

CLOUD COMPUTING CONCEPTS with Indranil Gupta (Indy)

SNAPSHOTS

Lecture B

GLOBAL SNAPSHOT ALGORITHM



System Model

- Problem: Record a global snapshot (state for each process, and state for each channel)
- System Model:
 - N processes in the system
 - There are two uni-directional communication channels between each ordered process pair : $Pj \rightarrow Pi$ and $Pi \rightarrow Pj$
 - Communication channels are FIFO-ordered
 - First in, first out
 - No failure
 - All messages arrive intact and are not duplicated
 - Other papers later relaxed some of these assumptions



REQUIREMENTS

- Snapshot should not interfere with normal application actions, and it should not require application to stop sending messages
- Each process is able to record its own state
 - Process state: Application-defined state or, in the worst case:
 - Its heap, registers, program counter, code, etc. (essentially the coredump)
- Global state is collected in a distributed manner
- Any process may initiate the snapshot
 - We'll assume just one snapshot run for now



CHANDY-LAMPORT GLOBAL SNAPSHOT ALGORITHM

- First, Initiator Pi records its own state
- Initiator process creates special messages called "Marker" messages
 - Not an application message, does not interfere with application messages
- for j=1 to N except i
 - Pi sends out a Marker message on outgoing channel C_{ii}
 - (*N-1*) channels
- Starts recording the incoming messages on each of the incoming channels at Pi: C_{ii} (for j=1 to N except i)



CHANDY-LAMPORT GLOBAL SNAPSHOT ALGORITHM (2)

Whenever a process Pi receives a Marker message on an incoming channel C_{ki}

- if (this is the first Marker Pi is seeing)
 - Pi records its own state first
 - Marks the state of channel C_{ki} as "empty"
 - For j=1 to N except i
 - Pi sends out a Marker message on outgoing channel C_{ij}
 - Starts recording the incoming messages on each of the incoming channels at Pi: C_{ji} (for j=1 to N except i and k)
- else // already seen a Marker message
 - Mark the state of channel C_{ki} as all the messages that have arrived on it since recording was turned on for C_{ki}



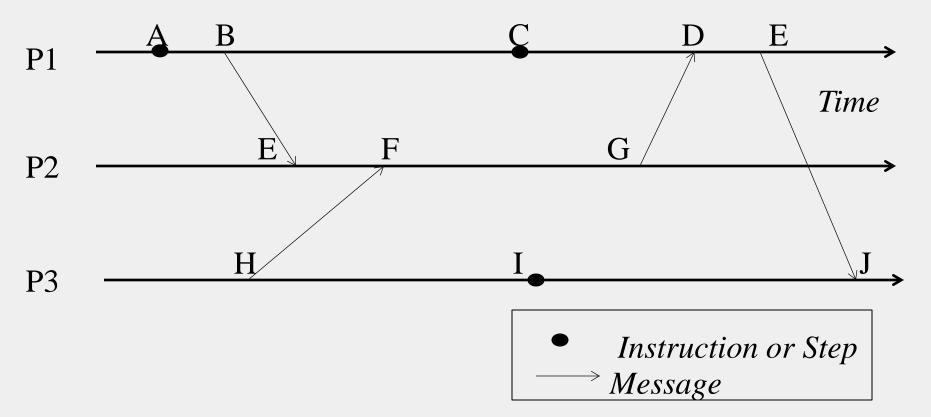
CHANDY-LAMPORT GLOBAL SNAPSHOT ALGORITHM (3)

The algorithm terminates when

- All processes have received a Marker
 - To record their own state
- All processes have received a Marker on all the (*N-1*) incoming channels at each
 - To record the state of all channels

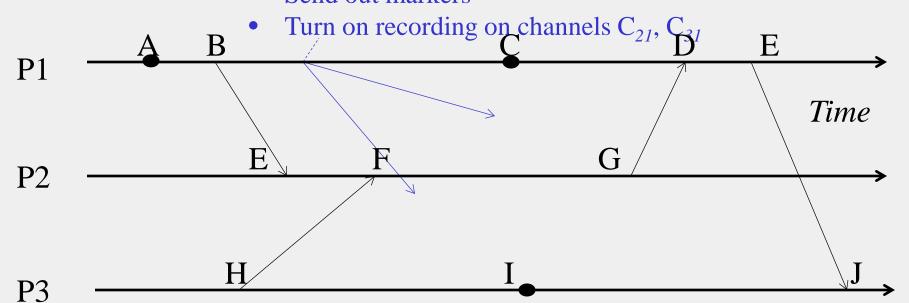
Then, (if needed), a central server collects all these partial state pieces to obtain the full global snapshot

EXAMPLE

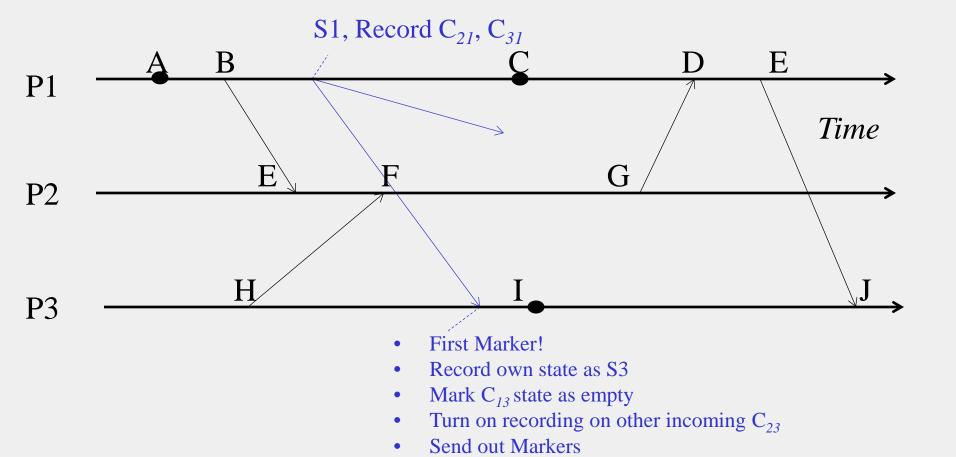


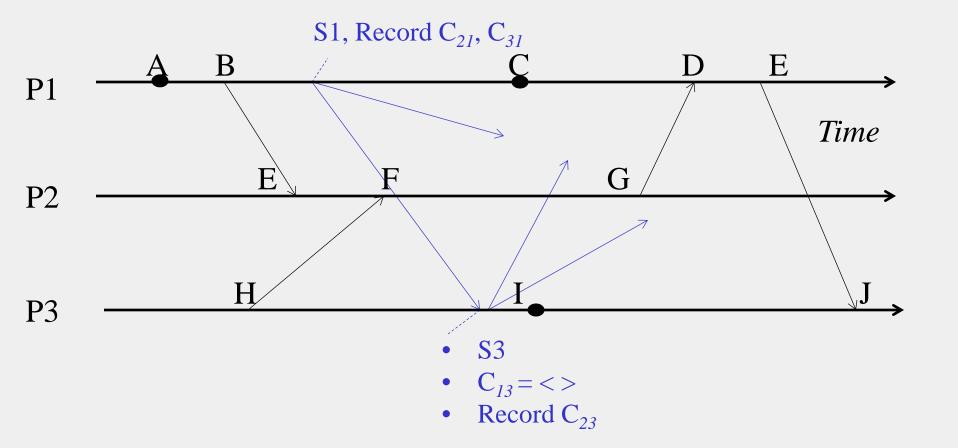
P1 is Initiator:

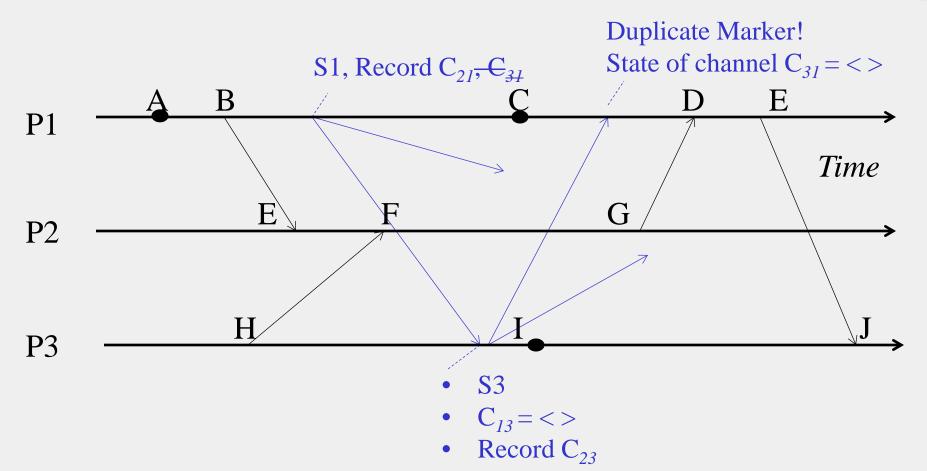
- Record local state S1
- Send out markers

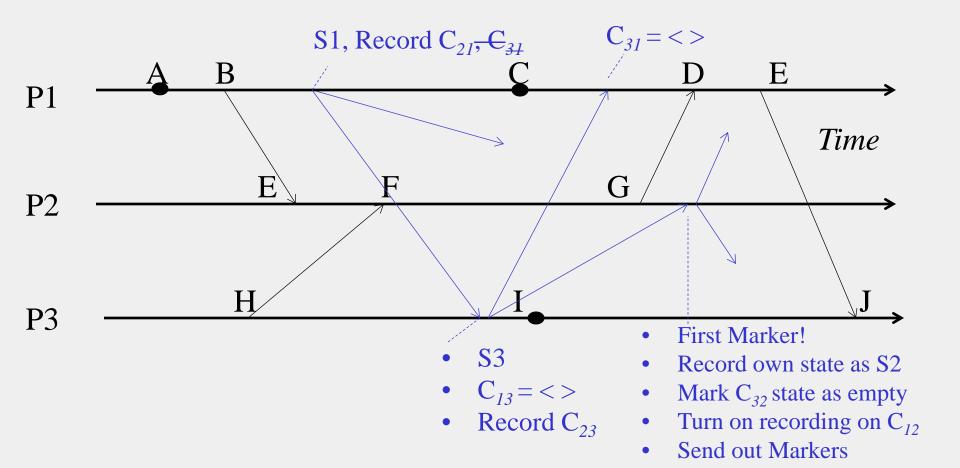


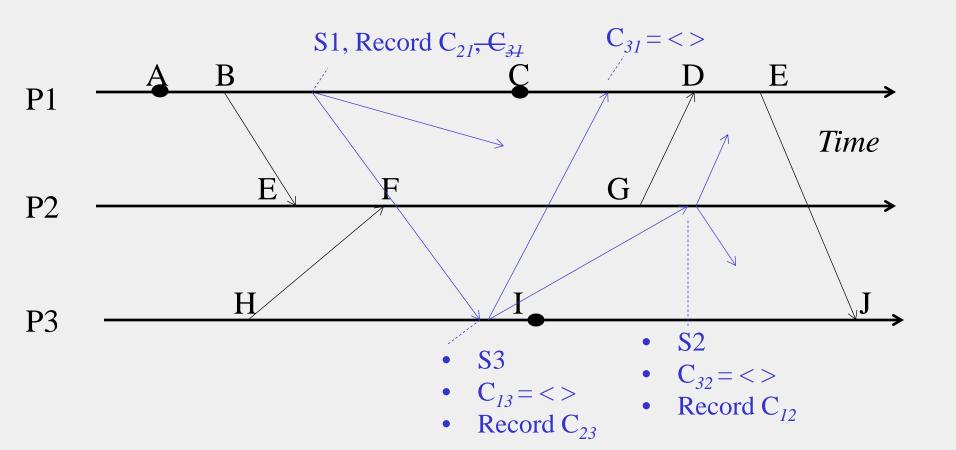


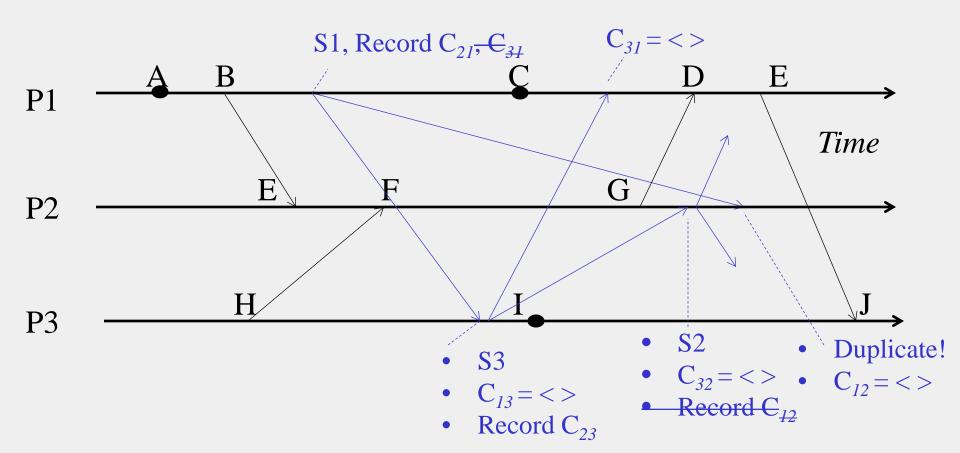


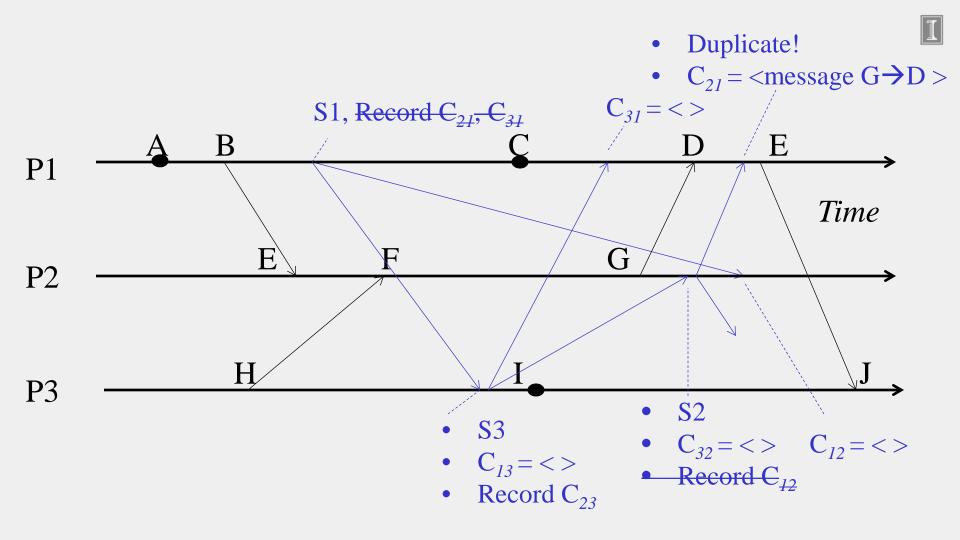


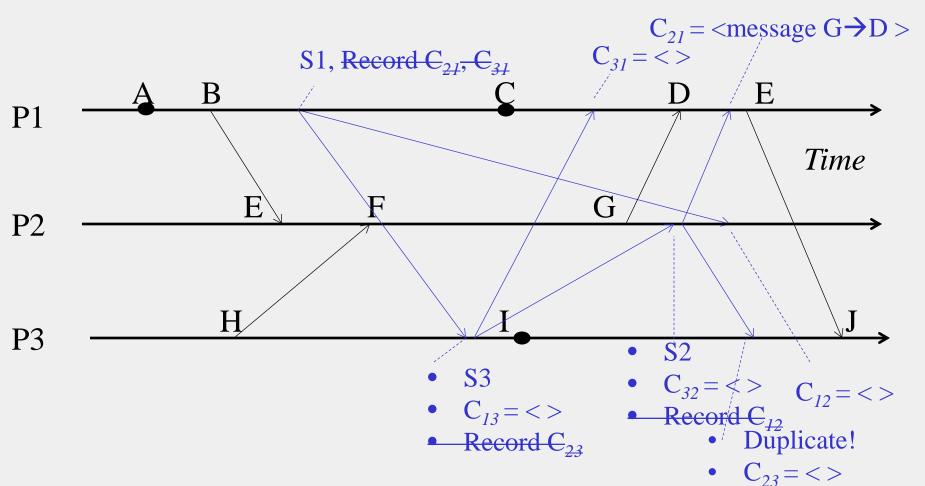




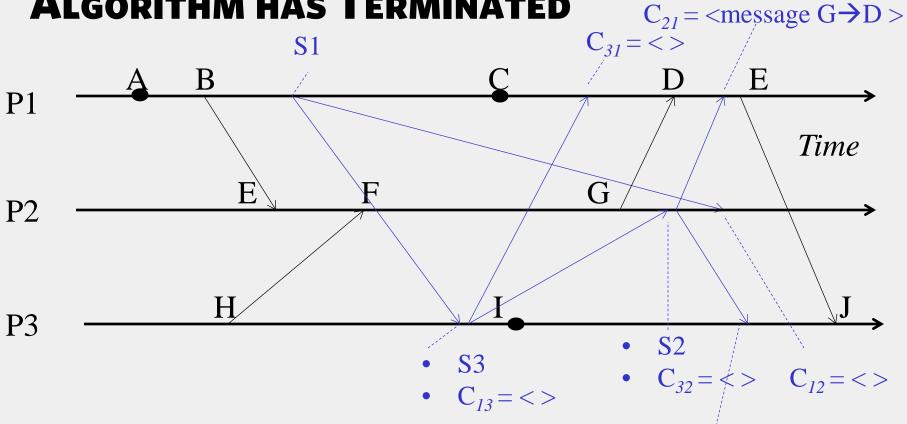






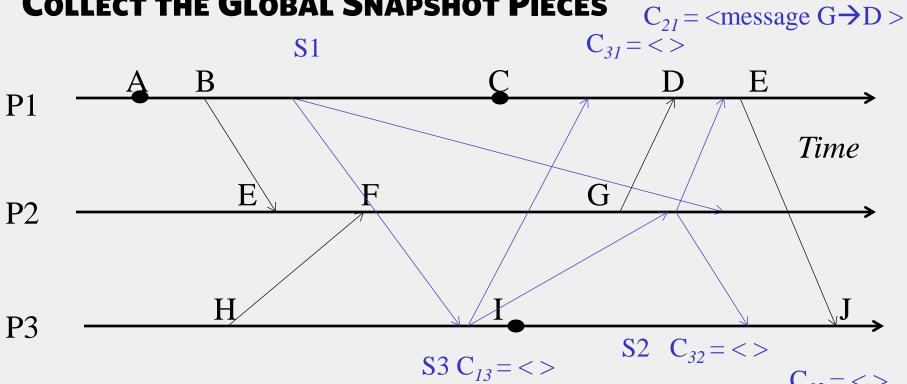


ALGORITHM HAS TERMINATED





COLLECT THE GLOBAL SNAPSHOT PIECES



$$C_{23} = <>$$



NEXT

- Global Snapshot calculated by Chandy-Lamport algorithm is <u>causally correct</u>
 - What?