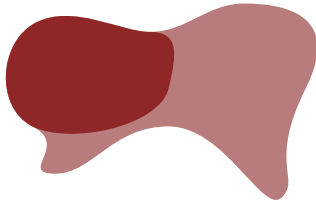
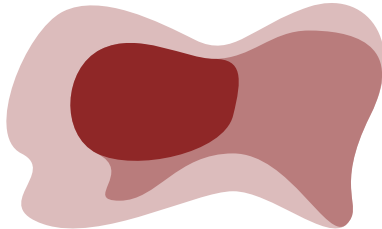


$$\mathcal{S}_1 = \pi_{\mathcal{S}_1}(y; \theta)$$



$$\mathcal{S}_2 = \pi_{\mathcal{S}_2}(y; \theta)$$



$$\mathcal{S}_3 = \pi_{\mathcal{S}_3}(y; \theta)$$