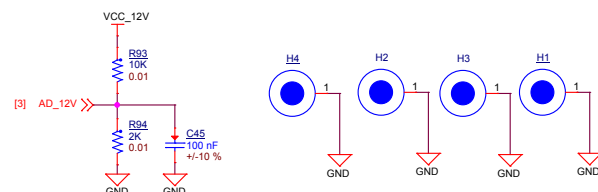
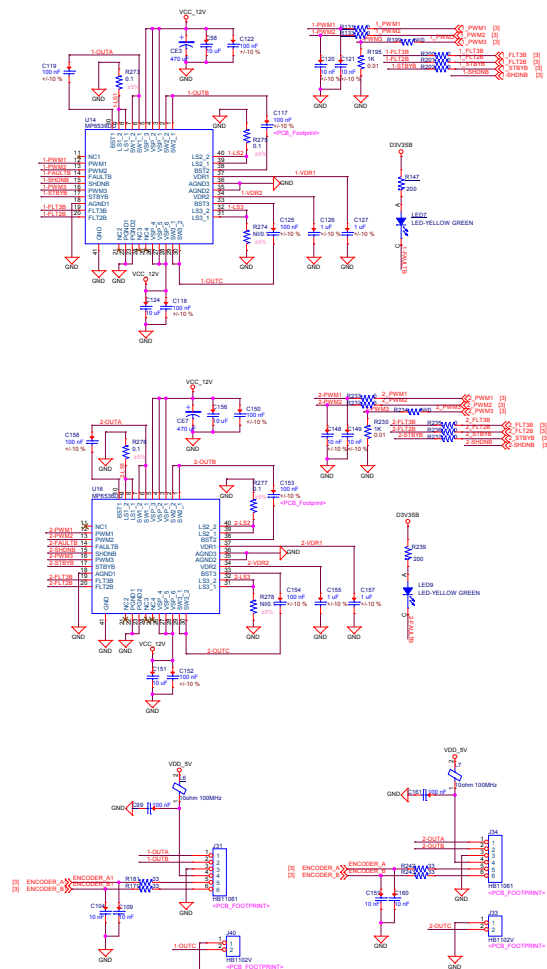


PowerName	Default voltage	Load	Current
VCC_12V	12V	MOTO	10A
VDD_5V	5V	Lidar	500mA
		Ultrasonic	400mA
		IR DROP	200mA
D3V3SB	3V3	STM32	200mA

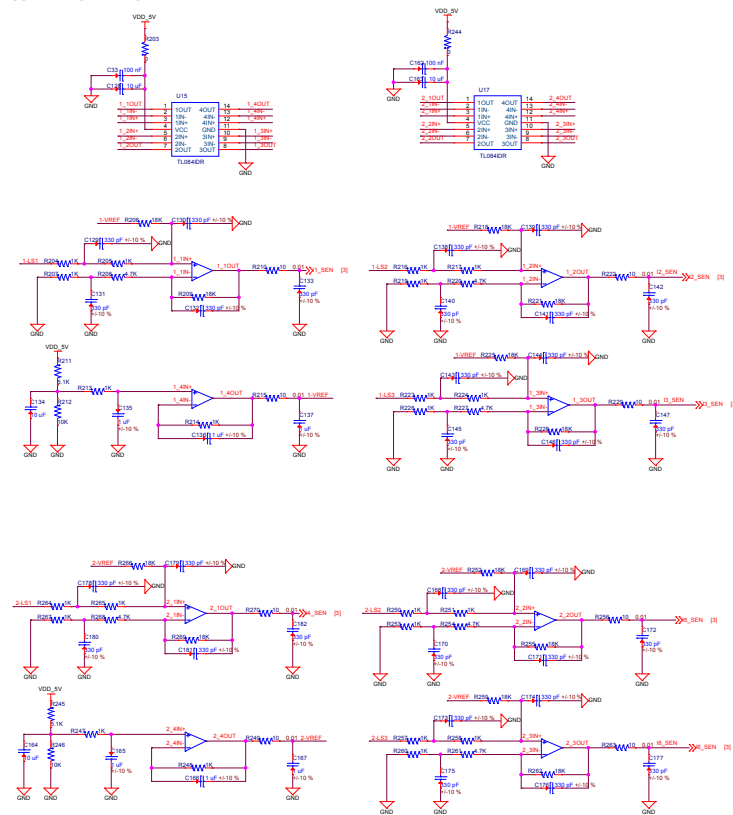




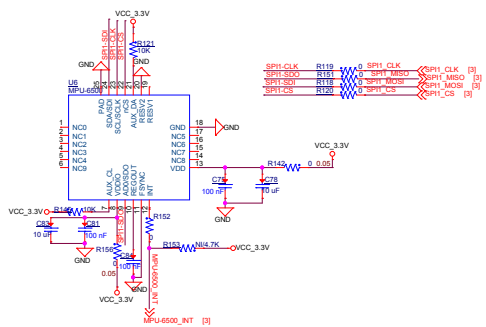
# MOTOR DRIVER



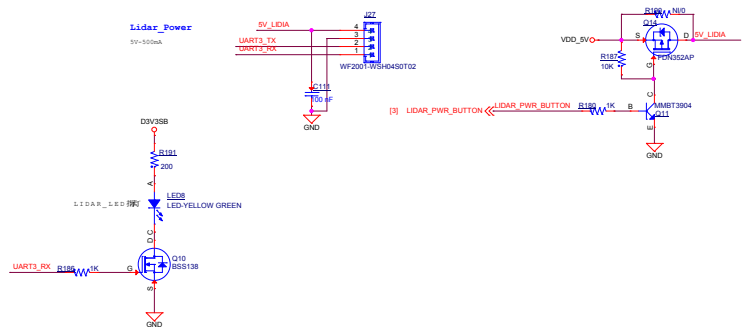
# CURRENT SAMPLING



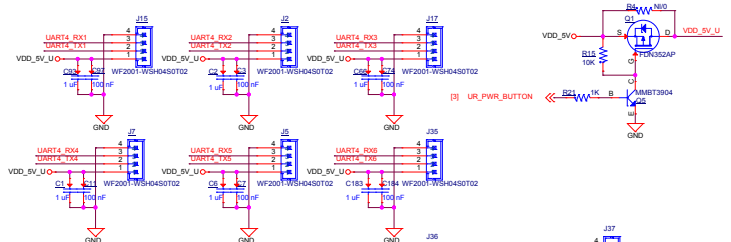
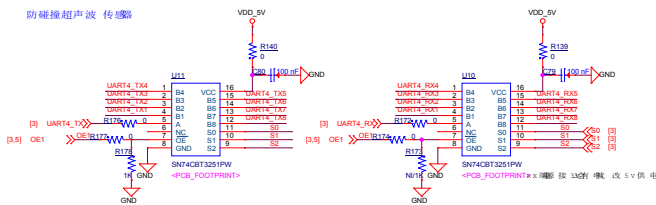
three-axis digital output gyroscope and Accelerometer



## Lidar\_Power



### 防碰撞超声波 传感器



## 防跌落红外传 感器

