



CS4379: Parallel and Concurrent Programming CS5379: Parallel Processing

Lecture 23

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Lecture Video

Please view the lecture video either from Teams or from the below link:

https://texastechuniversity.sharepoint.com/sites/CS4379-CS5379/Shared%20Documents/General/Lecture23.mp4

Course Info

Lecture Time: TR, 12:30-1:50

Lecture Location: ECE 217

Sessions: CS4379-001, CS4379-002, CS5379-001, CS5379-D01

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Outline

Questions?

- Collective Communications in MPI
- More on message passing: communication modes and avoiding deadlocks
- Datatypes in MPI

Collective Communications in MPI

- Collective operations are called by all processes in a communicator
- No message tags used
- In many applications, point-to-point can be replaced by collective communication, improving both simplicity and efficiency
 - Let the internal implementation optimize the communication for you
- Three broad classes:
 - Synchronization: barrier
 - Data movement routines: broadcast, gather, scatter
 - Global computation routines: reduction, scan

Barrier Routine

- Used to synchronize execution of a group of processes: int MPI_Barrier(MPI_Comm comm);
- A barrier is a simple way to separate two phases of computation to ensure that messages in two phases do no interact

Data Movement Routines

 Broadcast routine implements a one-to-all broadcast where a single named process (root) sends the same data to all other processes

int MPI_Bcast (void *buffer, int count, MPI_Datatype datatype, int root, MPI_Comm comm)

buffer starting address of buffer (choice)
count number of entries in buffer (integer)
datatype data type of buffer (handle)
root rank of broadcast root (integer)
comm communicator (handle)

Data Movement Routines

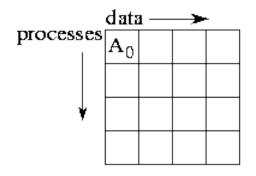
int MPI_Gather (void *sendbuf, int sendcnt, MPI_Datatype sendtype, void *recvbuf, int recvcount, MPI_Datatype recvtype, int root, MPI_Comm comm)

int MPI_Scatter (void *sendbuf, int sendcnt, MPI_Datatype sendtype, void *recvbuf, int recvcnt, MPI_Datatype recvtype, int root, MPI_Comm comm)

sendbuf starting address of send buffer (choice)
sendcount number of elements in send buffer (integer)
sendtype data type of send buffer elements (handle)
recvcount number of elements for any single receive (integer, significant only at root)
recvtype data type of recv buffer elements (significant only at root) (handle)
root rank of receiving/sending process (integer)
comm communicator (handle)

recybuf address of receive buffer (choice, significant only at root) (OUT)

Illustration of MPI Communication Functions



one-to-all broadcast

MPI_BCAST

\mathbf{A}_0		
\mathbf{A}_0		
\mathbf{A}_0		
\mathbf{A}_0		

\mathbf{A}_0		
\mathbf{A}_1		
\mathbf{A}_2		
\mathbf{A}_3		

all-to-one gather

MPI_GATHER

\mathbf{A}_0	\mathbf{A}_1	A_2	A_3

\mathbf{A}_0	\mathbf{A}_1	A_2	\mathbf{A}_3

one-to-all scatter

MPI_SCATTER

\mathbf{A}_0		
\mathbf{A}_1		
\mathbf{A}_2		
\mathbf{A}_3		

Collective Communication Operations

The all-to-all personalized communication operation is performed by:

- Each process sends to process i sendcount contiguous elements of type senddatatype starting from the i * sendcount location of its sendbuf
- The data that are received are stored in the recybuf array
- Each process receives from process i recvcount elements of type recvdatatype and stores them in its recvbuf array starting at location i * recvcount

All-to-all Personalized Communication

$M_{0,p-1}$	$\mathbf{M}_{1,p-1}$	$M_{p-1, p-1}$		$\mathbf{M}_{\mathrm{p-1,0}}$	$\mathbf{M}_{p-1,1}$	$M_{p-1, p-1}$
•	•	•		•	•	•
$M_{0,1}$	$M_{1,1}$	$M_{p-1,1}$		$M_{1,0}$	$M_{1,1}$	$\mathbf{M}_{1,p-1}$
$M_{0,0}$	$M_{1,0}$	$M_{p-1,0}$	All-to-all personalized communication	$M_{0,0}$	$M_{0,1}$	$\mathbf{M}_{0,p-1}$
0	1	• (p-1)		0	1	• (p-1)

Reduction Operations

 Reduction operations combine the values provided in the input buffer of each process using a specified operation OP, and return combined value into output buffer of single root process or output buffer of all processes

int MPI_Reduce (void *sendbuf, void *recvbuf, int count, MPI_Datatype datatype, MPI_Op op, int root, MPI_Comm comm)

int MPI_Allreduce (void *sendbuf, void *recvbuf, int count, MPI_Datatype datatype, MPI_Op op, MPI_Comm comm)

sendbuf address of send buffer (choice)
count number of elements in send buffer (integer)
datatype data type of elements of send buffer (handle)
op reduce operation (handle)
root rank of root process (integer)
comm communicator (handle)
recybuf address of receive buffer (choice, significant only at root) (OUT)

Illustration of Reduction Operations

Processes . . .

Initial Data:

57

03

62

MPI_REDUCE with MPI_MIN, root = 0:









MPI_ALLREDUCE with MPI_MIN:









 MPI_REDUCE with MPI_SUM , root = 1:









MPI Built-in Collective Computation Operations

MPI Max

MPI Min

MPI Prod

MPI Sum

MPI Land

MPI Lor

MPI Lxor

MPI Band

MPI Bor

MPI Bxor

MPI_Maxloc

MPI Minloc

Maximum

Minimum

Product

Sum

Logical and

Logical or

Logical exclusive or

Binary and

Binary or

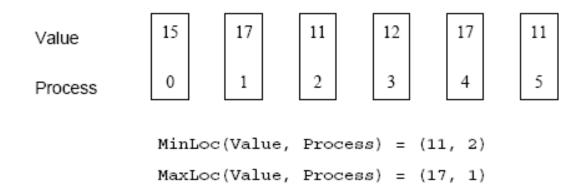
Binary exclusive or

Maximum and location

Minimum and location

Collective Communication Operations

- The operation MPI_MAXLOC combines pairs of values (v_i, l_i) and returns the pair (v, l) such that v is the maximum among all v_i 's and l is the corresponding l_i (if there are more than one, it is the smallest among all these l_i 's).
- $lacktriangleq ext{MPI_MINLOC}$ does the same, except for minimum value of v_i .



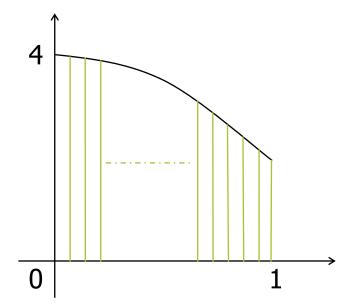
An example use of the MPI MINLOC and MPI MAXLOC operators.

Example: Calculating Pi

One way to calculate Pi:

$$\pi = \int_{0}^{1} \frac{4}{1+x^2} dx$$

- Calculating Pi via numerical integration
 - Divide and assign to processes
 - Each process calculates partial sum
 - Add all the partial sums together to get Pi



Example: PI in C (1/2)

```
#include "mpi.h"
#include <math.h>
int main(int argc, char *argv[])
   int done = 0, n, myid, numprocs, i, rc;
   double PI25DT = 3.141592653589793238462643;
   double mypi, pi, width, sum, x, a;
  MPI Init(&argc,&argv);
  MPI Comm size (MPI COMM WORLD, &numprocs);
   MPI Comm rank (MPI COMM WORLD, &myid);
   while (!done) {
     if (myid == 0) {
       printf("Enter the number of intervals: (0 quits)
                                                           ");
message/data
       scanf("%d",&n);
                                                           broadcasted
     }
                                                           root process
                                    MPI COMM WORLD);
     MPI Bcast (&n, 1, MPI INT),
     if (n == 0) break;
```

Example: PI in C (2/2)

```
width = 1.0 / (double) n;
  sum = 0.0;
                                                        send buffer
  for (i = myid + 1; i \le n; i += numprocs) {
                                                        receive buffer
    x = width * ((double)i - 0.5);
    sum += 4.0 / (1.0 + x*x);
                                                        operation
                                                        root process
  mypi = width * sum;
  MPI Reduce (&mypi, &pi, 1, MPI DOUBLE, MPI SUM)
             MPI COMM WORLD);
  if (myid == 0)
    printf("pi is approximately %.16f, Error is %.16f\n",
            pi, fabs(pi - PI25DT));
MPI Finalize();
return 0;
```

More on MPI Collective Routines

- Many Routines: Allgather, Allgatherv, Allreduce, Alltoall, Alltoallv,
 Bcast, Gather, Gatherv, Reduce, ReduceScatter, Scan, Scatter,
 Scatterv
- All versions deliver results to all participating processes.
- V versions allow the chunks to have different sizes.
- Allreduce, Reduce, ReduceScatter, and Scan take both built-in and user-defined combiner/reduction functions.
 - Create your own collective computations with:MPI_Op_create(user_fcn, commutes, &op);MPI_Op_free(&op);

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- Collective Communications in MPI
- More on message passing: communication modes and avoiding deadlocks
- Datatypes in MPI

Communication Modes

- MPI has multiple communication modes for sending messages:
 - Synchronous mode (MPI_Ssend): the send waits for a matching receive has begun. (Unsafe programs deadlock.)
 - Buffered mode (MPI_Bsend): the user supplies a buffer to the system for its use. (User allocates enough memory to make an unsafe program safe.)
 - Ready mode (MPI_Rsend): user guarantees that a matching receive has been posted.
 - Allows access to fast protocols
 - Undefined behavior if matching receive not posted
- Non-blocking versions (MPI_Issend, etc.)
- MPI_Recv/MPI_IRecv receives messages sent in any mode

Flavors of Communication

- For a send operation there are:
 - 4 communication modes: standard,ready,synchronous,buffered
 - 2 blocking modes: blocking, nonblocking
 - $^{\square}$ 4*2 =8 types of sends
- For a receive operation there are:
 - 1 communication mode: standard
 - 2 blocking modes: blocking, nonblocking
 - 1*2 = 2 types of receive

Naming Conventions

Send routines:

Comm Mode	Blocking	Non-blocking
Standard	MPI_Send	MPI_Isend
Ready	MPI_Rsend	MPI_Irsend
Synchronous	MPI_Ssend	MPI_Issend
Buffered	MPI_Bsend	MPI_lbsend

Receive routines:

Comm Mode	Blocking	Non-blocking
Standard	MPI_Recv	MPI_Irecv

 Any type of receive routine can be used to receive messages from any type of send routine

Send/Receive Operations

- In many applications, processes send to one process while receiving from another
- Deadlock may arise if care is not taken
- MPI provides routines for such send/receive operations

int MPI_Sendrecv(void *sendbuf, int sendcount, MPI_Datatype sendtype, int dest, int sendtag, void *recvbuf, int recvcount, MPI_Datatype recvtype, int source, int recvtag, MPI_Comm comm, MPI_Status *status)

Deadlocks

What happens with this code?

Process 0	Process 1
Send(1)	Send(0)
Recv(1)	Recv(0)

- MPI_Send and MPI_Recv are blocking comm:
 - MPI_Send does not complete until sending buffer is empty
 - MPI_Recv does not complete until receiving buffer is full
- Simple, but maybe "unsafe" because completion depends on the message size and availability of system buffers

Solutions to the Unsafe Problem

Order the operations more carefully:

Process 0	Process 1
Send(1)	Recv(0)
Recv(1)	Send(0)

• Supply receive buffer at same time as send:

Process 0	Process 1
Sendrecv(1)	Sendrecv(0)

More Solutions to the Unsafe Problem

Supply own space as buffer for send

Process 0	Process 1	
Bsend(1)	Bsend(0)	

Use non-blocking operations:

Process 0	Process 1
Isend(1)	Isend(0)
Irecv(1)	Irecv(0)
Waitall	Waitall

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Datatypes in MPI

- MPI datatypes have two purposes:
 - Heterogeneity
 - Noncontiguous data
- Basic vs. derived datatype:
 - Basic datatype
 - Derived datatype
 - Contiguous
 - Vector
 - Indexed
 - Hindexed
 - Structure

Basic Datatype in C

MPI Datatype	C Datatype
MPI_BYTE	
MPI_CHAR	singed char
MPI_DOUBLE	double
MPI_FLOAT	float
MPI_INT	int
MPI_LONG	long
MPI_LONG_DOUBLE	long double
MPI_PACKED	
MPI_SHORT	short
MPI_UNSIGNED_CHAR	unsigned char
MPI_UNSIGNED	unsigned int
MPI_UNSIGNED_LONG	unsigned long
MPI_UNSINGED_SHORT	unsigned short

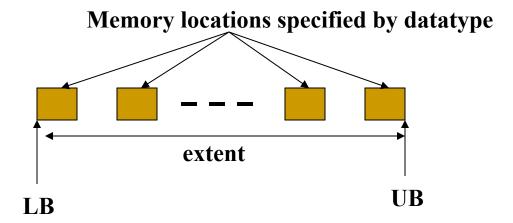
Additional datatypes defined in MPI 2.2 corresponding to C99 language types int32_t, int64_t, etc.

Typemaps in MPI

In MPI, a datatype is represented as a typemap

$$typemap = (type_0, disp_0), ..., (type_{n-1}, disp_{n-1})$$

Extent_of a datatype



An artificial extent can be set by using MPI_UB and MPI_LB

Typemaps in MPI (cont.)

- Example:
 - (int,0),(char,4) is a typemap
 - The extent of this typemap is 5

CONTIGUOUS Datatype

```
MPI_Type_contiguous(count, oldtype, &newtype)
MPI_Type_commit(&newtype)
```

 Assume an original datatype oldtype has typemap (double,0), (char,8), then

```
MPI_Type_contiguous(3,oldtype,&newtype);
```

To actually send such a data use the sequence of calls:

```
MPI_Type_contiguous(count,datatype,&newtype);
MPI_Type_commit(&newtype);
MPI_Send(buffer,1,newtype,dest,tag,comm);
MPI_Type_free(&newtype);
```

VECTOR Datatype

MPI_Type_vector(count, blocklength, stride, oldtype, &newtype)
MPI Type commit(&newtype)

29	30	31	32	33	34	35
22	23	24	25	26	27	28
15	16	17	18	19	20	21
8	9	10	11	12	13	14
1	2	3	4	5	6	7

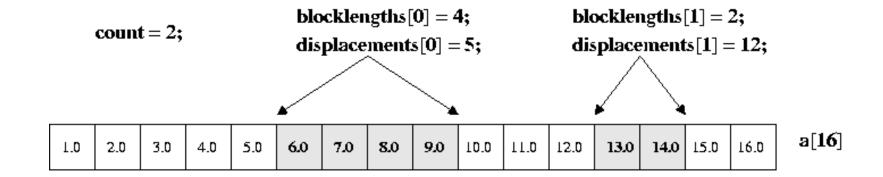
```
MPI_Type_Vector(5,1,7,MPI_DOUBLE,newtype);
MPI_Type_commit(&newtype);
MPI_Send(buffer,1,newtype,dest,tag,comm);
MPI_Type_free(&newtype);
```

INDEXED Datatype

MPI_Type_indexed(count, &array_of_blocklengths, &array_of_displacements, oldtype, &newtype)

MPI Type commit(&newtype)

MPI_Type_indexed(count, blocklengths, displacements, MPI_FLOAT, &indextype);



Hindexed:

MPI_Type_hindexed()
is the same except that
offsets array is
specified in bytes

MPI_Send(&a, 1, indextype, dest, tag, comm);

6.0 7.0 8.0 9.0 13.0 14.0

1 element of indextype

Structure Datatype

MPI_Type_struct(count, &array_of_blocklengths, &array_of_displacements, oldtypes, &newtype)

MPI_Type_commit(&newtype)

MPI_Type_struct(count, blocklengths, offsets, oldtypes, &particletype);

typedef struct { float f1, f2, f3, f4; int n1, n2;} Particle;

Particle particles [NELEM];

 $oldtypes[0] = MPI_FLOAT; \ oldtypes[1] = MPI_INT;$ $count = 2; \qquad offsets[0] = 0; \qquad offsets[1] = 4 * sizeof(float);$ $blockcounts[0] = 4; \qquad blockcounts[1] = 2;$ $6.0 \qquad 7.0 \qquad 8.0 \qquad 9.0 \qquad 10 \qquad 11 \qquad particles[NELEM];$

6.0 7.0 8.0 9.0 10 11

MPI_Send(particles, NELEM, particletype, dest, tag, comm);

6.0 7.0 8.0 9.0 10 11

1 element of particletype

Readings

Reference book ITPC – Chapter 6, 6.3-6.6





Questions?

Questions/Suggestions/Comments are always welcome!

Write me: yong.chen@ttu.edu

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