### Divide and Conquer

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#### **Preliminaries**

Divide and Conquer is the simplest and best-known technique for algorithmic design.

It is essential both from the point of view of recursion, and from the point of view of the top-down methodology.

There exist several extremely efficient algorithms whose structure fits the Divide-and-Conquer approach.



"Divide et Impera"

### Divide and Conquer

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### The Whole and the Parts



Ivan Turgenev (1818–1883) Russian writer

Whatever man prays for, he prays for a miracle. Every prayer reduces itself to this: — *Great God, grant that twice two be not four.* 

Prayer (July 1881), Poems in Prose

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### An Illustrative (yet hardly practical) Example

We wish to compute the sum of the elements stored in a size-n array. A brute force approach would be as simple as:

```
Brute force sum

func Sum (\downarrow A: TArray):\mathbb{N}

variables i, s: \mathbb{N}

begin

s \leftarrow A[1]

for i \leftarrow 2 to n do

s \leftarrow s + A[i]

endfor

return s

end
```

Can we think of another way of doing this?

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### An Illustrative (yet hardly practical) Example

The complexity (measured as the number of sums) of the brute force algorithm is  $t(n) = n - 1 \in \Theta(n)$ . As to the Divide-and-Conquer algorithm we have:

$$t(n) = \begin{cases} 0 & n = 1 \\ 2t(n/2) + 3 & n > 1 \end{cases}$$

Using the Master Theorem,  $\log_2 2 = 1$  and  $f(n) \in \Theta(1)$ , hence  $t(n) \in \Theta(n)$  too, but the multiplicative constant is larger: t(n) = 3n - 3.

The Divide and Conquer approach has not provided any computational gain in this problem. It can provide huge improvements in other problems though.

## An Illustrative (yet hardly practical) Example

If n = 1 computing the sum is trivial. If n > 1 we can divide the problem instance in two smaller instances of the same problem:

```
Divide-and-Conquer Sum

func Sum (\downarrow A: \text{TArray}, \downarrow I, r: \mathbb{N}):\mathbb{N}

variables m, s: \mathbb{N}

begin

if l=r then s \leftarrow A[I]

else

m \leftarrow (I+r)/2

s \leftarrow \text{Sum}(A, I, m) + \text{Sum}(A, m+1, r)

endif

return s

end
```

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#### Plan of Attack

Divide-and-Conquer algorithm approach the resolution of a problem as follows:

- A problem instance is divided in several smaller instances (ideally these *chunks* should be about the same size).
- 2 These instances are recursively solved (or in some other way if they are small enough).
- **3** The solutions obtained for the smaller instances are combined to obtain the solution to the original problem instance.

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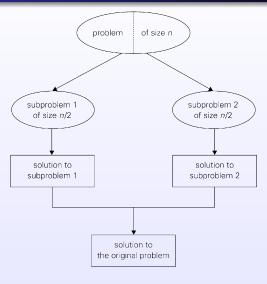
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# Typical Scheme



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### Another Example: Binary Search

```
Binary Search

func BinarySearch (\downarrow e: \mathbb{N}, \downarrow A: ARRAY [1..N] OF \mathbb{N}, \downarrow I, r: \mathbb{N}): \mathbb{B}

variables m: \mathbb{N}

begin

if I > r then return false

else

m \leftarrow (I + r)/2

if A[m] = e then return true

else

if A[m] > e then return BinarySearch(e, A, I, m - 1)

else return BinarySearch(e, A, m + 1, r)

endif

endif

endif

end
```

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#### Considerations

In general, a size-n instance is divided in  $a \ge 1$  instances with size n/b each.

It is often the case that a = b, i.e., the instance is divided in b > 1 equal chunks, and each of them is independently solved.

In some cases, it may be possible that not all subproblems have to be solved (i.e., a < b), or that subproblems overlap to some extent (i.e., a > b).

If the cost of dividing and combining is f(n), the total cost of the Divide-and-Conquer algorithm is t(n) = at(n/b) + f(n).

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# Binary Search Complexity

#### Binary search

Let t(n) = t(n/2) + 2 be the number of comparisons performed by the binary search algorithm in the worst case (t(0) = 0). With regard to the Master Theorem we have here that a = 1, b = 2, and f(n) = 1.

Since  $f(n) \in \Theta(1) = \Theta(n^0)$ , and  $d = \log_2 1 = 0$ , we are in the second case of the theorem with k = 0. Therefore,  $t(n) \in \Theta(n^d \log^{k+1} n) = \Theta(\log n)$ .

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## Mergesort



John von Neumann (1903–1957) Hungarian-American polymath Mergesort is a good example of successful application of the Divide-and-Conquer approach.

It was developed by John von Neumann in 1945. It allowed to sort large collections of data in early computers which had little RAM.

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### Sorting by Merging

```
Mergesort

proc Mergesort (\downarrow \uparrow A[1..n]: TArray)

variables B, C: TArray

begin

if n>1 then

B[1..\lfloor n/2\rfloor] \leftarrow A[1..\lfloor n/2\rfloor]
C[1..\lceil n/2\rceil] \leftarrow A[\lfloor n/2\rfloor + 1..n]
Mergesort(B)
Mergesort(C)
Merge(A, B, C)
endif

end
```

## Sorting by Merging

We have to sort an array A[1..n]. To this end:

- We divide the array in two halves  $A[1..\lfloor n/2 \rfloor]$  and  $A[\lfloor n/2 \rfloor + 1...n]$ .
- We recursively sort these two halves. If any of them has a single element or is empty, the process is trivial and does not require any recursive call.
- We merge the two sorted halves in order to come up with a completely sorted array.

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### Sorting by Merging

```
Mergesort

proc Merge (\downarrow \uparrow A[1..n]: TArray, \downarrow B[1..p], C[1..q]: TArray)

variables i, j, k: \mathbb{N}

begin

i \leftarrow 1; j \leftarrow 1; k \leftarrow 1

while (j \leqslant p) \land (k \leqslant q) do

if B[j] \leqslant C[k] then A[i] \leftarrow B[j]; j \leftarrow j+1

else A[i] \leftarrow C[k]; k \leftarrow k+1

endif

i \leftarrow i+1

endwhile

if j > p then A[i..n] \leftarrow C[k..q]

else A[i..n] \leftarrow B[j..p]

endif

end
```

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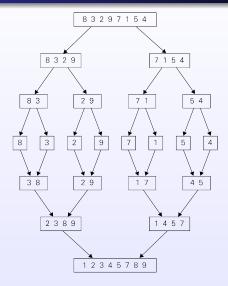
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### Mergesort at Work



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### Complexity of Mergesort

Focusing on element assignments, both procedure Mergesort and procedure Merge perform n operations each. Thus:

$$t(n) = \begin{cases} 0 & n \leq 1 \\ 2t(n/2) + 2n & n > 1 \end{cases}$$

Again, the Master Theorem indicates that  $t(n) \in \Theta(n \log n)$ .

### Complexity of Mergesort

Let us initially focus on time complexity. There are two choices for the basic operation:

Comparisons between elements

Assignments of elements

Comparisons are exclusively performed in the procedure Merge.

Each iteration in the main loop of Merge implies a single comparison. In the worst case it performs p+q-1=n-1 iterations, and hence

$$t(n) = \begin{cases} 0 & n \leq 1 \\ 2t(n/2) + n - 1 & n > 1 \end{cases}$$

According to the Master Theorem ( $\log_2 2 = 1$  and  $f(n) \in \Theta(n)$ ) we have that  $t(n) \in \Theta(n \log n)$ .

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### Complexity of Mergesort

Regarding space, procedure Mergesort uses two arrays whose combined size is n. The overall space consumption is therefore:

$$t(n) = \begin{cases} 1 & n = 1 \\ t(n/2) + n & n > 1 \end{cases}$$

According to the Master Theorem we have  $\log_2 1 = 0$ ,  $f(n) \in \Theta(n) \in \Omega(n^\epsilon)$  for some  $\epsilon > 0$  (for any  $0 < \epsilon \leqslant 1$  actually), and  $n/2 \leqslant cn$  for some c < 1 (for any  $1/2 \leqslant c < 1$  actually). Hence,  $t(n) \in \Theta(n)$ .

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### Quicksort



Tony Hoare (1934) British computer scientist

Quicksort is another successful example of the Divide-and-Conquer approach.

It is an extremely efficient sorting algorithm discovered by Sir C.A.R. "Tony" Hoare when working on a project for automatic translation between Russian and English.

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#### Quicksort

#### Quicksort

```
proc Quicksort (\downarrow\uparrow A: TArray, \downarrow I, r: \mathbb{N})
variables m: \mathbb{N}
begin

if r > I then

Divide(A, I, r, m)

Quicksort(A, I, m - 1)

Quicksort(A, m + 1, r)
endif
end
```

### Quicksort

We have to sort an array A[1..n]. To this end:

- We divide the array in two chunks A[1..m-1] and A[m+1..n], after having re-arranged the elements of the array so that
- We recursively sort these two chunks. The base case is trying to sort a chunk with one element (or none).

No further action is required after the recursive calls: the array is already sorted afterwards.

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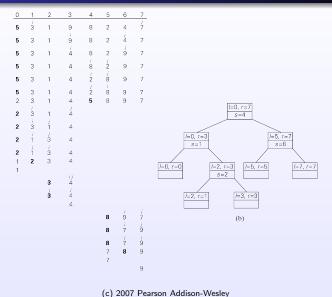
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#### Quicksort

#### Quicksort

```
proc Divide (\downarrow \uparrow A: TArray, \downarrow I, r: \mathbb{N}, \uparrow m: \mathbb{N})
variables p: \mathbb{N}
begin
p \leftarrow I
repeat
\text{while } (I \leqslant r) \land (A[I] \leqslant A[p]) \text{ do } I \leftarrow I+1 \text{ endwhile}
\text{while } (I \leqslant r) \land (A[r] > A[p]) \text{ do } r \leftarrow r-1 \text{ endwhile}
\text{if } I < r \text{ then swap}(A[I], A[r]) \text{ endif}
\text{until } I \geqslant r
\text{swap}(A[p], A[r])
m \leftarrow r
end
```

### Quicksort at Work



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### Complexity of Quicksort

In the worst case the partition produces two extremely asymmetrical chunks, i.e., one with 0 elements and another one with n-1 elements:

$$t(n) = \begin{cases} 0 & n \leq 1 \\ t(n-1) + n & n > 1 \end{cases}$$

Solving the recurrence we have  $t(n) \in \Theta(n^2)$  in the worst case.

If we consider element assignments as the basic operation, we come up with the same recurrence above, so the time complexity in that case is again  $\Theta(n^2)$ .

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## Complexity of Quicksort

Let us consider the time complexity of the algorithm. All element comparisons are done within procedure Divide.

Each call to Divide implies  $\Theta(n)$  comparisons (n being the number of elements in the current chuck). In the best case, the outcome of Divide is two equal-size chunks:

$$t(n) = \begin{cases} 0 & n \leq 1 \\ 2t(n/2) + n & n > 1 \end{cases}$$

According to the Master Theorem ( $\log_2 2 = 1$  and  $f(n) \in \Theta(n)$ ) and hence  $t(n) \in \Theta(n \log n)$ .

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### Complexity of Quicksort

In practice, The average complexity of Quicksort has the same order of growth than the best case, i.e.,  $\Theta(n \log n)$ . More precisely, it can be shown to be

$$t_{avg}(n) \approx 2n \ln n \approx 1.39n \log_2 n$$

There exist numerous strategies for minimizing the impact of the worst case: "smart choice" of the pivot, randomization, etc.

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### Integer Multiplication

Let us consider the problem of multiplying two large integers with a long number of digits each.

The sign can be easily dealt with, so we focus on positive integers.

Let us pick the following example: A=23 and B=14. To compute  $A \cdot B$  by brute force:

$$A \cdot B = 2 \cdot 10^2 + 11 \cdot 10^1 + 12 \cdot 10^0 = 200 + 110 + 12 = 322$$

If we consider that the product of two digits is the basic operation, we obviously perform  $n^2$  operations.

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Large Integer Multiplication

### A Different Approach

In more general terms, let  $A = a_1 a_0$  and  $B = b_1 b_0$ . The product C = AB can be expressed as:

$$C = c_2 10^2 + c_1 10^1 + c_0 10^0$$

where

$$c_2 = a_1 b_1$$
  
 $c_1 = a_1 b_0 + a_0 b_1$   
 $c_0 = a_0 b_0$ 

Notice that

$$c_1 = a_1b_0 + a_0b_1 = a_1b_0 + a_0b_1 + (a_1b_1 + a_0b_0) - (a_1b_1 + a_0b_0) =$$
  
=  $(a_1 + a_0)(b_1 + b_0) - (a_1b_1 + a_0b_0) =$   
=  $(a_1 + a_0)(b_1 + b_0) - (c_2 + c_0)$ 

We can try to exploit this result to speed-up the multiplication of larger integers.

### A Different Approach



Anatoliy A. Karatsuba (1937-2008) Russian mathematician Karatsuba algorithm uses a different approach and results in asymptotically faster multiplication.

It was discovered by Anatoliy Karatsuba in 1960, during a seminar on cybernetics by Andreiy Kolmogorov.

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### The General Case: Karatsuba's Algorithm

Let  $A = a_{n-1}a_{n-2}\cdots a_0$  and  $B = b_{n-1}b_{n-2}\cdots b_0$ . Now, let us divide A in half:

$$A = \overbrace{a_{n-1}a_{n-2}\cdots a_{n/2}}^{A_1} \overbrace{a_{n/2-1}\cdots a_1 a_0}^{A_0}$$

Analogously,  $B_1$  is the left half of B and  $B_0$  is its right half. Clearly:

$$A = A_1 10^{n/2} + A_0, \quad B = B_1 10^{n/2} + B_0$$

The same relationship seen before holds in this case:

$$C = AB = (A_1 10^{n/2} + A_0) (B_1 10^{n/2} + B_0) =$$

$$= (A_1 B_1) 10^n + (A_1 B_0 + A_0 B_1) 10^{n/2} + (A_0 B_0) =$$

$$= C_2 10^n + C_1 10^{n/2} + C_0$$

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### The General Case: Karatsuba's Algorithm

Once we have  $C_2$  and  $C_0$ , we can compute  $C_1$  as

$$C_1 = (A_1 + A_0)(B_1 + B_0) - (C_2 + C_0)$$

All calculations are done by means of sums and multiplications of integers with n/2 digits.

These multiplications can be done using the very same algorithm in a recursive way.

Recursion ends when the numbers have a single digit (or when they are small enough for a direct multiplication to be efficient).

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### Complexity of the Algorithm

If we measure complexity in terms of the number of one-digit multiplications we have

$$t(n) = \begin{cases} 1 & n = 1 \\ 3t(n/2) & n > 1 \end{cases}$$

Applying the Master Theorem we have that a = 3, b = 2,  $d = \log_b a = \log_2 3 \le 1.585$ , and  $f(n) = 0 \in \Theta(1)$ . Since there exists  $\epsilon > 0$  such that  $f(n) \in O(n^{d-\epsilon})$  (any  $\epsilon \in (0, d]$  would do), we have that  $t(n) \in \Theta(n^{1.585})$ .

This is a notable improvement with respect to the brute force approach which has complexity  $\Theta(n^2)$ .

#### The General Case: Knuth's Variant

When computing  $C_1$  in Karatsuba's algorithm:

$$C_1 = (A_1 + A_0)(B_1 + B_0) - (C_2 + C_0)$$

we can end up with some irregularity, because even when  $A_0$ ,  $A_1$ have n/2 digits each, their sum can have n/2 + 1 digits (and the same applies to  $B_0$ ,  $B_1$ ).

Knuth proposed a variant to tackle this issue:

$$C_1 = C_0 + C_2 - (A_0 - A_1)(B_0 - B_1)$$

The subtraction  $A_0 - A_1$  has exactly n/2 digits (but can be negative, so we have to take this into account in the procedure).

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# Complementary Bibliography



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