

# Its all about 3D!

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# Motivation

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- Recent technologies like 3D scanner, 3D printer and CT scanner allows us to record 3 dimensional data
- It allows us to get representations that are accurate up to 1mm

- Parametrization of a surface in terms of vanishing set of a function, *i.e.* consider

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# Representation of 3D data - Summary

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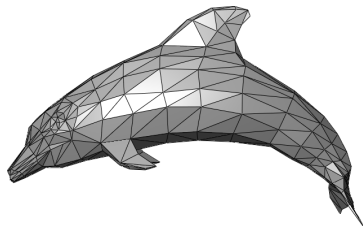
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- **Discretization:** Dividing a mesh into (planar) simpler subfaces and glue them together to obtain an approximation to the whole mesh.

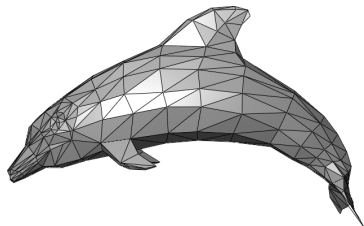
# Representation of 3D data - Triangular meshes

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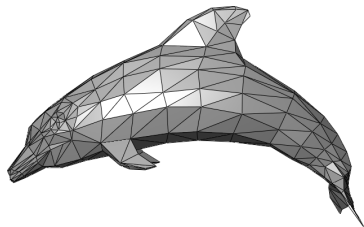
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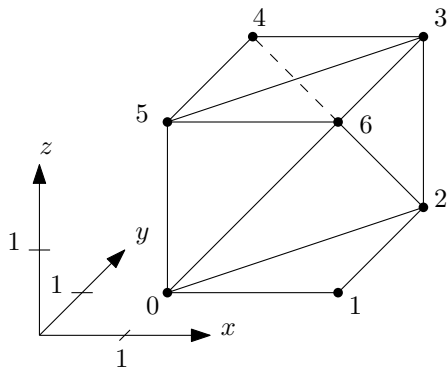
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- Store the coordinates of vertices in a  $n \times 3$  double (or float) list called **vertices**
- Store which vertices make up a triangle in a  $m \times 3$  unsigned integer list called **faces**



# Representation of 3D data - Triangular meshes, Example

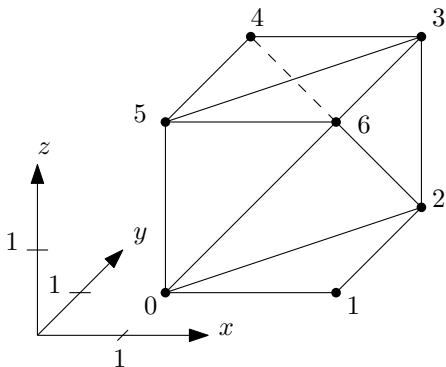
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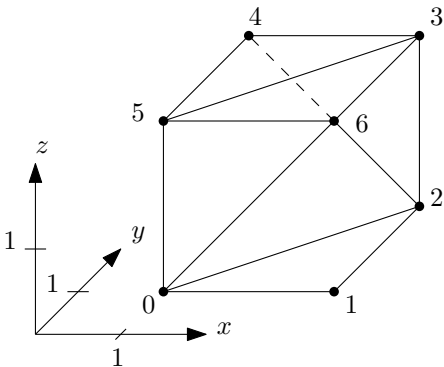




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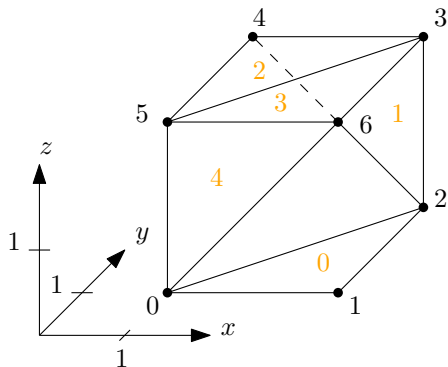


- Note that in general coordinates are real numbers

# Representation of 3D data - Triangular meshes, Example

- faces

$$\begin{pmatrix} 0 & 2 & 1 \\ 3 & 2 & 4 \\ 4 & 5 & 3 \\ 5 & 6 & 3 \\ 5 & 0 & 6 \end{pmatrix}$$

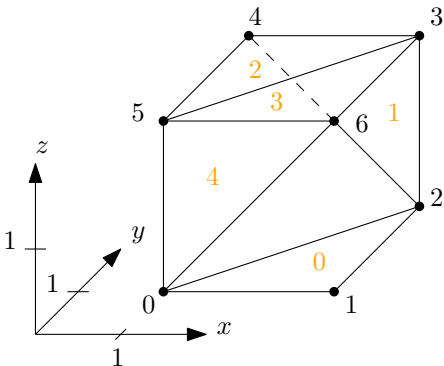


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- What about taking (2 1 0) instead of (0 2 1) for the first face?



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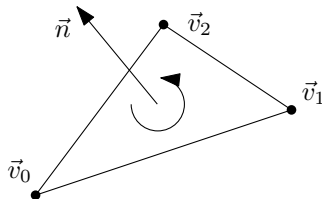
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- Convention:

$$\vec{n} = (\vec{v}_1 - \vec{v}_0) \times (\vec{v}_2 - \vec{v}_0)$$



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- This is a factor of  $\approx 687.45$  . With optimized code I think it is possible to even get factors around 1000.

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- Deformation of meshes

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- The exercise sheet is also within the Git