

Chapter 9: Multilinear Algebra and Determinants

Linear Algebra Done Right, by Sheldon Axler

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9A: Bilinear Forms and Quadratic Forms

Definition 1 (bilinear form). A **bilinear form** on V is a function $\beta: V \times V \rightarrow \mathbb{F}$ such that

$$v \mapsto \beta(v, u) \text{ and } v \mapsto \beta(u, v)$$

are both linear functionals on V for every $u \in V$.

Remark 2. A better but less popular terminology is “bilinear functional”. If V is real, then the function $(u, v) \mapsto \langle u, v \rangle$ is a bilinear form. If V is complex, then it isn’t.

Remark 3. If $\mathbb{F} = \mathbb{R}$, then a bilinear form differs from an inner product in that it does not require positive definiteness or symmetry.

Remark 4. A bilinear form β on V is a linear map on $V \times V$ only if $\beta = 0$.

Definition 5 ($V^{(2)}$). The set of bilinear forms on V is denoted by $V^{(2)}$.

Definition 6 (matrix of a bilinear form, $\mathcal{M}(\beta)$). Suppose β is a bilinear form on V and e_1, \dots, e_n is a basis of V . The **matrix** of β with respect to this basis is the n -by- n matrix $\mathcal{M}(\beta)$ whose entry $\mathcal{M}(\beta)_{j,k}$ in row j , column k is given by

$$\mathcal{M}(\beta)_{j,k} = \beta(e_j, e_k)$$

If the basis e_1, \dots, e_n is not clear from the context, then the notation $\mathcal{M}(\beta, (e_1, \dots, e_n))$ is used.

Corollary 7 ($\dim V^{(2)} = (\dim V)^2$). Suppose e_1, \dots, e_n is a basis of V . Then the map $\beta \mapsto \mathcal{M}(\beta)$ is an isomorphism of $V^{(2)}$ onto $\mathbb{F}^{n,n}$. Furthermore, $\dim V^{(2)} = (\dim V)^2$.

Lemma 8 (composition of a bilinear form and an operator). Suppose β is a bilinear form on V and $T \in \mathcal{L}(V)$. Define bilinear forms α and ρ on V by

$$\alpha(u, v) = \beta(u, Tv) \text{ and } \rho(u, v) = \beta(Tu, v)$$

Let e_1, \dots, e_n be a basis of V . Then

$$\mathcal{M}(\alpha) = \mathcal{M}(\beta)\mathcal{M}(T) \text{ and } \mathcal{M}(\rho) = \mathcal{M}(T)^\top \mathcal{M}(\beta)$$

Theorem 9 (change-of-basis formula). Suppose $\beta \in V^{(2)}$. Suppose e_1, \dots, e_n and f_1, \dots, f_n are bases of V . Let

$$A = \mathcal{M}(\beta(e_1, \dots, e_n)) \text{ and } B = \mathcal{M}(\beta, (f_1, \dots, f_n))$$

and $C = \mathcal{M}(I, (e_1, \dots, e_n), (f_1, \dots, f_n))$. Then

$$A = C^\top BC$$

Definition 10 (symmetric bilinear form, $V_{sym}^{(2)}$). A bilinear form $\rho \in V^{(2)}$ is called **symmetric** if

$$\rho(u, w) = \rho(w, u)$$

for all $u, w \in V$. The set of symmetric bilinear forms on V is denoted by $V_{sym}^{(2)}$.

Remark 11. For real inner product space, define $\rho(u, w) = \langle u, w \rangle \in V_{sym}^{(2)}$. Additional example include

$$\rho(u, w) = \langle u, Tw \rangle$$

where T is self-adjoint and

$$\rho(S, T) = \text{tr}(ST)$$

where here $\rho: \mathcal{L}(V) \times \mathcal{L}(V) \rightarrow \mathbb{F}$.

Definition 12 (symmetric matrix). A square matrix A is called **symmetric** if it equals its transpose.

Theorem 13 (symmetric bilinear forms are diagonalizable). Suppose $\rho \in V^{(2)}$. Then the following are equivalent.

- (a) ρ is a symmetric bilinear form on V .
- (b) $\mathcal{M}(\rho, (e_1, \dots, e_n))$ is a symmetric matrix for every basis e_1, \dots, e_n of V .
- (c) $\mathcal{M}(\rho, (e_1, \dots, e_n))$ is a symmetric matrix for some basis e_1, \dots, e_n of V .
- (d) $\mathcal{M}(\rho, (e_1, \dots, e_n))$ is a diagonal matrix for some basis e_1, \dots, e_n of V .

Theorem 14. Suppose V is a real inner product space and ρ is a symmetric bilinear form on V . Then ρ has a diagonal matrix with respect to some orthonormal basis of V .

Definition 15 (alternating bilinear form, $V_{alt}^{(2)}$). A bilinear form $\alpha \in V^{(2)}$ is called **alternating** if

$$\alpha(v, v) = 0$$

for all $v \in V$. The set of alternating bilinear forms on V is denoted by $V_{alt}^{(2)}$.

Lemma 16 (characterization of alternating linear forms). A bilinear form α on V is alternating if and only if

$$\alpha(u, w) = -\alpha(w, u)$$

for all $u, w \in V$.

Theorem 17. The sets $V_{sym}^{(2)}$ and $V_{alt}^{(2)}$ are subspaces of $V^{(2)}$. Furthermore,

$$V^{(2)} = V_{sym}^{(2)} \oplus V_{alt}^{(2)}$$

Definition 18 (quadratic form associated with a bilinear form, q_β). For β a bilinear form on V , define a function $q_\beta: V \rightarrow \mathbb{F}$ by $q_\beta(v) = \beta(v, v)$. A function $q: V \rightarrow \mathbb{F}$ is called a **quadratic form** on V if there exists a bilinear form β on V such that $q = q_\beta$.

Corollary 19 (quadratic form on \mathbb{F}^n). Suppose n is a positive integer and q is a function from \mathbb{F}^n to \mathbb{F} . Then q is a quadratic form on \mathbb{F}^n if and only if there exist numbers $A_{j,k} \in \mathbb{F}$ for $j, k \in \{1, \dots, n\}$ such that

$$q(x_1, \dots, x_n) = \sum_{k=1}^n \sum_{j=1}^n A_{j,k} x_j x_k$$

for all $(x_1, \dots, x_n) \in \mathbb{F}^n$.

Theorem 20 (characterizations of quadratic forms). Suppose $q: V \rightarrow \mathbb{F}$ is a function. Then following are equivalent.

- (a) q is a quadratic form.
- (b) There exists a unique symmetric bilinear form ρ on V such that $q = q_\rho$.
- (c) $q(\lambda v) = \lambda^2 q(v)$ for all $\lambda \in \mathbb{F}$ and all $v \in V$, and the function

$$(u, w) \mapsto q(u + w) - q(u) - q(w)$$

is a symmetric bilinear form on V .

- (d) $q(2v) = 4q(v)$ for all $v \in V$, and the function

$$(u, w) \mapsto q(u + w) - q(u) - q(w)$$

is a symmetric bilinear form on V .

Theorem 21 (diagonalization of quadratic form). Suppose q is a quadratic form on V .

- (a) There exist a basis e_1, \dots, e_n of V and $\lambda_1, \dots, \lambda_n \in \mathbb{F}$ such that

$$q(x_1 e_1 + \dots + x_n e_n) = \lambda_1 x_1^2 + \dots + \lambda_n x_n^2$$

for all $x_1, \dots, x_n \in \mathbb{F}$.

- (b) If $\mathbb{F} = \mathbb{R}$ and V is an inner product space, then the basis in (a) can be chosen to be an orthonormal basis of V .

Remark 22. For each quadratic form we can choose a basis such that the quadratic form looks like a weighted sum of squares of the coordinates.

Problem 1

Prove that if β is a bilinear form on \mathbb{F} , then there exists $c \in \mathbb{F}$ such that

$$\beta(x, y) = cxy$$

for all $x, y \in \mathbb{F}$.

Proof. We note that since the input is taken from \mathbb{F} , the basis is naturally 1. So we have that

$$\beta(x, y) = x\beta(1, y) = xy\beta(1, 1) = cxy$$

where we take $c = \beta(1, 1)$. □

Problem 2

Let $n = \dim V$. Suppose β is a bilinear form on V . Prove that there exist $\phi_1, \dots, \phi_n, \tau_1, \dots, \tau_n \in V'$ such that

$$\beta(u, v) = \phi_1(u) \cdot \tau_1(v) + \dots + \phi_n(u) \cdot \tau_n(v)$$

for all $u, v \in V$.

Proof.

$$\beta(u, v) = \beta\left(\sum_{i=1}^n u_i e_i, \sum_{j=1}^n v_j e_j\right) = \sum_{i=1}^n \sum_{j=1}^n u_i v_j \beta(e_i, e_j)$$

We can now define the linear function $\phi_i(u) = u_i = e_i^*(u)$ and $\tau_j'(v) = v_j = e_j^*(v)$. Then we have that

$$\beta(u, v) = \sum_{i=1}^n \phi_i(u) \left(\sum_{j=1}^n \beta(e_i, e_j) \tau_j'(v) \right) = \sum_{i=1}^n \phi(u) \tau_i(v)$$

□

Problem 3

Suppose $\beta: V \times V \rightarrow \mathbb{F}$ a bilinear form on V and also is a linear functional on $V \times V$. Prove that $\beta = 0$.

Proof. First we show that $\beta \in V_{alt}^{(2)}$. Take any $u \in V$, then we have

$$\begin{aligned} \beta((u, u) + (u, u)) &= 2\beta(u, u) \\ \beta(2u, 2u) &= 4\beta(u, u) \end{aligned}$$

this shows that $\beta(u, u) = 0$ for all u . Next we show the off-diagonal terms are 0: first,

$$\beta(u, w) = \sum_{i=1}^n \sum_{j=1}^n u_i w_j \beta(e_i, e_j) \quad \text{bilinearity}$$

at the same time,

$$\begin{aligned} \beta(u, w) &= \beta \left(\sum_{i=1}^n u_i e_i, \sum_{j=1}^n w_j e_j \right) \\ &= \beta \left(\sum_{i=1}^n (u_i e_i, w_i e_i) \right) \\ &= \sum_{i=1}^n \beta(u_i e_i, w_i e_i) \quad \text{linearity on } V \times V \\ &= \sum_{i=1}^n u_i w_i \beta(e_i, e_i) \end{aligned}$$

This shows that all off-diagonal terms are 0, i.e., $\beta(e_i, e_j) = 0$ for all $i \neq j$. Therefore, $\beta = 0$. \square

Problem 6

Prove or give a counterexample: If ρ is a symmetric bilinear form on V , then

$$\{v \in V : \rho(v, v) = 0\}$$

is a subspace of V .

Proof. Consider $V = \mathbb{R}^2$ and $\rho(x, y) = x_1 y_1 - x_2 y_2$. Let $x = (1, 1)$, $y = (-1, 1)$, then we have that $\rho(x, x) = 1 - 1 = 0$, $\rho(y, y) = 1 - 1 = 0$, but $\rho(x + y, x + y) = 0 - 4 = -4 \neq 0$. \square

Problem 8

Find formulas for $\dim V_{sym}^{(2)}$ and $\dim V_{alt}^{(2)}$ in terms of $\dim V$.

Proof. Let $\dim V = n$. For $\beta \in V_{sym}^{(2)}$, consider $\mathcal{M}(\beta)$. Its diagonal entries can be chosen arbitrarily. For off-diagonal entries, only half of them can be chosen arbitrarily, therefore the dimension is

$$\frac{n(n-1)}{2} + n = \frac{n(n+1)}{2}$$

For $\beta \in V_{alt}^{(2)}$, consider $\mathcal{M}(\beta)$. The diagonal entries are all 0 and only half of the off-diagonal entries can be chosen arbitrarily. Therefore the dimension is $\frac{n(n-1)}{2}$. \square

9B: Alternating Multilinear Forms

Definition 23 (V^m). For m a positive integer, define V^m by

$$V^m = \underbrace{V \times \cdots \times V}_{m \text{ times}}$$

Definition 24 (m-linear form, $V^{(m)}$, multilinear form). Below we introduce the definitions.

- For m a positive integer, an **m-linear form** on V is a function $\beta: V^m \rightarrow \mathbb{F}$ that is linear in each slot when the other slots are held fixed. This means that for each $k \in \{1, \dots, m\}$ and all $u_1, \dots, u_m \in V$, the function

$$v \mapsto \beta(u_1, \dots, u_{k-1}, v, u_{k+1}, \dots, u_m)$$

is a linear map from V to \mathbb{F} .

- The set of m -linear forms on V is denoted by $V^{(m)}$.
- A function β is called a **multilinear form** on V if it is an m -linear form on V for some positive integer m .

Remark 25. A 1-linear form on V is a linear functional on V . A 2-linear form on V is a bilinear form on V . $V^{(m)}$ is a vector space.

Example (m-linear forms). Suppose $\alpha, \beta \in V^{(2)}$. Define a function $\beta: V^4 \rightarrow \mathbb{F}$ by

$$\beta(v_1, v_2, v_3, v_4) = \alpha(v_1, v_2)\beta(v_3, v_4)$$

Then $\beta \in V^{(4)}$.

Example (m-linear forms). Define $\beta: (\mathcal{L}(V))^m \rightarrow \mathbb{F}$ by

$$\beta(T_1, \dots, T_m) = \text{tr}(T_1 \cdots T_m)$$

Then β is an m -linear form on $\mathcal{L}(V)$.

Definition 26 (alternating forms, $V_{alt}^{(m)}$). Suppose m is a positive integer.

- An m -linear form α on V is called **alternating** if $\alpha(v_1, \dots, v_m) = 0$ whenever v_1, \dots, v_m is a list of vectors in V with $v_j = v_k$ for some two distinct values of j and k in $\{1, \dots, m\}$.
- $V_{alt}^{(m)} = \{\alpha \in V^{(m)} : \alpha \text{ is an alternating } m\text{-linear form on } V\}$.

Corollary 27. Suppose m is a positive integer and α is an alternating m -linear form on V . If v_1, \dots, v_m is a linearly dependent list in V , then

$$\alpha(v_1, \dots, v_m) = 0$$

Corollary 28. Suppose $m > \dim V$. Then 0 is the only alternating m -linear form on V .

Theorem 29 (swapping input vectors in an alternating multilinear form). Suppose m is a positive integer, α is an alternating m -linear form on V , and v_1, \dots, v_m is a list of vectors in V . Then swapping the vectors in any two slots of $\alpha(v_1, \dots, v_m)$ changes the value of α by a factor of -1 .

Remark 30. An odd number of swaps cause the value of α to change by a factor of -1 and it won't change with an even number of swaps.

Definition 31 (permutation, perm m). Suppose m is a positive integer.

- A **permutation** of $(1, \dots, m)$ is a list (j_1, \dots, j_m) that contains each of the number $1, \dots, m$ exactly once.
- The set of permutations of $(1, \dots, m)$ is denoted by $\text{perm } m$.

Definition 32 (sign of a permutation). The **sign** of a permutation (j_1, \dots, j_m) is defined by

$$\text{sign}(j_1, \dots, j_m) = (-1)^N$$

where N is the number of pairs of integers (k, l) with $1 \leq k < l \leq m$ such that k appears after l in the list (j_1, \dots, j_m) .

Lemma 33. Swapping two entries in a permutation multiplies the sign of the permutation by -1 .

Lemma 34 (permutation and alternating multilinear form). Suppose m is a positive integer and $\alpha \in V_{\text{alt}}^{(m)}$. Then

$$\alpha(v_{j_1}, \dots, v_{j_m}) = (\text{sign}(j_1, \dots, j_m)) \alpha(v_1, \dots, v_m)$$

for every list v_1, \dots, v_m of vectors in V and all $(j_1, \dots, j_m) \in \text{perm } m$.

Theorem 35. Let $n = \dim V$. Suppose e_1, \dots, e_n is a basis of V and $v_1, \dots, v_n \in V$. For each $k \in \{1, \dots, n\}$, let $b_{1,k}, \dots, b_{n,k} \in \mathbb{F}$ be such that

$$v_k = \sum_{j=1}^n b_{j,k} e_j$$

Then

$$\alpha(v_1, \dots, v_n) = \alpha(e_1, \dots, e_n) \sum_{(j_1, \dots, j_n) \in \text{perm } n} (\text{sign}(j_1, \dots, j_n)) b_{j_1,1} \cdots b_{j_n,n}$$

for every alternating n -linear form α on V .

Theorem 36. The vector space $V_{\text{alt}}^{(\dim V)}$ has dimension one.

Corollary 37. Let $n = \dim V$,. Suppose α is a nonzero alternating n -linear form on V and e_1, \dots, e_n is a list of vectors in V . Then

$$\alpha(e_1, \dots, e_n) \neq 0$$

if and only if e_1, \dots, e_n is linearly independent.

Problem 1

Suppose m is a positive integer. Show that $\dim V^{(m)} = (\dim V)^m$.

Proof. Let $\dim V = n$ with basis e_1, \dots, e_n . The basis vector for $V^{(m)}$ can be formed via taking all possible m -tuples b_{j_1}, \dots, b_{j_m} where b_{j_i} is a component of the basis. There are n choices over m positions, so we have that $\dim V^{(m)} = (\dim V)^m$. \square

Problem 3

Suppose m is a positive integer and α is an m -linear form on V such that $\alpha(v_1, \dots, v_m) = 0$ whenever v_1, \dots, v_m is a list of vectors in V with $v_j = v_{j+1}$ for some $j \in \{1, \dots, m-1\}$. Prove that α is an alternating m -linear form on V .

Proof. Note that if the list v_1, \dots, v_n comes with consecutive identical numbers, then by definition the output becomes 0. To prove α to be an alternating m -linear form, consider $v_i = v_k$ for $i+1 < k$. Note that then we can now just swap and get the same result:

$$\alpha(v_1, \dots, v_i, v_{i+1}, \dots, v_k, \dots, v_n) = -\alpha(v_1, \dots, v_i, v_k, \dots, v_{i+1}, \dots, v_n) = 0$$

\square

Problem 5

Suppose m is a positive integer and β is an m -linear form on V . Define an m -linear form α by

$$\alpha(v_1, \dots, v_m) = \sum_{(j_1, \dots, j_m) \in \text{perm } m} (\text{sign}(j_1, \dots, j_m) \beta(v_{j_1}, \dots, v_{j_m}))$$

for $v_1, \dots, v_m \in V$. Explain why $\alpha \in V_{alt}^{(m)}$.

Proof. If there are two repeating vectors, let's say $v_p = v_q$, then we know that

$$\beta(v_1, \dots, v_p, \dots, v_q, \dots, v_m) = \beta(v_1, \dots, v_q, \dots, v_p, \dots, v_m)$$

However, through swapping, the coefficient differs by (-1) , so we have

$$\begin{aligned} & \text{sign}(1, \dots, p, \dots, q, \dots, m) \beta(v_1, \dots, v_p, \dots, v_q, \dots, v_m) \\ &= -\text{sign}(1, \dots, q, \dots, p, \dots, m) \beta(v_1, \dots, v_q, \dots, v_p, \dots, v_m) \end{aligned}$$

This basically shows the main idea of the proof. To make this more rigorous, we claim that for each permutation $\sigma \in \text{perm } m$, there is a corresponding

permutation $\sigma_{pq} \in \text{perm } m$ such that keeps everything unchanged while only swapping the position of p and q . This means that for each permutation, there is a corresponding “cancelling” pair permutation. Since we are summing all permutations, the result is finally 0, finishing the proof. \square

9C: Determinants

Definition 38 (α_T). Suppose that m is a positive integer and $T \in \mathcal{L}(V)$. For $\alpha \in V_{\text{alt}}^{(m)}$, define $\alpha_T \in V_{\text{alt}}^{(m)}$ by

$$\alpha_T(v_1, \dots, v_m) = \alpha(Tv_1, \dots, Tv_m)$$

for each list v_1, \dots, v_m of vectors in V .

Remark 39. The function $\alpha \mapsto \alpha_T$ is a linear map of $V_{\text{alt}}^{(m)}$ to itself. We know that $\dim V_{\text{alt}}^{(\dim V)} = 1$, so the linear map is simply a multiplication by some unique scalar. For the linear map $\alpha \mapsto \alpha_T$, we now define $\det T$ to be that scalar.

Definition 40 (determinant of an operator, $\det T$). Suppose $T \in \mathcal{L}(V)$. The **determinant** of T , denoted by $\det T$, is defined to be the unique number in \mathbb{F} such that

$$\alpha_T = (\det T)\alpha$$

for all $\alpha \in V_{\text{alt}}^{(\dim V)}$.

Remark 41. Let $n = \dim V$.

- If I is the identity operator on V , then $\alpha_I = \alpha$ for all $\alpha \in V_{\text{alt}}^{(n)}$. This gives that $\det I = 1$.
- More generally, if $\lambda \in \mathbb{F}$, then $\alpha_{\lambda I} = \lambda^n \alpha$ for all $\alpha \in V_{\text{alt}}^{(n)}$. Thus $\det(\lambda I) = \lambda^n$.
- Since $\alpha_{\lambda T} = \lambda^n \alpha_T = \lambda^n (\det T) \alpha$ for all $\alpha \in V_{\text{alt}}^{(n)}$, $\det(\lambda T) = \lambda^n \det T$.
- Suppose $T \in \mathcal{L}(V)$ and there is a basis e_1, \dots, e_n of V consisting of eigenvectors of T , with corresponding eigenvalues $\lambda_1, \dots, \lambda_n$. If $\alpha \in V_{\text{alt}}^{(n)}$, then

$$\alpha_T(e_1, \dots, e_n) = \alpha(\lambda_1 e_1, \dots, \lambda_n e_n) = (\lambda_1 \cdots \lambda_n) \alpha(e_1, \dots, e_n)$$

If $\alpha \neq 0$, then $\alpha(e_1, \dots, e_n) \neq 0$. Thus this means that

$$\det T = \lambda_1 \cdots \lambda_n$$

Definition 42 (determinant of a matrix, $\det A$). Suppose that n is a positive integer and A is an n -by- n square matrix with entries in \mathbb{F} . Let $T \in \mathcal{L}(\mathbb{F}^n)$ be the operator whose matrix with respect to the standard basis of \mathbb{F}^n equals A . The **determinant** of A , denoted by $\det A$, is defined by $\det A = \det T$.

Theorem 43 (determinant is an alternating multilinear form). Suppose that n is a positive integer. The map that takes a list v_1, \dots, v_n of vectors in \mathbb{F}^n to $\det(v_1 \cdots v_n)$ is an alternating n -linear form on \mathbb{F}^n .

Corollary 44 (formula for determinants of a matrix). Suppose that n is a positive integer and A is an n -by- n square matrix. Then

$$\det A = \sum_{(j_1, \dots, j_n) \in \text{perm } n} (\text{sign}(j_1, \dots, j_n)) A_{j_1, 1} \cdots A_{j_n, n}$$

Remark 45. The sum in the formula above contains $n!$ terms.

Corollary 46 (determinant of upper-triangular matrix). Suppose that A is an upper-triangular matrix with $\lambda_1, \dots, \lambda_n$ on the diagonal. Then $\det A = \lambda_1 \cdots \lambda_n$.

Theorem 47 (determinant is multiplicative). We have the following result:

- (a) Suppose $S, T \in \mathcal{L}(V)$. Then $\det(ST) = \det(S) \det(T)$.
- (b) Suppose A and B are square matrices of the same size. Then

$$\det(AB) = \det(A) \det(B)$$

Corollary 48. An operator $T \in \mathcal{L}(V)$ is **invertible** if and only if $\det T \neq 0$. Furthermore, if T is invertible, then $\det(T^{-1}) = \frac{1}{\det T}$.

Corollary 49. Suppose $T \in \mathcal{L}(V)$ and $\lambda \in \mathbb{F}$. Then λ is an eigenvalue of T if and only if $\det(\lambda I - T) = 0$.

Corollary 50. Suppose $T \in \mathcal{L}(V)$ and $S: W \rightarrow V$ is an invertible linear map. Then

$$\det(S^{-1}TS) = \det T$$

Corollary 51. Suppose $T \in \mathcal{L}(V)$ and e_1, \dots, e_n is a basis of V . Then

$$\det T = \det \mathcal{M}(T, (e_1, \dots, e_n))$$

Corollary 52. Suppose $\mathbb{F} = \mathbb{C}$ and $T \in \mathcal{L}(V)$. Then $\det T$ equals the product of the eigenvalues of T , with each eigenvalue included as many times as its multiplicity.

Corollary 53 (determinant of transpose, dual, or adjoint). We have the following result:

- (a) Suppose A is a square matrix. Then $\det A^\top = \det A$.
- (b) Suppose $T \in \mathcal{L}(V)$. Then $\det T' = \det T$.
- (c) Suppose V is an inner product space and $T \in \mathcal{L}(V)$. Then

$$\det(T^*) = \overline{\det T}$$

Corollary 54. Helpful results in evaluating the determinants:

- (a) If either two columns or two rows of a square matrix are equal, then the determinant of the matrix equals 0.

- (b) Suppose A is a square matrix and B is the matrix obtained from A by swapping either two columns or two rows. Then $\det A = -\det B$.
- (c) If one column or one row of a square matrix is multiplied by a scalar, then the value of the determinant is multiplied by the same scalar.
- (d) If a scalar multiple of one column of a square matrix is added to another column, then the value of the determinant is unchanged.
- (e) If a scalar multiple of one row of a square matrix is added to another row, then the value of the determinant is unchanged.

Corollary 55. Suppose V is an inner product space and $S \in \mathcal{L}(V)$ an unitary operator. Then $|\det S| = 1$.

Corollary 56. Suppose V is an inner product space and $T \in \mathcal{L}(V)$ is a positive operator. Then $\det T \geq 0$.

Corollary 57. Suppose V is an inner product space and $T \in \mathcal{L}(V)$. Then

$$|\det T| = \sqrt{\det(T^*T)} = \text{product of singular values of } T$$

Lemma 58. Suppose $\mathbb{F} = \mathbb{C}$ and $T \in \mathcal{L}(V)$. Let $\lambda_1, \dots, \lambda_m$ denote the distinct eigenvalues of T , and let d_1, \dots, d_m denote their multiplicities. Then

$$\det(zI - T) = (z - \lambda_1)^{d_1} \cdots (z - \lambda_m)^{d_m}$$

Definition 59 (characteristic polynomial). Suppose $T \in \mathcal{L}(V)$. The polynomial defined by

$$z \mapsto \det(zI - T)$$

is called the **characteristic polynomial** of T .

Theorem 60 (Cayley-Hamilton theorem). Suppose $T \in \mathcal{L}(V)$ and q is the characteristic polynomial of T . Then $q(T) = 0$.

Corollary 61 (characteristic polynomial, trace, and determinant). Suppose $T \in \mathcal{L}(V)$. Let $n = \dim V$. Then the characteristic polynomial of T can be written as

$$z^n - (\operatorname{tr} T)z^{n-1} + \cdots + (-1)^n(\det T)$$

Theorem 62 (Hadamard's inequality). Suppose A is an n -by- n matrix. Let v_1, \dots, v_n denote the columns of A . Then

$$|\det A| \leq \prod_{k=1}^n \|v_k\|$$

Theorem 63 (determinant of Vandermonde matrix). Suppose $n > 1$ and $\beta_1, \dots, \beta_n \in \mathbb{F}$. Then

$$\det \begin{pmatrix} 1 & \beta_1 & \beta_1^2 & \cdots & \beta_1^{n-1} \\ 1 & \beta_2 & \beta_2^2 & \cdots & \beta_2^{n-1} \\ 1 & \beta_3 & \beta_3^2 & \cdots & \beta_3^{n-1} \\ & & & \ddots & \\ 1 & \beta_n & \beta_n^2 & \cdots & \beta_n^{n-1} \end{pmatrix} = \prod_{1 \leq j < k \leq n} (\beta_k - \beta_j).$$

Problem 1

Prove or give a counterexample: $S, T \in \mathcal{L}(V) \Rightarrow \det(S + T) = \det S + \det T$.

Proof. Consider \mathbb{R}^2 , and that

$$\mathcal{M}(S) = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \quad \mathcal{M}(T) = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}$$

Then clearly $\det S = 1$ and $\det T = 2$. However, we have that

$$\mathcal{M}(S) + \mathcal{M}(T) = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix}$$

which has $\det(S + T) = 6 \neq \det S + \det T$. \square

Problem 3

Suppose $T \in \mathcal{L}(V)$ is nilpotent. Prove that $\det(I + T) = 1$.

Proof. We know that 0 is the only eigenvalue of T and thus the only eigenvalue of $I + T$ is 1. Hence $\det(I + T) = 1$. \square

Problem 5

Suppose A is a block triangular matrix

$$A = \begin{pmatrix} A_1 & & * \\ & \ddots & \\ 0 & & A_m \end{pmatrix}$$

where each A_k along the diagonal is a square matrix. Prove that

$$\det A = (\det A_1) \cdots (\det A_m)$$

Proof. One can show that $\det A = (\det A_1)(\det A_2)$ through direct proof. We use induction on m for solving this problem. The base case is trivial. We assume the statement holds for $m \leq k - 1$. Then for $m = k$, we can partition the matrix into two blocks:

$$\begin{bmatrix} A' & * \\ 0 & A_k \end{bmatrix}$$

where

$$A' = \begin{bmatrix} A_1 & & * \\ & \ddots & \\ 0 & & A_{k-1} \end{bmatrix}$$

Then we have that $\det A = (\det A')(\det A_k) = (\det A_1) \cdots (\det A_k)$, finishing the proof. \square

Problem 9

Suppose that V is a real vector space of even dimension, $T \in \mathcal{L}(V)$, and $\det T < 0$. Prove that T has at least two distinct eigenvalues.

Proof. Since $\det(T) \neq 0$, T is invertible and thus have n distinct eigenvalues with $n \geq 2$. Another argument could be that for real cases, there have to be at least one negative and one positive eigenvalue to make the determinant negative; for complex cases, there must be two conjugate pairs. \square

Problem 11

Prove or give a counter example: If $\mathbb{F} = \mathbb{R}, T \in \mathcal{L}(V)$, and $\det T > 0$, then T has a square root.

Proof. Not necessarily. Consider an operator in \mathbb{R}^2 with two negative eigenvalues which is clearly non-positive and therefore does not have a square root. \square

Problem 16

Suppose $T \in \mathcal{L}(V)$. Define $g: \mathbb{F} \rightarrow \mathbb{F}$ by $g(x) = \det(I + xT)$. Show that $g'(0) = \text{tr } T$.

Proof.

$$\begin{aligned} g'(x) &= \frac{d}{dx} \det(I + xT) \\ &= \frac{d}{dx} \prod_{i=1}^n (1 + x\lambda_i) \\ &= \sum_{i=1}^n \left(\lambda_i \prod_{j \neq i} (1 + x\lambda_j) \right) \end{aligned}$$

Substitute $x = 0$ yields that

$$g'(0) = \sum_{i=1}^n \lambda_i = \text{tr } T$$

\square

Problem 19

Suppose V is an inner product space, e_1, \dots, e_n is an orthonormal basis of V , and $T \in \mathcal{L}(V)$ is a positive operator.

- (a) Prove that $\det T \leq \prod_{k=1}^n \langle Te_k, e_k \rangle$.
- (b) Prove that if T is invertible, then the inequality in (a) is an equality if and only if e_k is an eigenvector of T for each $k = 1, \dots, n$.

Proof. (a) The matrix representation of T wrt. e_1, \dots, e_n is that $A_{ij} = \langle Te_i, e_j \rangle$. Hence the r.h.s of this inequality is simply the product of all the diagonal terms on the matrix of T . We prove this inequality through Cholesky decomposition. Note that

$$A = LL^*$$

for lower-triangular matrix L , and thus we have

$$\det T = \det A = (\det L)^2 = \left(\prod_{k=1}^n l_{kk} \right)^2 = \prod_{k=1}^n L_{kk}^2$$

We note that

$$A_{kk} = L_{kk}^2 + \sum_{j=1}^{k-1} L_{kj}^2$$

and thus we have

$$\det A \leq \prod_{k=1}^n A_{kk} = \prod_{k=1}^n \langle Te_k, e_k \rangle$$

- (b) If e_k is an eigenvector of T , then $\langle Te_k, e_k \rangle = \lambda_k$, the k -th eigenvalue of T . Then we know that $\det T$ is the product of all eigenvalues.

Conversely, if (a) is an equality, then we know that L is a diagonal matrix and thus A is also a diagonal matrix. Then the orthonormal basis e_1, \dots, e_n actually diagonalizes T and hence each of them is an eigenvector of T . \square

9D: Tensor Products

Definition 64 (bilinear functional on $V \times W$, the vector space $\mathcal{B}(V, W)$). A **bilinear functional** on $V \times W$ is a function $\beta: V \times W \rightarrow \mathbb{F}$ such that $v \mapsto \beta(v, w)$ is a linear functional on V for each $w \in W$ and $w \mapsto \beta(v, w)$ is a linear functional on W for each $v \in V$.

The vector space of bilinear functionals on $V \times W$ is denoted by $\mathcal{B}(V, W)$.

Remark 65. If $V = W$, then a bilinear functional on $V \times W$ is a bilinear form.

Corollary 66. $\dim \mathcal{B}(V, W) = (\dim V)(\dim W)$

Remark 67. We want a basis-free definition of the tensor product.

Definition 68 (tensor product, $V \otimes W, v \otimes w$). The **tensor product** $V \otimes W$ is defined to be $\mathcal{B}(V', W')$.

For $v \in V$ and $w \in W$, the **tensor product** $v \otimes w$ is the element of $V \otimes W$ defined by

$$(v \otimes w)(\varphi, \tau) = \varphi(v)\tau(w)$$

for all $(\varphi, \tau) \in V' \times W'$.

Corollary 69. $\dim(V \otimes W) = (\dim V)(\dim W)$.

Proposition 70 (bilinearity of tensor product). Suppose $v, v_1, v_2 \in V$ and $w, w_1, w_2 \in W$ and $\lambda \in \mathbb{F}$. Then

$$(v_1 + v_2) \otimes w = v_1 \otimes w + v_2 \otimes w \text{ and } v \otimes (w_1 + w_2) = v \otimes w_1 + v \otimes w_2$$

and

$$\lambda(v \otimes w) = (\lambda v) \otimes w = v \otimes (\lambda w)$$

Theorem 71 (basis of $V \otimes W$). Suppose e_1, \dots, e_m is a list of vectors in V and f_1, \dots, f_n is a list of vectors in W .

(a) If e_1, \dots, e_m and f_1, \dots, f_n are both linearly independent list, then

$$\{e_j \otimes f_k\}_{j=1, \dots, m; k=1, \dots, n}$$

is a linearly independent list in $V \otimes W$.

(b) If e_1, \dots, e_m is a basis of V and f_1, \dots, f_n is a basis of W , then the list $\{e_j \otimes f_k\}_{j=1, \dots, m; k=1, \dots, n}$ is a basis of $V \otimes W$.

Definition 72 (bilinear map). A **bilinear map** from $V \times W$ to a vector space U is a function $\Gamma: V \times W \rightarrow U$ such that $v \mapsto \Gamma(v, w)$ is a linear map from V to U for each $w \in W$ and $w \mapsto \Gamma(v, w)$ is a linear map from W to U for each $v \in V$.

Lemma 73 (converting bilinear maps to linear maps). Suppose U is a vector space.

- (a) Suppose $\Gamma: V \times W \rightarrow U$ is a bilinear map. Then there exists a unique linear map $\tilde{\Gamma}: V \otimes W \rightarrow U$ such that

$$\tilde{\Gamma}(v \otimes w) = \Gamma(v, w)$$

for all $(v, w) \in V \times W$.

- (b) Conversely, suppose $T: V \otimes W \rightarrow U$ is a linear map. Then there exists a unique bilinear map $T^\#: V \times W \rightarrow U$ such that

$$T^\#(v, w) = T(v \otimes w)$$

for all $(v, w) \in V \times W$.

Theorem 74 (inner product on tensor product of two inner product spaces). Suppose V and W are inner product spaces. Then there is a unique inner product on $V \otimes W$ such that

$$\langle v \otimes w, u \otimes x \rangle = \langle v, u \rangle \langle w, x \rangle$$

for all $u, v \in V$ and $w, x \in W$.

Remark 75. We have that $\|v \otimes w\| = \|v\| \|w\|$.

Corollary 76. Suppose V and W are inner product spaces, and e_1, \dots, e_m is an orthonormal basis of V and f_1, \dots, f_n is an orthonormal basis of W . Then

$$\{e_j \otimes f_k\}_{j=1, \dots, m; k=1, \dots, n}$$

is an orthonormal basis of $V \otimes W$.

Definition 77. An **m -linear** functional on $V_1 \times \dots \times V_m$ is a function $\beta: V_1 \times \dots \times V_m \rightarrow \mathbb{F}$ that is a linear functional in each slot when the other slots are held fixed.

The vector space of m -linear functionals on $V_1 \times \dots \times V_m$ is denoted by $\mathcal{B}(V_1, \dots, V_m)$.

Corollary 78. $\dim \mathcal{B}(V_1, \dots, V_m) = (\dim V_1) \times \dots \times (\dim V_m)$

Definition 79 (tensor product). The tensor product $V_1 \otimes \dots \otimes V_m$ is defined to be $\mathcal{B}(V'_1, \dots, V'_m)$.

For $v_1 \in V_1, \dots, v_m \in V_m$, the **tensor product** $v_1 \otimes \dots \otimes v_m$ is the element of $V_1 \otimes \dots \otimes V_m$ defined by

$$(v_1 \otimes \dots \otimes v_m)(\varphi_1, \dots, \varphi_m) = \varphi_1(v_1) \dots \varphi_m(v_m)$$

for all $(\varphi_1, \dots, \varphi_m) \in V'_1 \times \dots \times V'_m$.

Corollary 80. Suppose $\dim V_k = n_k$ and $e_1^k, \dots, e_{n_k}^k$ is a basis of V_k for $k = 1, \dots, m$. Then

$$\{e_{j_1}^1 \otimes \dots \otimes e_{j_m}^m\}_{j_1=1, \dots, n_1; \dots; j_m=1, \dots, n_m}$$

is a basis of $V_1 \otimes \dots \otimes V_m$.

Definition 81 (m-linear map). *An m-linear map from $V_1 \times \cdots \times V_m$ to a vector space U is a function $\Gamma: V_1 \times \cdots \times V_m \rightarrow U$ that is a linear map in each slot when the other slots are held fixed.*

Theorem 82 (converting m-linear map to linear maps). *Suppose U is a vector space.*

- (a) *Suppose that $\Gamma: V_1 \times \cdots \times V_m \rightarrow U$ is an m-linear map. Then there exists a unique linear map $\tilde{\Gamma}: V_1 \otimes \cdots \otimes V_m \rightarrow U$ such that*

$$\tilde{\Gamma}(v_1 \otimes \cdots \otimes v_m) = \Gamma(v_1, \dots, v_m)$$

for all $(v_1, \dots, v_m) \in V_1 \times \cdots \times V_m$.

- (b) *Conversely, suppose $T: V_1 \otimes \cdots \otimes V_m \rightarrow U$ is a linear map. Then there exists a unique m-linear map $T^\#: V_1 \times \cdots \times V_m \rightarrow U$ such that*

$$T^\#(v_1, \dots, v_m) = T(v_1 \otimes \cdots \otimes v_m)$$

for all $(v_1, \dots, v_m) \in V_1 \times \cdots \times V_m$.

Problem 1

Suppose $v \in V$ and $w \in W$. Prove that $v \otimes w = 0$ if and only if $v = 0$ or $w = 0$.

Proof. By definition, we have for any $(\varphi, \tau) \in V' \times W'$,

$$(v \otimes w)(\varphi, \tau) = \varphi(v)\tau(w)$$

Then this means that $\varphi(v)\tau(w) = 0$ for arbitrary choice of φ, τ , meaning that either $v = 0$ or $w = 0$. \square

Problem 3

Suppose that v_1, \dots, v_m is a linearly independent list in V . Suppose also that w_1, \dots, w_m is a list in W such that

$$v_1 \otimes w_1 + \dots + v_m \otimes w_m = 0$$

Prove that $w_1 = \dots = w_m = 0$.

Proof. By the linear map lemma and the linear independence of v_1, \dots, v_m , there exists $\varphi_1, \dots, \varphi_m \in V'$ such that

$$\varphi_j(v_k) = \begin{cases} 1 & \text{if } j = k \\ 0 & \text{if } j \neq k \end{cases}$$

where $j, k \in \{1, \dots, m\}$. Applying such $\{\varphi_i\}_{i=1}^m$ to the list

$$\sum_{i=1}^m v_i \otimes w_i$$

and take $\tau \in W'$ to be the identity map yields that

$$w_1 = \dots = w_m = 0$$

\square

Problem 5

Suppose m and n are positive integers. For $v \in \mathbb{F}^m$ and $w \in \mathbb{F}^n$, identify $v \otimes w$ with an m -by- n matrix as in Example 9.76. With that identification, show that the set

$$\{v \otimes w : v \in \mathbb{F}^m \text{ and } w \in \mathbb{F}^n\}$$

is the set of m -by- n matrices (with entries in \mathbb{F}) that have rank at most one.

Proof. If one examines the matrices with entries shown on the matrix, it's easy to tell that for row j and row k with $j \neq k$, one can get row k from row j through multiplying v_k/v_j . The same applies to arbitrary pairs of columns. Thus the matrix has at most rank one. \square

Problem 8

Suppose $v_1, \dots, v_m \in V$ and $w_1, \dots, w_m \in W$ are such that

$$v_1 \otimes w_1 + \dots + v_m \otimes w_m = 0$$

Suppose that U is a vector space and $\Gamma: V \times W \rightarrow U$ is a bilinear map. Show that

$$\Gamma(v_1, w_1) + \dots + \Gamma(v_m, w_m) = 0$$

Proof. We know there exists a unique “converting” linear map $\tilde{\Gamma}$ such that

$$\Gamma(v \otimes w) = \Gamma(v, w)$$

Hence applying this gives that

$$\begin{aligned} \sum_{i=1}^m \Gamma(v_i, w_i) &= \sum_{i=1}^m \tilde{\Gamma}(v_i \otimes w_i) \\ &= \tilde{\Gamma}\left(\sum_{i=1}^m v_i \otimes w_i\right) \\ &= 0 \end{aligned}$$

\square