$$EX_{k}=\lambda \Rightarrow X_{k}=X_{k}-\lambda, EX_{k}=0$$

$$X = \frac{1}{n}\sum_{k=1}^{n}X_{k} = \frac{1}{n}\sum_{k=1}^{n}(x_{k}+\lambda) = x + \lambda$$

$$1 \sum_{k=1}^{n}(x_{k}-x_{k})^{2} = \frac{1}{n}\sum_{k=1}^{n}(x_{k}-x_{k})^{2} = \frac{1}{n$$

November 12, 2020

 $y = \frac{1}{200} \sum_{k=1}^{200} (x_k - \overline{x})^2$

$$y = \sum_{k=1}^{1054} \sum_{k=1}^{2} \sum_{k=1}^{2} N(0, 9)$$

$$\frac{y}{9} = \sum_{k=1}^{1054} \left(\frac{3}{3}\right)^{2} N(0, 1)$$

$$\frac{$$

Foisson distribution with parameter
$$\emptyset$$
.

Prove that \overline{x} is sufficient statistics for \emptyset .

$$P(\overline{x} = \overline{x} | \overline{x} = t) = \frac{P(\overline{x} = \overline{x}, \overline{x} = t)}{P(\overline{x} = t)} \Longrightarrow P(\overline{x} = t)$$

$$\begin{cases}
X_1 = x_1 \\
X_2 = x_2 \\
X_1 + x_2 + \dots + x_n = nt
\end{cases}$$

$$\begin{cases}
X_1 = x_1 \\
X_2 = x_2
\end{cases} \Rightarrow x_1 + x_2 + \dots + x_n = nt
\end{cases}$$

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X_1 = x_1 \\
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\end{cases} \Rightarrow x_1 + x_2 + \dots + x_n = nt
\end{cases}$$

$$\begin{cases}
P(\overline{x} = x) \\
P(\overline{x} = x)
\end{cases} \Rightarrow P(\overline{x} = x) = P(\overline{x} = x)$$

$$\begin{cases}
P(\overline{x} = x) \\
P(\overline{x} = x)
\end{cases} \Rightarrow P(\overline{x} = x) = P(\overline{x} = x)$$

$$\Rightarrow P(\overline{x} = x) =$$

X1, X2, ..., Xn - a simple sample out of

Factorisation Oriterion

$$T(\vec{x})$$
 is sufficient for parameter $\emptyset \iff$
 $f_{\vec{x}}(\vec{x}, \emptyset) = g(T(\vec{x}), \emptyset) \cdot h(\vec{x})$

Symptotic for continuous distributions/

probability mass function for discrete distributions

probability mass function for discrete distributions

 $F(\vec{x} = \vec{x} \mid T(\vec{x}) = t) = F(\vec{x} = \vec{x}, T(\vec{x}) = t)$
 $F(\vec{x} = \vec{x} \mid T(\vec{x}) = t) = F(T(\vec{x}) = t)$
 $F(T(\vec{x}) = t) = F(T(\vec{x}), 0) \cdot h(\vec{x}) = F(T(\vec{x}) = t)$
 $F(T(\vec{x}) = t) = F(T(\vec{x}), 0) \cdot h(\vec{x}) = F(T(\vec{x}) = t)$
 $F(T(\vec{x}) = t) = F(T(\vec{x}), 0) \cdot h(\vec{x}) = F(T(\vec{x}) = t)$

$$\Rightarrow P(\vec{x} = \vec{x}) = \prod_{j=1}^{n} P(x_j = x_j) = \prod_{j=1}^{n} e^{-x_j} \frac{d^{2j}}{x_j!} = e^{-n\phi} e^{-x_j!} \frac{d^{2j}} \frac{d^{2j}}{x_j!} = e^{-n\phi} e^{-x_j!} \frac{d^{2j}}{x_j!} = e^{$$

X1, X2, ..., Xn ~ Poisson (0), independent

 $E(Var(y|X)) = E(E(y^2(X)) - E(E(y|X))^2) =$ $=Ey^{2}-E(E(y|x))^{2})=Ey^{2}-(Ey)^{2}+$ $+(Ey)^2-E(E(Y|X))^2=VarY+(E(E(Y|X)))^2$

$$(EY)^2 - E(E(Y|X))^2 = Var Y + (E(E(Y|X))^2)$$

$$E((E(Y|X))^2) = (ES)^2 - ES^2 = -1$$

(ES) - ES = - Var S = Vaz y - Vaz (E(y/x))

Var y = E(Var(y|x)) + Var(E(y|x))E(Y|X)

T is sufficient statistics for
$$\theta$$
 Rao-
 0^* is an unbiased estimator of θ Blackwell
 $\hat{\theta}^* = E(\theta^* | T)$. Then

 $E\hat{\theta}^* = E\theta^*$, i.e. θ^* is also unbiased,

 $Var \hat{\theta}^* \leq Var \theta^*$, and the equality is reached

if and only if θ^* is a function of T .

 $Var \theta^* = E(Var(\theta^* | T)) + Var(E(\theta^* | T)) = E(Var(\theta^* | T)) + Var \hat{\theta}^*$
 $Var \theta^* = E(Var(\theta^* | T)) + Var \hat{\theta}^*$

$$\begin{array}{l} X_{1}, X_{2}, \dots, X_{n} \sim \mathcal{U}[0], \emptyset] \\ 1 = 0 \\ X_{1}, X_{2}, \dots, X_{n} \sim \mathcal{U}[0], \emptyset] \\ 1 = 0 \\ X_{1}, X_{2}, \dots, X_{n} \sim \mathcal{U}[0], \emptyset] \\ 1 = 0 \\ X_{1}, X_{2}, \dots, X_{n} \sim \mathcal{U}[0], \emptyset] \\ 1 = 0 \\ X_{1}, X_{2}, \dots, X_{n} \sim \mathcal{U}[0], \emptyset] \\ 1 = 0 \\ X_{2}, \dots, X_{n} \sim \mathcal{U}[0], \emptyset] \\ 1 = 0 \\ X_{2}, \dots, X_{n} \sim \mathcal{U}[0], \emptyset] \\ 1 = 0 \\ X_{2}, \dots, X_{n} \sim \mathcal{U}[0], \emptyset] \\ 1 = 0 \\ X_{2}, \dots, X_{n} \sim \mathcal{U}[0], \emptyset] \\ 1 = 0 \\ X_{2}, \dots, X_{n} \sim \mathcal{U}[0], \emptyset] \\ 1 = 0 \\ X_{2}, \dots, X_{n} \sim \mathcal{U}[0], \emptyset] \\ 1 = 0 \\ X_{2}, \dots, X_{n} \sim \mathcal{U}[0], \emptyset] \\ 1 = 0 \\ X_{2}, \dots, X_{n} \sim \mathcal{U}[0], \emptyset] \\ 1 = 0 \\ X_{2}, \dots, X_{n} \sim \mathcal{U}[0], \emptyset] \\ 1 = 0 \\ X_{2}, \dots, X_{n} \sim \mathcal{U}[0], \emptyset] \\ 1 = 0 \\ X_{2}, \dots, X_{n} \sim \mathcal{U}[0], \emptyset] \\ 1 = 0 \\ X_{2}, \dots, X_{n} \sim \mathcal{U}[0], \emptyset] \\ 1 = 0 \\ X_{2}, \dots, X_{n} \sim \mathcal{U}[0], \emptyset] \\ 1 = 0 \\ X_{2}, \dots, X_{n} \sim \mathcal{U}[0], \emptyset] \\ 1 = 0 \\ X_{2}, \dots, X_{n} \sim \mathcal{U}[0], \emptyset] \\ 2 = 0 \\ X_{2}, \dots, X_{n} \sim \mathcal{U}[0], \emptyset] \\ 2 = 0 \\ X_{2}, \dots, X_{n} \sim \mathcal{U}[0], \emptyset] \\ 2 = 0 \\ X_{2}, \dots, X_{n} \sim \mathcal{U}[0], \emptyset] \\ 2 = 0 \\ X_{2}, \dots, X_{n} \sim \mathcal{U}[0], \emptyset] \\ 2 = 0 \\ X_{2}, \dots, X_{n} \sim \mathcal{U}[0], \emptyset] \\ 2 = 0 \\ X_{2}, \dots, X_{n} \sim \mathcal{U}[0], \emptyset] \\ 3 = 0 \\ X_{2}, \dots, X_{n} \sim \mathcal{U}[0], \emptyset]$$

 $=\frac{2}{h}E(x_1+\ldots+x_n\mid\max x_j=T)=$

 $\frac{2}{h}\left((h-1)\cdot\frac{T}{2}+T^2\right)=\frac{n+1}{h}T$