

Partial diff equation

- Huge topic!
- Diff. eqs with der. of more than one variable
- Often both space and time (but can be other things!)
- Examples from physics

• Wave eq. $\frac{1D}{\frac{\partial^2 u}{\partial x^2} = A \frac{\partial^2 u}{\partial t^2}}$

$$\frac{2D}{\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = A \frac{\partial^2 u}{\partial t^2}}$$

• Diffusion eq. $\frac{1D}{\frac{\partial^2 u}{\partial x^2} = A \frac{\partial u}{\partial t}}$

• Maxwell's eq. ...

• Poisson's eq. $\frac{2D}{\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = \rho(x, y)}$

• Schrödinger eq. $\frac{2D}{i \frac{\partial u}{\partial t} = -\frac{\partial^2 u}{\partial x^2} - \frac{\partial^2 u}{\partial y^2} + f(x, y, t) u}$

• Classification of PDEs

General 2nd order, linear PDE:

$$A \frac{\partial^2 u}{\partial x^2} + B \frac{\partial^2 u}{\partial x \partial y} + C \frac{\partial^2 u}{\partial y^2} + f\left(u, x, y, \frac{\partial u}{\partial x}, \frac{\partial u}{\partial y}\right) = G(x, y)$$

• Discriminant: $Q = B^2 - 4AC$

• Classification:

$Q < 0$: Elliptic

$Q = 0$: Parabolic

$Q > 0$: Hyperbolic

(analogy
with class.
of conic
sections)

• Our focus:

Three methods:

- Forward diff. (explicit)

- Backward diff (implicit)

- Crank-Nicolson (— — —)

• Partial diff eqs. (PDEs) cont.

• Will look at

1) Forward difference scheme

2) Backward diff. scheme

3) Crank-Nicolson

• Discretized partial derivatives :

• Example: 2 vars. $u(x, y) \rightarrow u_{ij}$

• First derivatives :

$$\frac{\partial u}{\partial x} \approx \begin{cases} \frac{u_{i+1,j} - u_{ij}}{\Delta x} + O(\Delta x) & \text{Forward diff.} \\ \frac{u_{ij} - u_{i-1,j}}{\Delta x} + O(\Delta x) & \text{Backward diff.} \\ \frac{u_{i+1,j} - u_{i-1,j}}{2\Delta x} + O(\Delta x^2) & \text{Central diff.} \end{cases}$$

(Similarly for $\frac{\partial u}{\partial y}$, keeping index i fixed.)

Notation: $\Delta x^2 = (\Delta x)^2$

• Second derivatives:

$$\frac{\partial^2 u}{\partial x^2} \approx \frac{u_{i+1,j} - 2u_{ij} + u_{i-1,j}}{(\Delta x)^2} + O(\Delta x^2)$$

$$\frac{\partial^2 u}{\partial x \partial y} = \frac{\partial}{\partial x} \left(\frac{\partial u}{\partial y} \right) \approx \frac{\left(\frac{\partial u}{\partial y} \right)_{i+1,j} - \left(\frac{\partial u}{\partial y} \right)_{i-1,j}}{2\Delta x}$$

Using central difference for each derivative

we won't need this

$$\approx \frac{u_{i+1,j+1} - u_{i+1,j-1} - u_{i-1,j+1} + u_{i-1,j-1}}{4\Delta x \Delta y} + O(\Delta x^2, \Delta y^2)$$

- Example: 1D diffusion eq. (heat eq.)

$$\frac{\partial u}{\partial t} = D \frac{\partial^2 u}{\partial x^2} \quad D \text{ constant}$$

- We'll take $D=1$
- Will use notation that dist. space and time indices: $u(x,t) \rightarrow u_i^n$ \nwarrow time
 \swarrow space

1) Forward difference, a.k.a "the explicit scheme"

- Discretize + approximate, using F.D. for $\frac{\partial u}{\partial t}$

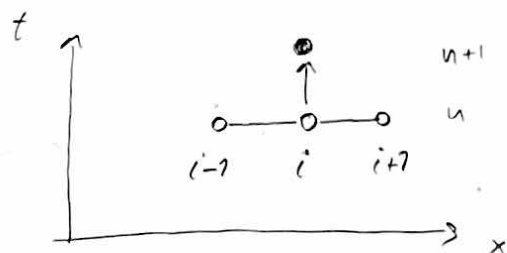
$$\frac{u_i^{n+1} - u_i^n}{\Delta t} = \frac{u_{i+1}^n - 2u_i^n + u_{i-1}^n}{\Delta x^2}$$

$$u_i^{n+1} = u_i^n + \frac{\Delta t}{\Delta x^2} [u_{i+1}^n - 2u_i^n + u_{i-1}^n]$$

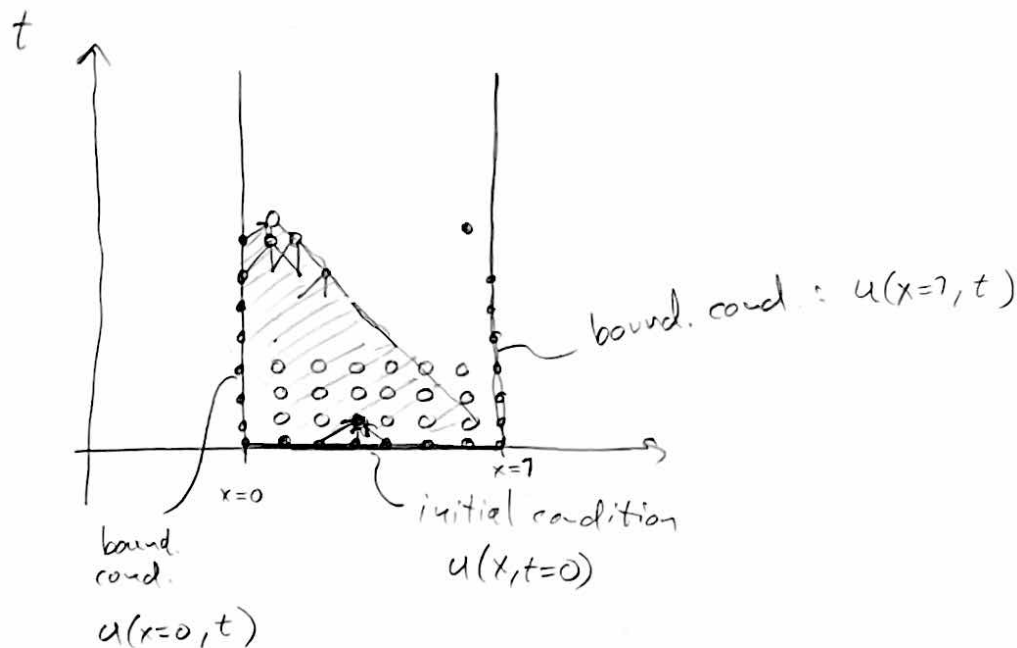
- Define $\alpha \equiv \frac{\Delta t}{\Delta x^2}$

$$\boxed{u_i^{n+1} = (1 - 2\alpha)u_i^n + \alpha(u_{i+1}^n + u_{i-1}^n)} \quad (*)$$

- Explicit: can obtain u_i^{n+1} (next time step) using only solution at current time step (n)



"computational molecule"



• Can express (*) as

$$\bar{u}^{n+1} = A \bar{u}^n$$

where

$$A = I - \alpha B$$

$$\text{and } B = \text{tridiag}(-1, 2, -1)$$

[Just matrix multiplication,
no need to solve a system
of equations.]

[But no need to perform
the full matrix-vector
multiplication here, since
A is a simple tridiag.
(Avoid a bunch of 0-multiplic.)]

• Criterion for stability:

$$\alpha = \frac{\Delta t}{(\Delta x)^2} \leq \frac{1}{2}$$

$$\Delta t \leq \frac{1}{2} \Delta x^2$$

To get high spatial
resolution, need
tiny time steps...

$$\Delta x = 0.1 \Rightarrow \Delta t \leq \frac{1}{2} (0.1)^2 = 0.005$$

$$\Delta x = 0.01 \Rightarrow \Delta t \leq 0.00005$$

$$\begin{aligned} &\text{With constant } D \leq 1: \\ &\alpha = \frac{D \Delta t}{\Delta x^2} \leq \frac{1}{2} \end{aligned}$$

[Shown in Marten's
lecture notes.
Based on "spectral
radius" of matrix
A, req. that
 $\rho(A) < 1$.]

- Accuracy : Global error from truncation is $\mathcal{O}(\Delta x^2) + \mathcal{O}(\Delta t)$

- Make sure to dist. accuracy and stability.

A method can be inaccurate but in a stable way,

In an unstable case the solution eventually "blows up"

2) Backward difference scheme (An implicit scheme)

- Now use $\frac{\partial u}{\partial t} \approx \frac{u_i^n - u_i^{n-1}}{\Delta t}$

- So diffusion eq. becomes

$$\frac{u_i^n - u_i^{n-1}}{\Delta t} = \frac{u_{i+1}^n - 2u_i^n + u_{i-1}^n}{\Delta x^2}$$

$$\Rightarrow \boxed{u_i^n(1 + 2\alpha) - \alpha[u_{i+1}^n + u_{i-1}^n] = u_i^{n-1}} \quad \alpha \equiv \frac{\Delta t}{\Delta x^2}$$

- Three unknown: $u_{i-1}^n, u_i^n, u_{i+1}^n$

- Cannot solve one such eq. in isolation
need the full system of eqs. to
have N eqs. w/ N unknowns



- Try inserting $u=1$, $u-1=0$
 $u=2$, $u-1=1$

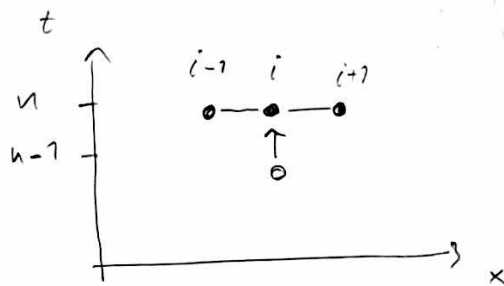
⇒ Get familiar tridiagonal system of equations

$$\boxed{A \bar{u}^n = \bar{u}^{n-1}}$$

with $A = \text{tridiag}(-\alpha, 1+2\alpha, -\alpha)$

or $\boxed{[1 + \alpha B] \bar{u}^n = \bar{u}^{n-1}}$

with $B = \text{tridiag}(-1, 2, -1)$



← calc. molecule

- We can solve $A \bar{u}^n = \bar{u}^{n-1}$ at every time step using e.g. a tridiagonal solver algo. (Proj. 1)
- Stable for all choices of $\Delta t, \Delta x$, i.e. no requirement on $\alpha = \frac{\Delta t}{\Delta x^2}$ for stability. But more work to implement than F.D.
- Accuracy $\sim O(\Delta t) + O(\Delta x^2)$ (Same as F.D.)

3) Crank-Nicolson scheme (implicit)

- Consider the different time derivatives ,

$$\boxed{\frac{\partial u}{\partial t} = F(x, t)}$$

- F.D. : $\frac{u_i^{n+1} - u_i^n}{\Delta t} = F_i^n \quad (1)$

- B.D., written with $n+1$ and n :

$$\frac{u_i^{n+1} - u_i^n}{\Delta t} = F_i^{n+1} \quad \leftarrow \text{Note}$$

- A linear combination of F.D. and B.D. is

$$\boxed{\frac{u_i^{n+1} - u_i^n}{\Delta t} = \theta F_i^{n+1} + (1-\theta) F_i^n} \quad , \theta \in [0, 1]$$

"The θ rule"

$$\theta = 1 \Leftrightarrow \text{F.D.}$$

$$\theta = 0 \Leftrightarrow \text{B.D.}$$

- Take $\theta = \frac{1}{2}$ to get Crank-Nicolson:

$$\boxed{\frac{u_i^{n+1} - u_i^n}{\Delta t} = \frac{1}{2} [F_i^{n+1} + F_i^n]}$$



• Apply to case of the diffusion eq.: $\boxed{\frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2}}$

$$\frac{u_i^{n+1} - u_i^n}{\Delta t} = \frac{1}{2} \left[\frac{u_{i+1}^{n+1} - 2u_i^{n+1} + u_{i-1}^{n+1}}{\Delta x^2} + \frac{u_{i+1}^n - 2u_i^n + u_{i-1}^n}{\Delta x^2} \right]$$

• Collect $(n+1)$ terms on LHS and n terms on the RHS

• Define $\alpha \equiv \frac{\Delta t}{\Delta x^2}$

$$\Rightarrow \underline{-\alpha u_{i-1}^{n+1} + (2+2\alpha)u_i^{n+1} - \alpha u_{i+1}^{n+1} = \alpha u_{i-1}^n + (2-2\alpha)u_i^n + \alpha u_{i+1}^n}$$

Same type of expr.
that you'll derive
for the case of
Schr. eq.

• Since we here only have 1D dim,
nothing fancy req. to put this into matrix form

$$\boxed{A \bar{u}^{n+1} = B \bar{u}^n}$$

where $A = 2I + \alpha T$

$B = 2I - \alpha T$

, $T = \text{tridiag}(-1, 2, -1)$

• Solve in two steps:

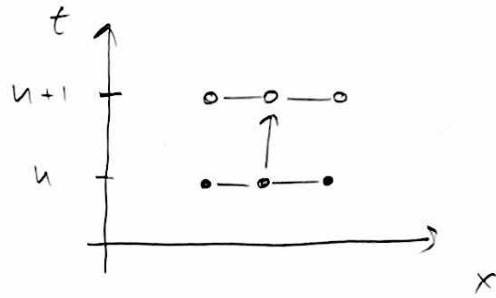
1) Multiply $B \bar{u}^n \equiv \bar{b}$

2) Solve $A \bar{u}^{n+1} = \bar{b}$ for \bar{u}^{n+1}

• Accuracy $\sim O(\Delta t^2) + O(\Delta x^2)$

• Stable for all $\Delta x, \Delta t$

• Calc. molecule :



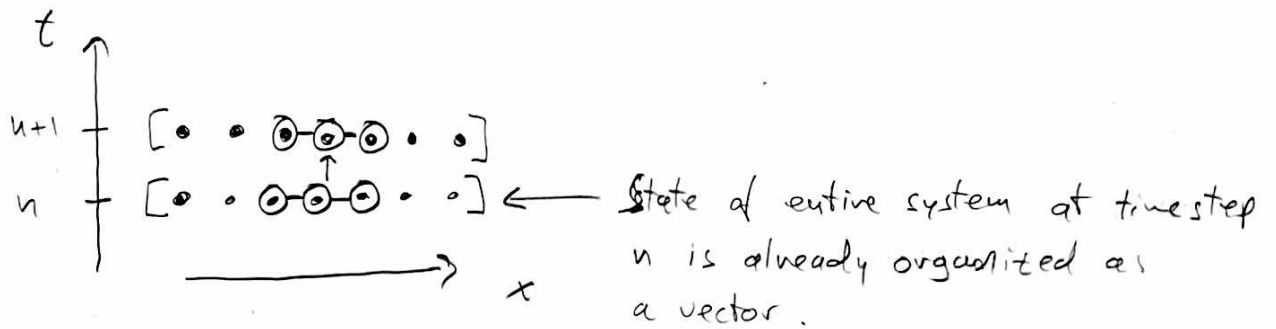
Summary of schemes :

<u>Scheme</u>	<u>Accuracy</u>	<u>Stability req.</u>
• Forward diff (explicit)	$O(\Delta t) + O(\Delta x^2)$	$\Delta t \leq \frac{1}{2} \Delta x^2$
• Backward diff (implicit)	$O(\Delta t) + O(\Delta x^2)$	any $\Delta t, \Delta x$
• Crank-Nicolson	$O(\Delta t^2) + O(\Delta x^2)$	any $\Delta t, \Delta x$

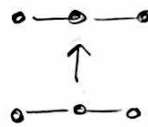
... Many other methods / variations exist...

• Why is the formulation in terms of a matrix eq. more complicated with 2 (or more) space dim.?

• Consider C-N in 1+1 dim. (x and t)



Comp. molecule:



The points at a given timestep are only neighbours along one dimension

⇒ Gave rise to simple tri-diag. structure for matrices A, B in

$$A \bar{u}^{n+1} = B \bar{u}^n$$

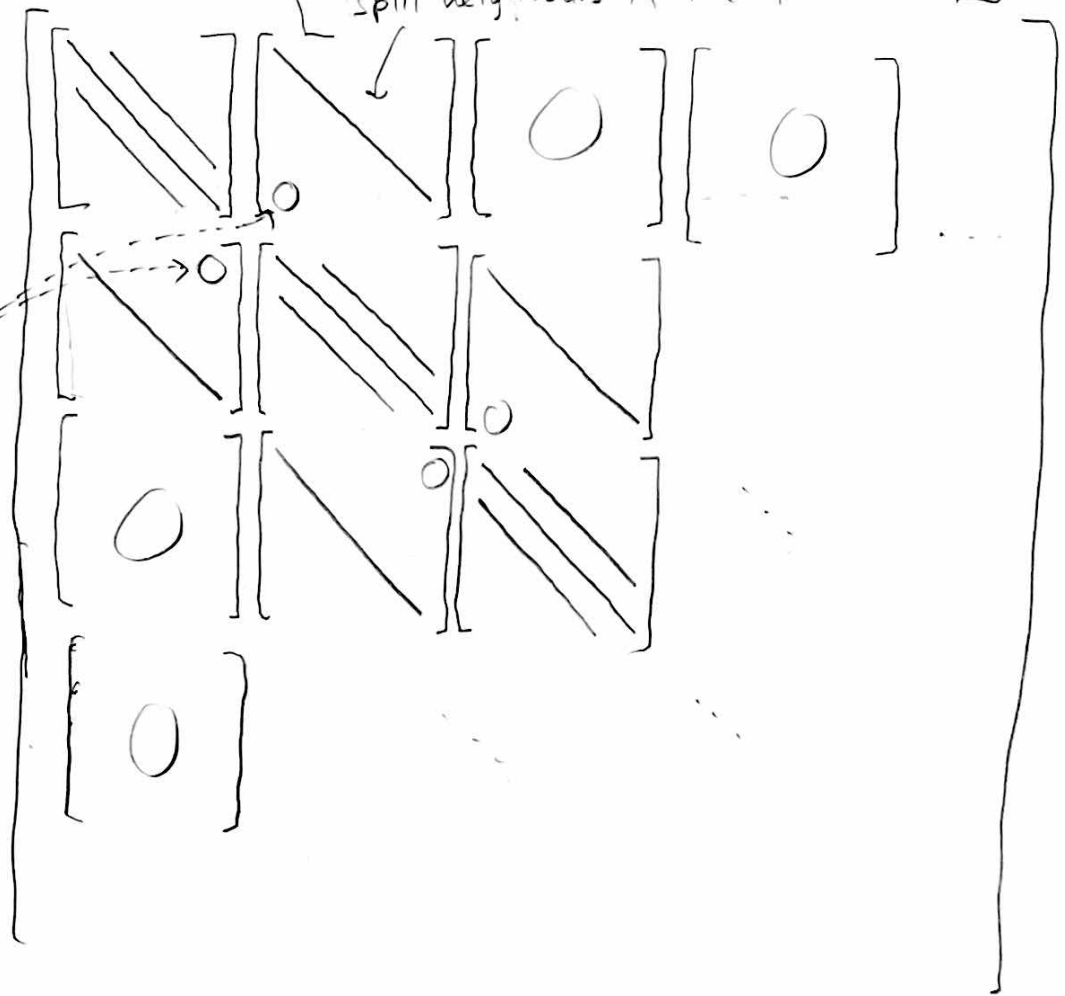


o Example

$A, B =$

[Get non-zero diagonals away from main diag. / due to the split neighbours in the y-direction]

Points where we hit boundary conditions



o Even higher dimensions

⇓
more complicated matrix structure
(e.g. more off-diagonals.)