Finding Lane Lines on the Road

Reflection

###1. My pipeline

My pipeline consisted of 5 steps. First, I converted the images to grayscale, then I applied the Gaussian smoothing. After that I used the canny function with its parameters.

The next step was to apply an image mask over the canny edges found.

I wasn't able to modify the draw_lines function, unfortunately.

Subsequently I applied Hough function.

###2. Shortcomings

I found hard to modify draw_lines

###3. Possible improvements

A possible improvement would be to make some changes to draw_lines