4408], std=[0.2675, 0.2565, 0.2761]),
    ToTensorV2(),
])

full_train_dataset = CIFAR100(root='./data', train=True, download=False)

train_dataset = deepcopy(full_train_dataset)
val_dataset = deepcopy(full_train_dataset)

train_dataset.transform = alb_transform(train_transform)
val_dataset.transform = alb_transform(test_transform)

generator = torch.Generator().manual_seed(42)
train_idx, val_idx = torch.utils.data.random_split(
    range(len(full_train_dataset)), [45000, 5000], generator=generator
)

train_set = torch.utils.data.Subset(train_dataset, train_idx.indices)
val_set = torch.utils.data.Subset(val_dataset, val_idx.indices)

test_set = CIFAR100(root='./data', train=False, download=False, transform=alb_transform(test_transform))
```

Пайплайн обучения:

Lightning:

- сохранялась лучшая на валидации модель

```
def train_model(model, log_save_dir, exp_name, max_epochs = 10, monitor="MulticlassAccuracy/val",
                return_lightning_model = True, opt_cls = torch.optim.AdamW, lr=1e-3):
    checkpoint_callback = ModelCheckpoint(
        monitor=monitor, mode="max", filename="model"
    )
    pl_model = LModel(model, optimizer_cls = opt_cls, lr = lr)
    trainer = L.Trainer(
        max_epochs=max_epochs,
        callbacks=[checkpoint_callback],
        num_sanity_val_steps=0,
        log_every_n_steps=10,
        logger=L.pytorch.loggers.TensorBoardLogger(save_dir=log_save_dir, name=exp_name),
        enable_progress_bar=True,
        precision="16-mixed"
    )
    trainer.fit(model = pl_model, train_dataloaders=train_loader, val_dataloaders=val_loader)
    if return_lightning_model:
        return pl_model
    else:
        return pl_model.model
```

```
class LModel(L.LightningModule):
    def __init__(self, model, lr=0.001, optimizer_cls=torch.optim.AdamW):
        super().__init__()
        self.save_hyperparameters(logger=False, ignore=["model"])
        self.lr = lr
        self.model = model
        self.criterion = nn.CrossEntropyLoss()
        metrics = MetricCollection([
            MulticlassAccuracy(num_classes=100,),
            MulticlassF1Score(num_classes=100,),
        ])
        self.train_metrics = metrics.clone(postfix="/train")
        self.val_metrics = metrics.clone(postfix="/val")
        self.test_metrics = metrics.clone(postfix="/test")
        self.optimizer_cls = optimizer_cls

    def configure_optimizers(self):
        optimizer = self.optimizer_cls(
            self.model.parameters(),
            lr=self.lr,
        )
        scheduler = torch.optim.lr_scheduler.ReduceLROnPlateau(
            optimizer,
        )
        return {
            "optimizer": optimizer,
            "lr_scheduler": {
                "scheduler": scheduler,
                "interval": "epoch",
                "monitor": "loss"
            },
        }

    def training_step(self, batch, batch_idx):
        x, y = batch
        out = self.model(x)
        loss = self.criterion(out, y)
        self.train_metrics.update(out, y)
        self.log("loss", loss, prog_bar=True)
        return loss

    def validation_step(self, batch, batch_idx):
        x, y = batch
        out = self.model(x)
        self.val_metrics.update(out, y)

    def on_train_epoch_end(self):
        self.log_dict(self.train_metrics.compute())
        self.train_metrics.reset()

        val_metrics = self.val_metrics.compute()
        self.log_dict(val_metrics)
        self.val_metrics.reset()

    def test_step(self, batch, batch_idx):
        x, y = batch
        out = self.model(x)
        self.test_metrics.update(out, y)

    def on_test_epoch_end(self):
        self.log_dict(self.test_metrics.compute())
        self.test_metrics.reset()
```

Пайплайн обучения:

Pruning (для заданного количества обучаемых параметров):

- `prune.L1Unstructured`
- `prune.ln_structured`

```
import torch.nn.utils.prune as prune

def apply_pruning(model, params_num, pruning_method = prune.L1Unstructured, structured=False, n=2, dim=0):
    params_num_total = count_parameters(model)
    prune_ratio = 1-params_num/params_num_total
    parameters_to_prune = []
    for module in model.modules():
        if isinstance(module, nn.Linear) or isinstance(module, nn.Conv2d):
            parameters_to_prune.append((module, 'weight'))

    if structured:
        for module, name in parameters_to_prune:
            prune.ln_structured(module, name=name, amount=prune_ratio, n=n, dim=dim)
            prune.remove(module, name)
        for name, param in model.named_parameters():
            if torch.count_nonzero(param) == 0:
                param.requires_grad = False
    else:
        prune.global_unstructured(
            parameters_to_prune,
            pruning_method=pruning_method,
            amount=prune_ratio,
        )

    for module, _ in parameters_to_prune:
        prune.remove(module, 'weight')
    for name, param in model.named_parameters():
        if torch.count_nonzero(param) == 0:
            param.requires_grad = False

    return model
```

Пайплайн обучения

```
def training_pipeline(base_model,base_model_name,max_epochs_base,max_epochs_par,par_nums = [1000, 5000, 10000, 50000, 100000, 500000, 1000000],
                    pruning_method = prune.L1Unstructured,opt_cls = torch.optim.AdamW,
                    lr =1e-3,opt_class_name="adamw",base_model_not_calculated=True,structured=False, n=2, dim=0):
    opt_cls_train_base = opt_cls
    opt_cls_train_par = opt_cls
    if opt_cls == 'ranger21':
        opt_cls_train_base = partial(my_optimizer_ranger, num_epochs=max_epochs_base)
        opt_cls_train_par = partial(my_optimizer_ranger, num_epochs=max_epochs_par)
    base_model = base_model
    if base_model_not_calculated:
        base_model = train_model(base_model,log_save_dir = f'./saved_models/{base_model_name}/{opt_class_name}',
                                exp_name = 'full_model',return_lightning_model=False,max_epochs=max_epochs_base,opt_cls = opt_cls_train_base,lr = lr)
    else:
        model_dir = f'./saved_models/{base_model_name}/{opt_class_name}/'
        base_mod_dir = model_dir+"full_model/"
        version_model = glob.glob(base_mod_dir+'*/model.ckpt')[-1]
        base_model = LModel.load_from_checkpoint(version_model,model=base_model).model
    for par_num in par_nums:
        model_par = apply_pruning(base_model,par_num,pruning_method=pruning_method,structured=structured, n=n, dim=dim)
        model_par = train_model(model_par,log_save_dir = f'./saved_models/{base_model_name}/{opt_class_name}',
                                exp_name = f'{par_num:.0f}_pars',max_epochs=max_epochs_par,opt_cls = opt_cls_train_par,lr = 5*lr/10)
```

Число эпох обучения модели до прунинга – 20 эпох.

Дообучение модели после прунинга – 10 эпох.

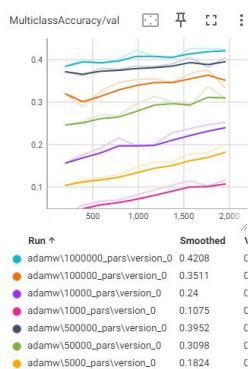
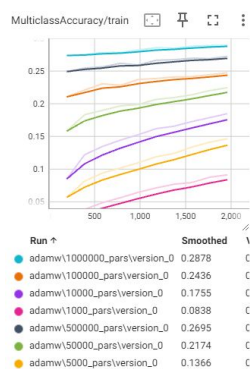
Используемые архитектуры: ResNet-18

Изменения:

- нет свертки 7x7 в начале.
- нет Max Pooling в начале.

Структура блоков не менялась.

Прунинг – prune.L1Unstructured



```
class CustomResnet(nn.Module):
    def __init__(self, class_nums=100, input_shape = (3,32,32)):
        super(CustomResnet, self).__init__()
        self.in_chans = 64
        self.conv1 = nn.Conv2d(3,64,kernel_size=1,stride=1,bias=False)
        self.bn1 = nn.BatchNorm2d(64)
        self.relu = nn.ReLU()

        self.layer1 = self.create_layers(64)
        self.layer2 = self.create_layers(128)
        self.layer3 = self.create_layers(256)
        self.layer4 = self.create_layers(512)

        self.dropout = nn.Dropout(p=0.3)
        self.avgpool = nn.AdaptiveAvgPool2d((1,1))
        self.fc = nn.Linear(512,class_nums)

    def create_layers(self, out_chans, block = BasicBlock, num_blocks=2, stride=1):
        downsample = None
        if stride != 1 or self.in_chans != out_chans:
            downsample = nn.Sequential(
                nn.Conv2d(self.in_chans, out_chans, kernel_size=1, stride=stride, bias=False),
                nn.BatchNorm2d(out_chans)
            )

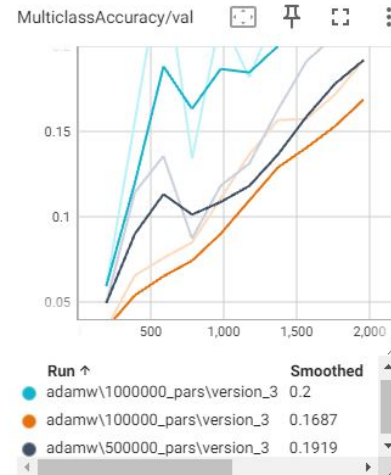
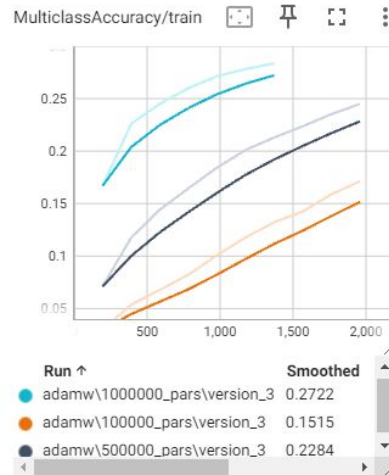
        layers = []
        for i in range(num_blocks):
            if i == 0:
                layers.append(block(self.in_chans, out_chans, stride = stride, downsample=downsample))
                self.in_chans = out_chans
            else:
                layers.append(block(out_chans, out_chans))
        return nn.Sequential(*layers)

    def forward(self, x):
        x = self.relu(self.bn1(self.conv1(x)))
        x = self.layer1(x)
        x = self.layer2(x)
        x = self.layer3(x)
        x = self.layer4(x)
        x = self.avgpool(x)
        x = self.dropout(x)
        x = torch.flatten(x,1)
        x = self.fc(x)
        return x
```

Используемые архитектуры: MobileNetV2

- Без stride=2 в начальной свертки
- изменен последний слой
- Число обучаемых параметров: 100k, 500k, 1M
- Прунинг
prune.ln_structed

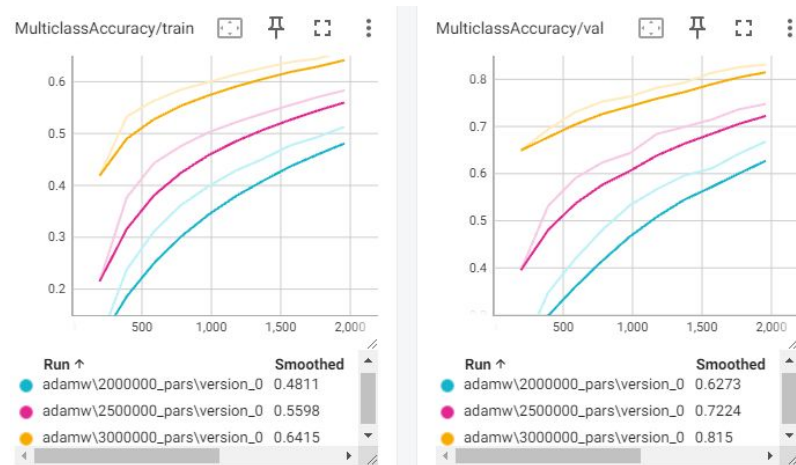
```
mobilenet_v2 = torchvision.models.mobilenet_v2(pretrained=True)
mobilenet_v2.features[0][0].stride = (1, 1)
mobilenet_v2.classifier[1] = nn.Linear(mobilenet_v2.last_channel, 100)
```



Используемые архитектуры: EfficientNet-B0

- Изменена начальная свертка.
- последний слой.
- Число обучаемых параметров: 2M, 2.5M, 3M.
- Прунинг `prune.ln_structed`.

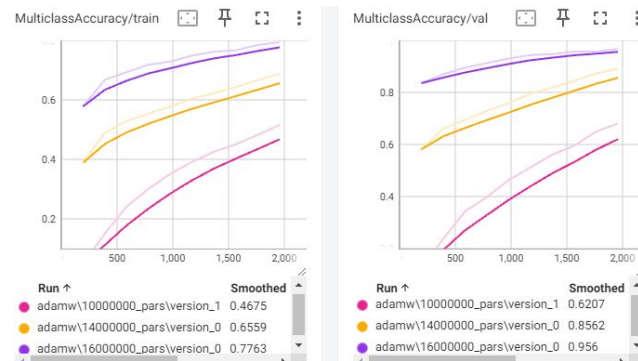
```
efficientnet_model = torchvision.models.efficientnet_b0(pretrained=True)
efficientnet_model.features[0] = nn.Conv2d(
    in_channels=3,
    out_channels=efficientnet_model.features[0].out_channels,
    kernel_size=(1, 1),
    stride=(1, 1),
    bias=False
)
efficientnet_model.classifier[1] = nn.Linear(efficientnet_model.classifier[1].in_features, 100)
```



Используемые архитектуры: ConvNeXT(tiny)

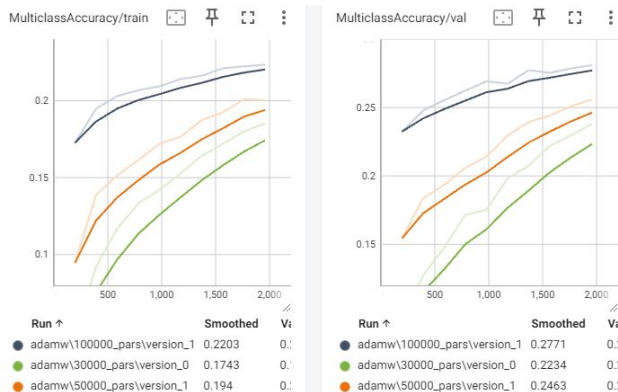
- начальная свертка
- последний слой
- Число обучаемых параметров: 10M, 14M, 16M
- Прунинг: `prune.ln_structed`

```
convnext_model = torchvision.models.convnext_tiny(weights='DEFAULT')  
  
convnext_model.features[0] = nn.Conv2d(3, 96, kernel_size=2, stride=2, padding=0)  
  
convnext_model.classifier[2] = nn.Linear(convnext_model.classifier[2].in_features, 100)
```



Используемые архитектуры: кастомные

- Число обучаемых параметров:
30k, 50k, 100k
- Прунинг:
prune.ln_structed



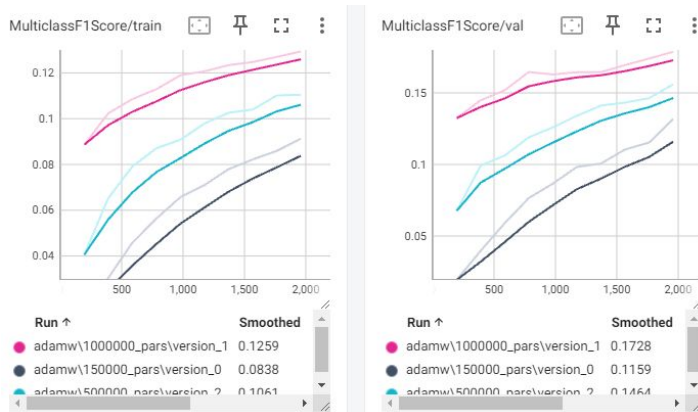
```
class CifarCNN(nn.Module):
    def __init__(self, init_shape = (3,32,32)):
        super().__init__()

        kernel_sizes = [3,3,3,3]
        final_out_channels = 25
        out_size = [init_shape[1], init_shape[2]]
        self.conv1 = nn.Conv2d(in_channels = init_shape[0], out_channels = 7, kernel_size = (kernel_sizes[0], kernel_sizes[0]))
        out_size = [out_size[0] - kernel_sizes[0] + 1, out_size[1] - kernel_sizes[0] + 1]
        self.conv2 = nn.Conv2d(in_channels = 7, out_channels = 15, kernel_size = (3,3))
        out_size = [out_size[0] - kernel_sizes[1] + 1, out_size[1] - kernel_sizes[1] + 1]
        self.pool1 = nn.MaxPool2d(kernel_size = (2,2))
        out_size = [out_size[0] // 2, out_size[1] // 2]
        self.conv3 = nn.Conv2d(in_channels = 15, out_channels = 20, kernel_size = (3,3))
        out_size = [out_size[0] - kernel_sizes[2] + 1, out_size[1] - kernel_sizes[2] + 1]
        self.conv4 = nn.Conv2d(in_channels = 20, out_channels = final_out_channels, kernel_size = (3,3))
        out_size = [out_size[0] - kernel_sizes[3] + 1, out_size[1] - kernel_sizes[3] + 1]
        self.pool2 = nn.MaxPool2d(kernel_size = (2,2))
        out_size = [out_size[0] // 2, out_size[1] // 2]
        self.flatten = nn.Flatten()
        self.fc1 = nn.Linear(out_size[0] * out_size[1] * final_out_channels, 256)
        self.fc2 = nn.Linear(256, 100)
        self.activation = nn.ReLU()

    def forward(self, x):
        x = self.activation(self.conv1(x))
        x = self.activation(self.conv2(x))
        x = self.pool1(x)
        x = self.activation(self.conv3(x))
        x = self.activation(self.conv4(x))
        x = self.pool2(x)
        x = self.flatten(x)
        x = self.activation(self.fc1(x))
        x = self.fc2(x)
        return x
```

Используемые архитектуры: кастомные

- Число обучаемых параметров:
30k, 50k, 100k
- Прунинг:
prune.ln_structed



```
class DeepCNN(nn.Module):
    def __init__(self, init_shape = (3,32,32)):
        super().__init__()
        kernel_sizes = [3,3,3,3,3]
        self.conv_layers = nn.ModuleList()
        out_size = [init_shape[1], init_shape[2]]
        out_channels_values = [8,16,32,64,128,256]
        in_channels = init_shape[0]
        for i, out_channels in enumerate(out_channels_values[:3]):
            out_size = [out_size[0]-kernel_sizes[i]+1, out_size[1]-kernel_sizes[i]+1]
            self.conv_layers.append(self.create_conv_block(in_channels, out_channels, kernel_sizes[i]))
            in_channels = out_channels
        self.conv_layers.append(nn.MaxPool2d(kernel_size=(2,2)))
        out_size = [out_size[0]//2, out_size[1]//2]
        for i, out_channels in enumerate(out_channels_values[3:]):
            out_size = [out_size[0]-kernel_sizes[i+3]+1, out_size[1]-kernel_sizes[i+3]+1]
            self.conv_layers.append(self.create_conv_block(in_channels, out_channels, kernel_sizes[i]))
            in_channels = out_channels
        self.conv_layers.append(nn.MaxPool2d(kernel_size=(2,2)))
        out_size = [out_size[0]//2, out_size[1]//2]
        in_features = in_channels*out_size[0]*out_size[1]
        out_features = [512, 256, 128]
        self.fc_layers = nn.ModuleList()
        for i, out_feature in enumerate(out_features):
            self.fc_layers.append(self.create_fc_block(in_features, out_feature))
            in_features = out_feature

        self.classifier = nn.Linear(in_features, 100)

        self.dropout = nn.Dropout(p=0.5)

    def create_conv_block(self, in_channels, out_channels, kernel_size):
        return nn.Sequential(nn.Conv2d(in_channels=in_channels, out_channels=out_channels, kernel_size=(kernel_size, kernel_size)),
                               nn.BatchNorm2d(out_channels),
                               nn.ReLU())

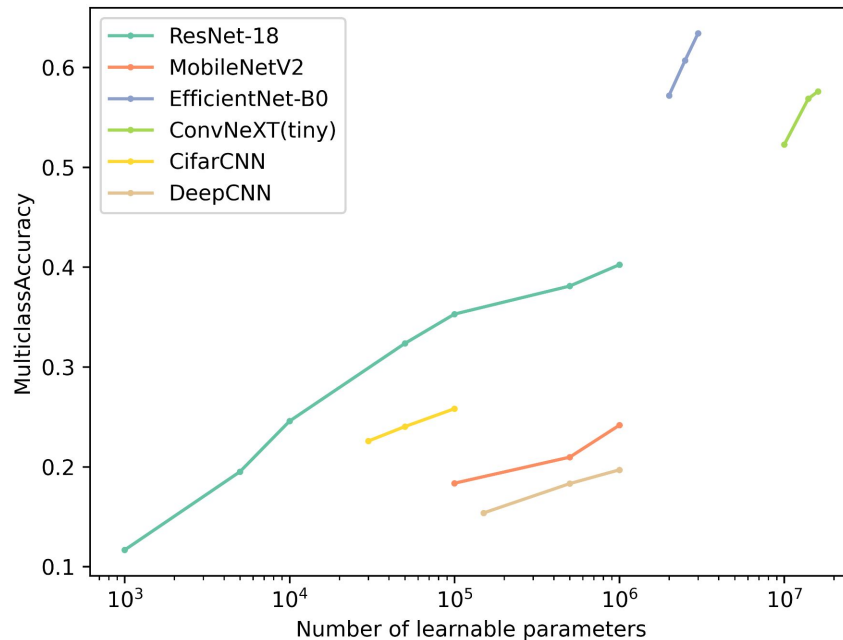
    def create_fc_block(self, in_features, out_features):
        return nn.Sequential(nn.Linear(in_features, out_features),
                               nn.BatchNorm1d(out_features),
                               nn.ReLU())

    def forward(self, x):
        for layer in self.conv_layers:
            x = layer(x)
        x = self.dropout(x)
        x = x.flatten(start_dim=1)
        for layer in self.fc_layers:
            x = layer(x)
        x = self.classifier(x)
        return x
```

Результаты обучения с ограничением на число параметров

Для теста бралась
сохраненная модель с
максимальным качеством на
валидации.

Максимальный скор (3M)
EfficientNet-Bo - 0.63



Результаты обучения: полные модели

CifarCNN: 194357

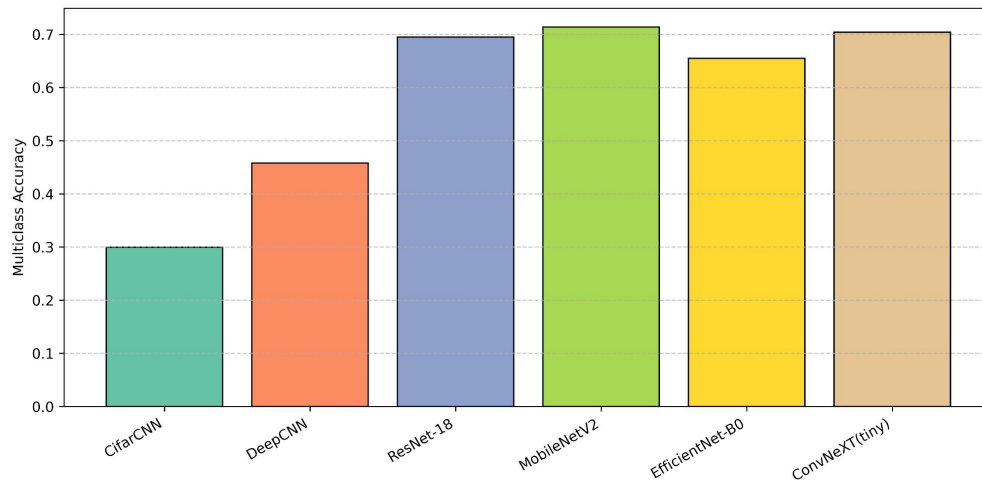
DeepCNN: 1750836

ResNet-18: 11208996

MobileNetV2: 2317860

EfficientNet-B0: 4092864

ConvNeXT(tiny): 27870628



Максимальный скор - 0.71 у MobileNetV2

Доп. значения метрик для графика

ResNet-18: [0.11659999191761017, 0.19499999284744263, 0.24570000171661377, 0.32349997758865356, 0.3528999984264374, 0.38100001215934753, 0.40240001678466797]

MobileNetV2: [0.1834999918937683, 0.20960000157356262, 0.24160000681877136]

EfficientNet-B0: [0.5719000101089478, 0.6068999767303467, 0.6341000199317932]

ConvNeXT(tiny): [0.5227000117301941, 0.5687999725341797, 0.5759000182151794]

CifarCNN: [0.2257000058889389, 0.240200012922287, 0.2581000030040741]

DeepCNN: [0.15370000898838043, 0.18310000002384186, 0.19689999520778656]

CifarCNN: 0.29930001497268677

DeepCNN: 0.4580000042915344

ResNet-18: 0.6949000358581543

MobileNetV2: 0.7136000394821167

EfficientNet-B0: 0.6552000045776367

ConvNeXT(tiny): 0.7042999863624573