Elektrobit

UDACITY

Functional Safety Concept Lane Assistance

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Document history

[Instructions: Fill in the date, version and description fields. You can fill out the Editor field with your name if you want to do so. Keep track of your editing as if this were a real-world project.

For example, if this were your first draft or first submission, you might say version 1.0. If this is a second submission attempt, then you'd add a second line with a new date and version 2.0]

Date	Version	Editor	Description
10/04/2017	1.0	Alessandro Gullì	First Submission

Table of Contents

[Instructions: We have provided a table of contents. If you change the document structure, please update the table of contents accordingly. The table of contents should show each section of the document and page numbers or links. Most word processors can do this for you. In Google Docs, you can use headings for each section and then go to Insert > Table of Contents. Microsoft Word has similar capabilities]

Purpose of the Functional Safety Concept

[Instructions: Answer what is the purpose of a functional safety concept?]

The goal of functional safety is avoiding accidents by reducing risk to acceptable level.

Inputs to the Functional Safety Concept

Safety goals from the Hazard Analysis and Risk Assessment

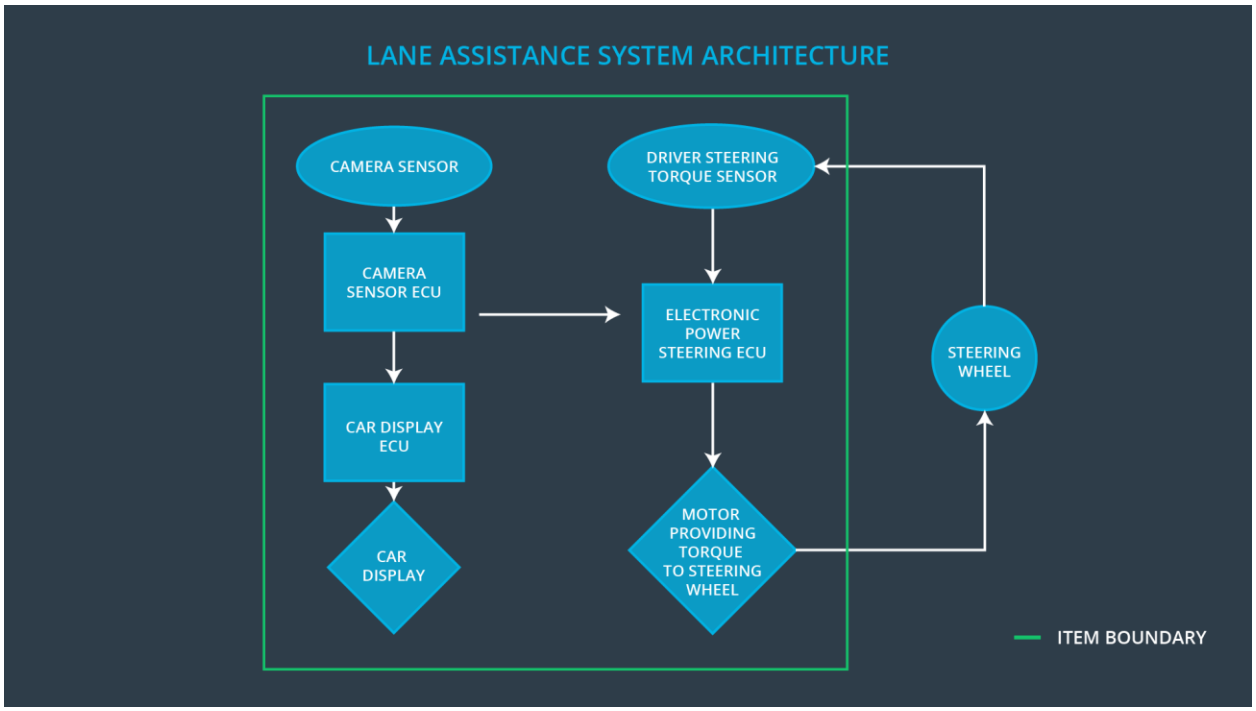
[Instructions:
REQUIRED:
Provide the lane departure warning and lane keeping assistance safety goals as discussed in the lessons and derived in the hazard analysis and risk assessment.

OPTIONAL:
If you expanded the hazard analysis and risk assessment to include other safety goals, include them here.
]

ID	Safety Goal
Safety_Goal_01	The oscillating torque of the steering wheel function from the lane departure system shall be limited
Safety_Goal_02	The lane keeping assistance function shall be time-limited, and the additional steering torque shall end after a given time interval so that the driver cannot misuse the system for autonomous driving.

Preliminary Architecture

[Instructions: Provide a preliminary architecture for the lane assistance item. Hint: See Lesson 3: Item Definition]



Description of architecture elements

[Instructions: Provide a description for each of the item elements; what is each element's purpose in the lane assistance item?]

Element	Description
Camera Sensor	The Camera Sensor reads in images from the road
Camera Sensor ECU	The Camera Sensor ECU identifies when the vehicle has accidentally departed its lane and send appropriate messages to the Car Display ECU and Electronic Power Steering ECU
Car Display	The Car Display receives from the Camera Sensor ECU data regarding the Lane Assistance System functionality informing the driver about the situation
Car Display ECU	The Car Display ECU receives from the Camera Sensor ECU the vehicle has accidentally departed its lane and send messages to the Car Display to notify what is happening
Driver Steering Torque Sensor	Measures the steering torque of the car and send the information to the Electronic Power Steering ECU
Electronic Power Steering ECU	Ensure torque output is below maximum

Motor	The Motor provides torque to the steering wheel

Functional Safety Concept

The functional safety concept consists of:

- Functional safety analysis
- Functional safety requirements
- Functional safety architecture
- Warning and degradation concept

Functional Safety Analysis

[Instructions: Fill in the functional safety analysis table below.]

Malfunction ID	**Main Function of the Item Related to Safety Goal Violations**	**Guidewords (NO, WRONG, EARLY, LATE, MORE, LESS)**	**Resulting Malfunction**
Malfunction_01	Lane Departure Warning (LDW) function shall apply an oscillating steering torque to provide the driver a haptic feedback	MORE	The lane departure warning function applies an oscillating torque with very high torque amplitude (above limit)
Malfunction_02	Lane Departure Warning (LDW) function shall apply an oscillating steering torque to provide the driver a haptic feedback	MORE	The lane departure warning function applies an oscillating torque with very high torque frequency (above limit)
Malfunction_03	Lane Keeping Assistance (LKA) function shall apply the steering torque when active in order to stay in ego lane	NO	The lane keeping assistance function is not limited in time duration which leads to misuse as an autonomous driving function

Functional Safety Requirements

[Instructions: Fill in the functional safety requirements for the lane departure warning]

Lane Departure Warning (LDW) Requirements:

ID	Functional Safety Requirement	ASIL	Fault-Tolerant Time Interval	Safe State
Functional Safety Requirement 01-01	The lane keeping item shall ensure that the lane departure oscillating torque amplitude is below Max_Torque_Amplitude	C	50 mS	LDW torque output is set to zero
Functional Safety Requirement 01-02	The Lane keeping item shall ensure that the lane departure oscillating torque frequency is below Max_Torque_Frequency	C	50 mS	LDW torque output is set to zero

Lane Departure Warning (LDW) Verification and Validation Acceptance Criteria:

ID	Validation Acceptance Criteria and Method	Verification Acceptance Criteria and Method
Functional Safety Requirement 01-01	Validate the choices of a reasonable range of torque values, afterward testing how drivers react to different torque amplitudes	Verify that the safety requirement is met; when the torque amplitude crosses the limit, the lane assistance output is set to zero within the 50 ms fault tolerant time interval. For this specific case, we would probably do a software test inserting a fault into the system and seeing what happens
Functional Safety Requirement 01-02	Validate the choices of a reasonable range of torque values, afterward testing how drivers react to different torque frequencies	Verify that the safety requirement is met; when the torque amplitude crosses the limit, the lane assistance output is set to zero within the 50 ms fault tolerant time interval. For this specific case, we would probably do a software test inserting a fault into the system and seeing what happens

[Instructions: Fill in the functional safety requirements for the lane keeping assistance]

Lane Keeping Assistance (LKA) Requirements:

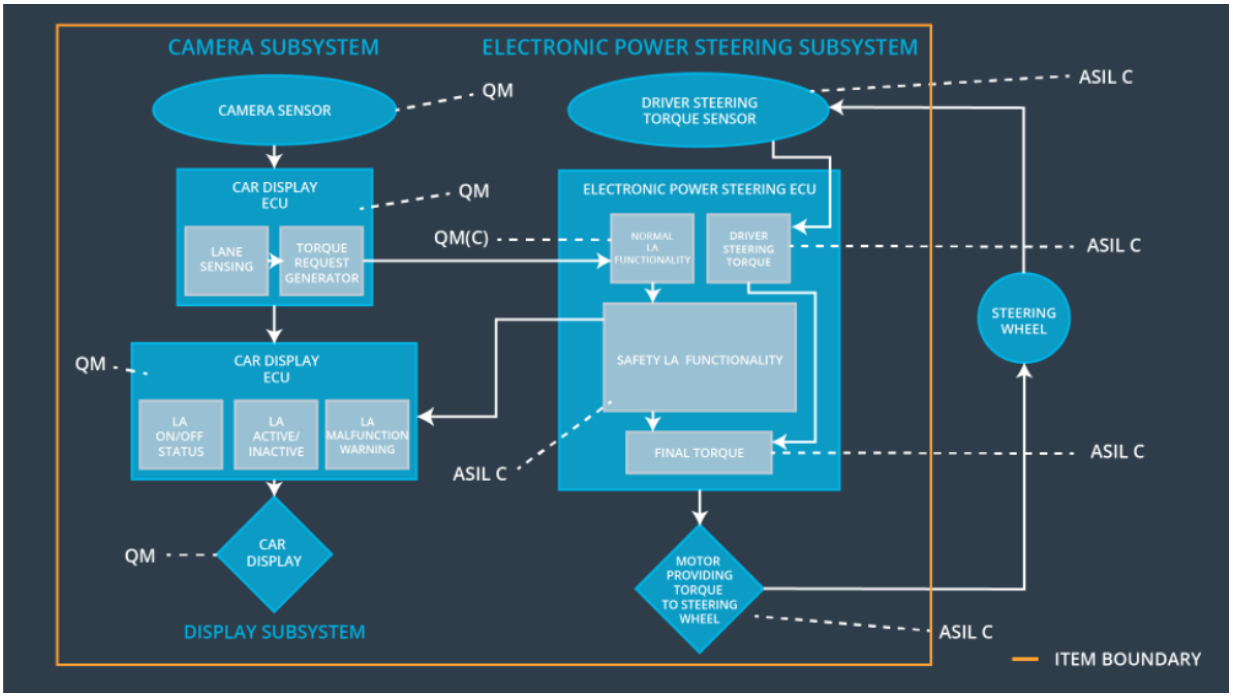
ID	Functional Safety Requirement	ASIL	Fault-Tolerant Time Interval	Safe State
Functional Safety Requirement 02-01	The lane keeping item shall ensure that the lane keeping assistance torque is applied for only Max_Duration	B	500 mS	LKA torque output is set to zero

Lane Keeping Assistance (LKA) Verification and Validation Acceptance Criteria:

ID	Validation Acceptance Criteria and Method	Verification Acceptance Criteria and Method
Functional Safety Requirement 02-01	Test and validate that the max_duration chosen really did dissuade drivers from taking their hands off the wheel	Verify that the system really does turn off if the lane keeping assistance every exceeded max_duration

Refinement of the System Architecture

[Instructions: Include the refined system architecture. Hint: The refined system architecture should include the system architecture from the end of the functional safety lesson including all of the ASIL labels.]



Allocation of Functional Safety Requirements to Architecture Elements

[Instructions: Mark which element or elements are responsible for meeting the functional safety requirement. Hint: Only one ECU is responsible for meeting all of the requirements.]

ID	Functional Safety Requirement	Electronic Power Steering ECU	Camera ECU	Car Display ECU
Functional Safety Requirement 01-01	The electronic power steering ECU shall ensure that lane departure warning oscillating torque amplitude is below Max_Torque_Amplitude	X		
Functional Safety Requirement 01-02	The electronic power steering ECU shall ensure that lane departure warning oscillating torque frequency is below Max_Torque_Frequency	X		

Functional Safety Requirement 02-01	The electronic power steering ECU shall ensure that the lane keeping assistance torque is applied for only Max_Duration	X		

Warning and Degradation Concept

[Instructions: Fill in the warning and degradation concept.]

ID	Degradation Mode	Trigger for Degradation Mode	Safe State invoked?	Driver Warning
WDC-01	Turn off the functionality	Malfunction	YES	Through the Car Display, a warning light turns on
WDC-02	Turn off the functionality	Malfunction	YES	Through the Car Display, a warning light turns on