

Signal detection in high energy physics via a semisupervised nonparametric approach

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- The Standard Model represents the state of the art in High Energy Physics (HEP)
 - it describes how the fundamental particles interact with each others and with the forces between them giving rise to the matter in the universe
- There are indications that it does not complete our understanding of the universe^[3]
 - research is carried on to explain the shortcomings of this theory
 - experiments are conducted within accelerators (e.g., LHC), where physical particles are made collide and the product of their collision detected
 - do collisions produce any unclassified particle?

- **Ingredients:**

- *background*: process describing the known physics, predominant, *always* observed
- *signal* (new particle): anomalous process, *if* present

- **Main assumption:**

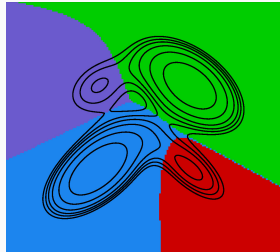
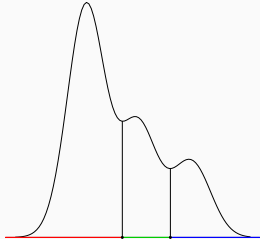
- (possible) signal behaves as a deviation from the background, occurring collectively as an excess over the invariant mass of the background [6]

- **Ingredients:**
 - $\mathcal{X}_b \sim f_b : \mathbb{R}^d \rightarrow \mathbb{R}^+ \cup \{0\}$ *labelled* data from background density, known or estimable arbitrarily well
 - $\mathcal{X}_{bs} \sim f_{bs} : \mathbb{R}^d \rightarrow \mathbb{R}^+ \cup \{0\}$: *unlabelled* data, from the whole process density, unknown, may contain signal
- **Main assumption:**
 - (possible) signal arises as a *mode* in f_{bs} , not seen in f_b

- **Aim:** identify the signal and discriminate it from the background
 - semi-supervised learning: knowledge of one class (background) out of the two possible (background and signal) \leftrightarrow anomaly detection problem
- **Main contribution:** semi-supervise a nonparametric unsupervised framework by integrating within the clustering process the additional information available on the background

The nonparametric unsupervised framework – the principle

- Clusters correspond to the domain of attraction of the modes of the density underlying the data
- The density identifies a partition of the sample space, not only of the data



The nonparametric unsupervised framework –the practice

- Operational search of the modal regions → problem not faced here, use of preexisting methods
 - bump hunting
 - detection of connected components of the density level sets
- Nonparametric estimate of the density, e.g. via kernel methods:

$$\hat{f}(\mathbf{x}; \mathcal{X}, h) = \frac{1}{n \cdot h^d} \sum_{i=1}^n \prod_{j=1}^d K\left(\frac{x_j - x_{ij}}{h}\right), \quad (1)$$

- requires h to be known → selection of the smoothing amount h
- requires d to be limited → selection of variables

Selection of variables

- **Main idea:** a variable is relevant if its marginal distribution f_{bs} shows a changed behavior with respect to $f_b \leftarrow$ this difference shall be due to the presence of a signal, not seen in background density
 - select randomly k variables
 - compare the marginals \hat{f}_b and \hat{f}_{bs} estimated on the selected variables via the application of a nonparametric test^[5]
 - if the comparison highlights a different behavior, update a counter for the selected variables
 - repeat a large number of times and evaluate the relevance of each single variable by evaluating the proportion of times allowing to select and work with a smaller subset
 - select the most relevant variables

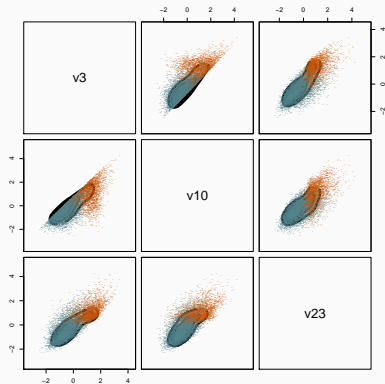
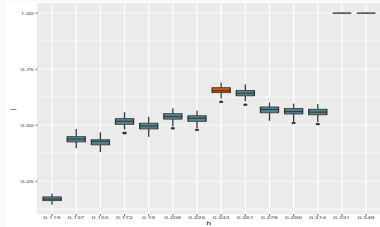
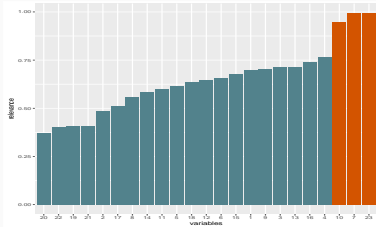
Selection of the smoothing amount h

- **Main idea:** tuning a nonparametric estimate of the unlabelled data by selecting the smoothing amount so that the induced modal partition will classify the labelled background data as accurately as possible.
 - estimate f_b by $\hat{f}_b \rightarrow$ a partition $\mathcal{P}_b(\mathcal{X}_b)$ remains associated
 - for h_{bs} varying in a range of plausible values:
 - estimate f_{bs} by $\hat{f}_{bs}(\cdot; \mathcal{X}_{bs}, h_{bs}) \rightarrow$ identify the partitions $\mathcal{P}_{bs}(\mathcal{X}_{bs})$ and $\mathcal{P}_{bs}(\mathcal{X}_b)$ both defined by the modal regions of \hat{f}_{bs} .
 - compare $\mathcal{P}_{bs}(\mathcal{X}_b)$ with $\mathcal{P}_b(\mathcal{X}_b)$ via the computation of some agreement index I
 - select the bandwidth h_{bs} that maximizes I to estimate f_{bs}
 - identify the ultimate partition $\mathcal{P}_{bs}(\mathcal{X}_{bs})^{[1]}$

Physical process simulated within ATLAS detector configuration^[2]

- **Experiment:** HEP proton-proton collisions (1 collision = 1 observation) → produce particles from two physical processes:
 - background: dominant standard model top quark pair production
 - signal: also decaying to top quark but lacking of an intermediate resonance
- **Variables:** kinematic features of the collisions
 - 18 low-level variables: leading lepton momenta, momenta of the 4 leading jets, b-tagging for each jet, missing transverse momentum magnitude and angle
 - 5 high-level variables: combine low-level information
- \mathcal{X}_b and \mathcal{X}_{bs} both labelled, labels of \mathcal{X}_{bs} employed to evaluate results only
- $n_b = 20000$; $n_{bs} = 10000$
- Signal amount set to 30% of \mathcal{X}_{bs}

Results



	Clusters	
	1	2
Label	1	2
Bkg	6176	847
Sgn	369	2608
Misclassification error:	12.16%	
True positive rate:	87.60%	

- Given the awkward problem, results are promising but the physical context requires high sensitivity and specificity
- Further research is required at different levels:
 - reduce arbitrariness → make smoothing selection fully automatic
 - reduce simplification → use more realistic signal to background ratio and handle imbalance

Relevant references

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