

CE394M: 1D-Finite Element Method

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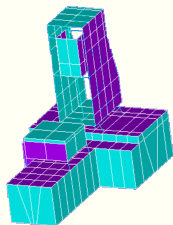
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Overview

1 FEM workflow

2 1D FEM

Finite Element Analysis



$$[\mathbf{K}^E]\{\mathbf{u}^E\} = \{\mathbf{F}^E\}$$



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$$[\mathbf{K}]\{\mathbf{u}\} = \{\mathbf{F}\}$$

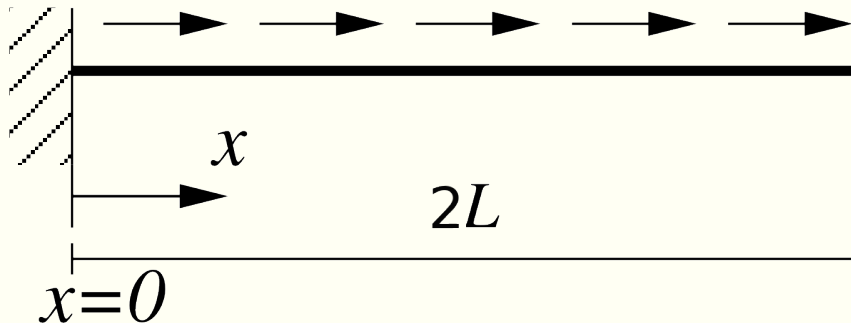


$$\{\mathbf{u}\} = [\mathbf{K}]^{-1}\{\mathbf{F}\}$$

FEM is a systematic procedure for approximating differential equations. For any problem in any spatial dimension it follows the same steps:

- 1 Identify the equation of interest
- 2 Cast the equation of interest in a weak form
- 3 Select a finite element type
- 4 Construct the element matrix and vector
- 5 Assemble the global matrix and vector and apply boundary conditions
- 6 Solve the system of linear equations

1D Finite Element Analysis of a cantilever beam

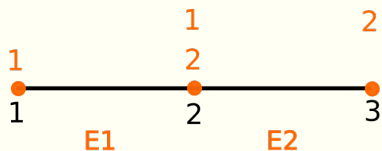


1D cantilever beam

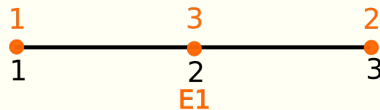
Assume L as unit length $L = 1$. Unit force $f = 1$.

1D Finite Element Analysis of a cantilever beam

What element should be used?



Linear elements



Quadrilateral element

1D discretization of a cantilever beam

1D FEM: Shape functions and derivatives

Shape function **N**:

$$N_1(x) = -\frac{x}{L} + 1$$

$$N_2(x) = \frac{x}{L}$$

$$N_1(x) = -x + 1$$

$$N_2(x) = x$$

B is the derivatives of the shape functions:

$$\mathbf{B} = \begin{bmatrix} \frac{dN_1(x)}{dx} & \frac{dN_2(x)}{dx} \end{bmatrix}$$

$$\mathbf{B} = \begin{bmatrix} -\frac{1}{L} & \frac{1}{L} \end{bmatrix} = \begin{bmatrix} -1 & 1 \end{bmatrix}$$

1D FEM: Stiffness and force

Element stiffness k_e :

$$k_e = \int \mathbf{B}^T E A B \, dx$$

$$k_e = \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

Right-hand side vector b_e is:

$$b_e = \int N^T f \, dx = \int_0^L \begin{bmatrix} -\frac{x}{L} + 1 \\ \frac{x}{L} \end{bmatrix}$$

$$b_e = \begin{bmatrix} -\frac{1}{2} \\ \frac{1}{2} \end{bmatrix}$$