

## Programming Project #3

CS4379: Parallel and Concurrent Programming  
CS5379: Parallel Processing  
Spring 2020

**Due 4/21 Tue., 11:59 p.m.** Please submit a soft copy on Blackboard. Late submissions are accepted till 4/25 Sat., 11:59 p.m. with 10% penalty each day. No submissions accepted after that.

Please submit a single tarball/zipped file containing all your source codes and documents. Please name your submission file starting as “LastName\_FirstName\_PP3”.

*Please note that we may request a 5-10 mins quick demo for grading.*

### OpenMP programming

**Source code samples:** Please checkout source code samples with executing the following command on the HPCC cluster:

```
git clone https://discl.cs.ttu.edu/gitlab/yongchen/cs4379cs5379.git
```

If you have already checked out a copy of the repo earlier, you can run the following command to update to the latest source code repo:

```
git pull
```

**Q1 (40%).** (Updated Problem 7.13 from reference book ITPC). Implement and test the OpenMP program for computing a matrix-matrix product in Example 7.14. Use the OMP\_NUM\_THREADS environment variable to control the number of threads and plot the performance with varying numbers of threads (1, 2, 4, 8, 16, and 32 threads). Consider three cases in which:

- (i) only the innermost loop is parallelized;
- (ii) the inner two loops are parallelized; and
- (iii) all three loops are parallelized.

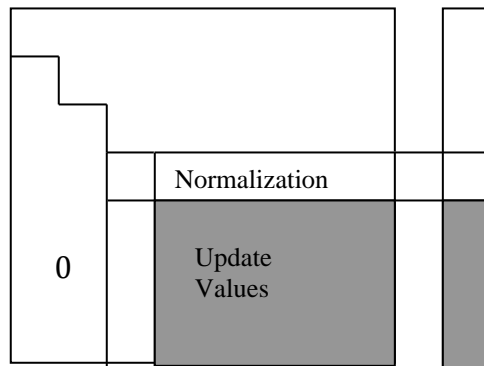
Please plot and report the results of all these cases.

**Q2 (60%).** In this part of the programming project, you are asked to write a parallel program **using OpenMP** for solving a set of dense linear equations of the form  $A*x=b$ , where  $A$  is an  $n*n$  matrix and  $b$  is a vector. You will use Gaussian elimination without pivoting described as below (same as what you have seen in Programming Project #2).

The algorithm has two parts (an example code gauss.c is provided):

- *Gaussian Elimination*: the original system of equation is reduced to an upper triangular form  $Ux=y$ , where  $U$  is a matrix of size  $n \times n$  in which all elements below the diagonal are zeros which are the modified values of the  $A$  matrix, and the diagonal elements have the value 1. The vector  $y$  is the modified version of the  $b$  vector when you do the updates on the matrix and the vector in the Gaussian elimination stage.
- *Back Substitution*: the new system of equations is solved to obtain the values of  $x$ .

The Gaussian elimination stage of the algorithm comprises  $(n-1)$  steps. In the algorithm, the  $i$ th step eliminates nonzero subdiagonal elements in column  $i$  by subtracting the  $i$ th row from row  $j$  in the range  $[i+1, n]$ , in each case scaling the  $i$ th row by the factor  $A_{ji}/A_{ii}$  so as to make the element  $A_{ji}$  zero. See figure below:



Hence the algorithm sweeps down the matrix from the top corner to the bottom right corner, leaving subdiagonal elements behind it.

In the reference book “Introduction to Parallel Computing” Chapter 8, Section 8.3 (also can be found from Blackboard, “Readings” section) contains more details about Gaussian elimination algorithm.

### Requirements and deliverables:

1. Come up with a parallel version of this program **using OpenMP**. A critical point of parallel programming is performance. Therefore, once you achieve a correct solution, please consider performing some experimentation with your program to try to optimize its performance.
2. There should be clear comments explaining your code.
3. Develop a Makefile to automate the compilation.
4. You need to report and plot the performance of your program with 1, 2, 4, 8, 16, and 32 threads on the HPCC cluster.
5. In addition, you may describe some of the different versions of your program that you tried, what performance results you got out of them, and why you think your current version is reasonably efficient (or what more you could do to make it more efficient) to show the level of effort.

**Suggestions:**

- Consider carefully the data dependencies in Gaussian elimination in your multithreaded program.
- Gaussian elimination involves  $O(n^3)$  operations. The back substitution stage requires only  $O(n^2)$  operations, so you are not expected to parallelize back substitution.
- You may observe performance slowdowns because of the synchronization overhead among threads.

**Grading Criteria:**

*Please note that we may request a 5-10 mins quick demo for grading.*

Q1	Percentage %	Criteria
40%	20	Correct implementation of (i) (code can be compiled, executed, and produce correct results)
	20	Correct implementation of (ii) (code can be compiled, executed, and produce correct results)
	20	Correct implementation of (iii) (code can be compiled, executed, and produce correct results)
	40	Successfully carry out all specified test cases and produce a report that includes plots of results.
Q2	Percentage %	Criteria
60%	10	Inline comments to briefly describe your code
	30	Correct use of OpenMP directives and library functions. Correct Makefile (at least automate compilation and cleanup).
	30	Correct parallelization and correct results.
	10	Successfully carry out specified test cases
	20	A brief document to report plotted results, any other solutions you have tried, and your findings in general.

**Note on cheating:** We have zero-tolerance policy for cheating. Working in groups is fine for discussing approaches and techniques. Copying problem solutions or code is cheating. Both the person copying and the person giving the answers will be equally penalized. Make sure you do your own work.

**Reference Materials:**

- OpenMP:
  - OpenMP Programming, <https://computing.llnl.gov/tutorials/openMP/>
  - OpenMP Specifications, <https://www.openmp.org/specifications/>
- Makefile:
  - <http://www.gnu.org/software/make/manual/make.pdf> or
  - [http://www.gnu.org/software/make/manual/html\\_node/index.html](http://www.gnu.org/software/make/manual/html_node/index.html)