



**POLITECNICO**  
MILANO 1863

# **Actor Model – Akka Evaluation Lab**

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# Rules

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- Complete the README.md file with
  - Your group identifier
    - From the group registration document
  - Name of each group member
  - A 200-word (max) description of the message flows in your solution
    - What actor talks to what other actor using what message, when, ...
- Create and submit a single zip file with the entire code of your project
  - Name of the file: akka-groupXX.zip
    - XX is the group identifier from the group registration document
  - Submit by the user corresponding to the contact email specified in the group registration document

# Preliminaries

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- You are to create a simple **sensor data processing** system using actors
- The system shall be composed of (at least) three different actor types
  - A variable number of **sensor data processors** that maintain the average of the sensor readings they receive
  - A single **dispatcher** actor that distributes incoming sensor readings according to two different policies (see next)
  - A variable number of **temperature sensor** actors that generate temperature readings

# Dispatching Logic: Load Balancing

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- The dispatcher permanently associates a given temperature sensor to a given sensor data processor
- It maintains the number of temperature sensors funneling data to the same sensor data processor as balanced as possible
  - Example: with five temperature sensors (A, B, C, D, E) and two sensor data processors (P1, P2)
    - C, B, E  $\rightarrow$  P1; A, D  $\rightarrow$  P2 is acceptable
    - C, B, A, E  $\rightarrow$  P1; D  $\rightarrow$  P2 is **not** acceptable

# Dispatching Logic: Round Robin

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- The dispatcher decides on an (any) ordering among data processors
- As a temperature reading is received, the dispatcher forwards the reading to the next sensor data processor in a circular order
  - Example: with five temperature readings coming in at time  $t_0, t_1, t_2, t_3, t_4$  and three sensor data processors
    - Say the ordering is P1, P2, P3
    - $t_0 \rightarrow P1; t_1 \rightarrow P2; t_2 \rightarrow P3; t_4 \rightarrow P1$  is acceptable
    - $t_0 \rightarrow P1; t_1 \rightarrow P2; t_2 \rightarrow P1; t_4 \rightarrow P3$  is **not** acceptable

# Message Types

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- The system shall use (at least) three types of messages
  - **TemperatureMsg** carries temperature readings
  - **DispatchLogic** tells the dispatcher what dispatching logic to use between Load Balancing and Round Robin
  - **GenerateMsg** tells the temperature sensors to generate a new reading

# Failures

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- When a sensor data processor receives a negative temperature reading, **it fails**
- Handling the failure must ensure that the average temperature before the failure is **retained**, yet the faulty temperature reading is excluded from the computation

# Code

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- In the assignment, you also find
  - A definition of the three basic message types
    - You are free to **extend** the message definitions, but you **cannot change** the existing code
    - You can of course define more message types, if needed
  - Two **working actors** corresponding to the (faulty) temperature sensors
    - You should not normally change the code here, but you may need to extend it
  - Templates for the **dispatcher** and the **processor** actors
  - A **template** for a test main method
    - This is necessarily incomplete!!
    - It cannot run as it is!!
    - It must run when you submit