

# 第四次课堂作业——频率域滤波

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课程名称: 数字图像处理II

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## 一、作业要求

实现以下内容

- 理想低通滤波器
- 布特沃思低通滤波器
- 高斯低通滤波器

## 二、理论介绍

### 1. 理想低通滤波器

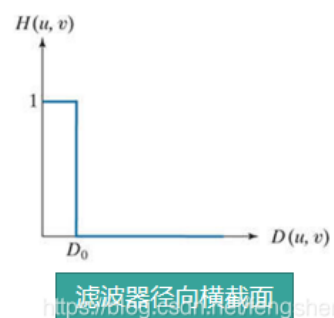
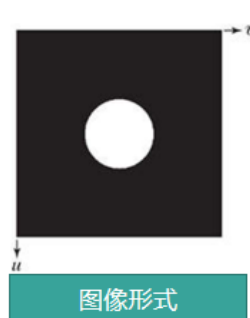
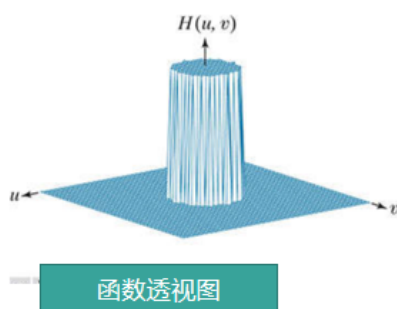
#### 1.1. 定义

**定义:**

$D$  是一个正常数,  $D(u,v)$  是频率域的点  $(u,v)$  到频率矩形中心的距离

$$H(u, v) = \begin{cases} 1 & \text{if } D(u, v) \leq D_0 \\ 0 & \text{if } D(u, v) > D_0 \end{cases}$$

$$D(u, v) = \left[ (u - P/2)^2 + (v - Q/2)^2 \right]^{1/2}$$



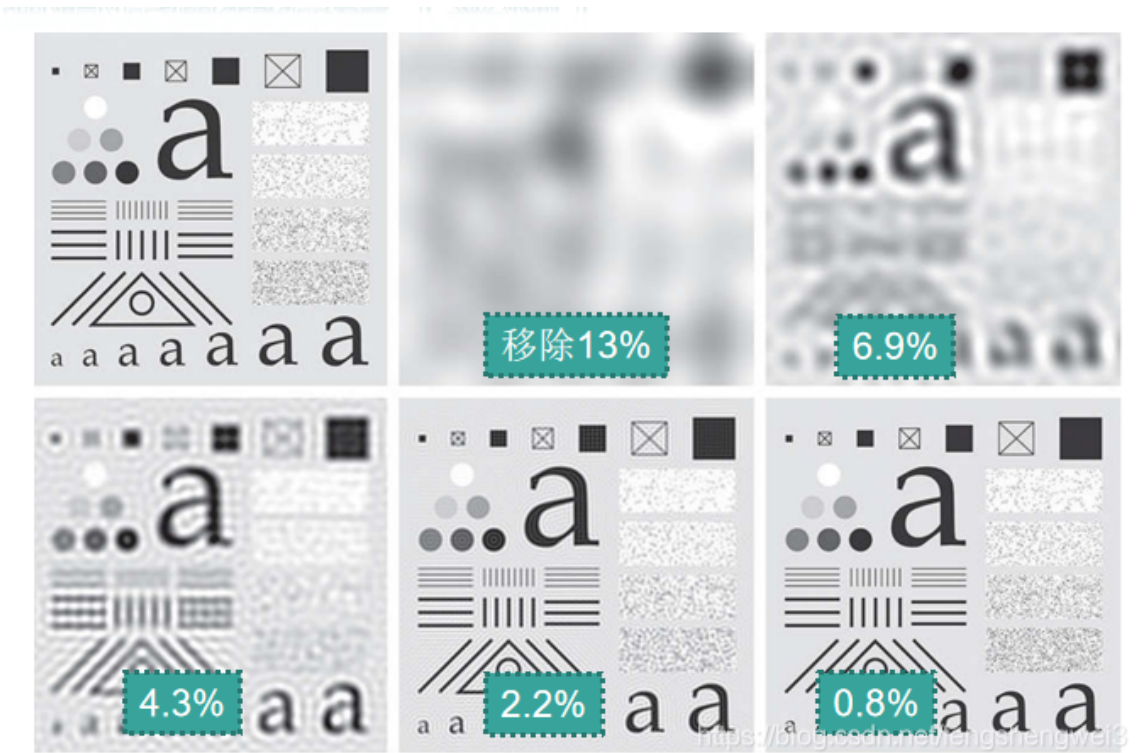
说明: 理想表明在半径为  $D_0$  的圆内, 所有频率无衰减的通过, 而在圆外则完全被衰减, 它是关于原点径向对称的, 也就是说定义一个径向截面, 然后旋转  $360^\circ$  就可以得到一个理想低通

滤波器

1.2. 示例



移除不同比例的高频分量的结果



1.3. 计算给定不同的半径值所过滤掉的功率大小

- (1) 首先计算总功率
- (2) 计算半径D0内的所有 (u,v) 对应的功率之和
- (3) 除以总功率\*100 即可得到百分比

$$P_T = \sum_{u=0}^{P-1} \sum_{v=0}^{Q-1} P(u,v)$$

$$\alpha = 100 \left[ \sum_u \sum_v P(u,v) / P_T \right]$$

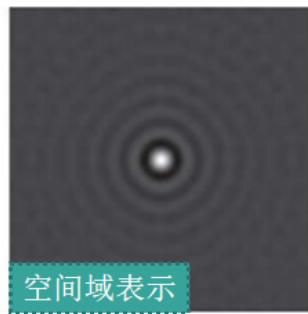
<https://blog.csdn.net/fengshengwei3>

## 1.4. 理想低通滤波器的振铃效应

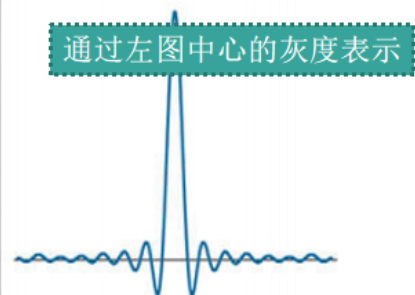
观察下面三幅图，边缘处都有波纹一样的效果，称为“振铃”效应，举个例子，敲锣的时候，会有“嗡嗡”的响声一样 过滤掉的频率越多，振铃效应越明显



理想低通滤波器



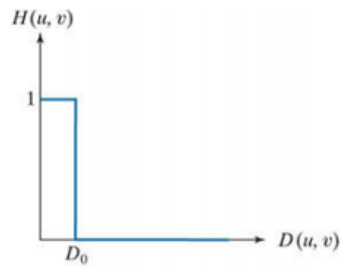
空间域表示



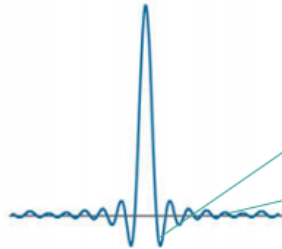
通过左图中心的灰度表示

<https://blog.csdn.net/fengshengwei3>

说明：由于理想低通滤波器的频率域剖面图类似于盒状滤波器，因此其空间域滤波器有sinc函数形状，空间域的滤波可以用卷积表示。



假如将图像中的一个像素作为一个离散冲击，其强度与灰度相关，一个sinc函数与冲击卷积就是在冲击处复制sinc函数



sinc函数的中心波瓣是造成模糊的主要原因

sinc函数的外侧波瓣则是造成振铃的原因

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结论：sinc函数的展开度与 $H(u, v)$ 滤波函数的半径成反比， $D_0$ 越大，sinc函数就会趋近于一个和图像卷积是根本不会发生模糊的冲击，低通滤波的目标是找到没有振铃或振铃效应很小的滤波器

## 2. 布特沃斯低通滤波器[BLPF]

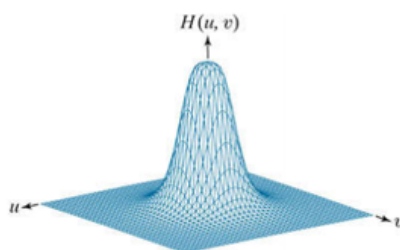
### 2.1. 定义

定义：

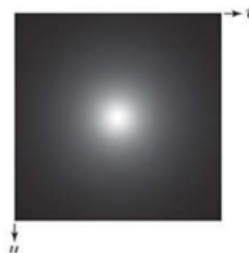
$D$  是一个正常数， $D(u, v)$  是频率域的点  $(u, v)$  到频率矩形中心的距离  
 $D_0$  是截至频率

$$H(u, v) = \frac{1}{1 + [D(u, v)/D_0]^{2n}}$$

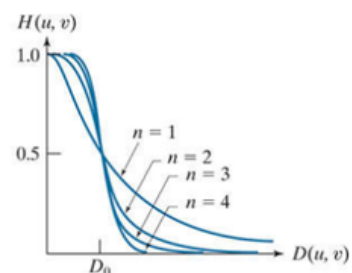
$$D(u, v) = \left[ (u - P/2)^2 + (v - Q/2)^2 \right]^{1/2}$$



函数透视图



图像形式



滤波器径向横截面

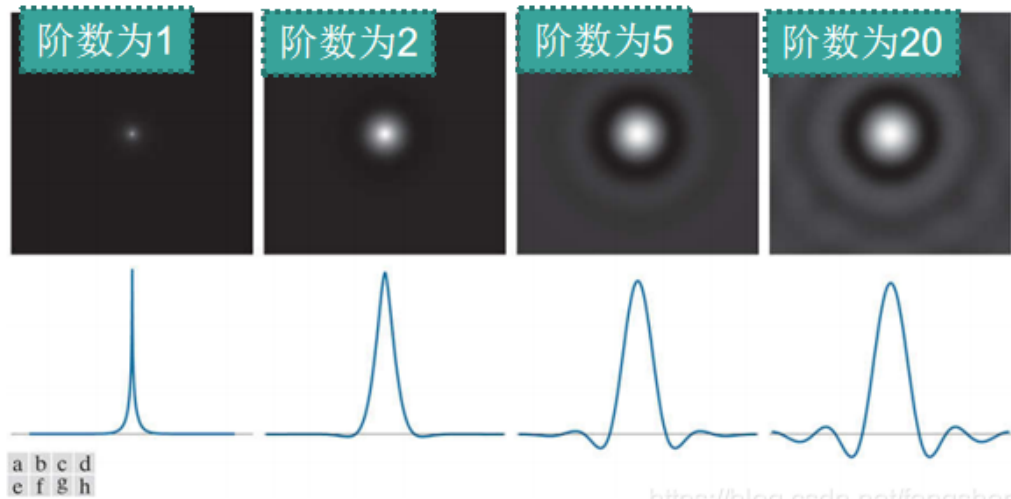
<https://blog.csdn.net/fengshengwei3>

### 2.2. 如何定义截止频率？

使  $H(u, v)$  下降为其最大值的某个百分比的点可以作为截止频率

### 2.3. 振铃效应说明

说明：巴特沃斯滤波器没有明显的截止频率，它是平滑过渡的，所以一阶情况下不会产生振铃效应 二阶也不会有明显的振铃效应，但是更高阶的振铃效应明显



## 2.4. 举例

不同截止频率对应的滤波结果



## 3. 高斯低通滤波器

### 3.1. 定义

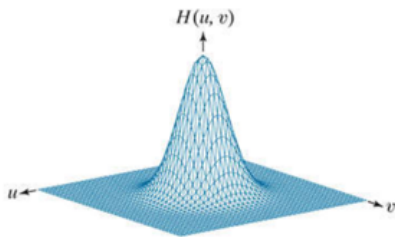


定义:

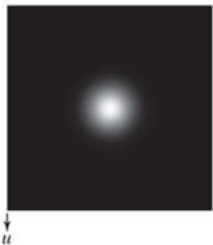
D 是一个正常数, D(u,v)是频率域的点 (u,v)到频率矩形中心的距离  
D0是截至频率

$$H(u, v) = e^{-D^2(u, v)/2D_0^2}$$

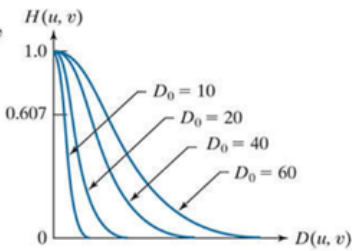
$$D(u, v) = \left[ (u - P/2)^2 + (v - Q/2)^2 \right]^{1/2}$$



函数透视图



图像形式



滤波器径向横截面

### 3.2. 示例

不同截止频率对应的滤波结果如下所示



### 4. 三种低通滤波的区别与联系

Ideal	Gaussian	Butterworth
$H(u,v) = \begin{cases} 1 & \text{if } D(u,v) \leq D_0 \\ 0 & \text{if } D(u,v) > D_0 \end{cases}$	$H(u,v) = e^{-D^2(u,v)/2D_0^2}$	$H(u,v) = \frac{1}{1 + [D(u,v)/D_0]^{2n}}$
简单直观	没有振铃效应	可以严格控制截止频率在低频和高频之间的过渡
有振铃现象，不适应与正常的应用中	平滑效果比二阶BLPF差	会产生轻微的振铃效应

<https://blog.csdn.net/fengshengwei3>

### 三、实验以及结果

#### 1. 导入库

```
In [1]: # @Author: Alephant—QSZ
import numpy as np
import cv2
import imageio
import matplotlib.pyplot as plt
from math import sqrt
from mpl_toolkits.mplot3d import Axes3D

eps = np.finfo(float).eps
```

#### 2. 绘图

##### 2.1. 绘制三维透视图

```
In [2]: def drawPerspective(handleax,input_matrix,title=None,cmap = "gray"):
    handleax.set_title(title)
    handleax.set_zlabel('Z') # 坐标轴
    handleax.set_ylabel('Y')
    handleax.set_xlabel('X')
    x,y = input_matrix.shape
    X = np.arange(0,x,1)
    Y = np.arange(0,y,1)
    # 由于图像x,y坐标和 meshgrid出来是互反的
    # 这里需要调转一下
    # 否则会出现mismatch的现象
    X,Y = np.meshgrid(Y, X)
    handleax.plot_surface(Y, X, input_matrix, cmap=cmap)
    #     handleax.plot_wireframe(Y, X, input_matrix, cmap=cmap)
```

##### 2.2. 绘制三维透视图

```
In [3]: def drawPerspective(handleax,input_matrix,title=None,cmap = "gray"):
    handleax.set_title(title)
    handleax.set_zlabel('Z') # 坐标轴
    handleax.set_ylabel('Y')
    handleax.set_xlabel('X')
    x,y = input_matrix.shape
```

```

X = np.arange(0,x,1)
Y = np.arange(0,y,1)
# 由于图像x,y坐标和 meshgrid出来是互反的
# 这里需要调转一下
# 否则会出现mismatch的现象
X,Y = np.meshgrid(Y, X)
handleax.plot_surface(Y, X, input_matrix, cmap=cmap)
#     handleax.plot_wireframe(Y, X, input_matrix, cmap=cmap)

```

## 2.3. 绘制平面图

```

In [4]: def drawPanel(handleax,input_matrix,title=None,cmap = "gray"):
        handleax.set_title(title)
        handleax.set_ylabel('Y')
        handleax.set_xlabel('X')
        handleax.imshow(input_matrix,cmap = cmap)

```

## 2.4. 绘制曲线图

```

In [5]: def drawCurv(handleax,functions,labels,filter_d0,title=None,cmap = "gray"):
        # 绘制从0到 3D_0的函数剖面图
        handleax.set_title(title)
        handleax.set_xlabel("$D(u,v)$")
        handleax.set_ylabel("$H(u,v)$")
        # 标出D_0点
        # handleax.annotate(r"$D_0$", xy = (filter_d0,0) , weight='heavy')

        for func,lab in zip(functions,labels):
            # 对每一对func和Label绘图 (针对需要画多条线的情况)
            X = np.arange(0,3*filter_d0+1,0.1)
            Y = func(X)
            handleax.plot(X,Y,label = lab)
        handleax.set_xticks([0,filter_d0])
        handleax.set_xticklabels(["$0$", "$D_0$"])
        handleax.legend()

```

## 3. 频率与转空间域

```

In [6]: def frequencyToSpatial(input_matrix):
        # 这里不太明白为什么shift与否最后都需要添加一个fftshift来得到想要的空间域图像
        shift_input_matrix = np.fft.ifftshift(input_matrix)
        #     shift_input_matrix = input_matrix
        spatial_img = np.abs(np.fft.ifft2(shift_input_matrix))
        spatial_img = np.fft.fftshift(spatial_img)
        return spatial_img

```

## 4. 理想滤波器

所谓“理想”是指无法通过硬件实现的硬截断

### 4.1. 理想低通滤波器 ILPF

```

In [7]: # 获得指定大小的理想滤波器
        def getIdealMask(mask_shape, filter_d0,h1_type):
            assert h1_type in ("lpf","hpf")
            rows,cols = mask_shape[0],mask_shape[1]

```

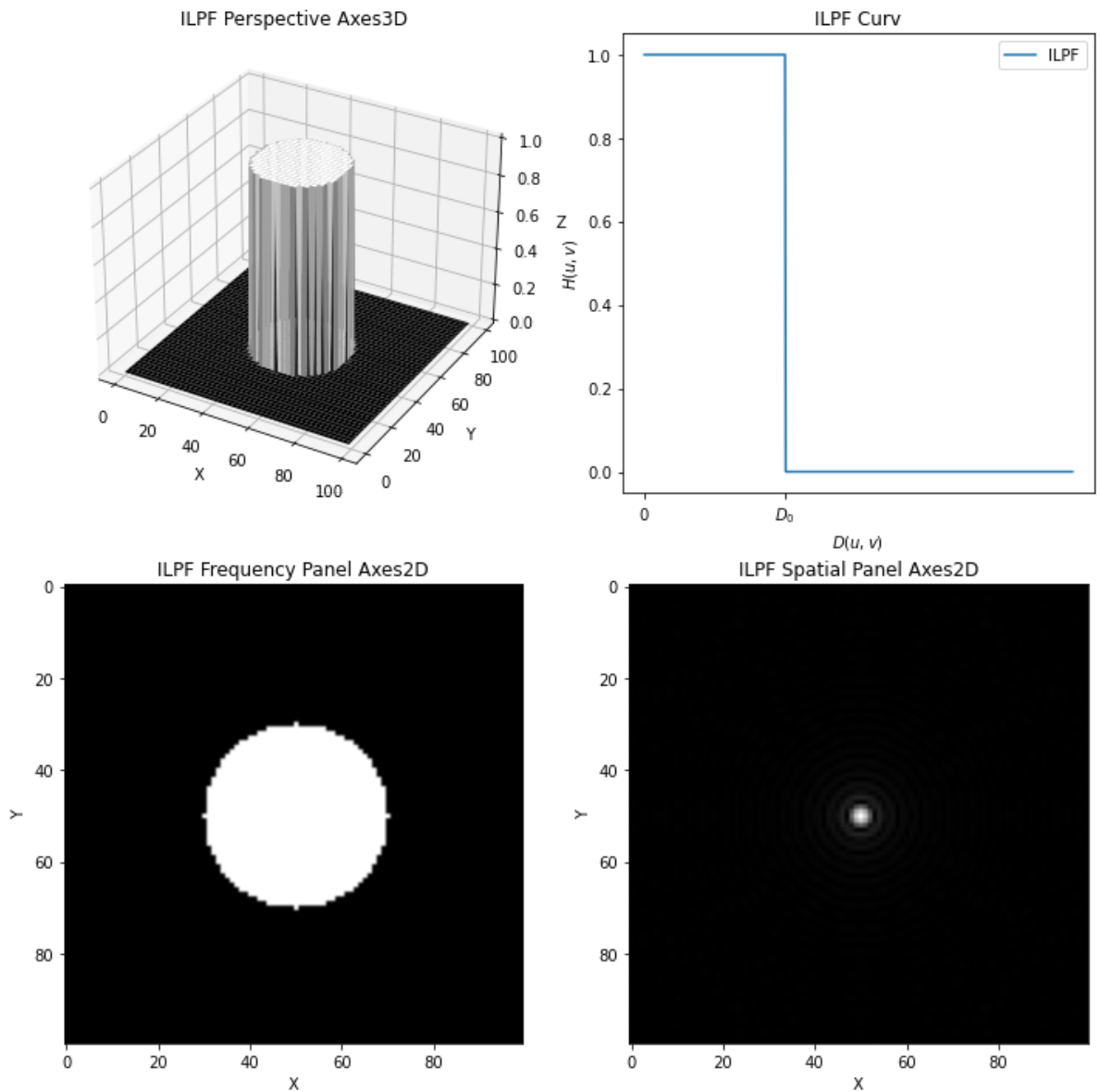


```

crow = rows/2
ccol = cols/2
mask = np.zeros((rows,cols))
for i in range(rows):
    for j in range(cols):
        dis = sqrt((i-crow)**2 + (j-ccol)**2)
        if hl_type == "lpf":
            if dis <= filter_d0:
                mask[i,j] = 1
            else:
                mask[i,j] = 0
        elif hl_type == "hpf":
            if dis <= filter_d0:
                mask[i,j] = 0
            else:
                mask[i,j] = 1
    return mask

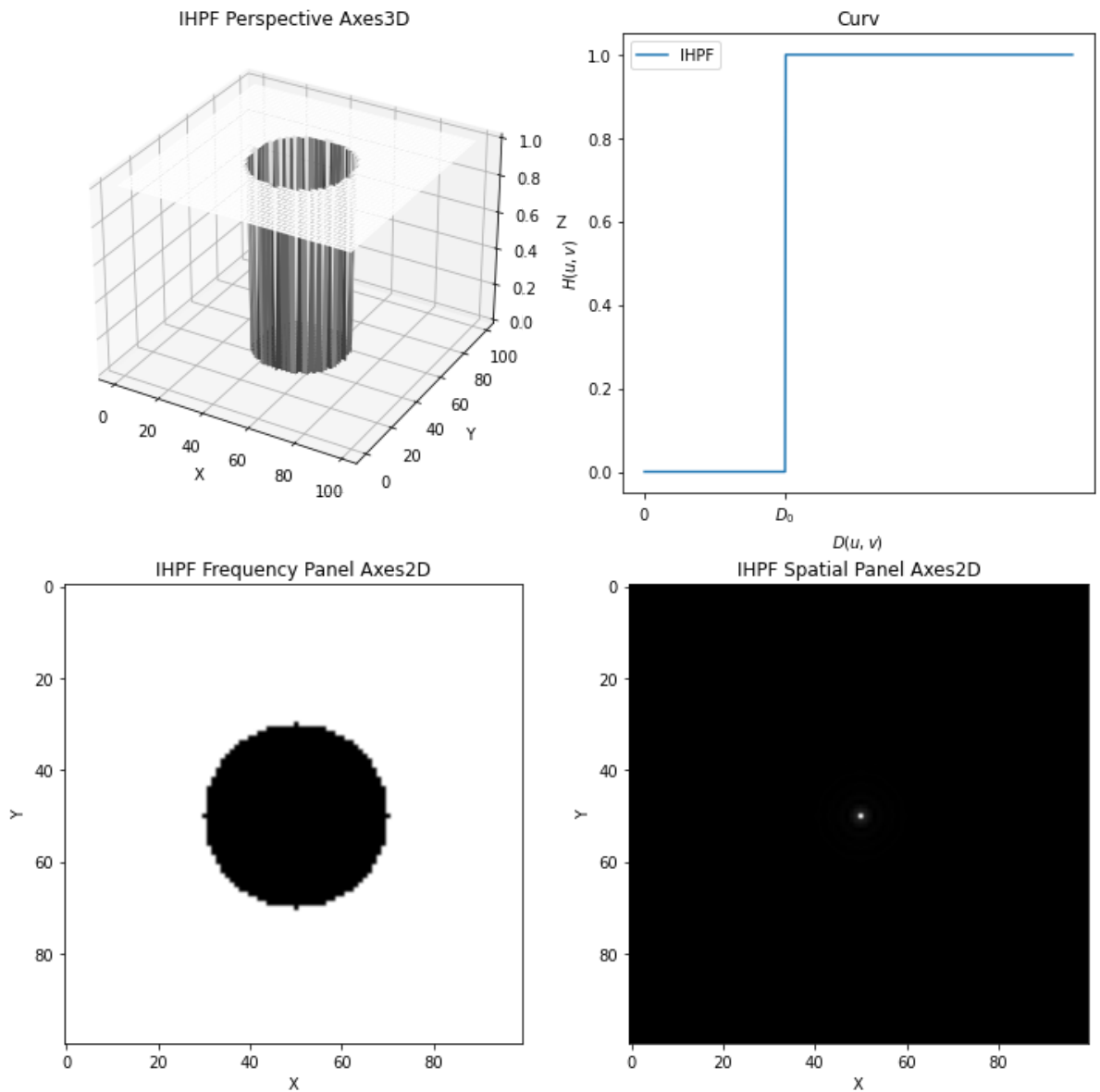
# 测试ILPF
# 参数设置
mask_shape = (100,100)
d = 20
filter_type = "lpf"
# 获得滤波器
myfilter = getIdealMask(mask_shape,d,filter_type)
# 绘图
plt.figure(figsize=(12,12))
ax1=plt.subplot(221,projection = "3d")
ax2=plt.subplot(222)
ax3=plt.subplot(223)
ax4=plt.subplot(224)
drawPerspective(ax1,myfilter,title = "ILPF Perspective Axes3D", cmap = "gray")
# 不想进行列表解析,需要调用frompyfunc构建np可以用的分段函数
ufunc1 = np.frompyfunc(lambda x: 0 if (x-d)>0 else 1, 1, 1)
drawCurv(ax2,[ufunc1],["ILPF"],d,title = "ILPF Curv")
drawPanel(ax3,myfilter,title = "ILPF Frequency Panel Axes2D")
spatial_myfilter = frequencyToSpatial(myfilter)
drawPanel(ax4,spatial_myfilter,title = "ILPF Spatial Panel Axes2D")
plt.show()

```



## 4.2. 理想高通滤波器 IHPF

```
In [8]: # 测试IHPF—理想高通滤波器
d = 20
filter_type = "hpf"
myfilter = getIdealMask(mask_shape,d,filter_type)
plt.figure(figsize=(12,12))
ax1=plt.subplot(221,projection = "3d")
ax2=plt.subplot(222)
ax3=plt.subplot(223)
ax4=plt.subplot(224)
drawPerspective(ax1,myfilter,title = "IHPF Perspective Axes3D", cmap = "gray")
# 不想进行列表解析, 需要调用frompyfunc构建np可以用的分段函数
ufunc1 = np.frompyfunc(lambda x: 1 if (x-d)>0 else 0, 1, 1)
drawCurv(ax2,[ufunc1],["IHPF"],d,title = "Curv")
drawPanel(ax3,myfilter,title = "IHPF Frequency Panel Axes2D")
spatial_myfilter = frequencyToSpatial(myfilter)
drawPanel(ax4,spatial_myfilter,title = "IHPF Spatial Panel Axes2D")
plt.show()
```



## 5. 布特沃斯滤波器

可通过硬件实现，可以通过阶数进行控制，一些资料中又称之为“巴特沃斯滤波器”

### 5.1. 布特沃斯低通滤波器 BLPF

```
In [9]: # 获得指定大小的布特沃斯滤波器
def getButterworthMask(mask_shape, filter_d0, hl_type, butter_n = 1):
    assert hl_type in ("lpf", "hpf")
    rows, cols = mask_shape[0], mask_shape[1]
    crow = rows/2
    ccol = cols/2
    mask = np.zeros((rows, cols))
    for i in range(rows):
        for j in range(cols):
            dis = sqrt((i-crow)**2 + (j-ccol)**2)
            if hl_type == "lpf":
                mask[i, j] = 1.0/(1+(dis/filter_d0)**(2*butter_n))
            elif hl_type == "hpf":
                # 除以0情况特判一下
                if np.abs(dis)<eps:
                    mask[i, j] = 0
            else:
```

```

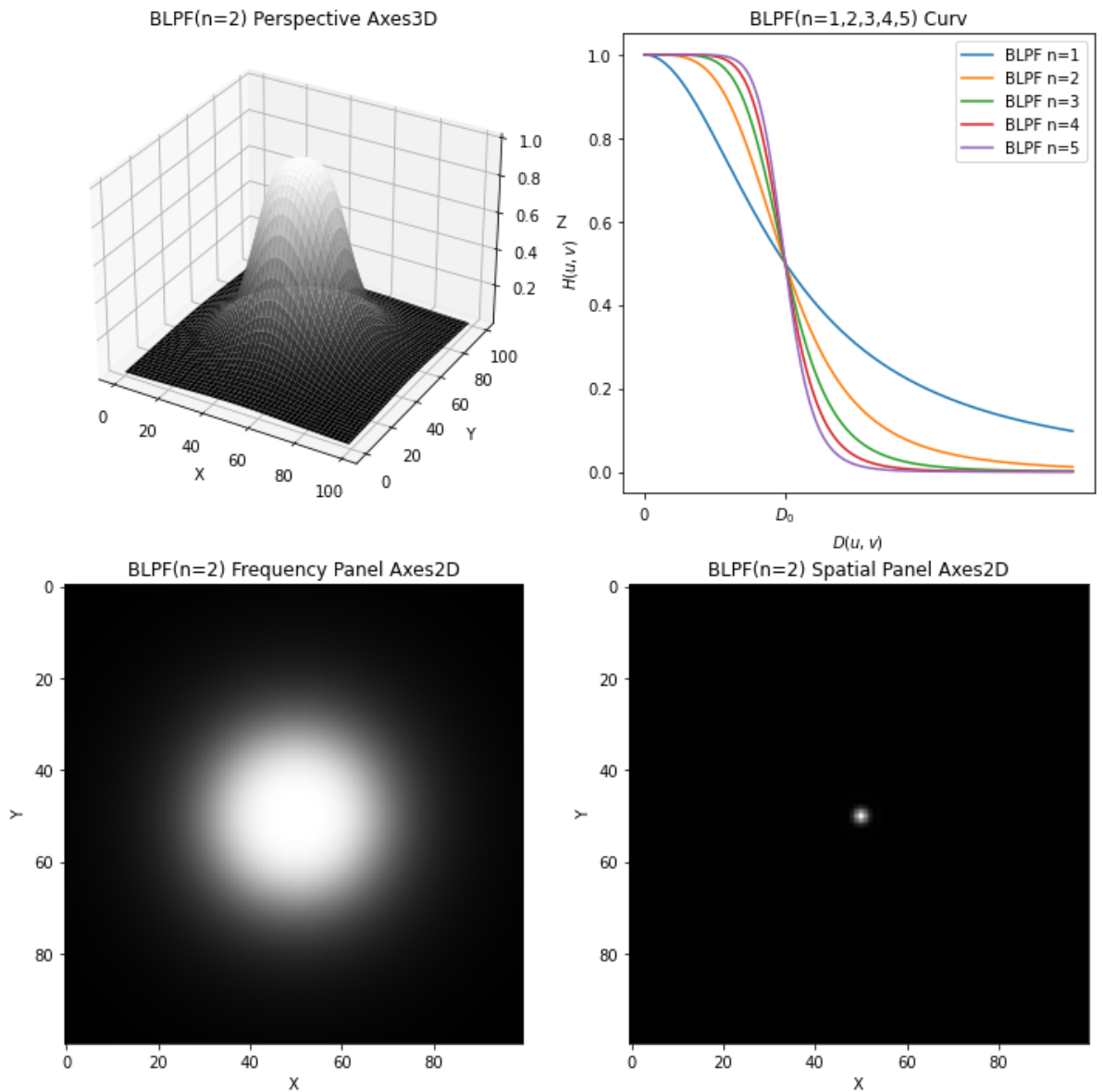
mask[i,j] = 1.0/(1+(filter_d0/dis)**(2*butter_n))

    return mask

# 测试BLPF
# 参数设置
mask_shape = (100,100)
d = 20
filter_type = "lpf"
# 获得滤波器
myfilter = getButterworthMask(mask_shape,d,filter_type, butter_n=2)
# 绘图
plt.figure(figsize=(12,12))
ax1=plt.subplot(221,projection = "3d")
ax2=plt.subplot(222)
ax3=plt.subplot(223)
ax4=plt.subplot(224)
drawPerspective(ax1,myfilter,title = "BLPF(n=2) Perspective Axes3D", cmap = "gray")
funcs = []
labels = []
for i in range(1,6):
    labels.append("BLPF "+"n="+str(i))
    funcs.append(lambda x:1.0/(1+(x/d)**(2*1)))
    funcs.append(lambda x:1.0/(1+(x/d)**(2*2)))
    funcs.append(lambda x:1.0/(1+(x/d)**(2*3)))
    funcs.append(lambda x:1.0/(1+(x/d)**(2*4)))
    funcs.append(lambda x:1.0/(1+(x/d)**(2*5)))

drawCurv(ax2,funcs,labels,d,title = "BLPF(n=1,2,3,4,5) Curv")
drawPanel(ax3,myfilter,title = "BLPF(n=2) Frequency Panel Axes2D")
spatial_myfilter = frequencyToSpatial(myfilter)
drawPanel(ax4,spatial_myfilter,title = "BLPF(n=2) Spatial Panel Axes2D")
plt.show()

```



## 5.2. 布特沃斯高通滤波器 BHPF

```
In [10]: # 测试BHPF
d = 20
filter_type = "hpf"
myfilter = getButterworthMask(mask_shape,d,filter_type, butter_n=1)
plt.figure(figsize=(12,12))
ax1=plt.subplot(221,projection = "3d")
ax2=plt.subplot(222)
ax3=plt.subplot(223)
ax4=plt.subplot(224)
drawPerspective(ax1,myfilter,title = "BHPF(n=2) Perspective Axes3D", cmap = "gray")
funcs = []
labels = []
for i in range(1,6):
    # funcs.append(Lambda x:1.0/(1+(d/x)**(2*i)))
    # ufunc = np.frompyfunc(Lambda x: 0 if np.abs(x)<eps else 1.0/(1+(d/x)**(2*i)), 1, 1)
    # funcs.append(ufunc)
    labels.append("BHPF "+n="+str(i))
ufunc1 = np.frompyfunc(lambda x: 0 if np.abs(x)<eps else 1.0/(1+(d/x)**(2*1)), 1, 1)
ufunc2 = np.frompyfunc(lambda x: 0 if np.abs(x)<eps else 1.0/(1+(d/x)**(2*2)), 1, 1)
ufunc3 = np.frompyfunc(lambda x: 0 if np.abs(x)<eps else 1.0/(1+(d/x)**(2*3)), 1, 1)
ufunc4 = np.frompyfunc(lambda x: 0 if np.abs(x)<eps else 1.0/(1+(d/x)**(2*4)), 1, 1)
ufunc5 = np.frompyfunc(lambda x: 0 if np.abs(x)<eps else 1.0/(1+(d/x)**(2*5)), 1, 1)
funcs.append(ufunc1)
```

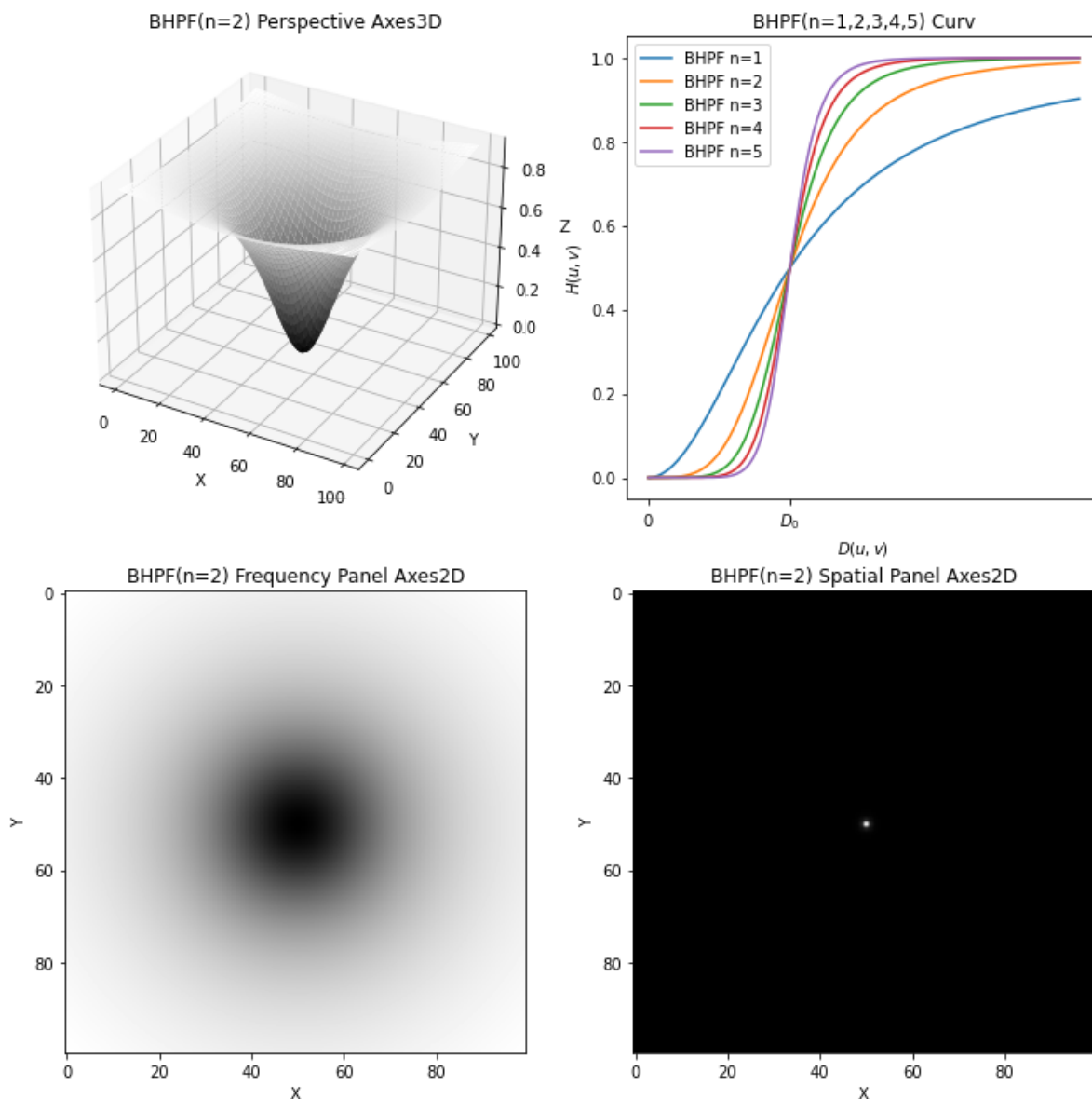


```

funcs.append(ufunc2)
funcs.append(ufunc3)
funcs.append(ufunc4)
funcs.append(ufunc5)

drawCurv(ax2,funcs,labels,d,title = "BHPF(n=1,2,3,4,5) Curv")
drawPanel(ax3,myfilter,title = "BHPF(n=2) Frequency Panel Axes2D")
spatial_myfilter = frequencyToSpatial(myfilter)
drawPanel(ax4,spatial_myfilter,title = "BHPF(n=2) Spatial Panel Axes2D")
plt.show()

```



## 6. 高斯滤波器

### 6.1. 高斯低通滤波器 GLPF

```

In [11]: # 获得指定大小的高斯滤波器
def getGaussianMask(mask_shape,filter_d0,hl_type):
    assert hl_type in ("lpf","hpf")
    rows,cols = mask_shape[0],mask_shape[1]
    crow = rows/2
    ccol = cols/2
    mask = np.zeros((rows,cols))
    for i in range(rows):

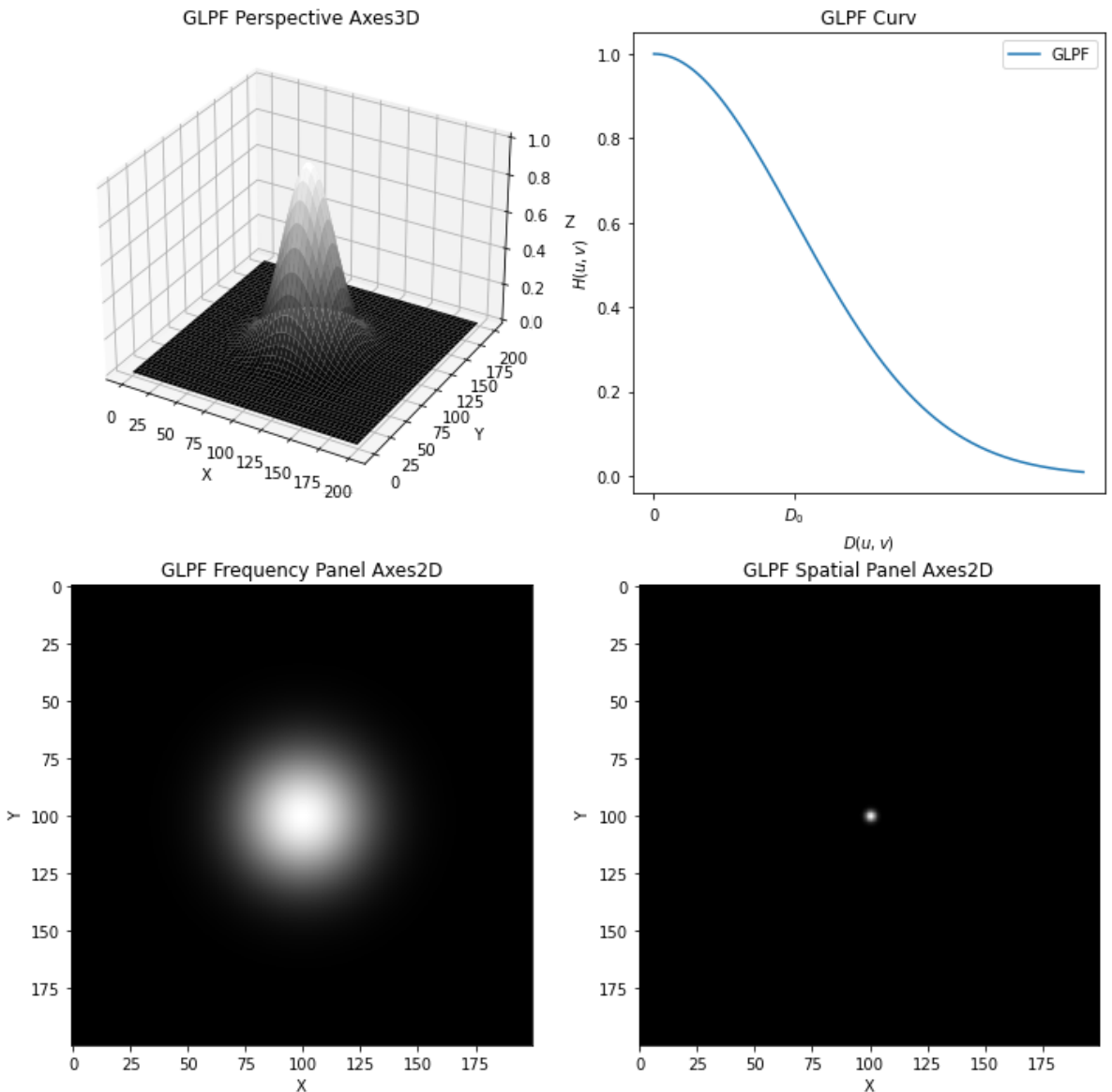
```

```

    for j in range(cols):
        dis = sqrt((i-crow)**2 + (j-ccol)**2)
        if hl_type == "hpf":
            mask[i,j] = 1-np.exp(-(dis**2) / (2*(filter_d0**2)))
        elif hl_type == "lpf":
            mask[i,j] = np.exp(-(dis**2)/(2*(filter_d0**2)))
    return mask

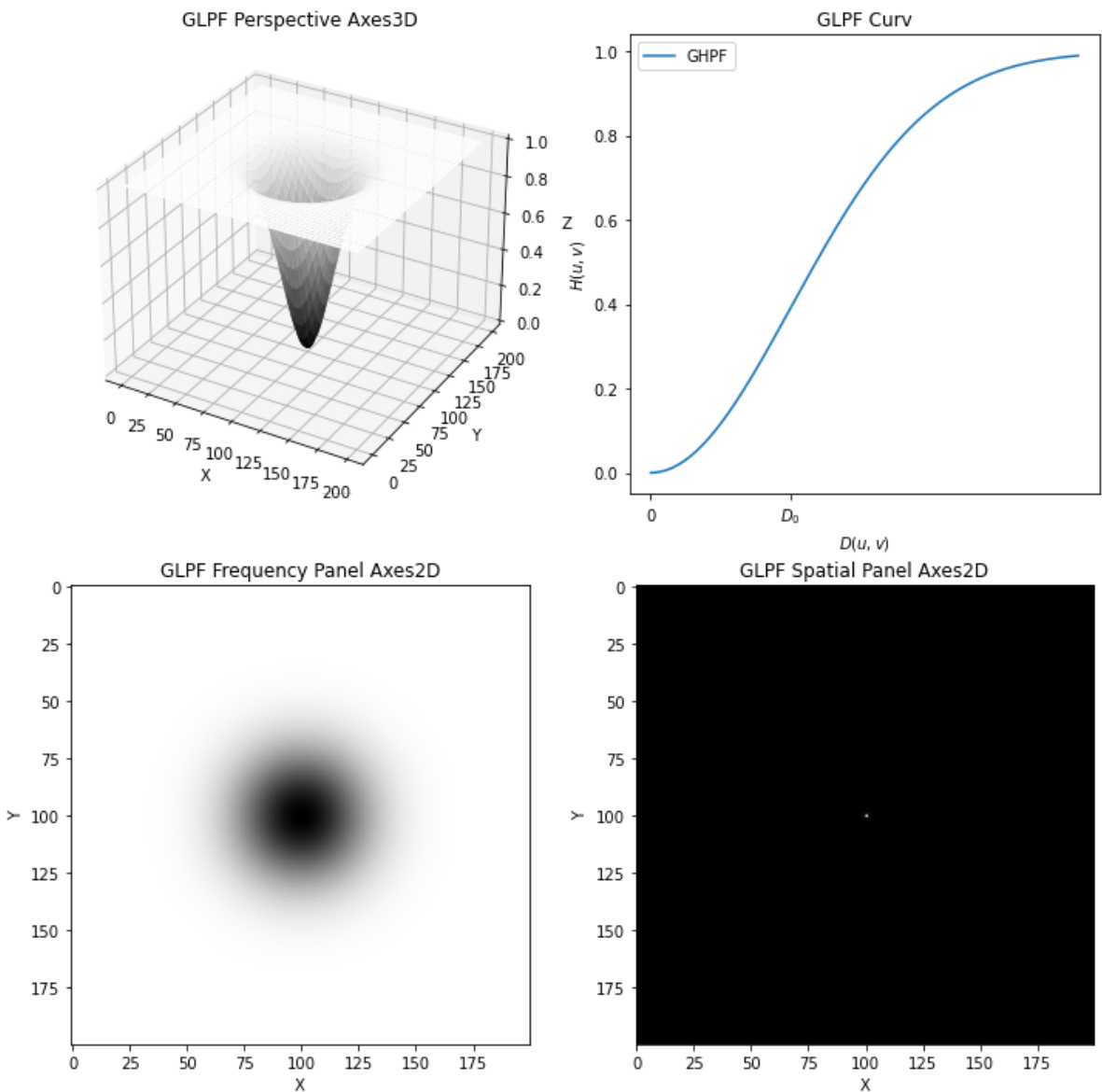
# 测试GLPF
# 参数设置
mask_shape = (200,200)
d = 20
filter_type = "lpf"
# 获得滤波器
myfilter = getGaussianMask(mask_shape,d,filter_type)
# 绘图
plt.figure(figsize=(12,12))
ax1=plt.subplot(221,projection = "3d")
ax2=plt.subplot(222)
ax3=plt.subplot(223)
ax4=plt.subplot(224)
drawPerspective(ax1,myfilter,title = "GLPF Perspective Axes3D", cmap = "gray")
drawCurve(ax2,[lambda x:np.exp(-(x**2)/(2*(d**2)))],["GLPF"],d,title = "GLPF Curv")
drawPanel(ax3,myfilter,title = "GLPF Frequency Panel Axes2D")
spatial_myfilter = frequencyToSpatial(myfilter)
drawPanel(ax4,spatial_myfilter,title = "GLPF Spatial Panel Axes2D")
plt.show()

```



## 6.2. 高斯高通滤波器 GLPF

```
In [12]: # 测试GLPF
d = 20
filter_type = "hpf"
myfilter = getGaussianMask(mask_shape,d,filter_type)
plt.figure(figsize=(12,12))
ax1=plt.subplot(221,projection = "3d")
ax2=plt.subplot(222)
ax3=plt.subplot(223)
ax4=plt.subplot(224)
drawPerspective(ax1,myfilter,title = "GLPF Perspective Axes3D", cmap = "gray")
drawCurve(ax2,[lambda x:1-np.exp(-(x**2)/(2*(d**2)))],["GLPF"],d,title = "GLPF Curve")
drawPanel(ax3,myfilter,title = "GLPF Frequency Panel Axes2D")
spatial_myfilter = frequencyToSpatial(myfilter)
drawPanel(ax4,spatial_myfilter,title = "GLPF Spatial Panel Axes2D")
plt.show()
```



## 四、参考资料

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