Continuous Time Equations for Analog Tape Modeling

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Hysteresis

The magnetostatic field recorded to magnetic tape can be described using a hysteresis loop. A circuit simulation of a hysteresis loop by Martin Holters and Udo Zolzer, using the Jiles-Atherton magnetisation model can be found at http://dafx16.vutbr.cz/dafxpapers/08-DAFx-16_paper_10-PN.pdf. They use the following differential equation to describe magnetisation 'M' as a function of magnetic field 'H':

$$\frac{dM}{dH} = \frac{(1-c)\delta_M(M_{an} - M)}{(1-c)\delta_M(M_{an} - M)} + c\frac{dM_{an}}{dH}$$

where M_{an} is the anisotropic magnetisation given by:

$$M_{an} = M_s L \left(\frac{H + \alpha M}{a} \right)$$

where M_s is the magnetisation saturation, and L is the Langevin function:

$$L(x) = \coth(x) - \frac{1}{x}$$

$$L'(x) = \frac{1}{x^2} - \coth^2(x) + 1$$

$$L''(x) = 2\coth(x) \cdot (\coth^2(x) - 1) - \frac{2}{x^3}$$

Let
$$Q(t) = \frac{H + \alpha M}{a}$$

Differentiating, we get:

$$\frac{dM}{dt} = \frac{(1-c)\delta_M(M_sL(Q)-M)}{(1-c)\delta k - \alpha(M_sL(Q)-M)} \frac{dH}{dt} + c\frac{M_s}{a} \left(\frac{dH}{dt} + \alpha\frac{dM}{dt}\right) L'(Q)$$

$$\frac{d^2M}{dt^2} = \frac{(1-c)\delta_M(M_sL(Q)-M)}{(1-c)\delta k - \alpha(M_sL(Q)-M)} \frac{d^2H}{dt^2} + \frac{(1-c)\delta_M(M_sL'(Q)-\dot{M})}{(1-c)\delta k - \alpha(M_sL(Q)-M)} \frac{dH}{dt} + \frac{(1-c)\delta_M(M_sL(Q)-M)(-\alpha(M_sL(Q)-M))}{((1-c)\delta k - \alpha(M_sL(Q)-M))} \frac{dH}{dt} + \frac{(1-c)\delta_M(M_sL(Q)-M)(-\alpha(M_sL(Q)-M))}{((1-c)\delta k - \alpha(M_sL(Q)-M))} \frac{dH}{dt} + \frac{(1-c)\delta_M(M_sL(Q)-M)}{((1-c)\delta k - \alpha(M_sL(Q)-M)} \frac{dH}{dt} + \frac{(1-c)\delta_M($$

Simplify:

$$\frac{d^2M}{dt^2} = \frac{\frac{(1-c)\delta_M(M_sL(Q)-M)}{(1-c)\delta_k-\alpha(M_sL(Q)-M)}\frac{d^2H}{dt^2} + \frac{(1-c)\delta_M(M_sL'(Q)-\dot{M})}{(1-c)\delta_k-\alpha(M_sL(Q)-M)}\frac{dH}{dt} + \frac{(1-c)\delta_M(M_sL(Q)-M)(-\alpha(M_sL'(Q)-\dot{M}))}{((1-c)\delta_k-\alpha(M_sL(Q)-M))^2}\frac{dH}{dt} + c\frac{M_s}{a}\log(1-c)\frac{M_s}{a}\frac{L'(Q)}{a}$$

$$\frac{dM}{dt} = \frac{\frac{(1-c)\delta_M(M_sL(Q)-M)}{(1-c)\delta_k - \alpha(M_sL(Q)-M)} \frac{dH}{dt} + c\frac{M_s}{a} \frac{dH}{dt} L'(Q)}{1 - c\alpha \frac{M_s}{a} L'(Q)} = f(t, M, \vec{u})$$

where
$$\vec{u} = \begin{bmatrix} H \\ \dot{H} \\ \ddot{H} \end{bmatrix}$$

Using trapezoidal rule:

$$\dot{\hat{H}}(n) = 2\frac{\hat{H}(n) - \hat{H}(n-1)}{T} - \dot{\hat{H}}(n-1)$$

and similar for \hat{H} . Now, using the semi-implicit trapezoidal rule [Yeh]:

$$\hat{M}(n) = \hat{M}(n-1) + \frac{T}{2} \frac{f[n, \hat{M}(n-1), \vec{u}(n)] + f[n-1, \hat{M}(n-1), \vec{u}(n-1)]}{1 - \frac{T}{2} \ddot{M}(n-1)}$$