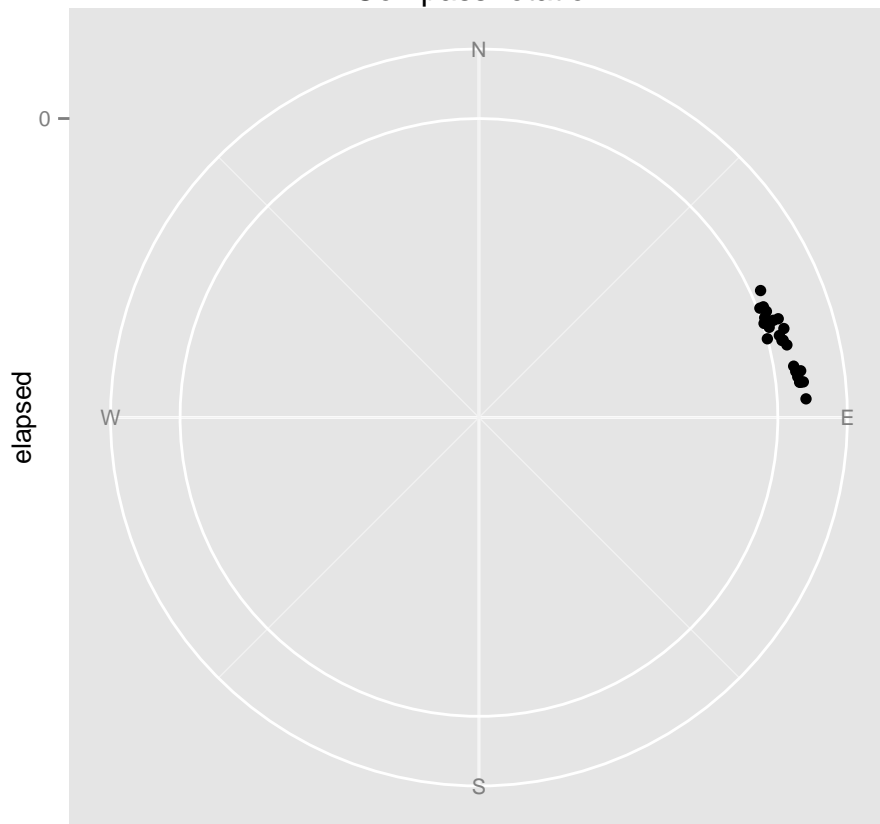
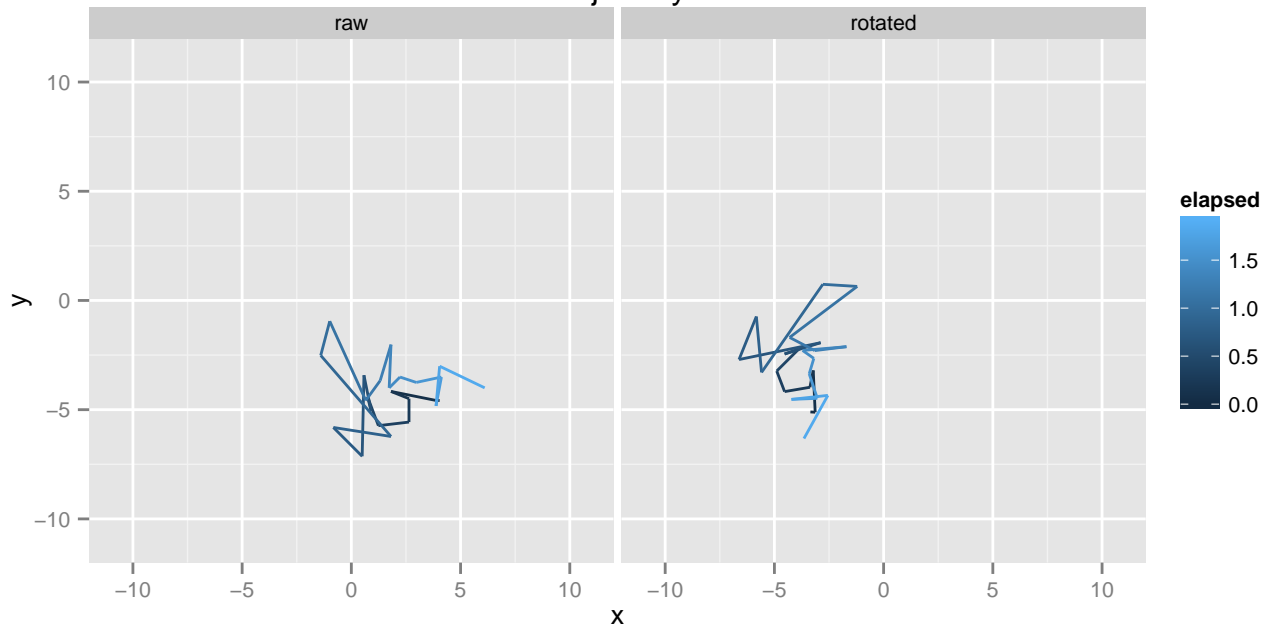


Compass rotation

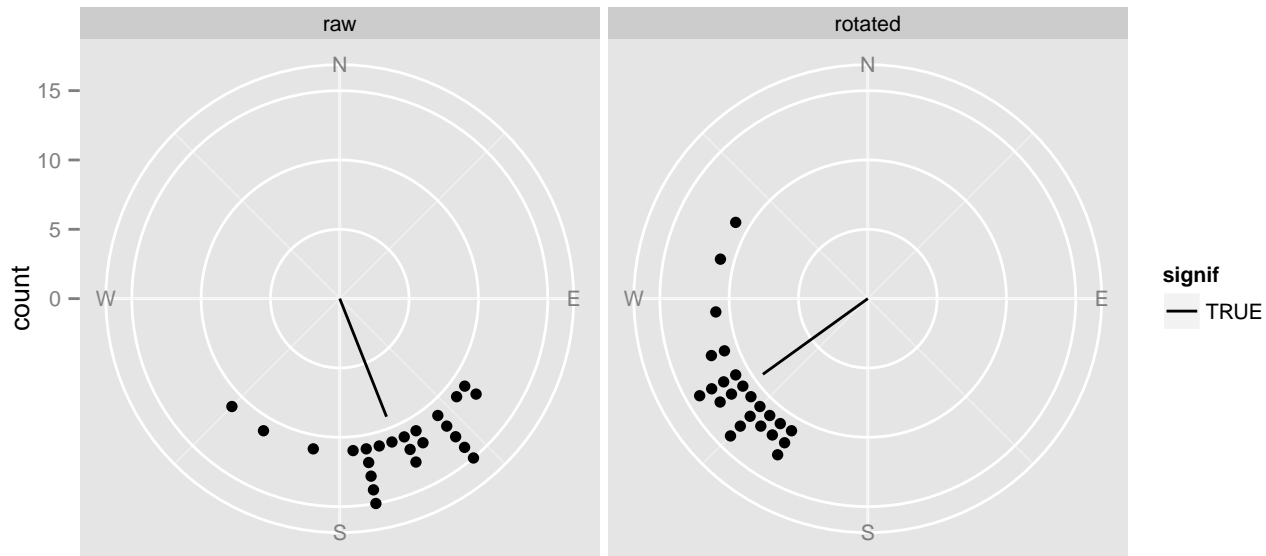


Trajectory



Positions

158° ($r=0.916$, $p=0$) | 234° ($r=0.932$, $p=0$)



Positions

158° ($r=0.916$, $p=0$) | 234° ($r=0.932$, $p=0$)

