quantum++ 0.1

Generated by Doxygen 1.8.7

Wed Nov 5 2014 01:48:24

Contents

1	quantum++ - A C++11 quantum computing library															
2	Nam	nespace	Index													3
	2.1	Names	pace List				 		3							
3	Hier	archical	Index													5
	3.1	Class I	Hierarchy				 		5							
4	Clas	s Index														7
	4.1	Class I	∟ist				 		7							
5	File	Index														9
	5.1	File Lis	st				 		9							
6	Nam	nespace	Documer	ntatio	n											11
	6.1	qpp Na	mespace	Refer	ence		 		11							
		6.1.1	Typedef	Docur	mentat	tion	 		19							
			6.1.1.1	bra			 		19							
			6.1.1.2	cma	at		 		19							
			6.1.1.3	cplx			 		19							
			6.1.1.4	dma	at		 		19							
			6.1.1.5	Dyn	ColVe	ct .	 		19							
			6.1.1.6	Dyn	Mat .		 		19							
			6.1.1.7	Dyn	RowV	ect .	 		19							
			6.1.1.8	ket			 		20							
		6.1.2	Function	n Docu	ımenta	ation	 		20							
			6.1.2.1	absı	m		 		20							
			6.1.2.2	adjo	int .		 		20							
			6.1.2.3	amp	olitudes	S	 		21							
			6.1.2.4	amp	olitudes	S	 		21							
			6.1.2.5	antio	comm		 		22							
			6.1.2.6	appl	ly		 		22							
			6.1.2.7	appl	lyCTR	L	 		23							

iv CONTENTS

6.1.2.8	channel	24
6.1.2.9	channel	25
6.1.2.10	choi	26
6.1.2.11	choi2kraus	27
6.1.2.12	comm	28
6.1.2.13	compperm	29
6.1.2.14	conjugate	30
6.1.2.15	cosm	30
6.1.2.16	cwise	31
6.1.2.17	det	31
6.1.2.18	disp	32
6.1.2.19	disp	32
6.1.2.20	disp	33
6.1.2.21	disp	33
6.1.2.22	disp	34
6.1.2.23	displn	34
6.1.2.24	displn	35
6.1.2.25	displn	36
6.1.2.26	displn	36
6.1.2.27	displn	37
6.1.2.28	entanglement	37
6.1.2.29	evals	38
6.1.2.30	evects	39
6.1.2.31	expm	39
6.1.2.32	funm	40
6.1.2.33	gconcurrence	40
6.1.2.34	grams	41
6.1.2.35	grams	42
6.1.2.36	grams	42
6.1.2.37	hevals	43
6.1.2.38	hevects	43
6.1.2.39	inverse	44
6.1.2.40	invperm	44
6.1.2.41	kron	45
6.1.2.42	kron	45
6.1.2.43	kron	46
6.1.2.44	kron	46
6.1.2.45	kronpow	47
6.1.2.46	load	47
6.1.2.47	loadMATLABmatrix	48

CONTENTS

6.1.2.48	loadMATLABmatrix	 48
6.1.2.49	loadMATLABmatrix	 48
6.1.2.50	logdet	 49
6.1.2.51	logm	 49
6.1.2.52	measure	 50
6.1.2.53	measure	 51
6.1.2.54	measure	 52
6.1.2.55	mket	 53
6.1.2.56	mket	 53
6.1.2.57	mket	 55
6.1.2.58	mprj	 55
6.1.2.59	mprj	 56
6.1.2.60	mprj	 56
6.1.2.61	multiidx2n	 57
6.1.2.62	n2multiidx	 57
6.1.2.63	norm	 58
6.1.2.64	omega	 58
6.1.2.65	operator"""_i	 59
6.1.2.66	operator"""_i	 59
6.1.2.67	powm	 59
6.1.2.68	prj	 60
6.1.2.69	prod	 60
6.1.2.70	prod	 61
6.1.2.71	ptrace	 61
6.1.2.72	ptrace1	 62
6.1.2.73	ptrace2	 63
6.1.2.74	ptranspose	 64
6.1.2.75	qmutualinfo	 65
6.1.2.76	rand	 66
6.1.2.77	rand	 66
6.1.2.78	rand	 67
6.1.2.79	rand	 67
6.1.2.80	randH	 68
6.1.2.81	randint	 68
6.1.2.82	randket	 69
6.1.2.83	randkraus	 69
6.1.2.84	randn	 70
6.1.2.85	randn	 70
6.1.2.86	randn	 71
6.1.2.87	randn	 71

vi CONTENTS

		6.1.2.88	randperm	72
		6.1.2.89	randrho	72
		6.1.2.90	randU	73
		6.1.2.91	$randV \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots$	73
		6.1.2.92	renyi	73
		6.1.2.93	renyi_inf	74
		6.1.2.94	reshape	75
		6.1.2.95	save	75
		6.1.2.96	saveMATLABmatrix	75
		6.1.2.97	saveMATLABmatrix	75
		6.1.2.98	saveMATLABmatrix	76
		6.1.2.99	schmidtcoeff	76
		6.1.2.100	schmidtprob	77
		6.1.2.101	schmidtU	78
		6.1.2.102	schmidtV	79
		6.1.2.103	shannon	80
		6.1.2.104	sinm	81
		6.1.2.105	spectralpowm	82
		6.1.2.106	sqrtm	82
		6.1.2.107	sum	83
		6.1.2.108	sum	83
		6.1.2.109	super	84
		6.1.2.110	syspermute	84
		6.1.2.111	trace	85
		6.1.2.112	transpose	86
		6.1.2.113	tsallis	86
	6.1.3	Variable D	Documentation	87
		6.1.3.1	chop	87
		6.1.3.2	ee	87
		6.1.3.3	eps	87
		6.1.3.4	$gt \ldots \ldots \ldots \ldots \ldots \ldots \ldots$	87
		6.1.3.5	init	87
		6.1.3.6	maxn	88
		6.1.3.7	$pi\ldots\ldots\ldots\ldots\ldots\ldots\ldots\ldots$	88
		6.1.3.8	rdevs	88
		6.1.3.9	st	88
6.2	qpp::ex	perimental	Namespace Reference	88
	6.2.1	Detailed [Description	89
	6.2.2	Function I	Documentation	89
		6.2.2.1	apply	89

CONTENTS vii

			6.2.2.2	channel	90
			6.2.2.3	choi	91
			6.2.2.4	CTRL	92
			6.2.2.5	randkraus	93
			6.2.2.6	super	94
	6.3	qpp::int	ternal Nan	nespace Reference	94
		6.3.1	Detailed	Description	95
		6.3.2	Function	Documentation	95
			6.3.2.1	_check_col_vector	95
			6.3.2.2	_check_dims	95
			6.3.2.3	_check_dims_match_cvect	95
			6.3.2.4	_check_dims_match_mat	95
			6.3.2.5	_check_dims_match_rvect	95
			6.3.2.6	_check_eq_dims	95
			6.3.2.7	_check_nonzero_size	95
			6.3.2.8	_check_perm	95
			6.3.2.9	_check_row_vector	95
			6.3.2.10	_check_square_mat	95
			6.3.2.11	_check_subsys_match_dims	95
			6.3.2.12	_check_vector	95
			6.3.2.13	_kron2	96
			6.3.2.14	_multiidx2n	96
			6.3.2.15	_n2multiidx	96
			6.3.2.16	variadic_vector_emplace	96
			6.3.2.17	variadic_vector_emplace	96
7	Class	e Door	mentation		97
•	7.1			lass Reference	97
		7.1.1	•	Description	98
		7.1.2		Enumeration Documentation	98
			7.1.2.1	Type	98
		7.1.3	_	tor & Destructor Documentation	99
			7.1.3.1	Exception	99
			7.1.3.2		100
		7.1.4		Function Documentation	100
			7.1.4.1		100
			7.1.4.2		100
		7.1.5	Member	Data Documentation	101
			7.1.5.1	_custom	101
			7.1.5.2	_msg	101

viii CONTENTS

		7.1.5.3 _type
		7.1.5.4 _where
7.2	qpp::G	ates Class Reference
	7.2.1	Detailed Description
	7.2.2	Constructor & Destructor Documentation
		7.2.2.1 Gates
	7.2.3	Member Function Documentation
		7.2.3.1 CTRL
		7.2.3.2 expandout
		7.2.3.3 Fd
		7.2.3.4 ld
		7.2.3.5 Rn
		7.2.3.6 Xd
		7.2.3.7 Zd
	7.2.4	Friends And Related Function Documentation
		7.2.4.1 internal::Singleton < const Gates >
	7.2.5	Member Data Documentation
		7.2.5.1 CNOTab
		7.2.5.2 CNOTba
		7.2.5.3 CZ
		7.2.5.4 FRED
		7.2.5.5 H
		7.2.5.6 ld2
		7.2.5.7 S
		7.2.5.8 SWAP
		7.2.5.9 T
		7.2.5.10 TOF
		7.2.5.11 X
		7.2.5.12 Y
		7.2.5.13 Z
7.3	qpp::In	it Class Reference
	7.3.1	Detailed Description
	7.3.2	Constructor & Destructor Documentation
		7.3.2.1 Init
		7.3.2.2 ~Init
	7.3.3	Friends And Related Function Documentation
		7.3.3.1 internal::Singleton < const Init >
7.4	qpp::ex	perimental::Qudit Class Reference
	7.4.1	Constructor & Destructor Documentation
		7.4.1.1 Qudit

CONTENTS

	7.4.2	Member F	unction Documentation	11		
		7.4.2.1	getD	11		
		7.4.2.2	getRho	11		
		7.4.2.3	measure	11		
		7.4.2.4	measure	12		
	7.4.3	Member D	ata Documentation	12		
		7.4.3.1	_D 1	12		
		7.4.3.2	_rho	12		
7.5	qpp::Ra	andomDevid	ces Class Reference	12		
	7.5.1	Detailed D	escription	13		
	7.5.2	Constructo	Constructor & Destructor Documentation			
		7.5.2.1	RandomDevices	13		
	7.5.3	Friends An	d Related Function Documentation	14		
		7.5.3.1 i	nternal::Singleton< RandomDevices >	14		
	7.5.4	Member D	ata Documentation	14		
		7.5.4.1	_rd	14		
		7.5.4.2	_rng	14		
7.6	qpp::in	ternal::Singl	eton< T > Class Template Reference	14		
	7.6.1	Detailed D	escription	15		
	7.6.2	Constructo	r & Destructor Documentation	15		
		7.6.2.1	Singleton	15		
		7.6.2.2	~Singleton	15		
		7.6.2.3	Singleton	15		
	7.6.3	Member F	unction Documentation	15		
		7.6.3.1	get_instance	15		
		7.6.3.2	pperator=	15		
7.7	qpp::St	tates Class	Reference	15		
	7.7.1	Detailed D	escription	17		
	7.7.2	Constructo	r & Destructor Documentation	17		
		7.7.2.1	States	17		
	7.7.3	Friends An	d Related Function Documentation	18		
		7.7.3.1 i	nternal::Singleton < const States >	18		
	7.7.4	Member D	ata Documentation	18		
		7.7.4.1	000	18		
		7.7.4.2	001	18		
		7.7.4.3	010	18		
		7.7.4.4	o11	18		
		7.7.4.5	GHZ	18		
		7.7.4.6	ob00	18		
		7.7.4.7	pb01	18		

CONTENTS

			7.7.4.8 p	b10				 	 	 	 118
			7.7.4.9 p	b11				 	 	 	 118
			7.7.4.10 p	GHZ				 	 	 	 118
			7.7.4.11 p	W				 	 	 	 118
			7.7.4.12 p	x0				 	 	 	 119
			7.7.4.13 p	x1				 	 	 	 119
			7.7.4.14 p	y0				 	 	 	 119
			7.7.4.15 p	y1				 	 	 	 119
			7.7.4.16 p	z0				 	 	 	 119
			7.7.4.17 p	z1				 	 	 	 119
			7.7.4.18 V	V				 	 	 	 119
			7.7.4.19 x	0				 	 	 	 119
			7.7.4.20 x	1				 	 	 	 119
			7.7.4.21 y	0				 	 	 	 119
			7.7.4.22 y	1				 	 	 	 119
			7.7.4.23 z	0				 	 	 	 119
				1							
	7.8	qpp::Ti	mer Class R	eference				 	 	 	 120
		7.8.1	Detailed De	escription .				 	 	 	 120
		7.8.2	Constructor	* & Destructor	r Documen	itation		 	 	 	 120
			7.8.2.1 T	ïmer				 	 	 	 120
		7.8.3		nction Docum							
				econds							
			7.8.3.2 ti	c				 	 	 	 121
			7.8.3.3 to	oc				 	 	 	 121
		7.8.4	Friends And	d Related Fur	nction Docu	umentatio	on	 	 	 	 121
			7.8.4.1 o	perator<<				 	 	 	 121
		7.8.5	Member Da	ita Document	ation			 	 	 	 121
				end							
			7.8.5.2	start				 	 	 	 121
8	File	Docume	entation								123
	8.1	include	/classes/exc	eption.h File I	Reference			 	 	 	 123
	8.2			· es.h File Refe							124
	8.3			h File Referei							
	8.4			devs.h File Re							
	8.5			gleton.h File F							
	8.6			es.h File Refe							
	8.7			er.h File Refe							
	8.8			File Reference							

CONTENTS xi

Ind	lex		145
	8.21	include/types.h File Reference	143
		include/random.h File Reference	
	8.19	include/qpp.h File Reference	141
	8.18	include/operations.h File Reference	139
	8.17	include/MATLAB/matlab.h File Reference	138
	8.16	include/io.h File Reference	137
	8.15	include/instruments.h File Reference	136
	8.14	include/internal/functions.h File Reference	135
	8.13	include/functions.h File Reference	132
	8.12	include/experimental/test.h File Reference	131
	8.11	include/experimental/classes/qudit.h File Reference	130
	8.10	include/entropies.h File Reference	129
	8.9	include/entanglement.h File Reference	128

Chapter 1

quantum++ - A C++11 quantum computing library

```
Version

0.1

Author

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```

This is the main page of the documentation. More coming soon.

2	quantum++ - A C++11 quantum computing library

Chapter 2

Namespace Index

Z. I Namesbace List	2.1	Nam	espa	ce L	ist
---------------------	-----	-----	------	------	-----

Here	is a	list o	of all	namespaces	with	brief	descriptions
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qpp	
qpp::experimental	88
qpp::internal	94

Namespace Index

Chapter 3

Hierarchical Index

3.1 Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

exception	
qpp::Exception	7
pp::experimental::Qudit	0
pp::internal::Singleton< T >	4
qpp::Init	8
qpp::States	5
pp::internal::Singleton< const Gates >	4
qpp::Gates	1
pp::internal::Singleton< const Init >	4
pp::internal::Singleton< const States >	4
pp::internal::Singleton< RandomDevices >	4
qpp::RandomDevices	2
nn·Timer	r

6 **Hierarchical Index**

Chapter 4

Class Index

4.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

8 Class Index

Chapter 5

File Index

5.1 File List

Here is a list of all files with brief descriptions:

include/constants.n	27
include/entanglement.h	28
include/entropies.h	29
include/functions.h	32
include/instruments.h	36
include/io.h	37
include/operations.h	39
include/qpp.h	41
include/random.h	42
include/types.h	43
include/classes/exception.h	23
include/classes/gates.h	24
include/classes/init.h	24
include/classes/randevs.h	25
include/classes/singleton.h	25
include/classes/states.h	26
include/classes/timer.h	27
include/experimental/test.h	
include/experimental/classes/qudit.h	
include/internal/functions.h	
include/MATLAB/matlab.h	38

10 File Index

Chapter 6

Namespace Documentation

6.1 qpp Namespace Reference

Namespaces

- · experimental
- internal

Classes

class Exception

Generates custom exceptions, used when validating function parameters.

class Gates

const Singleton class that implements most commonly used gates

class Init

const Singleton class that performs additional initializations/cleanups

· class RandomDevices

Singeleton class that manages the source of randomness in the library.

· class States

const Singleton class that implements most commonly used states

class Timer

Measures time.

Typedefs

```
    using cplx = std::complex < double >
        Complex number in double precision.
```

• template<typename Scalar >

```
using DynMat = Eigen::Matrix < Scalar, Eigen::Dynamic, Eigen::Dynamic >
```

Dynamic Eigen matrix over the field specified by Scalar.

```
    template<typename Scalar >
        using DynColVect = Eigen::Matrix< Scalar, Eigen::Dynamic, 1 >
```

Dynamic Eigen column vector over the field specified by Scalar.

```
    template<typename Scalar >
        using DynRowVect = Eigen::Matrix< Scalar, 1, Eigen::Dynamic >
        Dynamic Eigen row vector over the field specified by Scalar.
```

• using ket = DynColVect< cplx >

Complex (double precision) dynamic Eigen column vector. using bra = DynRowVect< cplx > Complex (double precision) dynamic Eigen row vector. using cmat = DynMat< cplx > Complex (double precision) dynamic Eigen matrix. using dmat = DynMat< double > Real (double precision) dynamic Eigen matrix. **Functions** constexpr std::complex< double > operator""_i (unsigned long long int x) User-defined literal for complex $i = \sqrt{-1}$ (integer overload) constexpr std::complex< double > operator""_i (long double x) User-defined literal for complex $i = \sqrt{-1}$ (real overload) std::complex< double > omega (std::size t D) D-th root of unity. • template<typename Derived > cmat schmidtcoeff (const Eigen::MatrixBase< Derived > &A, const std::vector< std::size_t > &dims) Schmidt coefficients of the bi-partite pure state A. template<typename Derived > cmat schmidtU (const Eigen::MatrixBase< Derived > &A, const std::vector< std::size t > &dims) Schmidt basis on Alice's side. template<typename Derived > cmat schmidtV (const Eigen::MatrixBase< Derived > &A, const std::vector< std::size t > &dims) Schmidt basis on Bob's side. template<typename Derived > cmat schmidtprob (const Eigen::MatrixBase< Derived > &A, const std::vector< std::size_t > &dims) Schmidt probabilities of the bi-partite pure state A. template<typename Derived > double entanglement (const Eigen::MatrixBase< Derived > &A, const std::vector< std::size_t > &dims) Entanglement of the bi-partite pure state A. template<typename Derived > double gconcurrence (const Eigen::MatrixBase< Derived > &A) G-concurrence of the bi-partite pure state A. template<typename Derived > double shannon (const Eigen::MatrixBase< Derived > &A) Shannon/von-Neumann entropy of the probability distribution/density matrix A. template<typename Derived > double renyi (const double alpha, const Eigen::MatrixBase< Derived > &A) Renyi- α entropy of the probability distribution/density matrix A, for $\alpha \geq 0$. • template<typename Derived > double renyi_inf (const Eigen::MatrixBase< Derived > &A) Renyi- ∞ entropy (min entropy) of the probability distribution/density matrix A. template<typename Derived > double tsallis (const double alpha, const Eigen::MatrixBase< Derived > &A) Tsallis- α entropy of the probability distribution/density matrix A, for $\alpha \geq 0$ template<typename Derived > double qmutualinfo (const Eigen::MatrixBase< Derived > &A, const std::vector< std::size_t > &subsysA,

template<typename Derived >
 DynMat< typename Derived::Scalar > transpose (const Eigen::MatrixBase< Derived > &A)

const std::vector< std::size_t > &subsysB, const std::vector< std::size_t > &dims)

Quantum mutual information between 2 subsystems of a composite system.

```
6.1 qpp Namespace Reference
          Transpose.
    • template<typename Derived >
      DynMat< typename Derived::Scalar > conjugate (const Eigen::MatrixBase< Derived > &A)
          Complex conjugate.

    template<typename Derived >

      DynMat< typename Derived::Scalar > adjoint (const Eigen::MatrixBase< Derived > &A)
          Adjoint.

    template<typename Derived >

      DynMat< typename Derived::Scalar > inverse (const Eigen::MatrixBase< Derived > &A)

    template<typename Derived >

      Derived::Scalar trace (const Eigen::MatrixBase< Derived > &A)

    template<typename Derived >

      Derived::Scalar det (const Eigen::MatrixBase< Derived > &A)

    template<typename Derived >

      Derived::Scalar logdet (const Eigen::MatrixBase< Derived > &A)
         Logarithm of the determinant.

    template<typename Derived >

      Derived::Scalar sum (const Eigen::MatrixBase< Derived > &A)
          Element-wise sum of A.

    template<typename Derived >

      Derived::Scalar prod (const Eigen::MatrixBase< Derived > &A)
         Element-wise product of A.

    template<typename Derived >

      double norm (const Eigen::MatrixBase< Derived > &A)
          Trace norm.
    template<typename Derived >
      DynColVect< cplx > evals (const Eigen::MatrixBase< Derived > &A)
          Eigenvalues.
    • template<typename Derived >
      cmat evects (const Eigen::MatrixBase< Derived > &A)
          Eigenvectors.

    template<typename Derived >

      DynColVect< double > hevals (const Eigen::MatrixBase< Derived > &A)
```

Hermitian eigenvalues.

template<typename Derived >

cmat hevects (const Eigen::MatrixBase< Derived > &A)

Hermitian eigenvectors.

template<typename Derived >

cmat funm (const Eigen::MatrixBase< Derived > &A, cplx(*f)(const cplx &))

Functional calculus f(A)

template<typename Derived >

cmat sqrtm (const Eigen::MatrixBase< Derived > &A)

Matrix square root.

template<typename Derived >

cmat absm (const Eigen::MatrixBase< Derived > &A)

Matrix absolut value.

template<typename Derived >

cmat expm (const Eigen::MatrixBase< Derived > &A)

Matrix exponential.

```
• template<typename Derived >
  cmat logm (const Eigen::MatrixBase< Derived > &A)
     Matrix logarithm.
template<typename Derived >
  cmat sinm (const Eigen::MatrixBase< Derived > &A)
     Matrix sin.

    template<typename Derived >

  cmat cosm (const Eigen::MatrixBase< Derived > &A)
     Matrix cos.

    template<typename Derived >

  cmat spectralpowm (const Eigen::MatrixBase< Derived > &A, const cplx z)
     Matrix power.
 template<typename Derived >
  DynMat< typename Derived::Scalar > powm (const Eigen::MatrixBase< Derived > &A, std::size t n)

    template<typename OutputScalar , typename Derived >

  DynMat< OutputScalar > cwise (const Eigen::MatrixBase< Derived > &A, OutputScalar(*f)(const typename
  Derived::Scalar &))
     Functor.
template<typename T >
  DynMat< typename T::Scalar > kron (const T &head)
     Kronecker product (variadic overload)
• template<typename T , typename... Args>
  DynMat< typename T::Scalar > kron (const T &head, const Args &...tail)
     Kronecker product (variadic overload)

    template<typename Derived >

  DynMat< typename Derived::Scalar > kron (const std::vector< Derived > &As)
     Kronecker product (std::vector overload)

    template<typename Derived >

  DynMat< typename Derived::Scalar > kron (const std::initializer list< Derived > &As)
     Kronecker product (std::initializer_list overload)

    template<typename Derived >

  DynMat< typename Derived::Scalar > kronpow (const Eigen::MatrixBase< Derived > &A, std::size_t n)
     Kronecker power.
• template<typename Derived >
  DynMat< typename Derived::Scalar > reshape (const Eigen::MatrixBase< Derived > &A, std::size_t rows,
  std::size t cols)
     Reshape.

    template<typename Derived1 , typename Derived2 >

  DynMat< typename Derived1::Scalar > comm (const Eigen::MatrixBase< Derived1 > &A, const Eigen::←
  MatrixBase < Derived2 > &B)
     Commutator.

    template<typename Derived1 , typename Derived2 >

  DynMat< typename Derived1::Scalar > anticomm (const Eigen::MatrixBase< Derived1 > &A, const Eigen ←
  ::MatrixBase< Derived2 > &B)
     Anti-commutator.

    template<typename Derived >

  DynMat< typename Derived::Scalar > prj (const Eigen::MatrixBase< Derived > &V)
     Projector.
• template<typename Derived >
  DynMat< typename Derived::Scalar > grams (const std::vector< Derived > &Vs)
     Gram-Schmidt orthogonalization (std::vector overload)

    template<typename Derived >

  DynMat< typename Derived::Scalar > grams (const std::initializer_list< Derived > &Vs)
```

Gram-Schmidt orthogonalization (std::initializer_list overload)

• template<typename Derived >

DynMat< typename Derived::Scalar > grams (const Eigen::MatrixBase< Derived > &A)

Gram-Schmidt orthogonalization (Eigen expression (matrix) overload)

std::vector< std::size_t > n2multiidx (std::size_t n, const std::vector< std::size_t > &dims)

Non-negative integer index to multi-index.

std::size t multiidx2n (const std::vector< std::size t > &midx, const std::vector< std::size t > &dims)

Multi-index to non-negative integer index.

ket mket (const std::vector< std::size t > &mask)

Multi-partite qubit ket.

ket mket (const std::vector< std::size_t > &mask, const std::vector< std::size_t > &dims)

Multi-partite qudit ket (different dimensions overload)

ket mket (const std::vector < std::size_t > &mask, std::size_t d)

Multi-partite qudit ket (same dimensions overload)

cmat mprj (const std::vector< std::size_t > &mask)

Projector onto multi-partite qubit ket.

cmat mprj (const std::vector< std::size_t > &mask, const std::vector< std::size_t > &dims)

Projector onto multi-partite qudit ket (different dimensions overload)

cmat mprj (const std::vector< std::size t > &mask, std::size t d)

Projector onto multi-partite qudit ket (same dimensions overload)

std::vector< std::size_t > invperm (const std::vector< std::size_t > &perm)

Inverse permutation.

std::vector< std::size_t > compperm (const std::vector< std::size_t > &perm, const std::vector< std::size_t > &sigma)

Compose permutations.

template<typename InputIterator >

std::vector< double > amplitudes (InputIterator first, InputIterator last)

Computes the absolut values squared of a range of complex numbers.

• template<typename Derived >

std::vector< double > amplitudes (const Eigen::MatrixBase< Derived > &V)

Computes the absolut values squared of a column vector.

 $\bullet \ \ \text{template}{<} \text{typename InputIterator} >$

auto sum (InputIterator first, InputIterator last) -> typename InputIterator::value_type

Element-wise sum of a range.

template<typename InputIterator >

auto prod (InputIterator first, InputIterator last) -> typename InputIterator::value_type

Element-wise product of a range.

template<typename Derived >

```
std::pair < std::vector < double >
```

 $, \, \mathsf{std} :: \mathsf{vector} < \mathsf{cmat} >> \mathsf{measure} \,\, (\mathsf{const} \,\, \mathsf{Eigen} :: \mathsf{MatrixBase} < \, \mathsf{Derived} > \& \mathsf{A}, \, \mathsf{const} \,\, \mathsf{std} :: \mathsf{vector} < \, \mathsf{cmat} > \& \mathsf{Ks})$

Measures the state A using the set of Kraus operators Ks.

 $\bullet \ \ \text{template}{<} \text{typename Derived} >$

```
std::pair < std::vector < double >
```

, std::vector < cmat >> measure (const Eigen::MatrixBase < Derived > &A, const $std::initializer_list < cmat > &Ks$)

Measures the state A using the set of Kraus operators Ks (std::initializer_list overload)

template<typename Derived >

```
std::pair < std::vector < double >
```

, std::vector< cmat > > measure (const Eigen::MatrixBase< Derived > &A, const cmat &U)

Measures the state A in the orthonormal basis specified by the unitary matrix U. The normalized basis vectors are the columns of U.

• template<typename InputIterator >

void disp (const InputIterator &first, const InputIterator &last, const std::string &separator, const std::string &start="[", const std::string &end="]", std::ostream &os=std::cout)

Displays a range. Does not add a newline.

• template<typename InputIterator >

std::ostream & displn (const InputIterator &first, const InputIterator &last, const std::string &separator, const std::string &start="[", const std::string &end="]", std::ostream &os=std::cout)

Displays a range. Adds a newline.

• template<typename T >

std::ostream & disp (const T &x, const std::string &separator, const std::string &start="[", const std::string &end="]", std::ostream &os=std::cout)

Displays a standard container that supports std::begin, std::end and forward iteration. Does not add a newline.

• template<typename T >

std::ostream & displn (const T &x, const std::string &separator, const std::string &start="[", const std::string &end="]", std::ostream &os=std::cout)

Displays a standard container that supports std::begin, std::end and forward iteration. Adds a newline.

template<typename T >

std::ostream & disp (const T *x, const std::size_t n, const std::string &separator, const std::string &start="[", const std::string &end="]", std::ostream &os=std::cout)

Displays a C-style array. Does not add a newline.

template<typename T >

std::ostream & displn (const T *x, const std::size_t n, const std::string &separator, const std::string &start="[", const std::string &end="]", std::ostream &os=std::cout)

Displays a C-style array. Adds a newline.

template<typename Derived >

std::ostream & disp (const Eigen::MatrixBase< Derived > &A, double chop=qpp::chop, std::ostream &os=std::cout)

Displays an Eigen expression in matrix friendly form. Does not add a new line.

• template<typename Derived >

std::ostream & displn (const Eigen::MatrixBase< Derived > &A, double chop=qpp::chop, std::ostream &os=std::cout)

Displays an Eigen expression in matrix friendly form. Adds a newline.

std::ostream & disp (const cplx z, double chop=qpp::chop, std::ostream &os=std::cout)

Displays a number (implicitly converted to std::complex<double>) in friendly form. Does not add a new line.

• std::ostream & displn (const cplx z, double chop=qpp::chop, std::ostream &os=std::cout)

Displays a number (implicitly converted to std::complex<double>) in friendly form. Adds a new line.

• template<typename Derived >

void save (const Eigen::MatrixBase< Derived > &A, const std::string &fname)

Saves Eigen expression to a binary file (internal format) in double precision.

• template<typename Derived >

DynMat< typename Derived::Scalar > load (const std::string &fname)

Loads Eigen matrix from a binary file (internal format) in double precision.

template<typename Derived >

Derived loadMATLABmatrix (const std::string &mat_file, const std::string &var_name)

 $Loads\ an\ Eigen\ dynamic\ matrix\ from\ a\ MATLAB\ .mat\ file,\ generic\ version.$

template<>

dmat loadMATLABmatrix (const std::string &mat_file, const std::string &var_name)

Loads an Eigen dynamic matrix from a MATLAB .mat file, specialization for double matrices (qpp::dmat)

template<>

cmat loadMATLABmatrix (const std::string &mat_file, const std::string &var_name)

Loads an Eigen dynamic matrix from a MATLAB .mat file, specialization for complex matrices (qpp::cmat)

template<typename Derived >

void saveMATLABmatrix (const Eigen::MatrixBase< Derived > &A, const std::string &mat_file, const std
::string &var_name, const std::string &mode)

Saves an Eigen dynamic matrix to a MATLAB .mat file, generic version.

template<>

void saveMATLABmatrix (const Eigen::MatrixBase< dmat > &A, const std::string &mat_file, const std::string &var_name, const std::string &mode)

Saves an Eigen dynamic matrix to a MATLAB .mat file, specialization for double matrices (qpp::dmat)

• template<>

void saveMATLABmatrix (const Eigen::MatrixBase < cmat > &A, const std::string &mat_file, const std::string &var_name, const std::string &mode)

Saves an Eigen dynamic matrix to a MATLAB .mat file, specialization for complex matrices (qpp::cmat)

• template<typename Derived1 , typename Derived2 >

DynMat< typename Derived1::Scalar > applyCTRL (const Eigen::MatrixBase< Derived1 > &state, const Eigen::MatrixBase< Derived2 > &A, const std::vector< std::size_t > &ctrl, const std::vector< std::size_t > &subsys, std::size_t n, std::size_t d=2)

Applies the controlled-gate A to the part subsys of a multipartite state vector or density matrix.

• template<typename Derived1 , typename Derived2 >

DynMat< typename Derived1::Scalar > apply (const Eigen::MatrixBase< Derived1 > &state, const Eigen ← ::MatrixBase< Derived2 > &A, const std::vector< std::size t > &subsys, std::size t n, std::size t d=2)

Applies the gate A to the part subsys of a multipartite state vector or density matrix.

• template<typename Derived >

cmat channel (const Eigen::MatrixBase< Derived > &rho, const std::vector< cmat > &Ks)

Applies the channel specified by the set of Kraus operators Ks to the density matrix rho.

template<typename Derived >

cmat channel (const Eigen::MatrixBase< Derived > &rho, const std::vector< cmat > &Ks, const std::vector<
std::size_t > &subsys, std::size_t n, std::size_t d=2)

Applies the channel specified by the set of Kraus operators Ks to the part of the density matrix rho specified by subsys.

cmat super (const std::vector< cmat > &Ks)

Superoperator matrix representation.

cmat choi (const std::vector< cmat > &Ks)

Choi matrix representation.

• std::vector< cmat > choi2kraus (const cmat &A)

Extracts orthogonal Kraus operators from Choi matrix.

template<typename Derived >

DynMat< typename Derived::Scalar > ptrace1 (const Eigen::MatrixBase< Derived > &A, const std::vector<
std::size_t > &dims)

Partial trace.

template<typename Derived >

DynMat< typename Derived::Scalar > ptrace2 (const Eigen::MatrixBase< Derived > &A, const std::vector< std::size_t > &dims)

Partial trace.

 $\bullet \ \ \text{template}{<} \text{typename Derived} >$

DynMat< typename Derived::Scalar > ptrace (const Eigen::MatrixBase< Derived > &A, const std::vector<
std::size_t > &subsys, const std::vector< std::size_t > &dims)

Partial trace.

• template<typename Derived >

DynMat< typename Derived::Scalar > ptranspose (const Eigen::MatrixBase< Derived > &A, const std
::vector< std::size_t > &subsys, const std::vector< std::size_t > &dims)

Partial transpose.

template<typename Derived >

System permutation.

template<typename Derived >

Derived rand (std::size_t rows, std::size_t cols, double a=0, double b=1)

Generates a random matrix with entries uniformly distributed in the interval [a, b)

• template<>

```
dmat rand (std::size_t rows, std::size_t cols, double a, double b)
```

Generates a random real matrix with entries uniformly distributed in the interval [a, b), specialization for double matrices (qpp::dmat)

• template<>

```
cmat rand (std::size_t rows, std::size_t cols, double a, double b)
```

Generates a random complex matrix with entries (both real and imaginary) uniformly distributed in the interval [a, b), specialization for complex matrices (qpp::cmat)

• double rand (double a=0, double b=1)

Generates a random real number uniformly distributed in the interval [a, b)

int randint (int a=std::numeric_limits< int >::min(), int b=std::numeric_limits< int >::max())

Generates a random integer (int) uniformly distributed in the interval [a, b].

• template<typename Derived >

```
Derived randn (std::size_t rows, std::size_t cols, double mean=0, double sigma=1)
```

Generates a random matrix with entries normally distributed in N(mean, sigma)

template<>

```
dmat randn (std::size_t rows, std::size_t cols, double mean, double sigma)
```

Generates a random real matrix with entries normally distributed in N(mean, sigma), specialization for double matrices (qpp::dmat)

template<>

```
cmat randn (std::size_t rows, std::size_t cols, double mean, double sigma)
```

Generates a random complex matrix with entries (both real and imaginary) normally distributed in N(mean, sigma), specialization for complex matrices (qpp::cmat)

• double randn (double mean=0, double sigma=1)

Generates a random real number (double) normally distributed in N(mean, sigma)

cmat randU (std::size t D)

Generates a random unitary matrix.

• cmat randV (std::size t Din, std::size t Dout)

Generates a random isometry matrix.

std::vector < cmat > randkraus (std::size_t N, std::size_t D)

Generates a set of random Kraus operators.

• cmat randH (std::size t D)

Generates a random Hermitian matrix.

ket randket (std::size_t D)

Generates a random normalized ket (pure state vector)

• cmat randrho (std::size t D)

Generates a random density matrix.

std::vector< std::size_t > randperm (std::size_t n)

Generates a random uniformly distributed permutation.

Variables

• constexpr double chop = 1e-10

Used in qpp::disp() and qpp::displn() for setting to zero numbers that have their absolute value smaller than qpp::ct← ::chop.

• constexpr double eps = 1e-12

Used to decide whether a number or expression in double precision is zero or not.

• constexpr std::size_t maxn = 64

Maximum number of qubits.

constexpr double pi = 3.141592653589793238462643383279502884

π

```
    constexpr double ee = 2.718281828459045235360287471352662497

         Base of natural logarithm, e.
    • RandomDevices & rdevs = RandomDevices::get_instance()
         qpp::RandomDevices Singleton
    const Gates & gt = Gates::get_instance()
         qpp::Gates const Singleton
    const States & st = States::get_instance()
         qpp::States const Singleton
    const Init & init = Init::get_instance()
         qpp::Init const Singleton
6.1.1 Typedef Documentation
6.1.1.1 using qpp::bra = typedef DynRowVect<cplx>
Complex (double precision) dynamic Eigen row vector.
6.1.1.2 using qpp::cmat = typedef DynMat<cplx>
Complex (double precision) dynamic Eigen matrix.
6.1.1.3 using qpp::cplx = typedef std::complex < double >
Complex number in double precision.
6.1.1.4 using qpp::dmat = typedef DynMat<double>
Real (double precision) dynamic Eigen matrix.
6.1.1.5 template<typename Scalar > using qpp::DynColVect = typedef Eigen::Matrix<Scalar, Eigen::Dynamic, 1>
Dynamic Eigen column vector over the field specified by Scalar.
Example:
auto colvect = DynColVect<float>(2); // type of colvect is Eigen::Matrix<float, Eigen::Dynamic, 1>
6.1.1.6 template<typename Scalar > using qpp::DynMat = typedef Eigen::Matrix<Scalar, Eigen::Dynamic,
       Eigen::Dynamic>
Dynamic Eigen matrix over the field specified by Scalar.
Example:
auto mat = DynMat<float>(2,3); // type of mat is Eigen::Matrix<float, Eigen::Dynamic>
6.1.1.7 template<typename Scalar > using qpp::DynRowVect = typedef Eigen::Matrix<Scalar, 1, Eigen::Dynamic>
Dynamic Eigen row vector over the field specified by Scalar.
Example:
```

auto rowvect = DynRowVect<float>(3); // type of rowvect is Eigen::Matrix<float, 1, Eigen::Dynamic>

6.1.1.8 using qpp::ket = typedef DynColVect<cplx>

Complex (double precision) dynamic Eigen column vector.

6.1.2 Function Documentation

6.1.2.1 template<typename Derived > cmat qpp::absm (const Eigen::MatrixBase< Derived > & A)

Matrix absolut value.

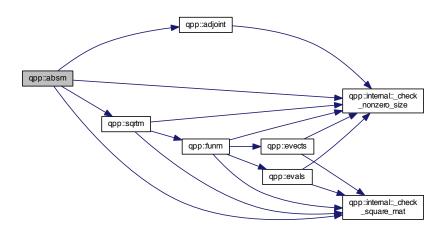
Parameters

Α	Eigen expression

Returns

Matrix absolut value of A

Here is the call graph for this function:



6.1.2.2 template<typename Derived > DynMat<typename Derived::Scalar> qpp::adjoint (const Eigen::MatrixBase < Derived > & A)

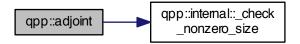
Adjoint.

Α	Eigen expression

Returns

Adjoint (Hermitian conjugate) of A, as a dynamic matrix over the same scalar field as A

Here is the call graph for this function:



6.1.2.3 template<typename InputIterator > std::vector<double> qpp::amplitudes (InputIterator first, InputIterator last)

Computes the absolut values squared of a range of complex numbers.

Parameters

first	Iterator to the first element of the range
last	Iterator to the last element of the range

Returns

Real vector consisting of the range's absolut values squared

6.1.2.4 template<typename Derived > std::vector<double> qpp::amplitudes (const Eigen::MatrixBase< Derived > & V)

Computes the absolut values squared of a column vector.

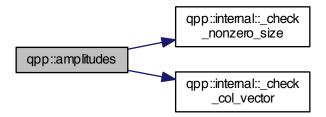
Parameters

V Eigen expression

Returns

Real vector consisting of the absolut values squared

Here is the call graph for this function:



6.1.2.5 template<typename Derived1, typename Derived2 > DynMat<typename Derived1::Scalar> qpp::anticomm (const Eigen::MatrixBase< Derived1 > & A, const Eigen::MatrixBase< Derived2 > & B)

Anti-commutator.

Anti-commutator $\{A, B\} = AB + BA$

Both A and B must be Eigen expressions over the same scalar field

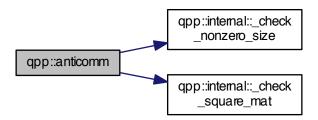
Parameters

Α	Eigen expression
В	Eigen expression

Returns

Anti-commutator AB+BA, as a dynamic matrix over the same scalar field as A

Here is the call graph for this function:



6.1.2.6 template < typename Derived1 , typename Derived2 > DynMat < typename Derived1::Scalar > qpp::apply (const Eigen::MatrixBase < Derived1 > & state, const Eigen::MatrixBase < Derived2 > & A, const std::vector < std::size_t > & subsys, std::size_t n, std::size_t d = 2)

Applies the gate A to the part subsys of a multipartite state vector or density matrix.

Note

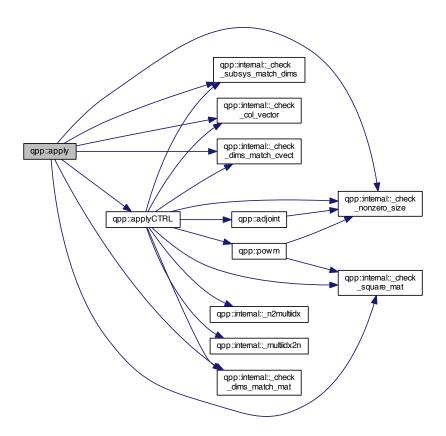
The dimension of the gate A must match the dimension of subsys

state	Eigen expression
Α	Eigen expression
subsys	Subsystem indexes where the gate A is applied
n	Total number of subsystems
d	Local dimensions of all local Hilbert spaces (must all be equal)

Returns

Gate A applied to the part subsys of state

Here is the call graph for this function:



6.1.2.7 template<typename Derived1 , typename Derived2 > DynMat<typename Derived1::Scalar> qpp::applyCTRL (const Eigen::MatrixBase< Derived1 > & state, const Eigen::MatrixBase< Derived2 > & A, const std::vector< std::size_t > & ctrl, const std::vector< std::size_t > & subsys, std::size_t n, std::size_t d = 2)

Applies the controlled-gate A to the part subsys of a multipartite state vector or density matrix.

Note

The dimension of the gate A must match the dimension of subsys

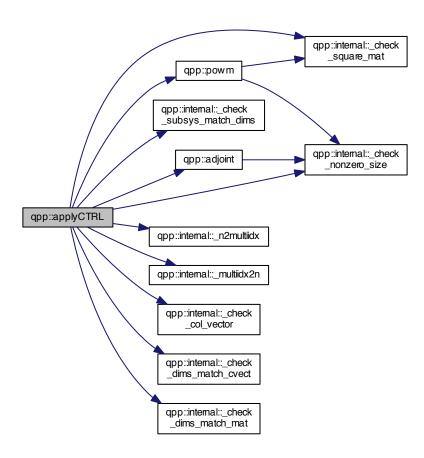
stat	Eigen expression
,	A Eigen expression
ct	Control subsystem indexes
subsy	Subsystem indexes where the gate A is applied

n	Total number of subsystems
d	Local dimensions of all local Hilbert spaces (must all be equal)

Returns

CTRL-A gate applied to the part subsys of state

Here is the call graph for this function:



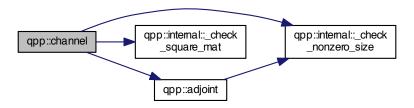
6.1.2.8 template<typename Derived > cmat qpp::channel (const Eigen::MatrixBase< Derived > & rho, const std::vector< cmat > & Ks)

Applies the channel specified by the set of Kraus operators Ks to the density matrix rho.

rho	Eigen expression
Ks	Set of Kraus operators

Output density matrix after the action of the channel

Here is the call graph for this function:



6.1.2.9 template<typename Derived > cmat qpp::channel (const Eigen::MatrixBase< Derived > & rho, const std::vector< cmat > & Ks, const std::vector< std::size_t > & subsys, std::size_t n, std::size_t d = 2)

Applies the channel specified by the set of Kraus operators *Ks* to the part of the density matrix *rho* specified by *subsys*.

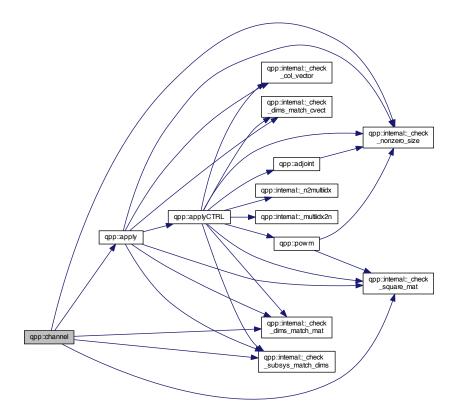
Parameters

rho	Eigen expression
Ks	Set of Kraus operators
subsys	Subsystems' indexes
n	Total number of subsystems
d	Local dimensions of all local Hilbert spaces (must all be equal)

Returns

Output density matrix after the action of the channel

Here is the call graph for this function:



6.1.2.10 cmat qpp::choi (const std::vector < cmat > & Ks)

Choi matrix representation.

Constructs the Choi matrix of the channel specified by the set of Kraus operators Ks in the standard operator basis $\{|i\rangle\langle j|\}$ ordered in lexicographical order, i.e. $|0\rangle\langle 0|,\,|0\rangle\langle 1|$ etc.

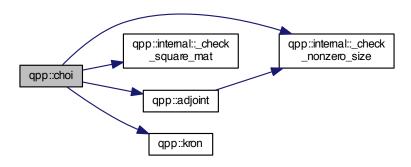
Note

The superoperator matrix S and the Choi matrix C are related by $S_{ab,mn} = C_{ma,nb}$

Ks Set of Kraus operators

Choi matrix representation

Here is the call graph for this function:



6.1.2.11 std::vector<cmat> qpp::choi2kraus (const cmat & A)

Extracts orthogonal Kraus operators from Choi matrix.

Extracts a set of orthogonal (under Hilbert-Schmidt operator norm) Kraus operators from the Choi representation *A* of the channel

Note

The Kraus operators satisfy $Tr(K_i^\dagger K_j) = \delta_{ij}$ for all i
eq j

Α	Choi matrix
---	-------------

Set of Kraus operators

Here is the call graph for this function:



 $6.1.2.12 \quad template < typename \ Derived 1 \ , \ typename \ Derived 2 > DynMat < typename \ Derived 1 :: Scalar > qpp::comm \ (\ const \ Eigen::MatrixBase < Derived 1 > \& A, \ const \ Eigen::MatrixBase < Derived 2 > \& B \)$

Commutator.

Commutator [A,B] = AB - BA

Both A and B must be Eigen expressions over the same scalar field

Parameters

Α	Eigen expression
В	Eigen expression

Returns

Commutator AB - BA, as a dynamic matrix over the same scalar field as A

Here is the call graph for this function:



6.1.2.13 std::vector < std::size_t > & perm, const std::vector < std::size_t > & perm, const std::vector < std::size_t > & sigma)

Compose permutations.

perm	Permutation
sigma	Permutation

Returns

Composition of the permutations *perm* o *sigma* = perm(sigma)

Here is the call graph for this function:



6.1.2.14 template<typename Derived > DynMat<typename Derived::Scalar> qpp::conjugate (const Eigen::MatrixBase< Derived > & A)

Complex conjugate.

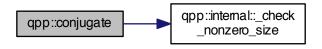
Parameters

	Α	Eigen expression
--	---	------------------

Returns

Complex conjugate of A, as a dynamic matrix over the same scalar field as A

Here is the call graph for this function:



6.1.2.15 template < typename Derived > cmat qpp::cosm (const Eigen::MatrixBase < Derived > & A)

Matrix cos.

Α	Eigen expression
---	------------------

Returns

Matrix cosine of A

Here is the call graph for this function:



6.1.2.16 template < typename OutputScalar , typename Derived > DynMat < OutputScalar > qpp::cwise (const Eigen::MatrixBase < Derived > & A, OutputScalar(*)(const typename Derived::Scalar &) f)

Functor.

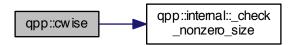
Parameters

Α	Eigen expression
f	Pointer-to-function from scalars of A to OutputScalar

Returns

Component-wise f(A), as a dynamic matrix over the *OutputScalar* scalar field

Here is the call graph for this function:



6.1.2.17 template<typename Derived > Derived::Scalar qpp::det (const Eigen::MatrixBase< Derived > & A)

Determinant.

Α	Eigen expression
---	------------------

Returns

Determinant of A, as a scalar in the same scalar field as A Returns $\pm \infty$ when the determinant overflows/underflows

Here is the call graph for this function:



6.1.2.18 template<typename InputIterator > void qpp::disp (const InputIterator & first, const InputIterator & last, const std::string & separator, const std::string & std::string & end = "] ", std::ostream & os = std::cout)

Displays a range. Does not add a newline.

See also

qpp::displn()

Parameters

first	Iterator to the first element of the range
last	Iterator to the last element of the range
separator	Separator
start	Left marking
end	Right marking
os	Output stream

Returns

Output stream

6.1.2.19 template<typename T > std::ostream& qpp::disp (const T & x, const std::string & separator, const std::string & start = " [", const std::string & end = "] ", std::ostream & os = std::cout)

Displays a standard container that supports std::begin, std::end and forward iteration. Does not add a newline.

See also

qpp::displn()

X	Container
separator	Separator
start	Left marking
end	Right marking
os	Output stream

Returns

Output stream

Here is the call graph for this function:



6.1.2.20 template<typename T > std::ostream& qpp::disp (const T * x, const std::size_t n, const std::string & separator, const std::string & start = " [", const std::string & end = "] ", std::ostream & os = std::cout)

Displays a C-style array. Does not add a newline.

See also

qpp::displn()

Parameters

X	Pointer to the first element
n	Number of elements to be displayed
separator	Separator
start	Left marking
end	Right marking
os	Output stream

Returns

Output stream

6.1.2.21 template<typename Derived > std::ostream& qpp::disp (const Eigen::MatrixBase< Derived > & A, double chop = qpp::chop, std::ostream & os = std::cout)

Displays an Eigen expression in matrix friendly form. Does not add a new line.

See also

qpp::displn()

Α	Eigen expression
chop	Set to zero the elements smaller in absolute value than <i>chop</i>
os	Output stream

Returns

Output stream

6.1.2.22 std::ostream& qpp::disp (const cplx z, double chop = qpp::chop, std::ostream & os = std::cout)

Displays a number (implicitly converted to std::complex<double>) in friendly form. Does not add a new line.

See also

qpp::displn()

Parameters

Z	Real/complex number
chop	Set to zero the elements smaller in absolute value than chop
os	Output stream

Returns

Output stream

Here is the call graph for this function:



6.1.2.23 template<typename InputIterator > std::ostream& qpp::displn (const InputIterator & first, const InputIterator & last, const std::string & separator, const std::string & start = " [", const std::string & end = "] ", std::ostream & os = std::cout)

Displays a range. Adds a newline.

See also

qpp::disp()

first	Iterator to the first element of the range
last	Iterator to the last element of the range
separator	Separator
start	Left marking
end	Right marking
os	Output stream

Returns

Output stream

Here is the call graph for this function:



6.1.2.24 template<typename T > std::ostream& qpp::displn (const T & x, const std::string & separator, const std::string & start = " [", const std::string & end = "] ", std::ostream & os = std::cout)

Displays a standard container that supports std::begin, std::end and forward iteration. Adds a newline.

See also

qpp::disp()

Parameters

X	Container
separator	Separator
start	Left marking
end	Right marking
os	Output stream

Returns

Output stream

Here is the call graph for this function:



6.1.2.25 template < typename T > std::ostream& qpp::displn (const T * x, const std::size_t n, const std::string & separator, const std::string & start = " [", const std::string & end = "] ", std::ostream & os = std::cout)

Displays a C-style array. Adds a newline.

See also

qpp::disp()

Parameters

X	Pointer to the first element
n	Number of elements to be displayed
separator	Separator
start	Left marking
end	Right marking
OS	Output stream

Returns

Output stream

Here is the call graph for this function:



6.1.2.26 template < typename Derived > std::ostream& qpp::displn (const Eigen::MatrixBase < Derived > & A, double chop = qpp::chop, std::ostream & os = std::cout)

Displays an Eigen expression in matrix friendly form. Adds a newline.

See also

qpp::disp()

Α	Eigen expression
chop	Set to zero the elements smaller in absolute value than chop
os	Output stream

Output stream

Here is the call graph for this function:



6.1.2.27 std::ostream & os = std::cout)

Displays a number (implicitly converted to std::complex<double>) in friendly form. Adds a new line.

See also

qpp::disp()

Parameters

Z	Real/complex number
chop	Set to zero the elements smaller in absolute value than <i>chop</i>
os	Output stream

Returns

Output stream

Here is the call graph for this function:



6.1.2.28 template < typename Derived > double qpp::entanglement (const Eigen::MatrixBase < Derived > & A, const std::vector < std::size_t > & dims)

Entanglement of the bi-partite pure state A.

Defined as the von-Neumann entropy of the reduced density matrix of one of the subsystems

See also

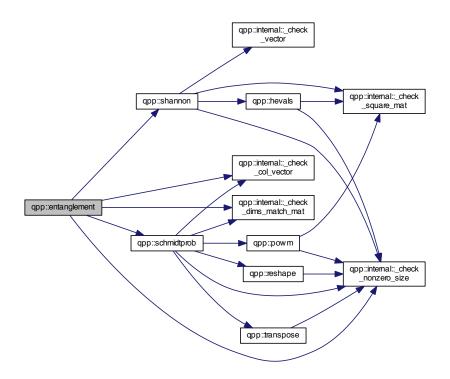
qpp::shannon()

Α	Eigen expression
dims	Subsystems' dimensions

Returns

Entanglement, with the logarithm in base 2

Here is the call graph for this function:



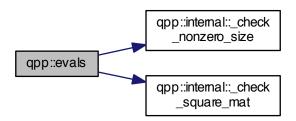
 $6.1.2.29 \quad template < typename \ Derived > DynColVect < cplx > qpp::evals \ (\ const \ Eigen::MatrixBase < Derived > \& \ A \)$

Eigenvalues.

Α	Eigen expression
---	------------------

Eigenvalues of A, as a complex dynamic column vector

Here is the call graph for this function:



6.1.2.30 template < typename Derived > cmat qpp::evects (const Eigen::MatrixBase < Derived > & A)

Eigenvectors.

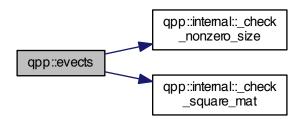
Parameters

Α	Eigen expression
---	------------------

Returns

Eigenvectors of A, as columns of a complex matrix

Here is the call graph for this function:



6.1.2.31 template < typename Derived > cmat qpp::expm (const Eigen::MatrixBase < Derived > & A)

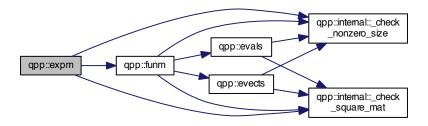
Matrix exponential.

Α	Eigen expression
---	------------------

Returns

Matrix exponential of A

Here is the call graph for this function:



6.1.2.32 template < typename Derived > cmat qpp::funm (const Eigen::MatrixBase < Derived > & A, cplx(*)(const cplx &) f)

Functional calculus f(A)

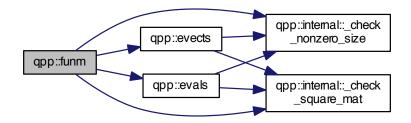
Parameters

Α	Eigen expression
f	Pointer-to-function from complex to complex

Returns

f(A)

Here is the call graph for this function:



 $\textbf{6.1.2.33} \quad \textbf{template} < \textbf{typename Derived} > \textbf{double qpp::gconcurrence (const Eigen::MatrixBase} < \textbf{Derived} > \textbf{\& A)}$

G-concurrence of the bi-partite pure state A.

Uses qpp::logdet() to avoid overflows

See also

qpp::logdet()

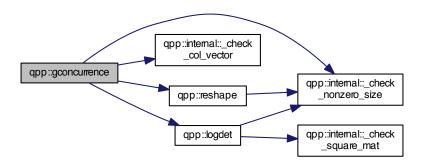
Parameters

Α	Eigen expression
dims	Subsystems' dimensions

Returns

G-concurrence

Here is the call graph for this function:



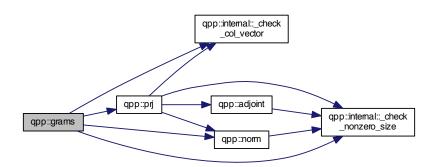
6.1.2.34 template<typename Derived > DynMat<typename Derived::Scalar> qpp::grams (const std::vector< Derived > & Vs)

Gram-Schmidt orthogonalization (std::vector overload)

Vs	std::vector of Eigen expressions as column vectors

Gram-Schmidt vectors of *Vs* as columns of a dynamic matrix over the same scalar field as its arguments

Here is the call graph for this function:



6.1.2.35 template<typename Derived > DynMat<typename Derived::Scalar> qpp::grams (const std::initializer_list< Derived > & Vs)

Gram-Schmidt orthogonalization (std::initializer_list overload)

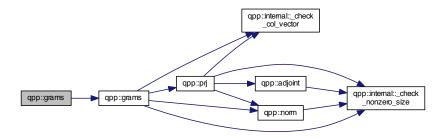
Parameters

Vs std::initializer_list of Eigen expressions as column vectors

Returns

Gram-Schmidt vectors of Vs as columns of a dynamic matrix over the same scalar field as its arguments

Here is the call graph for this function:



6.1.2.36 template<typename Derived > DynMat<typename Derived::Scalar> qpp::grams (const Eigen::MatrixBase< Derived > & A)

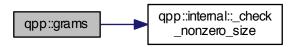
Gram-Schmidt orthogonalization (Eigen expression (matrix) overload)

Α	Eigen expression, the input vectors are the columns of A

Returns

Gram-Schmidt vectors of the columns of A, as columns of a dynamic matrix over the same scalar field as A

Here is the call graph for this function:



6.1.2.37 template<typename Derived > DynColVect<double> qpp::hevals (const Eigen::MatrixBase< Derived > & A)

Hermitian eigenvalues.

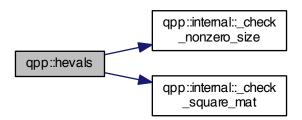
Parameters

Α	Eigen expression

Returns

Eigenvalues of Hermitian A, as a real dynamic column vector

Here is the call graph for this function:



6.1.2.38 template < typename Derived > cmat qpp::hevects (const Eigen::MatrixBase < Derived > & A)

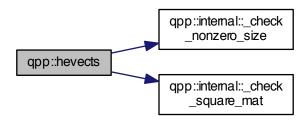
Hermitian eigenvectors.

Α	Eigen expression
---	------------------

Returns

Eigenvectors of Hermitian A, as columns of a complex matrix

Here is the call graph for this function:



6.1.2.39 template < typename Derived > DynMat < typename Derived::Scalar > qpp::inverse (const Eigen::MatrixBase < Derived > & A)

Inverse.

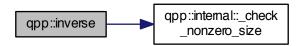
Parameters

Α	Eigen expression

Returns

Inverse of A, as a dynamic matrix over the same scalar field as A

Here is the call graph for this function:



6.1.2.40 std::vector<std::size_t> qpp::invperm (const std::vector< std::size_t > & perm)

Inverse permutation.

perm	Permutation
------	-------------

Returns

Inverse of the permutation perm

Here is the call graph for this function:



6.1.2.41 template<typename T > DynMat<typename T::Scalar> qpp::kron (const T & head)

Kronecker product (variadic overload)

Used to stop the recursion for the variadic template version of qpp::kron()

Parameters

head Eigen expression	
-----------------------	--

Returns

Its argument head

6.1.2.42 template<typename T , typename... Args> DynMat<typename T::Scalar> qpp::kron (const T & head, const Args &... tail)

Kronecker product (variadic overload)

head	Eigen expression
tail	Variadic Eigen expression (zero or more parameters)

Kronecker product of all input parameters, evaluated from left to right, as a dynamic matrix over the same scalar field as its arguments

Here is the call graph for this function:



6.1.2.43 template < typename Derived > DynMat < typename Derived::Scalar > qpp::kron (const std::vector < Derived > & As)

Kronecker product (std::vector overload)

Parameters

As	std::vector of Eigen expressions

Returns

Kronecker product of all elements in *As*, evaluated from left to right, as a dynamic matrix over the same scalar field as its arguments

Here is the call graph for this function:



6.1.2.44 template < typename Derived > DynMat < typename Derived::Scalar > qpp::kron (const std::initializer_list < Derived > & As)

Kronecker product (std::initializer_list overload)

As	std::initializer_list of Eigen expressions, such as {A1, A2, ,Ak}

Kronecker product of all elements in *As*, evaluated from left to right, as a dynamic matrix over the same scalar field as its arguments

Here is the call graph for this function:



6.1.2.45 template<typename Derived > DynMat<typename Derived::Scalar> qpp::kronpow (const Eigen::MatrixBase< Derived > & A, std::size_t n)

Kronecker power.

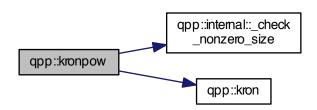
Parameters

Α	Eigen expression
n	Non-negative integer

Returns

Kronecker product of A with itself n times $A^{\otimes n}$, as a dynamic matrix over the same scalar field as A

Here is the call graph for this function:



6.1.2.46 template<typename Derived > DynMat<typename Derived::Scalar> qpp::load (const std::string & fname)

Loads Eigen matrix from a binary file (internal format) in double precision.

The template parameter cannot be automatically deduced and must be explicitly provided, depending on the scalar field of the matrix that is being loaded.

Example:

```
// loads a previously saved Eigen dynamic complex matrix from "input.bin"
auto mat = load<cmat>("input.bin");
```

See also

gpp::loadMATLABmatrix()

Parameters

Α	Eigen expression
fname	Output file name

6.1.2.47 template < typename Derived > Derived qpp::loadMATLABmatrix (const std::string & mat_file, const std::string & var_name)

Loads an Eigen dynamic matrix from a MATLAB .mat file, generic version.

This is the generic version that always throws *qpp::Exception::Type::UNDEFINED_TYPE*. It is specialized only for *qpp::dmat* and *qpp::cmat* (the only matrix types that can be loaded)

6.1.2.48 template <> dmat qpp::loadMATLABmatrix (const std::string & mat_file, const std::string & var_name)

Loads an Eigen dynamic matrix from a MATLAB .mat file, specialization for double matrices (qpp::dmat)

The template parameter cannot be automatically deduced and must be explicitly provided

Example:

```
// loads a previously saved Eigen dynamic double matrix from the
MATLAB file "input.mat"
auto mat = loadMATLABmatrix<dmat>("input.mat");
```

Note

If var name is a complex matrix, only the real part is loaded

Parameters

mat_file	MATALB .mat file
var_name	Variable name in the .mat file representing the matrix to be loaded

Returns

Eigen double dynamic matrix (qpp::dmat)

6.1.2.49 template <> cmat qpp::loadMATLABmatrix (const std::string & mat_file, const std::string & var_name)

Loads an Eigen dynamic matrix from a MATLAB .mat file, specialization for complex matrices (qpp::cmat)

The template parameter cannot be automatically deduced and must be explicitly provided

Example:

```
// loads a previously saved Eigen dynamic complex matrix from the
MATLAB file "input.mat"
auto mat = loadMATLABmatrix<cmat>("input.mat");
```

mat_file	MATALB .mat file
var_name	Variable name in the .mat file representing the matrix to be loaded

Returns

Eigen complex dynamic matrix (qpp::cmat)

6.1.2.50 template<typename Derived > Derived::Scalar qpp::logdet (const Eigen::MatrixBase< Derived > & A)

Logarithm of the determinant.

Especially useful when the determinant overflows/underflows

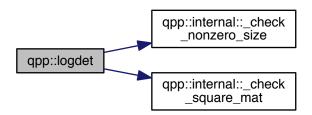
Parameters

Α	Eigen expression

Returns

Logarithm of the determinant of A, as a scalar in the same scalar field as A

Here is the call graph for this function:



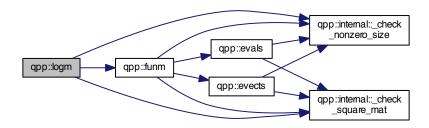
6.1.2.51 template < typename Derived > cmat qpp::logm (const Eigen::MatrixBase < Derived > & A)

Matrix logarithm.

Α	Eigen expression

Matrix logarithm of A

Here is the call graph for this function:



6.1.2.52 template < typename Derived > std::pair < std::vector < double >, std::vector < cmat > > qpp::measure (const Eigen::MatrixBase < Derived > & A, const std::vector < cmat > & Ks)

Measures the state A using the set of Kraus operators Ks.

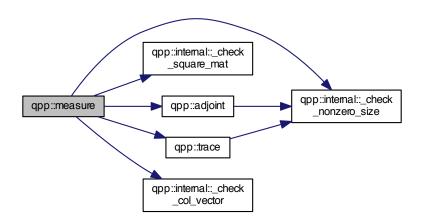
Parameters

Α	Eigen expression
Ks	Set of Kraus operators

Returns

Pair of vector of probabilities and vector of post-measurement normalized states

Here is the call graph for this function:



 $\label{lem:const} \textbf{6.1.2.53} \quad \text{template} < \text{typename Derived} > \text{std::pair} < \text{std::vector} < \text{double} > \text{, std::vector} < \text{cmat} > > \text{qpp::measure (const Eigen::MatrixBase} < \text{Derived} > \& \textit{A}, \text{ const std::initializer_list} < \text{cmat} > \& \textit{Ks} \text{)}$

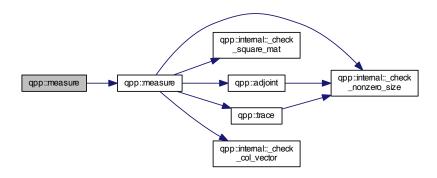
Measures the state A using the set of Kraus operators Ks (std::initializer_list overload)

Α	Eigen expression
Ks	Set of Kraus operators

Returns

Pair of vector of probabilities and vector of post-measurement normalized states

Here is the call graph for this function:



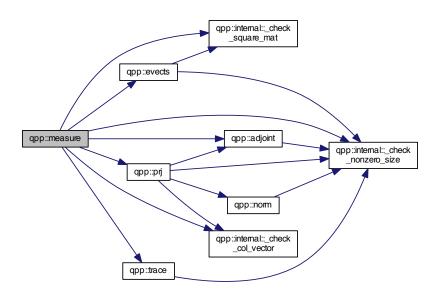
6.1.2.54 template < typename Derived > std::pair < std::vector < double >, std::vector < cmat > > qpp::measure (const Eigen::MatrixBase < Derived > & A, const cmat & U)

Measures the state A in the orthonormal basis specified by the unitary matrix U. The normalized basis vectors are the columns of U.

Α	Eigen expression
U	Unitary matrix representing the measurement basis

Pair of vector of probabilities and vector of post-measurement normalized states

Here is the call graph for this function:



6.1.2.55 ket qpp::mket (const std::vector< std::size_t > & mask)

Multi-partite qubit ket.

Constructs the multi-partite qubit ket $|mask\rangle$, where mask is a std::vector of 0's and 1's

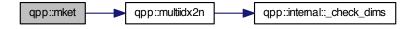
Parameters

mask std::vector of 0's and 1's

Returns

Multi-partite qubit state vector, as a complex dynamic column vector

Here is the call graph for this function:



6.1.2.56 ket qpp::mket (const std::vector < std::size_t > & mask, const std::vector < std::size_t > & dims)

Multi-partite qudit ket (different dimensions overload)

Constructs the multi-partite qudit ket $|mask\rangle$, where mask is a std::vector of non-negative integers Each element in mask has to be smaller than the corresponding element in dims

mask	std::vector of non-negative integers
dims	Dimensions of the multi-partite system

Returns

Multi-partite qudit state vector, as a complex dynamic column vector

Here is the call graph for this function:



6.1.2.57 ket qpp::mket (const std::vector< std::size_t > & mask, std::size_t d)

Multi-partite qudit ket (same dimensions overload)

Constructs the multi-partite qudit ket $|mask\rangle$, all subsystem having equal dimension d mask is a std::vector of non-negative integers, and each element in mask has to be strictly smaller than d

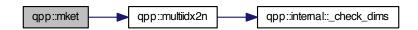
Parameters

mask	std::vector of non-negative integers
d	Subsystems' dimension

Returns

Multi-partite qudit state vector, as a complex dynamic column vector

Here is the call graph for this function:



6.1.2.58 cmat qpp::mprj (const std::vector< std::size_t > & mask)

Projector onto multi-partite qubit ket.

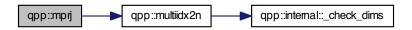
Constructs the projector onto the multi-partite qubit ket $|mask\rangle$, where mask is a std::vector of 0's and 1's

mask	std::vector of 0's and 1's
------	----------------------------

Returns

Projector onto multi-partite qubit state vector, as a complex dynamic matrix

Here is the call graph for this function:



6.1.2.59 cmat qpp::mprj (const std::vector< std::size_t > & mask, const std::vector< std::size_t > & dims)

Projector onto multi-partite qudit ket (different dimensions overload)

Constructs the projector onto the multi-partite qudit ket $|mask\rangle$, where mask is a std::vector of non-negative integers Each element in mask has to be smaller than the corresponding element in dims

Parameters

mask	std::vector of non-negative integers
dims	Dimensions of the multi-partite system

Returns

Projector onto multi-partite qudit state vector, as a complex dynamic matrix

Here is the call graph for this function:



6.1.2.60 cmat qpp::mprj (const std::vector< std::size_t > & mask, std::size_t d)

Projector onto multi-partite qudit ket (same dimensions overload)

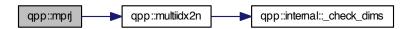
Constructs the projector onto the multi-partite qudit ket $|mask\rangle$, all subsystem having equal dimension d mask is a std::vector of non-negative integers, and each element in mask has to be strictly smaller than d

mask	std::vector of non-negative integers
d	Subsystems' dimension

Returns

Projector onto multi-partite qudit state vector, as a complex dynamic matrix

Here is the call graph for this function:



6.1.2.61 std::size_t qpp::multiidx2n (const std::vector < std::size_t > & midx, const std::vector < std::size_t > & dims)

Multi-index to non-negative integer index.

Uses standard lexicographical order, i.e. 00...0, 00...1 etc.

Parameters

midx	Multi-index
dims	Dimensions of the multi-partite system

Returns

Non-negative integer index

Here is the call graph for this function:



6.1.2.62 std::vector<std::size_t> qpp::n2multiidx (std::size_t n, const std::vector< std::size_t > & dims)

Non-negative integer index to multi-index.

Uses standard lexicographical order, i.e. 00...0, 00...1 etc.

n	Non-negative integer index
dims	Dimensions of the multi-partite system

Returns

Multi-index of the same size as dims

Here is the call graph for this function:



6.1.2.63 template < typename Derived > double qpp::norm (const Eigen::MatrixBase < Derived > & A)

Trace norm.

Parameters

Α	Eigen expression

Returns

Trace norm (Frobenius norm) of A, as a real number

Here is the call graph for this function:



6.1.2.64 std::complex<double> qpp::omega (std::size_t D)

D-th root of unity.

D	Non-negative integer

D-th root of unity $\exp(2\pi i/D)$

6.1.2.65 constexpr std::complex<double> qpp::operator""_i (unsigned long long int x)

User-defined literal for complex $i = \sqrt{-1}$ (integer overload)

Example:

```
auto z = 4_i; // type of z is std::complex<double>
```

6.1.2.66 constexpr std::complex<double> qpp::operator""_i (long double x)

User-defined literal for complex $i = \sqrt{-1}$ (real overload)

Example:

```
auto z = 4.5_i; // type of z is std::complex<double>
```

6.1.2.67 template<typename Derived > DynMat<typename Derived::Scalar> qpp::powm (const Eigen::MatrixBase < Derived > & A, std::size_t n)

Matrix power.

Explicitly multiplies the matrix A with itself n times

By convention $A^0 = I$

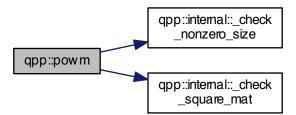
Parameters

Α	Eigen expression
n	Non-negative integer

Returns

Matrix power A^n , as a dynamic matrix over the same scalar field as A

Here is the call graph for this function:



6.1.2.68 template<typename Derived > DynMat<typename Derived::Scalar> qpp::prj (const Eigen::MatrixBase< Derived > & V)

Projector.

Normalized projector onto state vector

Parameters

V	Eigen expression

Returns

Projector onto the state vector V, or the matrix Zero if V has norm zero (i.e. smaller than qpp::eps), as a dynamic matrix over the same scalar field as A

Here is the call graph for this function:



6.1.2.69 template<typename Derived > Derived::Scalar qpp::prod (const Eigen::MatrixBase< Derived > & A)

Element-wise product of A.

Parameters

Α	Eigen expression

Returns

Element-wise product of A, as a scalar in the same scalar field as A

Here is the call graph for this function:



6.1.2.70 template<typename InputIterator > auto qpp::prod (InputIterator first, InputIterator last) -> typename InputIterator::value_type

Element-wise product of a range.

Parameters

first	Iterator to the first element of the range
last	Iterator to the last element of the range

Returns

Element-wise product of the range, as a scalar in the same scalar field as the range

6.1.2.71 template<typename Derived > DynMat<typename Derived::Scalar> qpp::ptrace (const Eigen::MatrixBase< Derived > & A, const std::vector< std::size_t > & subsys, const std::vector< std::size_t > & dims)

Partial trace.

Partial trace of the multi-partite density matrix over a list of subsystems

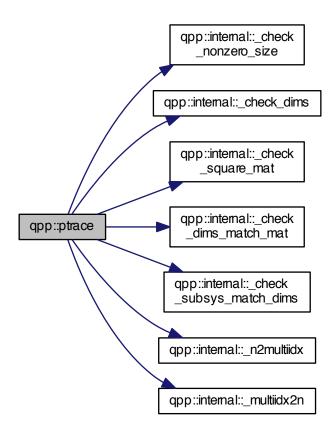
Parameters

Α	Eigen expression
subsys	Subsystem indexes
dims	Dimensions of the multi-partite system

Returns

Partial trace $Tr_{subsys}(\cdot)$ over the subsytems *subsys* in a multi-partite system, as a dynamic matrix over the same scalar field as A

Here is the call graph for this function:



6.1.2.72 template < typename Derived > DynMat < typename Derived::Scalar > qpp::ptrace1 (const Eigen::MatrixBase < Derived > & A, const std::vector < std::size_t > & dims)

Partial trace.

Partial trace of density matrix over the first subsystem in a bi-partite system

Α	Eigen expression
dims	Dimensions of bi-partite system (must be a std::vector with 2 elements)

Partial trace $Tr_A(\cdot)$ over the first subsytem A in a bi-partite system $A\otimes B$, as a dynamic matrix over the same scalar field as A

Here is the call graph for this function:



6.1.2.73 template < typename Derived > DynMat < typename Derived::Scalar > qpp::ptrace2 (const Eigen::MatrixBase < Derived > & A, const std::vector < std::size_t > & dims)

Partial trace.

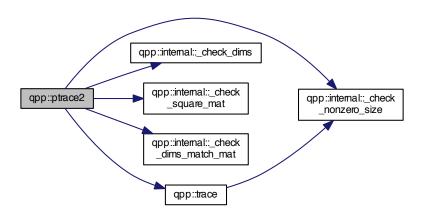
Parameters

Α	Eigen expression
dims	Dimensions of bi-partite system (must be a std::vector with 2 elements)

Returns

Partial trace $Tr_B(\cdot)$ over the second subsystem B in a bi-partite system $A \otimes B$, as a dynamic matrix over the same scalar field as A

Here is the call graph for this function:



6.1.2.74 template<typename Derived > DynMat<typename Derived::Scalar> qpp::ptranspose (const Eigen::MatrixBase < Derived > & A, const std::vector< std::size_t > & subsys, const std::vector< std::size_t > & dims)

Partial transpose.

Partial transpose of the multi-partite density matrix over a list of subsystems

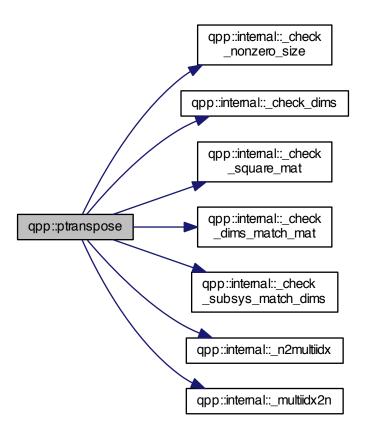
Parameters

Α	Eigen expression
subsys	Subsystem indexes
dims	Dimensions of the multi-partite system

Returns

Partial transpose $(\cdot)^{T_{subsys}}$ over the subsytems subsys in a multi-partite system, as a dynamic matrix over the same scalar field as A

Here is the call graph for this function:



6.1.2.75 template < typename Derived > double qpp::qmutualinfo (const Eigen::MatrixBase < Derived > & A, const std::vector < std::size_t > & subsysB, const std::vector < std::size_t > & subsysB, const std::vector < std::size_t > & dims)

Quantum mutual information between 2 subsystems of a composite system.

Α	Eigen expression
subsysA	Indexes of the first subsystem
subsysB	Indexes of the second subsystem
dims	Subsystems' dimensions

Mutual information between the 2 subsystems

Here is the call graph for this function:



6.1.2.76 template < typename Derived > Derived qpp::rand (std::size_t rows, std::size_t cols, double a = 0, double b = 1)

Generates a random matrix with entries uniformly distributed in the interval [a, b)

If complex, then both real and imaginary parts are uniformly distributed in [a, b)

This is the generic version that always throws *qpp::Exception::Type::UNDEFINED_TYPE*. It is specialized only for *qpp::dmat* and *qpp::cmat*

6.1.2.77 template <> dmat qpp::rand (std::size_t rows, std::size_t cols, double a, double b)

Generates a random real matrix with entries uniformly distributed in the interval [a, b), specialization for double matrices (*qpp::dmat*)

The template parameter cannot be automatically deduced and must be explicitly provided

Example:

```
// generates a 3 x 3 random Eigen::MatrixXd, with entries uniformly distributed in [-1,1) auto mat = rand<dmat>(3, 3, -1, 1);
```

rows	Number of rows of the random generated matrix
cols	Number of columns of the random generated matrix
ć	Beginning of the interval, belongs to it
, L	End of the interval, does not belong to it

Returns

Random real matrix

6.1.2.78 template <> cmat qpp::rand (std::size_t rows, std::size_t cols, double a, double b)

Generates a random complex matrix with entries (both real and imaginary) uniformly distributed in the interval [a, b), specialization for complex matrices (*qpp::cmat*)

The template parameter cannot be automatically deduced and must be explicitly provided

Example:

```
// generates a 3 x 3 random Eigen::MatrixXcd, with entries (both real and imaginary) uniformly distributed
    in [-1,1)
auto mat = rand<cmat>(3, 3, -1, 1);
```

Parameters

rows	Number of rows of the random generated matrix
cols	Number of columns of the random generated matrix
а	Beginning of the interval, belongs to it
b	End of the interval, does not belong to it

Returns

Random complex matrix

Here is the call graph for this function:



6.1.2.79 double qpp::rand (double a = 0, double b = 1)

Generates a random real number uniformly distributed in the interval [a, b)

а	Beginning of the interval, belongs to it
b	End of the interval, does not belong to it

Random real number (double) uniformly distributed in the interval [a, b)

Here is the call graph for this function:



6.1.2.80 cmat qpp::randH (std::size_t D)

Generates a random Hermitian matrix.

Parameters

D	Dimension of the Hilbert space

Returns

Random Hermitian matrix

Here is the call graph for this function:



Generates a random integer (int) uniformly distributed in the interval [a, b].

а	Beginning of the interval, belongs to it
b	End of the interval, does not belong to it

Returns

Random integer (int) uniformly distributed in the interval [a, b]

Here is the call graph for this function:



6.1.2.82 ket qpp::randket (std::size_t D)

Generates a random normalized ket (pure state vector)

Parameters

D	Dimension of the Hilbert space

Returns

Random normalized ket

Here is the call graph for this function:



6.1.2.83 std::vector<cmat> qpp::randkraus (std::size_t N, std::size_t D)

Generates a set of random Kraus operators.

Note

The set of Kraus operators satisfy the closure condition $\sum_i K_i^\dagger K_i = I$

N	Number of Kraus operators
D	Dimension of the Hilbert space

Returns

Set of N Kraus operators satisfying the closure condition

Here is the call graph for this function:



6.1.2.84 template<typename Derived > Derived qpp::randn (std::size_t rows, std::size_t cols, double mean = 0, double sigma = 1)

Generates a random matrix with entries normally distributed in N(mean, sigma)

If complex, then both real and imaginary parts are normally distributed in N(mean, sigma)

This is the generic version that always throws *qpp::Exception::Type::UNDEFINED_TYPE*. It is specialized only for *qpp::dmat* and *qpp::cmat*

6.1.2.85 template<> dmat qpp::randn (std::size_t rows, std::size_t cols, double mean, double sigma)

Generates a random real matrix with entries normally distributed in N(mean, sigma), specialization for double matrices (*qpp::dmat*)

The template parameter cannot be automatically deduced and must be explicitly provided

Example:

```
// generates a 3 x 3 random Eigen::MatrixXd, with entries normally distributed in N(0,2) auto mat = randn<dmat>(3, 3, 0, 2);
```

rows	Number of rows of the random generated matrix
cols	Number of columns of the random generated matrix
mean	Mean
sigma	Standard deviation

Random real matrix

Here is the call graph for this function:



6.1.2.86 template <> cmat qpp::randn (std::size_t rows, std::size_t cols, double mean, double sigma)

Generates a random complex matrix with entries (both real and imaginary) normally distributed in N(mean, sigma), specialization for complex matrices (*qpp::cmat*)

The template parameter cannot be automatically deduced and must be explicitly provided

Example:

```
// generates a 3 x 3 random Eigen::MatrixXcd, with entries (both real and imaginary) normally distributed in N(0,2) auto mat = randn<cmat>(3, 3, 0, 2);
```

Parameters

rows	Number of rows of the random generated matrix
cols	Number of columns of the random generated matrix
mean	Mean
sigma	Standard deviation

Returns

Random complex matrix

Here is the call graph for this function:



6.1.2.87 double qpp::randn (double mean = 0, double sigma = 1)

Generates a random real number (double) normally distributed in N(mean, sigma)

mean	Mean
sigma	Standard deviation

Returns

Random real number normally distributed in N(mean, sigma)

Here is the call graph for this function:



6.1.2.88 std::vector<std::size_t> qpp::randperm (std::size_t n)

Generates a random uniformly distributed permutation.

Uses Knuth's shuffle method (as implemented by std::shuffle), so that all permutations are equally probable Parameters

n	Size of the permutation

Returns

Random permutation of size n

Here is the call graph for this function:



6.1.2.89 cmat qpp::randrho (std::size_t D)

Generates a random density matrix.

D	Dimension of the Hilbert space
---	--------------------------------

Returns

Random density matrix

6.1.2.90 cmat qpp::randU (std::size_t D)

Generates a random unitary matrix.

Parameters

D	Dimension of the Hilbert space

Returns

Random unitary

6.1.2.91 cmat qpp::randV (std::size_t Din, std::size_t Dout)

Generates a random isometry matrix.

Parameters

Din	Size of the input Hilbert space
Dout	Size of the output Hilbert space

Returns

Random isometry matrix

Here is the call graph for this function:



 $\textbf{6.1.2.92} \quad \textbf{template} < \textbf{typename Derived} > \textbf{double qpp::renyi} \, (\, \, \textbf{const double} \, \, \textbf{alpha}, \, \, \textbf{const Eigen::MatrixBase} < \, \textbf{Derived} > \& \, \textbf{\textit{A}} \, \,)$

Renyi- α entropy of the probability distribution/density matrix A, for $\alpha \geq 0$.

alpha	Non-negative real number

A Eigen expression, representing a probability distribution (real dynamic column vector) or a density matrix (complex dynamic matrix)

Returns

Renyi- α entropy, with the logarithm in base 2

Here is the call graph for this function:



6.1.2.93 template<typename Derived > double qpp::renyi_inf (const Eigen::MatrixBase< Derived > & A)

Renyi- ∞ entropy (min entropy) of the probability distribution/density matrix A.

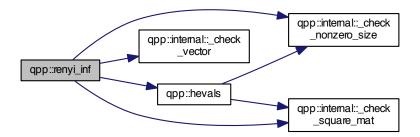
Parameters

A Eigen expression, representing a probability distribution (real dynamic column vector) or a density matrix (complex dynamic matrix)

Returns

Renyi- ∞ entropy (min entropy), with the logarithm in base 2

Here is the call graph for this function:



6.1.2.94 template<typename Derived > DynMat<typename Derived::Scalar> qpp::reshape (const Eigen::MatrixBase< Derived > & A, std::size_t rows, std::size_t cols)

Reshape.

Uses column-major order when reshaping (same as MATLAB)

Parameters 4 8 1

Α	Eigen expression
rows	Number of rows of the reshaped matrix
cols	Number of columns of the reshaped matrix

Returns

Reshaped matrix with rows rows and cols columns, as a dynamic matrix over the same scalar field as A

Here is the call graph for this function:



6.1.2.95 template < typename Derived > void qpp::save (const Eigen::MatrixBase < Derived > & A, const std::string & fname)

Saves Eigen expression to a binary file (internal format) in double precision.

See also

qpp::saveMATLABmatrix()

Parameters

Α	Eigen expression
fname	Output file name

 $6.1.2.96 \quad template < typename \ Derived > void \ qpp::saveMATLAB matrix (\ const \ Eigen::MatrixBase < Derived > \& \ \textit{A, } \ const \ std::string \& \ \textit{mat_file, } \ const \ std::string \& \ \textit{var_name, } \ const \ std::string \& \ \textit{mode} \)$

Saves an Eigen dynamic matrix to a MATLAB .mat file, generic version.

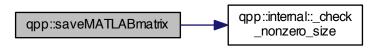
This is the generic version that always throws *qpp::Exception::Type::UNDEFINED_TYPE*. It is specialized only for *qpp::dmat* and *qpp::cmat* (the only matrix types that can be saved)

6.1.2.97 template<> void qpp::saveMATLABmatrix (const Eigen::MatrixBase< dmat > & A, const std::string & mat_file, const std::string & var_name, const std::string & mode)

Saves an Eigen dynamic matrix to a MATLAB .mat file, specialization for double matrices (qpp::dmat)

,	A Eigen expression over the complex field
mat_fil	e MATALB .mat file
var_nam	Variable name in the .mat file representing the matrix to be saved
mod	Saving mode (append, overwrite etc.), see MATLAB's <i>matOpen()</i> documentation for details

Here is the call graph for this function:



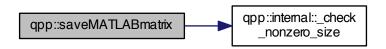
6.1.2.98 template<> void qpp::saveMATLABmatrix (const Eigen::MatrixBase< cmat > & A, const std::string & mat_file, const std::string & var_name, const std::string & mode)

Saves an Eigen dynamic matrix to a MATLAB .mat file, specialization for complex matrices (qpp::cmat)

Parameters

	Α	Eigen expression over the complex field
	mat_file	MATALB .mat file
	var_name	Variable name in the .mat file representing the matrix to be saved
Ī	mode	Saving mode (append, overwrite etc.), see MATLAB's matOpen() documentation for details

Here is the call graph for this function:



6.1.2.99 template < typename Derived > cmat qpp::schmidtcoeff (const Eigen::MatrixBase < Derived > & A, const std::vector < std::size_t > & dims)

Schmidt coefficients of the bi-partite pure state A.

Note

The sum of the squares of the Schmidt coefficients equals 1

See also

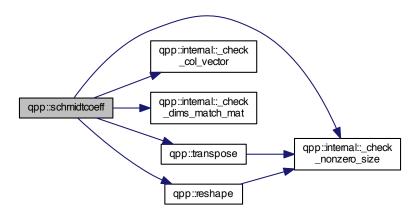
qpp::schmidtprob()

Α	Eigen expression
dims	Subsystems' dimensions

Returns

Schmidt coefficients of A, as a complex dynamic matrix, with the Schmidt coefficients on the diagonal

Here is the call graph for this function:



6.1.2.100 template < typename Derived > cmat qpp::schmidtprob (const Eigen::MatrixBase < Derived > & A, const std::vector < std::size_t > & dims)

Schmidt probabilities of the bi-partite pure state A.

Defined as the squares of the Schmidt coefficients The sum of the Schmidt probabilities equals 1

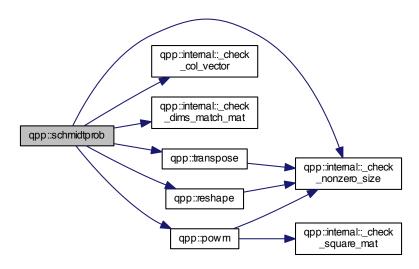
See also

qpp::schmidtcoeff()

Α	Eigen expression
dims	Subsystems' dimensions

Schmidt probabilities of A, as a complex dynamic matrix, with the Schmidt probabilities on the diagonal

Here is the call graph for this function:



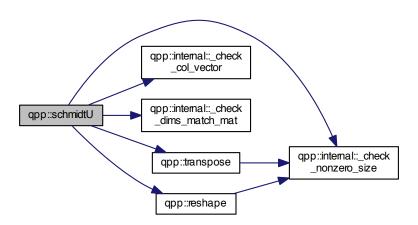
6.1.2.101 template < typename Derived > cmat qpp::schmidtU (const Eigen::MatrixBase < Derived > & A, const std::vector < std::size_t > & dims)

Schmidt basis on Alice's side.

Α	Eigen expression
dims	Subsystems' dimensions

Unitary matrix U representing the Schmidt basis on Alice's side, as a complex dynamic matrix, acting on the computational basis as $U|j\rangle=|\bar{j}\rangle$ (Schmidt vector)

Here is the call graph for this function:



6.1.2.102 template < typename Derived > cmat qpp::schmidtV (const Eigen::MatrixBase < Derived > & A, const std::vector < std::size_t > & dims)

Schmidt basis on Bob's side.

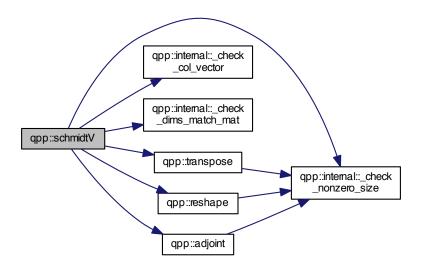
Parameters

Α	Eigen expression
dims	Subsystems' dimensions

Returns

Unitary matrix V representing the Schmidt basis on Bob's side, as a complex dynamic matrix, acting on the computational basis as $V|j\rangle=|\bar{j}\rangle$ (Schmidt vector)

Here is the call graph for this function:



6.1.2.103 template < typename Derived > double qpp::shannon (const Eigen::MatrixBase < Derived > & A)

Shannon/von-Neumann entropy of the probability distribution/density matrix A.

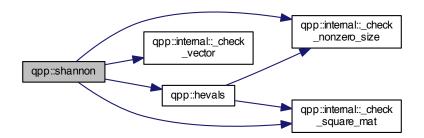
Parameters

A Eigen expression, representing a probability distribution (real dynamic column vector) or a density matrix (complex dynamic matrix)

Returns

Shannon/von-Neumann entropy, with the logarithm in base 2

Here is the call graph for this function:



Α	Eigen expression
---	------------------

Returns

Matrix sine of A

Here is the call graph for this function:



6.1.2.105 template<typename Derived > cmat qpp::spectralpowm (const Eigen::MatrixBase< Derived > & A, const cplx z)

Matrix power.

Uses the spectral decomposition of \emph{A} to compute the matrix power By convention $\emph{A}^0 = \emph{I}$

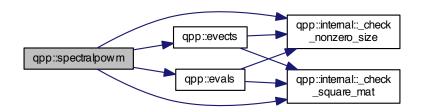
Parameters

Α	Eigen expression
Z	Complex number

Returns

Matrix power A^z

Here is the call graph for this function:



6.1.2.106 template<typename Derived > cmat qpp::sqrtm (const Eigen::MatrixBase< Derived > & A)

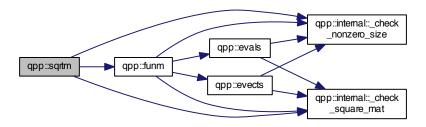
Matrix square root.

Α	Eigen expression

Returns

Matrix square root of A

Here is the call graph for this function:



 $6.1.2.107 \quad template < typename \ Derived > Derived :: Scalar \ qpp::sum \ (\ const \ Eigen:: Matrix Base < Derived > \& \ A \)$

Element-wise sum of A.

Parameters

A Eigen expression

Returns

Element-wise sum of A, as a scalar in the same scalar field as A

Here is the call graph for this function:



6.1.2.108 template<typename InputIterator > auto qpp::sum (InputIterator first, InputIterator last) -> typename InputIterator::value_type

Element-wise sum of a range.

first	Iterator to the first element of the range
last	Iterator to the last element of the range

Returns

Element-wise sum of the range, as a scalar in the same scalar field as the range

6.1.2.109 cmat qpp::super (const std::vector < cmat > & Ks)

Superoperator matrix representation.

Constructs the superoperator matrix of the channel specified by the set of Kraus operators Ks in the standard operator basis $\{|i\rangle\langle j|\}$ ordered in lexicographical order, i.e. $|0\rangle\langle 0|$, $|0\rangle\langle 1|$ etc.

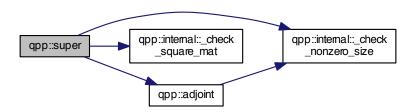
Parameters

Ks	Set of Kraus operators
----	------------------------

Returns

Superoperator matrix representation

Here is the call graph for this function:



6.1.2.110 template<typename Derived > DynMat<typename Derived::Scalar> qpp::syspermute (const Eigen::MatrixBase< Derived > & A, const std::vector< std::size_t > & perm, const std::vector< std::size_t > & dims)

System permutation.

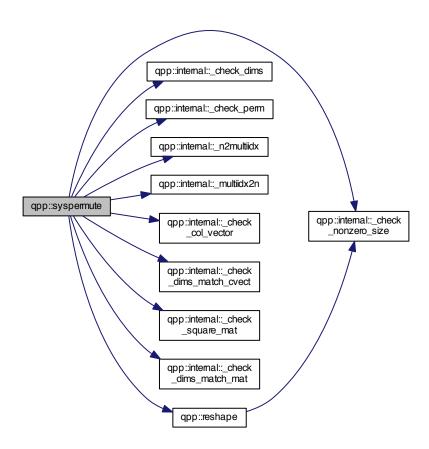
Permutes the subsystems in a state vector or density matrix

The qubit perm[i] is permuted to the location i

Α	Eigen expression
perm	Permutation
dims	Subsystems' dimensions

Permuted system, as a dynamic matrix over the same scalar field as A

Here is the call graph for this function:



6.1.2.111 template<typename Derived > Derived::Scalar qpp::trace (const Eigen::MatrixBase< Derived > & A)

Trace.

Α	Eigen expression

Trace of A, as a scalar in the same scalar field as A

Here is the call graph for this function:



6.1.2.112 template<typename Derived > DynMat<typename Derived::Scalar> qpp::transpose (const Eigen::MatrixBase< Derived > & A)

Transpose.

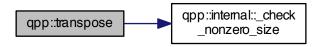
Parameters

Α	Eigen expression

Returns

Transpose of A, as a dynamic matrix over the same scalar field as A

Here is the call graph for this function:



 $6.1.2.113 \quad template < typename \ Derived > double \ qpp::tsallis \ (\ const \ double \ alpha, \ const \ Eigen::Matrix Base < Derived > \& \ A \)$

Tsallis- α entropy of the probability distribution/density matrix ${\it A}$, for $\alpha \geq 0$

When $\alpha \to 1$ the Tsallis entropy converges to the Shannon/von-Neumann entropy, with the logarithm in base e

alpha	Non-negative real number

A Eigen expression, representing a probability distribution (real dynamic column vector) or a density matrix (complex dynamic matrix)

Returns

Renyi- α entropy, with the logarithm in base 2

Here is the call graph for this function:



6.1.3 Variable Documentation

6.1.3.1 constexpr double qpp::chop = 1e-10

Used in *qpp::disp()* and *qpp::displn()* for setting to zero numbers that have their absolute value smaller than *qpp ⇔ ::ct::chop*.

6.1.3.2 constexpr double qpp::ee = 2.718281828459045235360287471352662497

Base of natural logarithm, e.

6.1.3.3 constexpr double qpp::eps = 1e-12

Used to decide whether a number or expression in double precision is zero or not.

Example:

```
if(std::abs(x) < qpp::eps) // x is zero</pre>
```

6.1.3.4 const Gates& qpp::gt = Gates::get_instance()

qpp::Gates const Singleton

Initializes the gates, see the class *qpp::Gates*

6.1.3.5 const Init& qpp::init = Init::get_instance()

qpp::Init const Singleton

Additional initializations/cleanups

6.1.3.6 constexpr std::size_t qpp::maxn = 64

Maximum number of qubits.

Used internally to allocate arrays on the stack (for speed reasons)

6.1.3.7 constexpr double qpp::pi = 3.141592653589793238462643383279502884

 π

6.1.3.8 RandomDevices& qpp::rdevs = RandomDevices::get_instance()

qpp::RandomDevices Singleton

Initializes the random devices, see the class qpp::RandomDevices

6.1.3.9 const States& qpp::st = States::get_instance()

qpp::States const Singleton

Initializes the states, see the class qpp::States

6.2 qpp::experimental Namespace Reference

Classes

class Qudit

Functions

Applies the gate A to the part subsys of a multipartite state vector or density matrix.

 $\bullet \ \ \text{template}{<} \text{typename Derived} >$

cmat channel (const Eigen::MatrixBase< Derived > &rho, const std::vector< cmat > &Ks, const std::vector<
std::size_t > &subsys, const std::vector< std::size_t > &dims)

Applies the channel specified by the set of Kraus operators Ks to the part of the density matrix rho specified by subsys.

cmat super (const std::vector < cmat > &Ks)

Superoperator matrix representation.

 $\bullet \ \ \text{template}{<} \text{typename Derived} >$

DynMat< typename Derived::Scalar > CTRL (const Eigen::MatrixBase< Derived > &A, const std::vector< std::size_t > &ctrl, const std::vector< std::size_t > &subsys, std::size_t n, std::size_t d=2)

Generates the multipartite multiple-controlled-A gate in matrix form.

cmat choi (const std::vector < cmat > &Ks)

Choi matrix representation.

• std::vector< cmat > randkraus (std::size t n, std::size t D)

Generates a set of random Kraus operators.

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U.Z.		DCIO	IIICU	DCO	GIIDL	IUI

	Ex	perimental/tes	t functions.	do no	t use/modify	these	functions	/classes
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6.2.2 Function Documentation

6.2.2.1 template < typename Derived1 , typename Derived2 > DynMat < typename Derived1::Scalar > qpp::experimental::apply (const Eigen::MatrixBase < Derived1 > & state, const Eigen::MatrixBase < Derived2 > & A, const std::vector < std::size_t > & subsys, const std::vector < std::size_t > & dims)

Applies the gate A to the part subsys of a multipartite state vector or density matrix.

Note

The dimension of the gate A must match the dimension of subsys

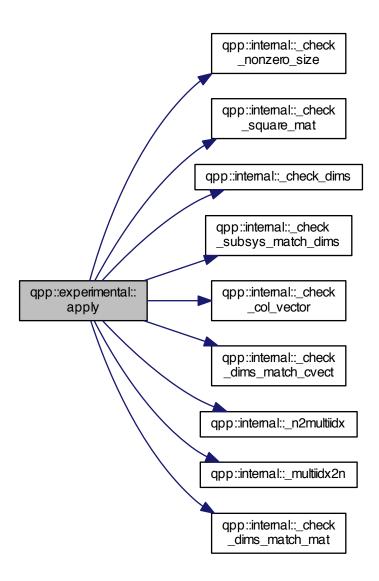
Parameters

state	Eigen expression
Α	Eigen expression
subsys	Subsystem indexes where the gate A is applied
dims	Local dimensions of all local Hilbert spaces (can be different)

Returns

Gate A applied to the part subsys of state

Here is the call graph for this function:



6.2.2.2 template<typename Derived > cmat qpp::experimental::channel (const Eigen::MatrixBase< Derived > & rho, const std::vector< cmat > & Ks, const std::vector< std::size_t > & subsys, const std::vector< std::size_t > & dims)

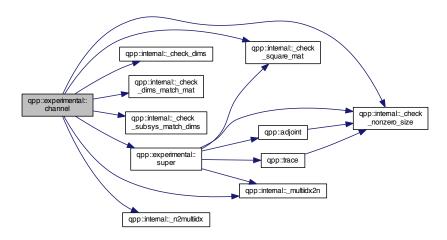
Applies the channel specified by the set of Kraus operators *Ks* to the part of the density matrix *rho* specified by *subsys*.

rho	Eigen expression
Ks	Set of Kraus operators

subsys	Subsystems' indexes
dims	Local dimensions of all local Hilbert spaces (can be different)

Output density matrix after the action of the channel

Here is the call graph for this function:



6.2.2.3 cmat qpp::experimental::choi (const std::vector < cmat > & Ks)

Choi matrix representation.

Constructs the Choi matrix of the channel specified by the set of Kraus operators Ks in the standard operator basis $\{|i\rangle\langle j|\}$ ordered in lexicographical order, i.e. $|0\rangle\langle 0|,\,|0\rangle\langle 1|$ etc.

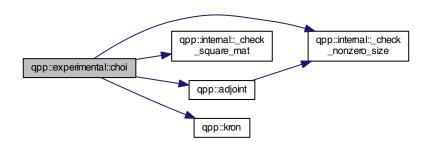
Note

The superoperator matrix S and the Choi matrix C are related by $S_{ab,mn} = C_{ma,nb}$

	Ks Set of Kraus operators	
--	---------------------------	--

Choi matrix representation

Here is the call graph for this function:



6.2.2.4 template<typename Derived > DynMat<typename Derived::Scalar> qpp::experimental::CTRL (const Eigen::MatrixBase< Derived > & A, const std::vector< std::size_t > & ctrl, const std::vector< std::size_t > & subsys, std::size_t n, std::size_t d = 2)

Generates the multipartite multiple-controlled-A gate in matrix form.

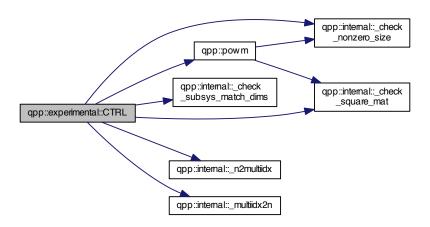
Note

The dimension of the gate A must match the dimension of subsys

Α	Eigen expression
ctrl	Control subsystem indexes
subsys	Subsystem indexes where the gate A is applied
n	Total number of subsystes
d	Local dimensions of all local Hilbert spaces (must all be equal)

CTRL-A gate, as a matrix over the same scalar field as A

Here is the call graph for this function:



6.2.2.5 std::vector<cmat> qpp::experimental::randkraus (std::size_t n, std::size_t D)

Generates a set of random Kraus operators.

Note

The set of Kraus operators satisfy the closure condition $\sum_i K_i^\dagger K_i = I$

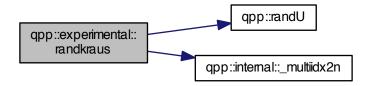
Parameters

n	Number of Kraus operators
D	Dimension of the Hilbert space

Returns

Set of *n* Kraus operators satisfying the closure condition

Here is the call graph for this function:



6.2.2.6 cmat qpp::experimental::super (const std::vector< cmat > & Ks)

Superoperator matrix representation.

Constructs the superoperator matrix of the channel specified by the set of Kraus operators Ks in the standard operator basis $\{|i\rangle\langle j|\}$ ordered in lexicographical order, i.e. $|0\rangle\langle 0|$, $|0\rangle\langle 1|$ etc.

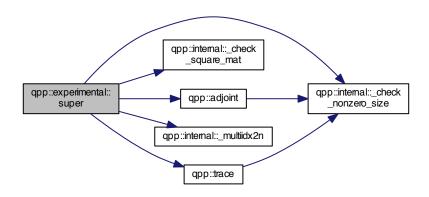
Parameters

Ks	Set of Kraus operators

Returns

Superoperator matrix representation

Here is the call graph for this function:



6.3 qpp::internal Namespace Reference

Classes

· class Singleton

Singleton policy class, used internally to implement the singleton pattern via CRTP (Curiously recurring template pattern)

Functions

- void _n2multiidx (std::size_t n, std::size_t numdims, const std::size_t *dims, std::size_t *result)
- std::size_t _multiidx2n (const std::size_t *midx, std::size_t numdims, const std::size_t *dims)
- template<typename Derived >
 bool _check_square_mat (const Eigen::MatrixBase< Derived > &A)
- template<typename Derived >
 bool _check_vector (const Eigen::MatrixBase< Derived > &A)
- template<typename Derived >
 bool check row vector (const Eigen::MatrixBase< Derived > &A)
- template<typename Derived >
 bool check col vector (const Eigen::MatrixBase< Derived > &A)
- template<typename T >
 bool _check_nonzero_size (const T &x)

- bool <u>_check_dims</u> (const std::vector< std::size_t > &dims)
- $\bullet \ \ \text{template}{<} \text{typename Derived} >$
 - bool _check_dims_match_mat (const std::vector< std::size_t > &dims, const Eigen::MatrixBase< Derived > &A)
- template<typename Derived >
 - bool _check_dims_match_cvect (const std::vector< std::size_t > &dims, const Eigen::MatrixBase< Derived > &V)
- template<typename Derived >
 - bool _check_dims_match_rvect (const std::vector< std::size_t > &dims, const Eigen::MatrixBase< Derived > &V)
- bool <u>check_eq_dims</u> (const std::vector< std::size_t > &dims, std::size_t dim)
- bool _check_subsys_match_dims (const std::vector< std::size_t > &subsys, const std::vector< std::size_t > &dims)
- bool <u>_check_perm</u> (const std::vector< std::size_t > &perm)
- template<typename T >

MatrixBase< Derived2 > &B)

- void variadic vector emplace (std::vector< T > &)
- template<typename T, typename First, typename... Args>
 void variadic_vector_emplace (std::vector< T > &v, First &&first, Args &&...args)

6.3.1 Detailed Description

Internal implementation details, do not use/modify these functions/classes

- 6.3.2 Function Documentation
- 6.3.2.1 template < typename Derived > bool qpp::internal::_check_col_vector (const Eigen::MatrixBase < Derived > & A)
- 6.3.2.2 bool qpp::internal::_check_dims (const std::vector< std::size_t > & dims)
- 6.3.2.3 template < typename Derived > bool qpp::internal::_check_dims_match_cvect (const std::vector < std::size_t > & dims, const Eigen::MatrixBase < Derived > & $\it V$)
- 6.3.2.4 template<typename Derived > bool qpp::internal::_check_dims_match_mat (const std::vector< std::size_t > & dims, const Eigen::MatrixBase< Derived > & A)
- 6.3.2.5 template<typename Derived > bool qpp::internal::_check_dims_match_rvect (const std::vector< std::size_t > & dims, const Eigen::MatrixBase< Derived > & V)
- 6.3.2.6 bool qpp::internal::_check_eq_dims (const std::vector < std::size_t > & dims, std::size_t dim)
- 6.3.2.7 template<typename T > bool qpp::internal::_check_nonzero_size (const T & x)
- 6.3.2.8 bool qpp::internal::_check_perm (const std::vector < std::size_t > & perm)
- 6.3.2.9 template<typename Derived > bool qpp::internal::_check_row_vector (const Eigen::MatrixBase< Derived > & A)
- 6.3.2.10 template < typename Derived > bool qpp::internal::_check_square_mat (const Eigen::MatrixBase < Derived > & A)
- 6.3.2.11 bool qpp::internal::_check_subsys_match_dims (const std::vector < std::size_t > & subsys, const std::vector < std::size_t > & dims)
- 6.3.2.12 template < typename Derived > bool qpp::internal::_check_vector (const Eigen::MatrixBase < Derived > & A)

Here is the call graph for this function:



- 6.3.2.14 std::size_t qpp::internal::_multiidx2n (const std::size_t * midx, std::size_t numdims, const std::size_t * dims)
 [inline]
- 6.3.2.15 void qpp::internal::_n2multiidx (std::size_t *n*, std::size_t *numdims*, const std::size_t * *dims*, std::size_t * *result*) [inline]
- 6.3.2.16 template < typename T > void qpp::internal::variadic_vector_emplace (std::vector < T > &)
- 6.3.2.17 template<typename T , typename First , typename... Args> void qpp::internal::variadic_vector_emplace (std::vector< T > & v, First && first, Args &&... args)

Here is the call graph for this function:



Chapter 7

Class Documentation

7.1 qpp::Exception Class Reference

Generates custom exceptions, used when validating function parameters.

#include <exception.h>

Inheritance diagram for qpp::Exception:



 $Collaboration\ diagram\ for\ qpp:: Exception:$



Public Types

enum Type {

Type::UNKNOWN_EXCEPTION = 1, Type::ZERO_SIZE, Type::MATRIX_NOT_SQUARE, Type::MATRIX_← NOT_CVECTOR,

Type::MATRIX_NOT_RVECTOR, Type::MATRIX_NOT_VECTOR, Type::MATRIX_NOT_SQUARE_OR_C↔ VECTOR, Type::MATRIX_NOT_SQUARE_OR_RVECTOR,

Type::MATRIX_NOT_SQUARE_OR_VECTOR, Type::MATRIX_MISMATCH_SUBSYS, Type::DIMS_INVA-LID, Type::DIMS_NOT_EQUAL,

Type::DIMS_MISMATCH_MATRIX, Type::DIMS_MISMATCH_CVECTOR, Type::DIMS_MISMATCH_RVE← CTOR, Type::DIMS_MISMATCH_VECTOR,

Type::SUBSYS_MISMATCH_DIMS, Type::PERM_INVALID, Type::NOT_QUBIT_GATE, Type::NOT_QUBI← T_SUBSYS,

Type::NOT_BIPARTITE, Type::OUT_OF_RANGE, Type::TYPE_MISMATCH, Type::UNDEFINED_TYPE, Type::CUSTOM_EXCEPTION }

Exception types, add more exceptions here if needed.

Public Member Functions

• Exception (const std::string &where, const Type &type)

Constructs an exception.

• Exception (const std::string &where, const std::string &custom)

Constructs an exception.

virtual const char * what () const noexceptoverride

Overrides std::exception::what()

Private Member Functions

• std::string construct exception msg ()

Constructs the exception's description from its type.

Private Attributes

- · std::string where
- · std::string _msg
- Type type
- std::string custom

7.1.1 Detailed Description

Generates custom exceptions, used when validating function parameters.

Customize this class if more exceptions are needed

7.1.2 Member Enumeration Documentation

7.1.2.1 enum qpp::Exception::Type [strong]

Exception types, add more exceptions here if needed.

See also

qpp:Exception::_construct_exception_msg()

Enumerator

UNKNOWN_EXCEPTION UNKNOWN EXCEPTION. Unknown exception

ZERO SIZE ZERO SIZE. Zero sized object, e.g. empty Eigen::Matrix or std::vector with no elements

MATRIX_NOT_SQUARE MATRIX_NOT_SQUARE. Eigen::Matrix is not square

MATRIX_NOT_CVECTOR MATRIX_NOT_CVECTOR. Eigen::Matrix is not a column vector

MATRIX NOT RVECTOR MATRIX NOT RVECTOR. Eigen::Matrix is not a row vector

MATRIX_NOT_VECTOR MATRIX_NOT_VECTOR. Eigen::Matrix is not a row/column vector

MATRIX_NOT_SQUARE_OR_CVECTOR MATRIX_NOT_SQUARE_OR_CVECTOR. Eigen::Matrix is not square nor a column vector

MATRIX_NOT_SQUARE_OR_RVECTOR MATRIX_NOT_SQUARE_OR_RVECTOR. Eigen::Matrix is not square nor a row vector

MATRIX_NOT_SQUARE_OR_VECTOR MATRIX_NOT_SQUARE_OR_VECTOR. Eigen::Matrix is not square nor a row/column vector

MATRIX MISMATCH SUBSYS SUBSYS MISMATCH MATRIX.

DIMS_INVALID DIMS_INVALID. Matrix size mismatch subsystems' size (e.g. in apply(), or channel() std↔ ::vector<std::size_t> representing the dimensions has zero size or contains zeros

DIMS_NOT_EQUAL DIMS_NOT_EQUAL. std::vector<std::size_t> representing the dimensions contains non-equal elements

DIMS_MISMATCH_MATRIX DIMS_MISMATCH_MATRIX. Product of the dimenisons' std::vector<std↔ ::size t> is not equal to the number of rows of Eigen::Matrix (assumed to be square)

DIMS_MISMATCH_CVECTOR DIMS_MISMATCH_CVECTOR. Product of the dimenisons' std::vector<std↔ ::size_t> is not equal to the number of cols of Eigen::Matrix (assumed to be a column vector)

DIMS_MISMATCH_RVECTOR DIMS_MISMATCH_RVECTOR. Product of the dimenisons' std::vector<std↔ ::size_t> is not equal to the number of cols of Eigen::Matrix (assumed to be a row vector)

DIMS_MISMATCH_VECTOR DIMS_MISMATCH_VECTOR. Product of the dimenisons' std::vector<std

::size_t> is not equal to the number of cols of Eigen::Matrix (assumed to be a row/column vector)

SUBSYS_MISMATCH_DIMS SUBSYS_MISMATCH_DIMS. std::vector<std::size_t> representing the subsystems' labels has duplicatates, or has entries that are larger than the size of the std::vector<std::size t> representing the dimensions

PERM_INVALID PERM_INVALID. Invalid std::vector<std::size_t> permutation

NOT QUBIT GATE NOT QUBIT GATE. Eigen::Matrix is not 2 x 2

NOT QUBIT SUBSYS NOT QUBIT SUBSYS. Subsystems are not 2-dimensional

NOT_BIPARTITE NOT_BIPARTITE. std::vector<std::size_t> representing the dimensions has size different from 2

OUT_OF_RANGE OUT_OF_RANGE. Parameter out of range

TYPE MISMATCH TYPE MISMATCH. Types do not match (i.e. Matrix<double> vs Matrix<cplx>)

UNDEFINED TYPE UNDEFINED TYPE. Templated function not defined for this type

CUSTOM_EXCEPTION CUSTOM_EXCEPTION. Custom exception, user must provide a custom message

7.1.3 Constructor & Destructor Documentation

7.1.3.1 qpp::Exception::Exception (const std::string & where, const Type & type) [inline]

Constructs an exception.

Parameters

where	Text representing where the exception occured
type	Exception's type, see the strong enumeration qpp::Exception::TYPE

Here is the call graph for this function:



7.1.3.2 qpp::Exception::Exception (const std::string & where, const std::string & custom) [inline]

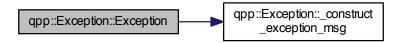
Constructs an exception.

This is an overloaded member function, provided for convenience. It differs from the above function only in what argument(s) it accepts.

Parameters

where	Text representing where the exception occured
custom	Exception's description

Here is the call graph for this function:



7.1.4 Member Function Documentation

7.1.4.1 std::string qpp::Exception::_construct_exception_msg() [inline], [private]

Constructs the exception's description from its type.

Must modify the code of this function if more exceptions are added

Returns

Exception's description

7.1.4.2 virtual const char* qpp::Exception::what () const [inline], [override], [virtual], [noexcept]

Overrides std::exception::what()

Returns

Exception's description

7.1.5 Member Data Documentation

```
7.1.5.1 std::string qpp::Exception::_custom [private]
```

7.1.5.2 std::string qpp::Exception::_msg [private]

7.1.5.3 Type qpp::Exception::_type [private]

7.1.5.4 std::string qpp::Exception::_where [private]

The documentation for this class was generated from the following file:

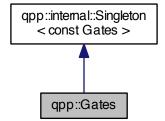
• include/classes/exception.h

7.2 qpp::Gates Class Reference

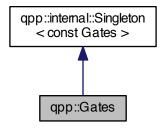
const Singleton class that implements most commonly used gates

#include <gates.h>

Inheritance diagram for qpp::Gates:



Collaboration diagram for qpp::Gates:



Public Member Functions

cmat Rn (double theta, std::vector< double > n) const

Rotation of theta about the 3-dimensional real unit vector n.

cmat Zd (std::size_t D) const

Generalized Z gate for qudits.

cmat Fd (std::size_t D) const

Fourier transform gate for qudits.

• cmat Xd (std::size t D) const

Generalized X gate for qudits.

• template<typename Derived = Eigen::MatrixXcd>

Derived Id (std::size_t D) const

Identity gate.

 $\bullet \ \ \text{template}{<} \text{typename Derived} >$

DynMat< typename Derived::Scalar > CTRL (const Eigen::MatrixBase< Derived > &A, const std::vector< std::size_t > &ctrl, const std::vector< std::size_t > &subsys, std::size_t n, std::size_t d=2) const

Generates the multipartite multiple-controlled-A gate in matrix form.

• template<typename Derived >

DynMat< typename Derived::Scalar > expandout (const Eigen::MatrixBase< Derived > &A, std::size_t pos, const std::vector< std::size_t > &dims) const

Expands out.

Public Attributes

```
• cmat Id2 { cmat::Identity(2, 2) }
```

Identity gate.

cmat H { cmat::Zero(2, 2) }

Hadamard gate.

cmat X { cmat::Zero(2, 2) }

Pauli Sigma-X gate.

cmat Y { cmat::Zero(2, 2) }

Pauli Sigma-Y gate.

cmat Z { cmat::Zero(2, 2) }

Pauli Sigma-Z gate.

cmat S { cmat::Zero(2, 2) }

```
S gate.

cmat T { cmat::Zero(2, 2) }
T gate.

cmat CNOTab { cmat::Identity(4, 4) }
Controlled-NOT control target gate.

cmat CZ { cmat::Identity(4, 4) }
Controlled-Phase gate.

cmat CNOTba { cmat::Zero(4, 4) }
Controlled-NOT target control gate.

cmat SWAP { cmat::Identity(4, 4) }
SWAP gate.

cmat TOF { cmat::Identity(8, 8) }
Toffoli gate.

cmat FRED { cmat::Identity(8, 8) }
Fredkin gate.
```

Private Member Functions

• Gates ()
Initializes the gates.

Friends

class internal::Singleton < const Gates >

Additional Inherited Members

7.2.1 Detailed Description

const Singleton class that implements most commonly used gates

7.2.2 Constructor & Destructor Documentation

```
7.2.2.1 qpp::Gates::Gates( ) [inline], [private]
```

Initializes the gates.

7.2.3 Member Function Documentation

```
7.2.3.1 template<typename Derived > DynMat<typename Derived::Scalar> qpp::Gates::CTRL ( const Eigen::MatrixBase < Derived > & A, const std::vector< std::size_t > & ctrl, const std::vector< std::size_t > & subsys, std::size_t n, std::size_t d = 2 ) const [inline]
```

Generates the multipartite multiple-controlled-A gate in matrix form.

Note

The dimension of the gate A must match the dimension of subsys

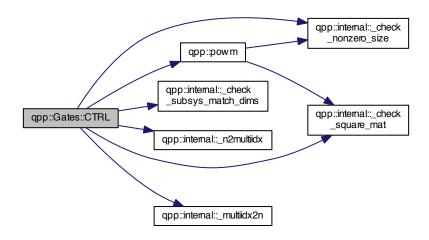
Parameters

Α	Eigen expression
ctrl	Control subsystem indexes
subsys	Subsystem indexes where the gate A is applied
n	Total number of subsystes
d	Local dimensions of all local Hilbert spaces (must all be equal)

Returns

CTRL-A gate, as a matrix over the same scalar field as A

Here is the call graph for this function:



Expands out.

Expands out *A* as a matrix in a multi-partite system Faster than using *qpp::kron*(I, I, ..., I, A, I, ..., I)

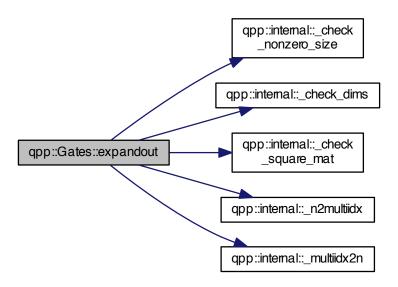
Parameters

Α	Eigen expression
pos	Position
dims	Dimensions of the multi-partite system

Returns

Tensor product $I \otimes \cdots \otimes I \otimes A \otimes I \otimes \cdots \otimes I$, with A on position pos, as a dynamic matrix over the same scalar field as A

Here is the call graph for this function:



7.2.3.3 cmat qpp::Gates::Fd (std::size_t D) const [inline]

Fourier transform gate for qudits.

Note

Defined as
$$F = \sum_{jk} \exp(2\pi i j k/D) |j\rangle\langle k|$$

Parameters

D Dimension of the Hilbert space

Returns

Fourier transform gate for qudits

Here is the call graph for this function:



7.2.3.4 template < typename Derived = Eigen::MatrixXcd > Derived qpp::Gates::Id(std::size_t D) const [inline]

Identity gate.

Note

Can change the return type from complex matrix (default) by explicitly specifying the template parameter

Parameters

D	Dimension of the Hilbert space

Returns

Identity gate

7.2.3.5 cmat qpp::Gates::Rn (double theta, std::vector< double > n) const [inline]

Rotation of theta about the 3-dimensional real unit vector n.

Parameters

theta	Rotation angle
n	3-dimensional real unit vector

Returns

Rotation gate

7.2.3.6 cmat qpp::Gates::Xd (std::size_t D) const [inline]

Generalized X gate for qudits.

Note

Defined as $X = \sum_j |j \oplus 1\rangle\langle j|$

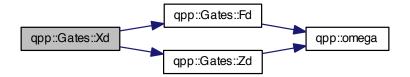
Parameters

D Dimension of the Hilbert space

Returns

Generalized X gate for qudits

Here is the call graph for this function:



7.2.3.7 cmat qpp::Gates::Zd (std::size_t D) const [inline]

Generalized Z gate for qudits.

Note

Defined as $Z = \sum_{j} \exp(2\pi i j/D) |j\rangle\langle j|$

Parameters

D Dimension of the Hilbert space

Returns

Generalized Z gate for qudits

Here is the call graph for this function:



7.2.4 Friends And Related Function Documentation

7.2.4.1 friend class internal::Singleton < const Gates > [friend]

7.2.5 Member Data Documentation

7.2.5.1 cmat qpp::Gates::CNOTab { cmat::Identity(4, 4) }

Controlled-NOT control target gate.

7.2.5.2 cmat qpp::Gates::CNOTba { cmat::Zero(4, 4) }

Controlled-NOT target control gate.

7.2.5.3 cmat qpp::Gates::CZ { cmat::Identity(4, 4) }

Controlled-Phase gate.

7.2.5.4 cmat qpp::Gates::FRED { cmat::Identity(8, 8) }

Fredkin gate.

7.2.5.5 cmat qpp::Gates::H { cmat::Zero(2, 2) }

Hadamard gate.

```
7.2.5.6 cmat qpp::Gates::Id2 { cmat::Identity(2, 2) }
Identity gate.
7.2.5.7 cmat qpp::Gates::S { cmat::Zero(2, 2) }
S gate.
7.2.5.8 cmat qpp::Gates::SWAP { cmat::Identity(4, 4) }
SWAP gate.
7.2.5.9 cmat qpp::Gates::T { cmat::Zero(2, 2) }
T gate.
7.2.5.10 cmat qpp::Gates::TOF { cmat::Identity(8, 8) }
Toffoli gate.
7.2.5.11 cmat qpp::Gates::X { cmat::Zero(2, 2) }
Pauli Sigma-X gate.
7.2.5.12 cmat qpp::Gates::Y { cmat::Zero(2, 2) }
Pauli Sigma-Y gate.
7.2.5.13 cmat qpp::Gates::Z { cmat::Zero(2, 2) }
Pauli Sigma-Z gate.
The documentation for this class was generated from the following file:
    • include/classes/gates.h
```

7.3 qpp::Init Class Reference

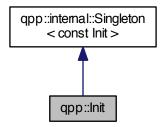
const Singleton class that performs additional initializations/cleanups

```
#include <init.h>
```

Inheritance diagram for qpp::Init:



Collaboration diagram for qpp::Init:



Public Member Functions

• Init ()

Additional initializations.

Private Member Functions

• ∼Init ()

Cleanups.

Friends

- class internal::Singleton < const Init >

Additional Inherited Members

7.3.1 Detailed Description

const Singleton class that performs additional initializations/cleanups

7.3.2 Constructor & Destructor Documentation

```
7.3.2.1 qpp::Init::Init() [inline]
```

Additional initializations.

```
7.3.2.2 qpp::Init::~Init() [inline], [private]
```

Cleanups.

7.3.3 Friends And Related Function Documentation

```
7.3.3.1 friend class internal::Singleton < const lnit > [friend]
```

The documentation for this class was generated from the following file:

· include/classes/init.h

7.4 qpp::experimental::Qudit Class Reference

```
#include <qudit.h>
```

Public Member Functions

- Qudit (const cmat &rho=States::get_instance().pz0)
- std::size_t measure (const cmat &U, bool destructive=false)
- std::size_t measure (bool destructive=false)
- cmat getRho () const
- std::size_t getD () const

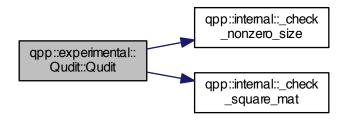
Private Attributes

- cmat _rho
- std::size_t _D

7.4.1 Constructor & Destructor Documentation

7.4.1.1 qpp::experimental::Qudit::Qudit(const cmat & rho = States::get_instance().pz0) [inline]

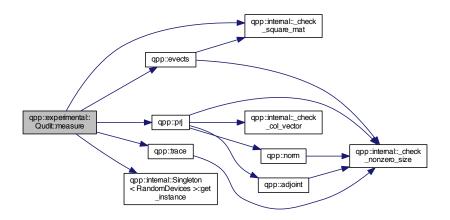
Here is the call graph for this function:



7.4.2 Member Function Documentation

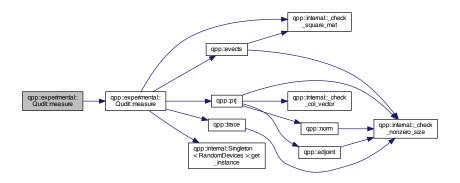
- 7.4.2.1 std::size_t qpp::experimental::Qudit::getD() const [inline]
- **7.4.2.2 cmat qpp::experimental::Qudit::getRho() const** [inline]
- 7.4.2.3 std::size_t qpp::experimental::Qudit::measure (const cmat & U, bool destructive = false) [inline]

Here is the call graph for this function:



7.4.2.4 std::size_t qpp::experimental::Qudit::measure (bool destructive = false) [inline]

Here is the call graph for this function:



7.4.3 Member Data Documentation

7.4.3.1 std::size_t qpp::experimental::Qudit::_D [private]

7.4.3.2 cmat qpp::experimental::Qudit::_rho [private]

The documentation for this class was generated from the following file:

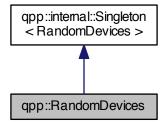
• include/experimental/classes/qudit.h

7.5 qpp::RandomDevices Class Reference

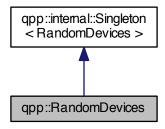
Singeleton class that manages the source of randomness in the library.

#include <randevs.h>

Inheritance diagram for qpp::RandomDevices:



Collaboration diagram for qpp::RandomDevices:



Public Attributes

std::mt19937 _rng

Mersenne twister random number generator engine.

Private Member Functions

· RandomDevices ()

Initializes and seeds the random number generators.

Private Attributes

std::random_device _rd
 used to seed std::mt19937 _rng

Friends

class internal::Singleton < RandomDevices >

Additional Inherited Members

7.5.1 Detailed Description

Singeleton class that manages the source of randomness in the library.

It consists of a wrapper around an std::mt19937 Mersenne twister random number generator engine and an std⇔ ::random_device engine. The latter is used to seed the Mersenne twister. The class also seeds the standard std::srand C number generator, as it is used by Eigen.

7.5.2 Constructor & Destructor Documentation

7.5.2.1 qpp::RandomDevices::RandomDevices() [inline], [private]

Initializes and seeds the random number generators.

7.5.3 Friends And Related Function Documentation

7.5.3.1 friend class internal::Singleton < RandomDevices > [friend]

7.5.4 Member Data Documentation

7.5.4.1 std::random_device qpp::RandomDevices::_rd [private]

used to seed std::mt19937 rng

7.5.4.2 std::mt19937 qpp::RandomDevices::_rng

Mersenne twister random number generator engine.

The documentation for this class was generated from the following file:

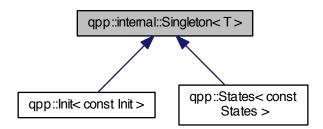
• include/classes/randevs.h

7.6 qpp::internal::Singleton < T > Class Template Reference

Singleton policy class, used internally to implement the singleton pattern via CRTP (Curiously recurring template pattern)

#include <singleton.h>

Inheritance diagram for qpp::internal::Singleton < T >:



Static Public Member Functions

• static T & get_instance ()

Protected Member Functions

- Singleton ()=default
- virtual ∼Singleton ()
- Singleton (const Singleton &)=delete
- Singleton & operator= (const Singleton &)=delete

7.6.1 Detailed Description

template<typename T>class qpp::internal::Singleton< T>

Singleton policy class, used internally to implement the singleton pattern via CRTP (Curiously recurring template pattern)

To implement a singleton, derive your class from *qpp::internal::Singleton*, make *qpp::internal::Singleton* a friend of your class, then declare the constructor of your class as private. To get an instance, use the static member function *qpp::internal::Singleton::get_instance()*, which returns a reference to your newly created singleton (thread-safe in C++11).

Example:

See also

Code of qpp::Gates, qpp::RandomDevices, qpp::States or qpp.h for real world examples of usage.

7.6.2 Constructor & Destructor Documentation

```
7.6.2.1 template<typename T> qpp::internal::Singleton< T>::Singleton( ) [protected], [default]
```

```
7.6.2.2 template<typename T> virtual qpp::internal::Singleton < T>::\simSingleton ( ) [inline], [protected], [virtual]
```

```
7.6.2.3 template<typename T> qpp::internal::Singleton < T >::Singleton ( const Singleton < T > & ) [protected], [delete]
```

7.6.3 Member Function Documentation

```
7.6.3.1 template < typename T > static T& qpp::internal::Singleton < T >::get_instance( ) [inline], [static]
```

```
7.6.3.2 template < typename T > Singleton & qpp::internal::Singleton < T > ::operator = ( const Singleton < T > & ) [protected], [delete]
```

The documentation for this class was generated from the following file:

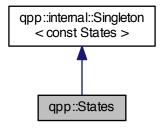
• include/classes/singleton.h

7.7 qpp::States Class Reference

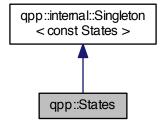
const Singleton class that implements most commonly used states

```
#include <states.h>
```

Inheritance diagram for qpp::States:



Collaboration diagram for qpp::States:



Public Attributes

```
    ket x0 { ket::Zero(2) }

      Pauli Sigma-X 0-eigenstate |+>
ket x1 { ket::Zero(2) }
      Pauli Sigma-X 1-eigenstate |->

    ket y0 { ket::Zero(2) }

      Pauli Sigma-Y 0-eigenstate.
ket y1 { ket::Zero(2) }
      Pauli Sigma-Y 1-eigenstate.

    ket z0 { ket::Zero(2) }

      Pauli Sigma-Z 0-eigenstate |0>

    ket z1 { ket::Zero(2) }

      Pauli Sigma-Z 1-eigenstate | 1>

    cmat px0 { cmat::Zero(2, 2) }

      Projector onto the Pauli Sigma-X 0-eigenstate |+><+|.
cmat px1 { cmat::Zero(2, 2) }
      Projector onto the Pauli Sigma-X 1-eigenstate |-><-|.

    cmat py0 { cmat::Zero(2, 2) }
```

```
Projector onto the Pauli Sigma-Y 0-eigenstate.
cmat py1 { cmat::Zero(2, 2) }
      Projector onto the Pauli Sigma-Y 1-eigenstate.

    cmat pz0 { cmat::Zero(2, 2) }

      Projector onto the Pauli Sigma-Z 0-eigenstate |0><0|.

    cmat pz1 { cmat::Zero(2, 2) }

      Projector onto the Pauli Sigma-Z 1-eigenstate | 1><1|.
ket b00 { ket::Zero(4) }
      Bell-00 state (following the convention in Nielsen and Chuang)
ket b01 { ket::Zero(4) }
      Bell-01 state (following the convention in Nielsen and Chuang)

    ket b10 { ket::Zero(4) }

      Bell-10 state (following the convention in Nielsen and Chuang)
ket b11 { ket::Zero(4) }
      Bell-11 state (following the convention in Nielsen and Chuang)
cmat pb00 { cmat::Zero(4, 4) }
      Projector onto the Bell-00 state.

    cmat pb01 { cmat::Zero(4, 4) }

      Projector onto the Bell-01 state.

    cmat pb10 { cmat::Zero(4, 4) }

      Projector onto the Bell-10 state.
cmat pb11 { cmat::Zero(4, 4) }
      Projector onto the Bell-11 state.

    ket GHZ { ket::Zero(8) }

      GHZ state.

    ket W { ket::Zero(8) }

      W state.

    cmat pGHZ { cmat::Zero(8, 8) }

      Projector onto the GHZ state.

    cmat pW { cmat::Zero(8, 8) }

      Projector onto the W state.
```

Private Member Functions

• States ()

Friends

class internal::Singleton < const States >

Additional Inherited Members

7.7.1 Detailed Description

const Singleton class that implements most commonly used states

7.7.2 Constructor & Destructor Documentation

```
7.7.2.1 qpp::States::States() [inline], [private]
```

Initialize the states

```
Friends And Related Function Documentation
7.7.3
7.7.3.1 friend class internal::Singleton < const States > [friend]
7.7.4 Member Data Documentation
7.7.4.1 ket qpp::States::b00 { ket::Zero(4) }
Bell-00 state (following the convention in Nielsen and Chuang)
7.7.4.2 ket qpp::States::b01 { ket::Zero(4) }
Bell-01 state (following the convention in Nielsen and Chuang)
7.7.4.3 ket qpp::States::b10 { ket::Zero(4) }
Bell-10 state (following the convention in Nielsen and Chuang)
7.7.4.4 ket qpp::States::b11 { ket::Zero(4) }
Bell-11 state (following the convention in Nielsen and Chuang)
7.7.4.5 ket qpp::States::GHZ { ket::Zero(8) }
GHZ state.
7.7.4.6 cmat qpp::States::pb00 { cmat::Zero(4, 4) }
Projector onto the Bell-00 state.
7.7.4.7 cmat qpp::States::pb01 { cmat::Zero(4, 4) }
Projector onto the Bell-01 state.
7.7.4.8 cmat qpp::States::pb10 { cmat::Zero(4, 4) }
Projector onto the Bell-10 state.
7.7.4.9 cmat qpp::States::pb11 { cmat::Zero(4, 4) }
Projector onto the Bell-11 state.
7.7.4.10 cmat qpp::States::pGHZ { cmat::Zero(8, 8) }
Projector onto the GHZ state.
7.7.4.11 cmat qpp::States::pW { cmat::Zero(8, 8) }
Projector onto the W state.
```

```
7.7.4.12 cmat qpp::States::px0 { cmat::Zero(2, 2) }
Projector onto the Pauli Sigma-X 0-eigenstate |+><+|.
7.7.4.13 cmat qpp::States::px1 { cmat::Zero(2, 2) }
Projector onto the Pauli Sigma-X 1-eigenstate |-><-|.
7.7.4.14 cmat qpp::States::py0 { cmat::Zero(2, 2) }
Projector onto the Pauli Sigma-Y 0-eigenstate.
7.7.4.15 cmat qpp::States::py1 { cmat::Zero(2, 2) }
Projector onto the Pauli Sigma-Y 1-eigenstate.
7.7.4.16 cmat qpp::States::pz0 { cmat::Zero(2, 2) }
Projector onto the Pauli Sigma-Z 0-eigenstate |0><0|.
7.7.4.17 cmat qpp::States::pz1 { cmat::Zero(2, 2) }
Projector onto the Pauli Sigma-Z 1-eigenstate |1><1|.
7.7.4.18 ket qpp::States::W { ket::Zero(8) }
W state.
7.7.4.19 ket qpp::States::x0 { ket::Zero(2) }
Pauli Sigma-X 0-eigenstate |+>
7.7.4.20 ket qpp::States::x1 { ket::Zero(2) }
Pauli Sigma-X 1-eigenstate |->
7.7.4.21 ket qpp::States::y0 { ket::Zero(2) }
Pauli Sigma-Y 0-eigenstate.
7.7.4.22 ket qpp::States::y1 { ket::Zero(2) }
Pauli Sigma-Y 1-eigenstate.
7.7.4.23 ket qpp::States::z0 { ket::Zero(2) }
Pauli Sigma-Z 0-eigenstate |0>
```

```
7.7.4.24 ket qpp::States::z1 { ket::Zero(2) }
```

Pauli Sigma-Z 1-eigenstate |1>

The documentation for this class was generated from the following file:

• include/classes/states.h

7.8 qpp::Timer Class Reference

Measures time.

```
#include <timer.h>
```

Public Member Functions

• Timer ()

Constructs an instance with the current time as the starting point.

• void tic ()

Resets the chronometer.

• const Timer & toc ()

Stops the chronometer.

• double seconds () const

Time passed in seconds.

Protected Attributes

- std::chrono::steady_clock::time_point _start
- std::chrono::steady_clock::time_point _end

Friends

• std::ostream & operator<< (std::ostream &os, const Timer &rhs)

Overload for std::ostream operators.

7.8.1 Detailed Description

Measures time.

Uses a std::chrono::steady_clock. It is not affected by wall clock changes during runtime.

7.8.2 Constructor & Destructor Documentation

```
7.8.2.1 qpp::Timer::Timer( ) [inline]
```

Constructs an instance with the current time as the starting point.

7.8.3 Member Function Documentation

7.8.3.1 double qpp::Timer::seconds () const [inline]

Time passed in seconds.

Returns

Number of seconds that passed between the instantiation/reset and invocation of qpp::Timer::toc()

```
7.8.3.2 void qpp::Timer::tic() [inline]
```

Resets the chronometer.

Resets the starting/ending point to the current time

```
7.8.3.3 const Timer& qpp::Timer::toc( ) [inline]
```

Stops the chronometer.

Set the current time as the ending point

Returns

Current instance

7.8.4 Friends And Related Function Documentation

7.8.4.1 std::ostream& operator<<(std::ostream & os, const Timer & rhs) [friend]

Overload for std::ostream operators.

Parameters

OS	Output stream
rhs	Timer instance

Returns

Writes to the output stream the number of seconds that passed between the instantiation/reset and invocation of app::Timer::toc().

7.8.5 Member Data Documentation

7.8.5.1 std::chrono::steady_clock::time_point qpp::Timer::_end [protected]

7.8.5.2 std::chrono::steady_clock::time_point qpp::Timer::_start [protected]

The documentation for this class was generated from the following file:

· include/classes/timer.h

Chapter 8

File Documentation

8.1 include/classes/exception.h File Reference

This graph shows which files directly or indirectly include this file:



Classes

class qpp::Exception

Generates custom exceptions, used when validating function parameters.

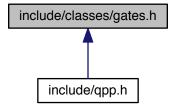
Namespaces

• qpp

124 File Documentation

8.2 include/classes/gates.h File Reference

This graph shows which files directly or indirectly include this file:



Classes

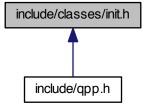
class qpp::Gates
 const Singleton class that implements most commonly used gates

Namespaces

qpp

8.3 include/classes/init.h File Reference

This graph shows which files directly or indirectly include this file:



Classes

· class qpp::Init

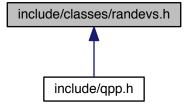
const Singleton class that performs additional initializations/cleanups

Namespaces

• qpp

8.4 include/classes/randevs.h File Reference

This graph shows which files directly or indirectly include this file:



Classes

• class qpp::RandomDevices

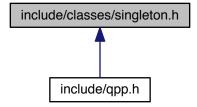
Singeleton class that manages the source of randomness in the library.

Namespaces

qpp

8.5 include/classes/singleton.h File Reference

This graph shows which files directly or indirectly include this file:



126 File Documentation

Classes

class qpp::internal::Singleton< T >

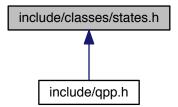
Singleton policy class, used internally to implement the singleton pattern via CRTP (Curiously recurring template pattern)

Namespaces

- qpp
- · qpp::internal

8.6 include/classes/states.h File Reference

This graph shows which files directly or indirectly include this file:



Classes

class qpp::States

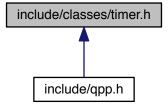
const Singleton class that implements most commonly used states

Namespaces

qpp

8.7 include/classes/timer.h File Reference

This graph shows which files directly or indirectly include this file:



Classes

• class qpp::Timer

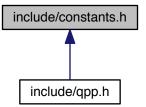
Measures time.

Namespaces

• qpp

8.8 include/constants.h File Reference

This graph shows which files directly or indirectly include this file:



Namespaces

qpp

128 File Documentation

Functions

```
• constexpr std::complex < double > qpp::operator""_i (unsigned long long int x) 
 User-defined literal for complex i = \sqrt{-1} (integer overload)
```

 $\bullet \ \ constexpr \ std::complex < double > qpp::operator""_i \ (long \ double \ x) \\$

User-defined literal for complex $i = \sqrt{-1}$ (real overload)

• std::complex < double > qpp::omega (std::size_t D)

D-th root of unity.

Variables

constexpr double qpp::chop = 1e-10

Used in qpp::disp() and qpp::displn() for setting to zero numbers that have their absolute value smaller than qpp::ct← ::chop.

• constexpr double qpp::eps = 1e-12

Used to decide whether a number or expression in double precision is zero or not.

• constexpr std::size_t qpp::maxn = 64

Maximum number of qubits.

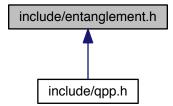
• constexpr double qpp::pi = 3.141592653589793238462643383279502884

π

constexpr double qpp::ee = 2.718281828459045235360287471352662497
 Base of natural logarithm, e.

8.9 include/entanglement.h File Reference

This graph shows which files directly or indirectly include this file:



Namespaces

qpp

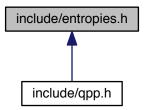
Functions

template<typename Derived >
 cmat qpp::schmidtcoeff (const Eigen::MatrixBase< Derived > &A, const std::vector< std::size_t > &dims)
 Schmidt coefficients of the bi-partite pure state A.

- template<typename Derived >
 cmat qpp::schmidtU (const Eigen::MatrixBase< Derived > &A, const std::vector< std::size_t > &dims)
 Schmidt basis on Alice's side.
- template<typename Derived >
 cmat qpp::schmidtV (const Eigen::MatrixBase< Derived > &A, const std::vector< std::size_t > &dims)
 Schmidt basis on Bob's side.
- template<typename Derived >
 cmat qpp::schmidtprob (const Eigen::MatrixBase< Derived > &A, const std::vector< std::size_t > &dims)
 Schmidt probabilities of the bi-partite pure state A.
- template<typename Derived >
 double qpp::entanglement (const Eigen::MatrixBase< Derived > &A, const std::vector< std::size_t > &dims)
 Entanglement of the bi-partite pure state A.
- template<typename Derived >
 double qpp::gconcurrence (const Eigen::MatrixBase< Derived > &A)
 G-concurrence of the bi-partite pure state A.

8.10 include/entropies.h File Reference

This graph shows which files directly or indirectly include this file:



Namespaces

• qpp

Functions

- template<typename Derived >
 double qpp::shannon (const Eigen::MatrixBase< Derived > &A)
 - Shannon/von-Neumann entropy of the probability distribution/density matrix A.
- template < typename Derived >
 double qpp::renyi (const double alpha, const Eigen::MatrixBase < Derived > &A)
- Renyi- α entropy of the probability distribution/density matrix A, for $\alpha \geq 0$.
- template<typename Derived >
 double qpp::renyi_inf (const Eigen::MatrixBase< Derived > &A)
 - Renyi- ∞ entropy (min entropy) of the probability distribution/density matrix A.
- template < typename Derived >
 double qpp::tsallis (const double alpha, const Eigen::MatrixBase < Derived > &A)

130 File Documentation

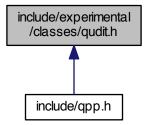
Tsallis- α entropy of the probability distribution/density matrix A, for $\alpha \geq 0$

template<typename Derived >
 double qpp::qmutualinfo (const Eigen::MatrixBase< Derived > &A, const std::vector< std::size_t >
 &subsysA, const std::vector< std::size_t > &subsysB, const std::vector< std::size_t > &dims)

Quantum mutual information between 2 subsystems of a composite system.

8.11 include/experimental/classes/qudit.h File Reference

This graph shows which files directly or indirectly include this file:



Classes

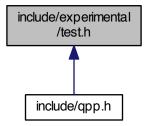
· class qpp::experimental::Qudit

Namespaces

- qpp
- qpp::experimental

8.12 include/experimental/test.h File Reference

This graph shows which files directly or indirectly include this file:



Namespaces

- · qpp::experimental
- qpp

Functions

template<typename Derived1, typename Derived2 >
 DynMat< typename Derived1::Scalar > qpp::experimental::apply (const Eigen::MatrixBase< Derived1 >
 &state, const Eigen::MatrixBase< Derived2 > &A, const std::vector< std::size_t > &subsys, const std
 ::vector< std::size_t > &dims)

Applies the gate A to the part subsys of a multipartite state vector or density matrix.

template<typename Derived >
 cmat qpp::experimental::channel (const Eigen::MatrixBase< Derived > &rho, const std::vector< cmat >
 &Ks, const std::vector< std::size_t > &subsys, const std::vector< std::size_t > &dims)

Applies the channel specified by the set of Kraus operators Ks to the part of the density matrix rho specified by subsys.

cmat qpp::experimental::super (const std::vector< cmat > &Ks)

Superoperator matrix representation.

template<typename Derived >
 DynMat< typename Derived::Scalar > qpp::experimental::CTRL (const Eigen::MatrixBase< Derived > &A, const std::vector< std::size_t > &cut, const std::vector< std::size_t n, std::size_t d=2)</p>

Generates the multipartite multiple-controlled-A gate in matrix form.

cmat qpp::experimental::choi (const std::vector< cmat > &Ks)

Choi matrix representation.

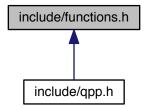
std::vector< cmat > qpp::experimental::randkraus (std::size_t n, std::size_t D)

Generates a set of random Kraus operators.

132 File Documentation

8.13 include/functions.h File Reference

This graph shows which files directly or indirectly include this file:



Namespaces

qpp

template<typename Derived >

double qpp::norm (const Eigen::MatrixBase< Derived > &A)

Functions

```
    template<typename Derived >

  DynMat< typename Derived::Scalar > qpp::transpose (const Eigen::MatrixBase< Derived > &A)
      Transpose.

    template<typename Derived >

  DynMat< typename Derived::Scalar > qpp::conjugate (const Eigen::MatrixBase< Derived > &A)
      Complex conjugate.

    template<typename Derived >

  DynMat< typename Derived::Scalar > qpp::adjoint (const Eigen::MatrixBase< Derived > &A)
• template<typename Derived >
  DynMat< typename Derived::Scalar > qpp::inverse (const Eigen::MatrixBase< Derived > &A)
      Inverse.

    template<typename Derived >

  Derived::Scalar qpp::trace (const Eigen::MatrixBase< Derived > &A)
      Trace.

    template<typename Derived >

  Derived::Scalar <a href="mailto:qpp::det">qpp::det</a> (const Eigen::MatrixBase</a> Derived > &A)
      Determinant.

    template<typename Derived >

  Derived::Scalar qpp::logdet (const Eigen::MatrixBase< Derived > &A)
      Logarithm of the determinant.
template<typename Derived >
  Derived::Scalar qpp::sum (const Eigen::MatrixBase< Derived > &A)
      Element-wise sum of A.
• template<typename Derived >
  Derived::Scalar <a href="mailto:open:prod">open:prod</a> (const Eigen::MatrixBase</a> Derived > &A)
      Element-wise product of A.
```

```
Trace norm.
• template<typename Derived >
  DynColVect< cplx > qpp::evals (const Eigen::MatrixBase< Derived > &A)
     Eigenvalues.

    template<typename Derived >

  cmat qpp::evects (const Eigen::MatrixBase< Derived > &A)
     Eigenvectors.
• template<typename Derived >
  DynColVect< double > qpp::hevals (const Eigen::MatrixBase< Derived > &A)
     Hermitian eigenvalues.

    template<typename Derived >

  cmat qpp::hevects (const Eigen::MatrixBase< Derived > &A)
     Hermitian eigenvectors.

    template<typename Derived >

  cmat qpp::funm (const Eigen::MatrixBase< Derived > &A, cplx(*f)(const cplx &))
     Functional calculus f(A)
template<typename Derived >
  cmat <a href="mailto:qpp::sqrtm">qpp::sqrtm</a> (const Eigen::MatrixBase</a> Derived > &A)
     Matrix square root.

    template<typename Derived >

  cmat qpp::absm (const Eigen::MatrixBase< Derived > &A)
     Matrix absolut value.

    template<typename Derived >

  cmat qpp::expm (const Eigen::MatrixBase< Derived > &A)
     Matrix exponential.
• template<typename Derived >
  cmat qpp::logm (const Eigen::MatrixBase< Derived > &A)
     Matrix logarithm.

    template<typename Derived >

  cmat qpp::sinm (const Eigen::MatrixBase< Derived > &A)
     Matrix sin.

    template<typename Derived >

  cmat qpp::cosm (const Eigen::MatrixBase< Derived > &A)
     Matrix cos.
• template<typename Derived >
  cmat qpp::spectralpowm (const Eigen::MatrixBase< Derived > &A, const cplx z)
     Matrix power.
• template<typename Derived >
  DynMat< typename Derived::Scalar > qpp::powm (const Eigen::MatrixBase< Derived > &A, std::size_t n)
     Matrix power.
• template<typename OutputScalar , typename Derived >
  DynMat< OutputScalar > qpp::cwise (const Eigen::MatrixBase< Derived > &A, OutputScalar(*f)(const type-
  name Derived::Scalar &))
     Functor.
template<typename T >
  DynMat< typename T::Scalar > qpp::kron (const T &head)
     Kronecker product (variadic overload)
• template<typename T , typename... Args>
  DynMat< typename T::Scalar > qpp::kron (const T &head, const Args &...tail)
     Kronecker product (variadic overload)
template<typename Derived >
  DynMat< typename Derived::Scalar > qpp::kron (const std::vector< Derived > &As)
```

Kronecker product (std::vector overload)

• template<typename Derived > DynMat< typename Derived::Scalar > qpp::kron (const std::initializer_list< Derived > &As) Kronecker product (std::initializer list overload) template<typename Derived > DynMat< typename Derived::Scalar > qpp::kronpow (const Eigen::MatrixBase< Derived > &A, std::size t n) Kronecker power. template<typename Derived > DynMat< typename Derived::Scalar > qpp::reshape (const Eigen::MatrixBase< Derived > &A, std::size t rows, std::size t cols) Reshape. template<typename Derived1 , typename Derived2 > DynMat< typename Derived1::Scalar > qpp::comm (const Eigen::MatrixBase< Derived1 > &A, const Eigen::MatrixBase< Derived2 > &B) Commutator. template<typename Derived1 , typename Derived2 > DynMat< typename Derived1::Scalar > qpp::anticomm (const Eigen::MatrixBase< Derived1 > &A, const Eigen::MatrixBase< Derived2 > &B) Anti-commutator. template<typename Derived > DynMat< typename Derived::Scalar > qpp::prj (const Eigen::MatrixBase< Derived > &V) template<typename Derived > DynMat< typename Derived::Scalar > qpp::grams (const std::vector< Derived > &Vs) Gram-Schmidt orthogonalization (std::vector overload) • template<typename Derived > DynMat< typename Derived::Scalar > qpp::grams (const std::initializer list< Derived > &Vs) Gram-Schmidt orthogonalization (std::initializer_list overload) template<typename Derived > DynMat< typename Derived::Scalar > qpp::grams (const Eigen::MatrixBase< Derived > &A) Gram-Schmidt orthogonalization (Eigen expression (matrix) overload) $\bullet \ \, \text{std::vector} < \text{std::size_t} > \text{qpp::n2multiidx} \ \, (\text{std::size_t} \ n, \ \text{const} \ \, \text{std::vector} < \text{std::size_t} > \text{\&dims}) \\$ Non-negative integer index to multi-index. std::size_t qpp::multiidx2n (const std::vector< std::size_t > &midx, const std::vector< std::size_t > &dims) Multi-index to non-negative integer index. ket qpp::mket (const std::vector< std::size t > &mask) Multi-partite qubit ket. ket qpp::mket (const std::vector < std::size_t > &mask, const std::vector < std::size_t > &dims) Multi-partite qudit ket (different dimensions overload) ket qpp::mket (const std::vector< std::size t > &mask, std::size t d) Multi-partite qudit ket (same dimensions overload) cmat qpp::mprj (const std::vector < std::size_t > &mask) Projector onto multi-partite qubit ket. cmat qpp::mprj (const std::vector< std::size_t > &mask, const std::vector< std::size_t > &dims) Projector onto multi-partite qudit ket (different dimensions overload) cmat qpp::mprj (const std::vector< std::size_t > &mask, std::size_t d) Projector onto multi-partite qudit ket (same dimensions overload) std::vector< std::size_t > qpp::invperm (const std::vector< std::size_t > &perm) Inverse permutation. std::vector< std::size_t > qpp::compperm (const std::vector< std::size_t > &perm, const std::vector< std. ::size_t > &sigma)

Compose permutations.

```
    template<typename InputIterator >
        std::vector< double > qpp::amplitudes (InputIterator first, InputIterator last)
        Computes the absolut values squared of a range of complex numbers.
```

 $\bullet \ \ \mathsf{template}{<} \mathsf{typename} \ \mathsf{Derived} >$

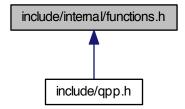
std::vector< double > qpp::amplitudes (const Eigen::MatrixBase< Derived > &V)

Computes the absolut values squared of a column vector.

- template<typename InputIterator >
 auto qpp::sum (InputIterator first, InputIterator last) -> typename InputIterator::value_type
 Element-wise sum of a range.
- template<typename InputIterator >
 auto qpp::prod (InputIterator first, InputIterator last) -> typename InputIterator::value_type
 Element-wise product of a range.

8.14 include/internal/functions.h File Reference

This graph shows which files directly or indirectly include this file:



Namespaces

- · qpp::internal
- qpp

Functions

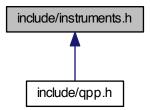
- void qpp::internal::_n2multiidx (std::size_t n, std::size_t numdims, const std::size_t *dims, std::size_t *result)
- std::size_t qpp::internal::_multiidx2n (const std::size_t *midx, std::size_t numdims, const std::size_t *dims)
- template<typename Derived >
 bool qpp::internal::_check_square_mat (const Eigen::MatrixBase< Derived > &A)
- template<typename Derived >
 bool qpp::internal::_check_vector (const Eigen::MatrixBase< Derived > &A)
- template<typename Derived >
 bool qpp::internal::_check_row_vector (const Eigen::MatrixBase< Derived > &A)
- template<typename Derived >
 bool qpp::internal::_check_col_vector (const Eigen::MatrixBase< Derived > &A)
- template<typename T >
 bool qpp::internal::_check_nonzero_size (const T &x)
- bool qpp::internal::_check_dims (const std::vector< std::size_t > &dims)

```
    template<typename Derived >
        bool qpp::internal::_check_dims_match_mat (const std::vector< std::size_t > &dims, const Eigen::Matrix
        Base< Derived > &A)
```

- template<typename Derived >
 bool qpp::internal::_check_dims_match_cvect (const std::vector< std::size_t > &dims, const Eigen::Matrix
 Base< Derived > &V)
- template<typename Derived >
 bool qpp::internal::_check_dims_match_rvect (const std::vector< std::size_t > &dims, const Eigen::Matrix
 Base< Derived > &V)
- bool qpp::internal::_check_eq_dims (const std::vector < std::size_t > &dims, std::size_t dim)
- bool qpp::internal::_check_subsys_match_dims (const std::vector< std::size_t > &subsys, const std
 ::vector< std::size_t > &dims)
- bool qpp::internal::_check_perm (const std::vector< std::size_t > &perm)
- template<typename Derived1, typename Derived2 >
 DynMat< typename Derived1::Scalar > qpp::internal::_kron2 (const Eigen::MatrixBase< Derived1 > &A, const Eigen::MatrixBase< Derived2 > &B)
- template<typename T > void qpp::internal::variadic_vector_emplace (std::vector< T > &)
- template<typename T, typename First, typename... Args>
 void qpp::internal::variadic_vector_emplace (std::vector< T > &v, First &&first, Args &&...args)

8.15 include/instruments.h File Reference

This graph shows which files directly or indirectly include this file:



Namespaces

qpp

Functions

- template<typename Derived >
 std::pair< std::vector< double >
 , std::vector< cmat >> qpp::measure (const Eigen::MatrixBase< Derived > &A, const std::vector< cmat >
 &Ks)
 - Measures the state A using the set of Kraus operators Ks.
- template<typename Derived >
 std::pair< std::vector< double >
 , std::vector< cmat > > qpp::measure (const Eigen::MatrixBase< Derived > &A, const std::initializer_list
 cmat > &Ks)

Measures the state A using the set of Kraus operators Ks (std::initializer_list overload)

• template<typename Derived >

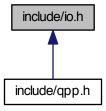
std::pair< std::vector< double >

, std::vector < cmat > > qpp::measure (const Eigen::MatrixBase < Derived > &A, const cmat &U)

Measures the state A in the orthonormal basis specified by the unitary matrix U. The normalized basis vectors are the columns of U.

8.16 include/io.h File Reference

This graph shows which files directly or indirectly include this file:



Namespaces

qpp

Functions

template<typename InputIterator >
 void qpp::disp (const InputIterator &first, const InputIterator &last, const std::string &separator, const std::string &start="[", const std::string &end="]", std::ostream &os=std::cout)

Displays a range. Does not add a newline.

template<typename InputIterator >
 std::ostream & qpp::displn (const InputIterator &first, const InputIterator &last, const std::string &separator,
 const std::string &start="[", const std::string &end="]", std::ostream &os=std::cout)

Displays a range. Adds a newline.

• template<typename T >

std::ostream & qpp::disp (const T &x, const std::string &separator, const std::string &start="[", const std::string &end="]", std::ostream &os=std::cout)

Displays a standard container that supports std::begin, std::end and forward iteration. Does not add a newline.

• template<typename T >

std::ostream & qpp::displn (const T &x, const std::string &separator, const std::string &start="[", const std::string &end="]", std::ostream &os=std::cout)

Displays a standard container that supports std::begin, std::end and forward iteration. Adds a newline.

• template<typename T >

std::ostream & qpp::disp (const T *x, const std::size_t n, const std::string &separator, const std::string &start="[", const std::string &end="]", std::ostream &os=std::cout)

Displays a C-style array. Does not add a newline.

• template<typename T >

std::ostream & qpp::displn (const T *x, const std::size_t n, const std::string &separator, const std::string &start="[", const std::string &end="]", std::ostream &os=std::cout)

Displays a C-style array. Adds a newline.

template<typename Derived >

std::ostream & qpp::disp (const Eigen::MatrixBase< Derived > &A, double chop=qpp::chop, std::ostream &os=std::cout)

Displays an Eigen expression in matrix friendly form. Does not add a new line.

template<typename Derived >

std::ostream & qpp::displn (const Eigen::MatrixBase< Derived > &A, double chop=qpp::chop, std::ostream &os=std::cout)

Displays an Eigen expression in matrix friendly form. Adds a newline.

std::ostream & qpp::disp (const cplx z, double chop=qpp::chop, std::ostream &os=std::cout)

Displays a number (implicitly converted to std::complex<double>) in friendly form. Does not add a new line.

std::ostream & qpp::displn (const cplx z, double chop=qpp::chop, std::ostream &os=std::cout)

Displays a number (implicitly converted to std::complex<double>) in friendly form. Adds a new line.

template<typename Derived >

void qpp::save (const Eigen::MatrixBase< Derived > &A, const std::string &fname)

Saves Eigen expression to a binary file (internal format) in double precision.

template<typename Derived >

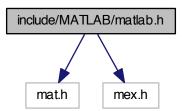
DynMat< typename Derived::Scalar > qpp::load (const std::string &fname)

Loads Eigen matrix from a binary file (internal format) in double precision.

8.17 include/MATLAB/matlab.h File Reference

```
#include "mat.h"
#include "mex.h"
```

Include dependency graph for matlab.h:



Namespaces

• qpp

Functions

 $\bullet \ \ \text{template}{<} \text{typename Derived} >$

Derived qpp::loadMATLABmatrix (const std::string &mat_file, const std::string &var_name)

Loads an Eigen dynamic matrix from a MATLAB .mat file, generic version.

• template<>

dmat qpp::loadMATLABmatrix (const std::string &mat_file, const std::string &var_name)

Loads an Eigen dynamic matrix from a MATLAB .mat file, specialization for double matrices (qpp::dmat)

template<>

cmat gpp::loadMATLABmatrix (const std::string &mat file, const std::string &var name)

Loads an Eigen dynamic matrix from a MATLAB .mat file, specialization for complex matrices (qpp::cmat)

template<typename Derived >

void qpp::saveMATLABmatrix (const Eigen::MatrixBase< Derived > &A, const std::string &mat_file, const std::string &var name, const std::string &mode)

Saves an Eigen dynamic matrix to a MATLAB .mat file, generic version.

template<>

void qpp::saveMATLABmatrix (const Eigen::MatrixBase< dmat > &A, const std::string &mat_file, const std
::string &var_name, const std::string &mode)

Saves an Eigen dynamic matrix to a MATLAB .mat file, specialization for double matrices (qpp::dmat)

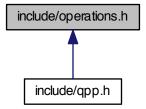
template<>

void qpp::saveMATLABmatrix (const Eigen::MatrixBase< cmat > &A, const std::string &mat_file, const std
::string &var_name, const std::string &mode)

Saves an Eigen dynamic matrix to a MATLAB .mat file, specialization for complex matrices (qpp::cmat)

8.18 include/operations.h File Reference

This graph shows which files directly or indirectly include this file:



Namespaces

qpp

Functions

template<typename Derived1, typename Derived2 >
 DynMat< typename Derived1::Scalar > qpp::applyCTRL (const Eigen::MatrixBase< Derived1 > &state, const Eigen::MatrixBase< Derived2 > &A, const std::vector< std::size_t > &ctrl, const std::vector< std::size_t > &subsys, std::size_t n, std::size_t d=2)

Applies the controlled-gate A to the part subsys of a multipartite state vector or density matrix.

template<typename Derived1 , typename Derived2 >
 DynMat< typename Derived1::Scalar > qpp::apply (const Eigen::MatrixBase< Derived1 > &state, const Eigen::MatrixBase< Derived2 > &A, const std::vector< std::size_t > &subsys, std::size_t n, std::size_t d=2)
 Applies the gate A to the part subsys of a multipartite state vector or density matrix.

template < typename Derived >
 cmat qpp::channel (const Eigen::MatrixBase < Derived > &rho, const std::vector < cmat > &Ks)

Applies the channel specified by the set of Kraus operators Ks to the density matrix rho.

template<typename Derived >
 cmat qpp::channel (const Eigen::MatrixBase< Derived > &rho, const std::vector< cmat > &Ks, const std
 ::vector< std::size_t > &subsys, std::size_t n, std::size_t d=2)

Applies the channel specified by the set of Kraus operators Ks to the part of the density matrix rho specified by subsys.

cmat qpp::super (const std::vector< cmat > &Ks)

Superoperator matrix representation.

cmat qpp::choi (const std::vector< cmat > &Ks)

Choi matrix representation.

std::vector< cmat > qpp::choi2kraus (const cmat &A)

Extracts orthogonal Kraus operators from Choi matrix.

template<typename Derived >

 $\label{lem:def:def:def:def:DynMat} DynMat < typename \ Derived::Scalar > qpp::ptrace1 \ (const \ Eigen::MatrixBase < Derived > &A, \ const \ std \\ ::vector < std::size_t > &dims)$

Partial trace.

• template<typename Derived >

 $\label{lem:def:def:def:def:DynMat} DynMat < typename \ Derived::Scalar > qpp::ptrace2 \ (const \ Eigen::MatrixBase < Derived > &A, \ const \ std \\ ::vector < std::size_t > &dims)$

Partial trace.

 $\bullet \ \ \text{template}{<} \text{typename Derived} >$

DynMat< typename Derived::Scalar > qpp::ptrace (const Eigen::MatrixBase< Derived > &A, const std⇔ ::vector< std::size_t > &subsys, const std::vector< std::size_t > &dims)

Partial trace.

• template<typename Derived >

 $\label{lem:def:def:def:def:DynMat} \begin{subarray}{ll} DynMat< typename Derived::Scalar > qpp::ptranspose (const Eigen::MatrixBase< Derived > &A, const std::vector< std::size_t > &subsys, const std::vector< std::size_t > &dims) \\ \end{subarray}$

Partial transpose.

template<typename Derived >

DynMat< typename Derived::Scalar > qpp::syspermute (const Eigen::MatrixBase< Derived > &A, const std::vector< std::size_t > &perm, const std::vector< std::size_t > &dims)

System permutation.

8.19 include/qpp.h File Reference

```
#include <algorithm>
#include <chrono>
#include <cmath>
#include <complex>
#include <cstdlib>
#include <cstring>
#include <ctime>
#include <exception>
#include <fstream>
#include <functional>
#include <initializer list>
#include <iomanip>
#include <iostream>
#include <iterator>
#include <limits>
#include <numeric>
#include <ostream>
#include <random>
#include <sstream>
#include <stdexcept>
#include <string>
#include <tuple>
#include <type_traits>
#include <utility>
#include <vector>
#include <Eigen/Dense>
#include <Eigen/SVD>
#include "constants.h"
#include "types.h"
#include "classes/exception.h"
#include "classes/singleton.h"
#include "classes/states.h"
#include "classes/randevs.h"
#include "internal/functions.h"
#include "classes/init.h"
#include "functions.h"
#include "classes/gates.h"
#include "entropies.h"
#include "entanglement.h"
#include "instruments.h"
#include "io.h"
#include "operations.h"
#include "random.h"
#include "classes/timer.h"
#include "experimental/test.h"
#include "experimental/classes/qudit.h"
Include dependency graph for qpp.h:
```

Namespaces

qpp

Variables

```
    RandomDevices & qpp::rdevs = RandomDevices::get_instance()

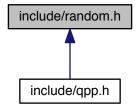
     gpp::RandomDevices Singleton
const Gates & qpp::gt = Gates::get_instance()
     qpp::Gates const Singleton
const States & qpp::st = States::get_instance()
     qpp::States const Singleton

    const Init & qpp::init = Init::get_instance()

     qpp::Init const Singleton
```

include/random.h File Reference 8.20

This graph shows which files directly or indirectly include this file:



Namespaces

qpp

Functions

```
• template<typename Derived >
  Derived qpp::rand (std::size_t rows, std::size_t cols, double a=0, double b=1)
      Generates a random matrix with entries uniformly distributed in the interval [a, b)
  dmat qpp::rand (std::size t rows, std::size t cols, double a, double b)
      Generates a random real matrix with entries uniformly distributed in the interval [a, b), specialization for double
      matrices (qpp::dmat)
template<>
  cmat gpp::rand (std::size t rows, std::size t cols, double a, double b)
      Generates a random complex matrix with entries (both real and imaginary) uniformly distributed in the interval [a, b),
      specialization for complex matrices (qpp::cmat)

    double <a href="mailto:qpp::rand">qpp::rand</a> (double a=0, double b=1)
```

 template<typename Derived > Derived qpp::randn (std::size_t rows, std::size_t cols, double mean=0, double sigma=1)

int qpp::randint (int a=std::numeric_limits< int >::min(), int b=std::numeric_limits< int >::max())

Generates a random real number uniformly distributed in the interval [a, b)

Generates a random integer (int) uniformly distributed in the interval [a, b].

Generates a random matrix with entries normally distributed in N(mean, sigma)

template<>

dmat qpp::randn (std::size_t rows, std::size_t cols, double mean, double sigma)

Generates a random real matrix with entries normally distributed in N(mean, sigma), specialization for double matrices (qpp::dmat)

template<>

cmat qpp::randn (std::size t rows, std::size t cols, double mean, double sigma)

Generates a random complex matrix with entries (both real and imaginary) normally distributed in N(mean, sigma), specialization for complex matrices (qpp::cmat)

• double qpp::randn (double mean=0, double sigma=1)

Generates a random real number (double) normally distributed in N(mean, sigma)

cmat qpp::randU (std::size_t D)

Generates a random unitary matrix.

cmat qpp::randV (std::size_t Din, std::size_t Dout)

Generates a random isometry matrix.

std::vector< cmat > qpp::randkraus (std::size_t N, std::size_t D)

Generates a set of random Kraus operators.

cmat qpp::randH (std::size_t D)

Generates a random Hermitian matrix.

ket qpp::randket (std::size_t D)

Generates a random normalized ket (pure state vector)

cmat qpp::randrho (std::size_t D)

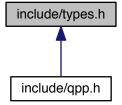
Generates a random density matrix.

std::vector< std::size_t > qpp::randperm (std::size_t n)

Generates a random uniformly distributed permutation.

8.21 include/types.h File Reference

This graph shows which files directly or indirectly include this file:



Namespaces

qpp

Typedefs

```
• using qpp::cplx = std::complex < double >
      Complex number in double precision.
template<typename Scalar >
  using <a href="mailto:qpp::DynMat">qpp::DynMat</a> = Eigen::Matrix< Scalar, Eigen::Dynamic, Eigen::Dynamic >
     Dynamic Eigen matrix over the field specified by Scalar.
• template<typename Scalar >
  using qpp::DynColVect = Eigen::Matrix < Scalar, Eigen::Dynamic, 1 >
     Dynamic Eigen column vector over the field specified by Scalar.
\bullet \ \ \text{template}{<} \text{typename Scalar} >
  using qpp::DynRowVect = Eigen::Matrix< Scalar, 1, Eigen::Dynamic >
     Dynamic Eigen row vector over the field specified by Scalar.
using qpp::ket = DynColVect< cplx >
      Complex (double precision) dynamic Eigen column vector.
using qpp::bra = DynRowVect< cplx >
      Complex (double precision) dynamic Eigen row vector.
using qpp::cmat = DynMat< cplx >
      Complex (double precision) dynamic Eigen matrix.
using qpp::dmat = DynMat< double >
     Real (double precision) dynamic Eigen matrix.
```

Index

absm	qpp::Exception, 99
qpp, 20	det
adjoint	qpp, 31
qpp, 20	disp
amplitudes	qpp, 32–34
qpp, 21	displn
anticomm	qpp, 34–37
qpp, 21	dmat
apply	qpp, 19
qpp, 22	
	ee ann 07
bra	qpp, 87
qpp, 19	entanglement
CUSTOM_EXCEPTION	qpp, 37
qpp::Exception, 99	eps
channel	qpp, 87 evals
	qpp, 38
qpp, 24, 25 choi	evects
qpp, 26	qpp, 39
choi2kraus	expm
qpp, 27	qpp, 39
chop	4PP, 00
qpp, 87	funm
cmat	qpp, 40
qpp, 19	
comm	gconcurrence
qpp, 28	qpp, 40
compperm	grams
qpp, 28	qpp, 41, 42
conjugate	gt
qpp, 30	qpp, <mark>87</mark>
cosm	hevals
qpp, 30	qpp, 43
cplx	hevects
qpp, 19	qpp, 43
cwise	4PP, 10
qpp, 31	init
	qpp, <mark>87</mark>
DIMS_INVALID	inverse
qpp::Exception, 99	qpp, 44
DIMS_MISMATCH_CVECTOR	invperm
qpp::Exception, 99	qpp, 44
DIMS_MISMATCH_MATRIX	
qpp::Exception, 99	ket
DIMS_MISMATCH_RVECTOR	qpp, 19
qpp::Exception, 99	kron
DIMS_MISMATCH_VECTOR	qpp, 45, 46
qpp::Exception, 99	kronpow
DIMS_NOT_EQUAL	qpp, 47

146 INDEX

load	qpp, 60
qpp, 47	ptrace
logdet	qpp, 61
qpp, 49	ptrace1
logm	qpp, 62
qpp, 49	ptrace2
MATRIX_MISMATCH_SUBSYS	qpp, 63 ptranspose
qpp::Exception, 99	qpp, 64
MATRIX NOT CVECTOR	4PP, 0 1
app::Exception, 99	qmutualinfo
MATRIX NOT RVECTOR	qpp, 65
qpp::Exception, 99	qpp, 11
MATRIX_NOT_SQUARE	absm, 20
qpp::Exception, 99	adjoint, 20
MATRIX_NOT_SQUARE_OR_CVECTOR	amplitudes, 21
qpp::Exception, 99	anticomm, 21
MATRIX_NOT_SQUARE_OR_RVECTOR	apply, 22
qpp::Exception, 99	bra, 19
MATRIX_NOT_SQUARE_OR_VECTOR	channel, 24, 25
qpp::Exception, 99	choi, 26
MATRIX_NOT_VECTOR	choi2kraus, 27 chop, 87
qpp::Exception, 99	cmat, 19
maxn	comm, 28
qpp, 87	compperm, 28
measure	conjugate, 30
qpp, 50, 52	cosm, 30
mket	cplx, 19
qpp, 53, 55	cwise, 31
mprj qpp, 55, 56	det, 31
multiidx2n	disp, 32-34
qpp, 57	displn, 34-37
4pp; 0;	dmat, 19
n2multiidx	ee, <mark>87</mark>
qpp, 57	entanglement, 37
NOT_BIPARTITE	eps, <mark>87</mark>
qpp::Exception, 99	evals, 38
NOT_QUBIT_GATE	evects, 39
qpp::Exception, 99	expm, 39
NOT_QUBIT_SUBSYS	funm, 40
qpp::Exception, 99	gconcurrence, 40
norm	grams, 41, 42
qpp, 58	gt, 87 hevals, 43
OUT OF RANGE	hevects, 43
qpp::Exception, 99	init, 87
omega	inverse, 44
qpp, 58	invperm, 44
٩٣٢	ket, 19
PERM_INVALID	kron, 45, 46
qpp::Exception, 99	kronpow, 47
pi	load, 47
qpp, 88	logdet, 49
powm	logm, 49
qpp, 59	maxn, 87
prj	measure, 50, 52
qpp, 59	mket, 53, 55
prod	mprj, 55, 56

INDEX 147

		CLIDOVO MICMATOLI DIMO 00
	multiidx2n, 57	SUBSYS_MISMATCH_DIMS, 99
	n2multiidx, 57	TYPE_MISMATCH, 99
	norm, 58	UNDEFINED_TYPE, 99
	omega, 58	UNKNOWN_EXCEPTION, 99
	pi, 88	ZERO_SIZE, 99
	powm, 59	
	prj, 59	rand
	prod, 60	qpp, 66, 67
	ptrace, 61	randint
	ptrace1, 62	qpp, 68
	ptrace2, 63	randket
	ptranspose, 64	qpp, 69
	gmutualinfo, 65	randkraus
	rand, 66, 67	qpp, 69
	randint, 68	randn
	randket, 69	qpp, 70, 71
	randkraus, 69	randperm
	randn, 70, 71	qpp, 72
		randrho
	randperm, 72	qpp, 72
	randrho, 72	rdevs
	rdevs, 88	qpp, 88
	renyi, 73	renyi
	reshape, 74	qpp, 73
	save, 75	reshape
	schmidtcoeff, 76	•
	schmidtprob, 77	qpp, 74
	shannon, 80	SUBSYS_MISMATCH_DIMS
	sinm, 80	qpp::Exception, 99
	spectralpowm, 82	save
	sqrtm, 82	
	st, 88	qpp, 75 schmidtcoeff
	sum, 83	
	super, 84	qpp, 76
	syspermute, 84	schmidtprob
	trace, 85	qpp, 77
	transpose, 86	shannon
	tsallis, 86	qpp, 80
ann.	::Exception	sinm
APP.	CUSTOM EXCEPTION, 99	qpp, 80
	DIMS INVALID, 99	spectralpowm
	DIMS_MISMATCH_CVECTOR, 99	qpp, 82
	DIMS MISMATCH MATRIX, 99	sqrtm
	DIMS_MISMATCH_RVECTOR, 99	qpp, 82
	DIMS_MISMATCH_RVECTOR, 99	st
	DIMS_MISMATCH_VECTOR, 99 DIMS_NOT_EQUAL, 99	qpp, 88
		sum
	MATRIX_MISMATCH_SUBSYS, 99	qpp, 83
	MATRIX_NOT_CVECTOR, 99	super
	MATRIX_NOT_RVECTOR, 99	qpp, 84
	MATRIX_NOT_SQUARE, 99	syspermute
	MATRIX_NOT_SQUARE_OR_CVECTOR, 99	qpp, 84
	MATRIX_NOT_SQUARE_OR_RVECTOR, 99	
	MATRIX_NOT_SQUARE_OR_VECTOR, 99	TYPE_MISMATCH
	MATRIX_NOT_VECTOR, 99	qpp::Exception, 99
	NOT_BIPARTITE, 99	trace
	NOT_QUBIT_GATE, 99	qpp, 85
	NOT_QUBIT_SUBSYS, 99	transpose
	OUT_OF_RANGE, 99	qpp, 86
	PERM_INVALID, 99	tsallis

148 INDEX

qpp, <mark>86</mark>

UNDEFINED_TYPE

qpp::Exception, 99 UNKNOWN_EXCEPTION qpp::Exception, 99

ZERO_SIZE

qpp::Exception, 99