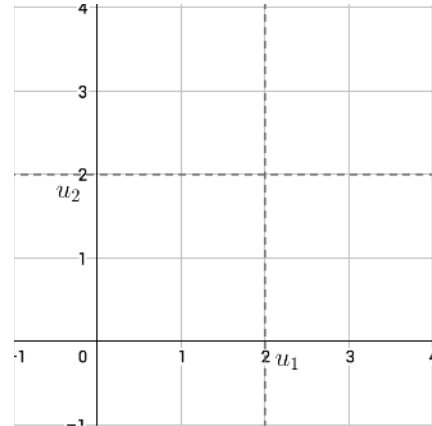


Linear Algebra

Vectors

- Every real number can be used to represent a point on a line which is a 1-Dimensional space (1D), \mathbb{R}^1
- A pair of real numbers can be used to represent a point in a plane, which is a 2D space, \mathbb{R}^2
- A triplet of real numbers can be used to represent a point in the 3D space, \mathbb{R}^3



Definition: A scalar is just another name for a real number

Definition: a vector of dimension n is a **ordered** collection of elements, called *vector components*

Notation: Vectors are usually represented by letters. In a typewritten word letters are usually written in **boldface**. In handwriting, the right arrow written above sometimes used to represent vectors. **We will underline vectors.**

Let $\underline{u} \in \mathbb{R}^n$, the i -th component of the vector will be written as $u_i, i = 1, \dots, n$

Vector Representation

$$\text{Let } \underline{u} \in \mathbb{R}^2, \underline{u} = \begin{pmatrix} 3 \\ 1 \end{pmatrix}$$

Representation 1: Two ordered numbers

Representation 2: an arrow starting from the origin point going 3 units right and 1 up

Representation 3: A vector can also be a point in \mathbb{R}^2 with the coordinates $x_1 = 3, x_2 = 1$, the end point of the arrow starting from the origin.

Definition: Two vectors are equal if and only if the corresponding components are equal. Let $\underline{u}, \underline{v} \in \mathbb{R}^n$ $\underline{u} = \underline{v} \iff u_i = v_i$, for any $i = 1, \dots, n$

Vectorial Addition

Definition: Let \underline{u} and $\underline{v} \in \mathbb{R}^n$. The vector $\underline{w} \in \mathbb{R}^n$, is the sum of \underline{u} and \underline{v} .

$$\underline{w} = \underline{u} + \underline{v}, \text{ if } \underline{u}_i + \underline{v}_i, \forall i = 1, \dots, n$$

(\underline{u} and \underline{v} must belong to the same space)

Definition: The product of a scalar $\alpha \in \mathbb{R}$ and a vector $\underline{u} \in \mathbb{R}^n$ is defined as:

$$\alpha \underline{u} = \begin{pmatrix} \alpha u_1 \\ \alpha u_2 \end{pmatrix}$$

Definition: Let $\alpha, \beta \in \mathbb{R}$ and \underline{u} and $\underline{v} \in \mathbb{R}^n$. The sum of the $\alpha \underline{u}$ and $\beta \underline{v}$ is called a **linear combination** of \underline{u} and \underline{v} :

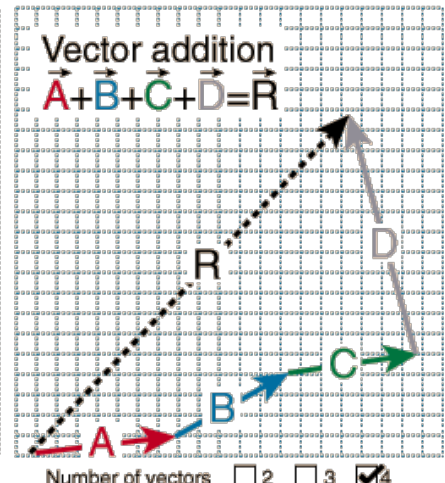
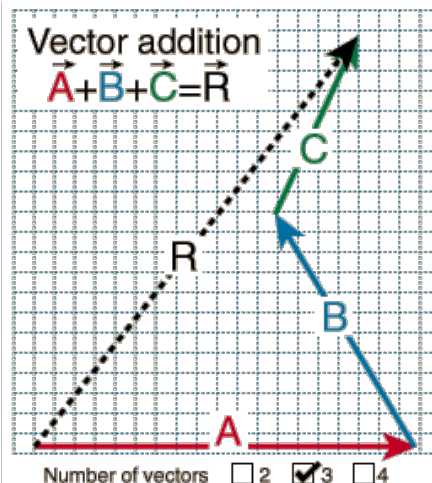
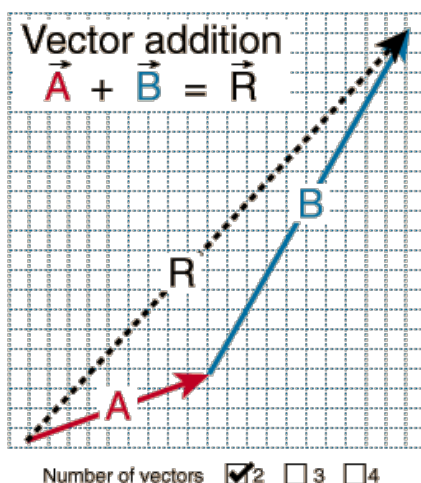
$$\alpha \underline{u} + \beta \underline{v} = \begin{pmatrix} \alpha u_1 + \beta v_1 \\ \alpha u_2 + \beta v_2 \end{pmatrix}$$

Definition: The vector $\underline{u} \in \mathbb{R}^n$ with all of its components $= 0$, is called the **zero vector** $\underline{0}$

Graphical Representation of Vectorial Operations

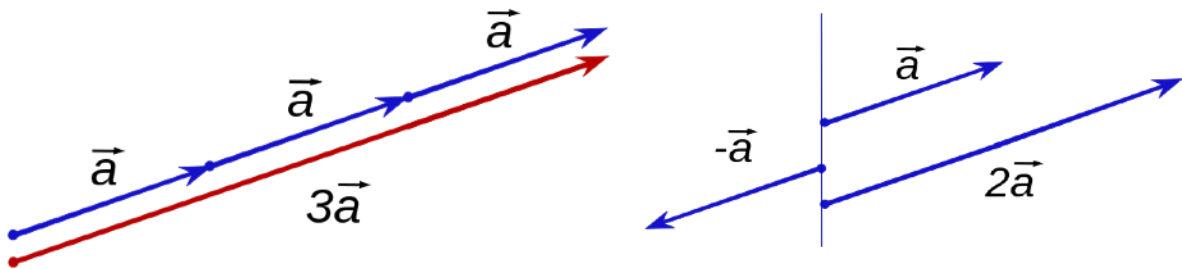
Vectorial Addition

1. Draw a vector \underline{A} to scale;
2. Draw a vector \underline{B} to scale, starting at the end of \underline{A} ;
3. Draw a line from the beginning of \underline{A} to the end of \underline{B} . The Angle can be measured and the size of \underline{R} determined by scaling



Vectorial Multiplication by a scalar (*scaling*)

4. Draw a vector \underline{A} to scale;
5. Scale it by n times, where n is the scalar, if n is negative, the process is called ***negating***;
6. Conserve the direction of the initial vector \underline{A} .



Consider $\underline{u}, \underline{v} \in \mathbb{R}^n$ are on the same line, if and only if there exists two scalars α and $\beta \in \mathbb{R}$ such that $\alpha \underline{u} + \beta \underline{v} = \underline{0}$ with $\alpha \neq 0$ or $\beta \neq 0$

Vectorial Dot Product

Definition: Let us consider the vectors $\underline{u}, \underline{v}$ Dot or Scalar Product is defined as:

$$\langle \underline{u}, \underline{v} \rangle = u_1 v_1 + u_2 v_2 + \dots + u_n v_n = \sum_{i=1}^n u_i v_i$$

If the Dot Product of two vectors is zero it means they are ortogonal

Properties of the dot product

$$\underline{u}, \underline{v} \in \mathbb{R}^n, \forall \alpha \in \mathbb{R}$$

$$\langle \alpha \underline{u}, \underline{v} \rangle = \alpha \langle \underline{u}, \underline{v} \rangle$$

Proof:

$$\langle \alpha \underline{u}, \underline{v} \rangle = (\alpha u_1) v_1 + (\alpha u_2) v_2 + \dots + (\alpha u_n) v_n =$$

$$\alpha (u_1 v_1 + u_2 v_2 + \dots + u_n v_n) = \alpha \langle \underline{u}, \underline{v} \rangle$$

Bilinearity:

Length of a Vector

Let us consider $\underline{u} = \begin{pmatrix} 3 \\ 4 \end{pmatrix}$, $\underline{v} = \underline{u}$, $\underline{u}, \underline{v} \in \mathbb{R}^2$

$$\langle \underline{u}, \underline{v} \rangle = u_1 \cdot v_1 + u_2 \cdot v_2 + \dots + u_n \cdot v_n = 9 + 16 = 5^2$$

Definition: The length of a vector $\underline{u} \in \mathbb{R}^n$ (also called the Euclidean Norm) is defined as:

$$||\underline{u}|| = \sqrt{\langle \underline{u}, \underline{u} \rangle}$$

Definition: A unit vector is a vector where the length equals 1. Let us consider

$$\underline{u} \in \mathbb{R}^n, ||\underline{u}|| \in \mathbb{R}^n, ||\underline{u}|| = 1$$

Notation: Sometimes unit vectors are represented using a “hat” on tops, \hat{u}

Question: How do we transform a vector $\underline{u} \in \mathbb{R}^n, \underline{u} \neq \underline{0}$, whose $||\underline{u}|| \neq 1$ and $\neq 0$ into a unit vector?

Answer: We divide it by its length: $\hat{u} = \frac{\underline{u}}{||\underline{u}||} \Rightarrow \underline{u} = \hat{u} ||\underline{u}||$

Question: if the end points of all unit vectors in a plane (\mathbb{R}^2 space, 2D). What do we get?

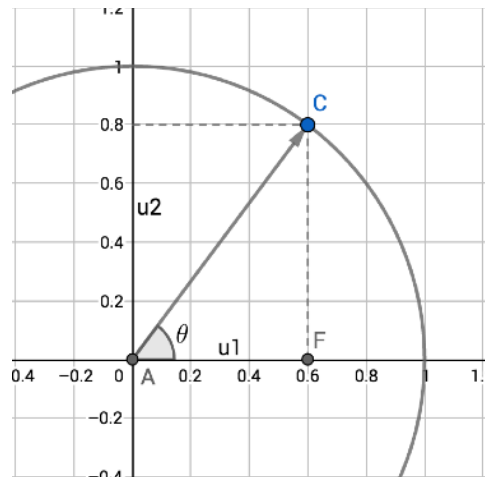
Answer: A circle of radius 1, which is called the *Trigonometric Circle*

Let us consider $\underline{u} \in \mathbb{R}^2, ||\underline{u}|| = 1$

$$\cos \theta = \frac{u_1}{||\underline{u}||}$$

$$\sin \theta = \frac{u_2}{||\underline{u}||} \Rightarrow \underline{u} = \begin{pmatrix} \cos \theta \\ \sin \theta \end{pmatrix}$$

$$||\underline{u}|| = 1$$



$$\langle \underline{u}, \underline{v} \rangle = \cos \theta \cos \gamma + \sin \theta \sin \gamma = \cos(\gamma - \theta) = \cos \Psi = \cos(\angle(\underline{u}, \underline{v}))$$

$$\Rightarrow \cos(\angle(\underline{u}, \underline{v})) = \langle \underline{u}, \underline{v} \rangle$$

We did this demonstration for 2D space, but it is valid for all the other spaces, \mathbb{R}^n

i.e., $\langle \underline{u}, \underline{v} \rangle = \cos(\angle(\underline{u}, \underline{v}))$, for: $\forall \underline{u}, \underline{v} \in \mathbb{R}^n$, that have $||\underline{u}|| = ||\underline{v}|| = 1$

How do we calculate the angle between two arbitrary vectors $\underline{u}, \underline{v} \in \mathbb{R}^n$, the lengths are $\neq 1$?

Let us consider $\underline{u}, \underline{v} \in \mathbb{R}^n, ||\underline{u}|| \neq 1, ||\underline{v}|| \neq 1, \underline{u}, \underline{v} \neq \underline{0}$

$$\begin{aligned}
\langle \underline{u}, \underline{v} \rangle &= \left\langle \frac{||\underline{u}||}{||\underline{u}||} \cdot \underline{u}, \frac{||\underline{v}||}{||\underline{v}||} \cdot \underline{v} \right\rangle = \left\langle ||\underline{u}|| \cdot \frac{1}{||\underline{u}||} \cdot \underline{u}, ||\underline{v}|| \cdot \frac{1}{||\underline{v}||} \cdot \underline{v} \right\rangle = \\
&= \langle ||\underline{u}|| \cdot \hat{\underline{u}}, ||\underline{v}|| \cdot \hat{\underline{v}} \rangle = ||\underline{u}|| \cdot ||\underline{v}|| \langle \hat{\underline{u}}, \hat{\underline{v}} \rangle = ||\underline{u}|| \cdot ||\underline{v}|| \cos(\angle(\underline{u}, \underline{v}))
\end{aligned}$$

Lemma:

Let us consider $\underline{u}, \underline{v} \in \mathbb{R}^n$, two arbitrary vectors $\underline{u}, \underline{v} \neq \underline{0}$, $||\underline{u}|| \neq 1$, $||\underline{v}|| \neq 1$

$$\cos(\angle(\underline{u}, \underline{v})) = \frac{\langle \underline{u}, \underline{v} \rangle}{||\underline{u}|| \cdot ||\underline{v}||}$$

Lemma (Cauchy Schwarz Inequality):

$$| \langle \underline{u}, \underline{v} \rangle | \leq ||\underline{u}|| \cdot ||\underline{v}||$$