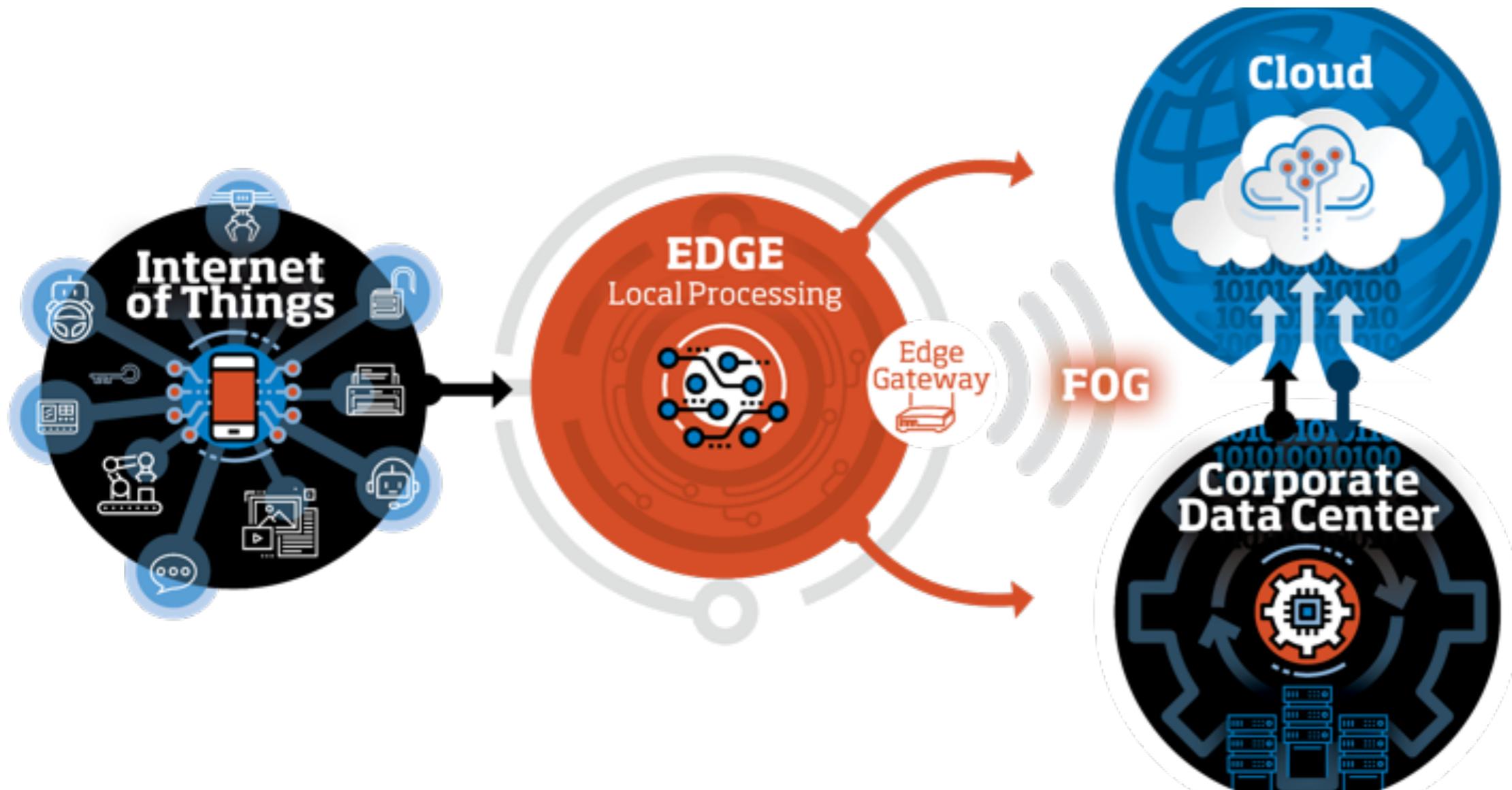


# IoT Lab

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Technische Universität München

# IoT Components



# Goals

- Familiarization with IoT Cloud concepts
- Implement a concrete use case
- Deploy machine learning technologies

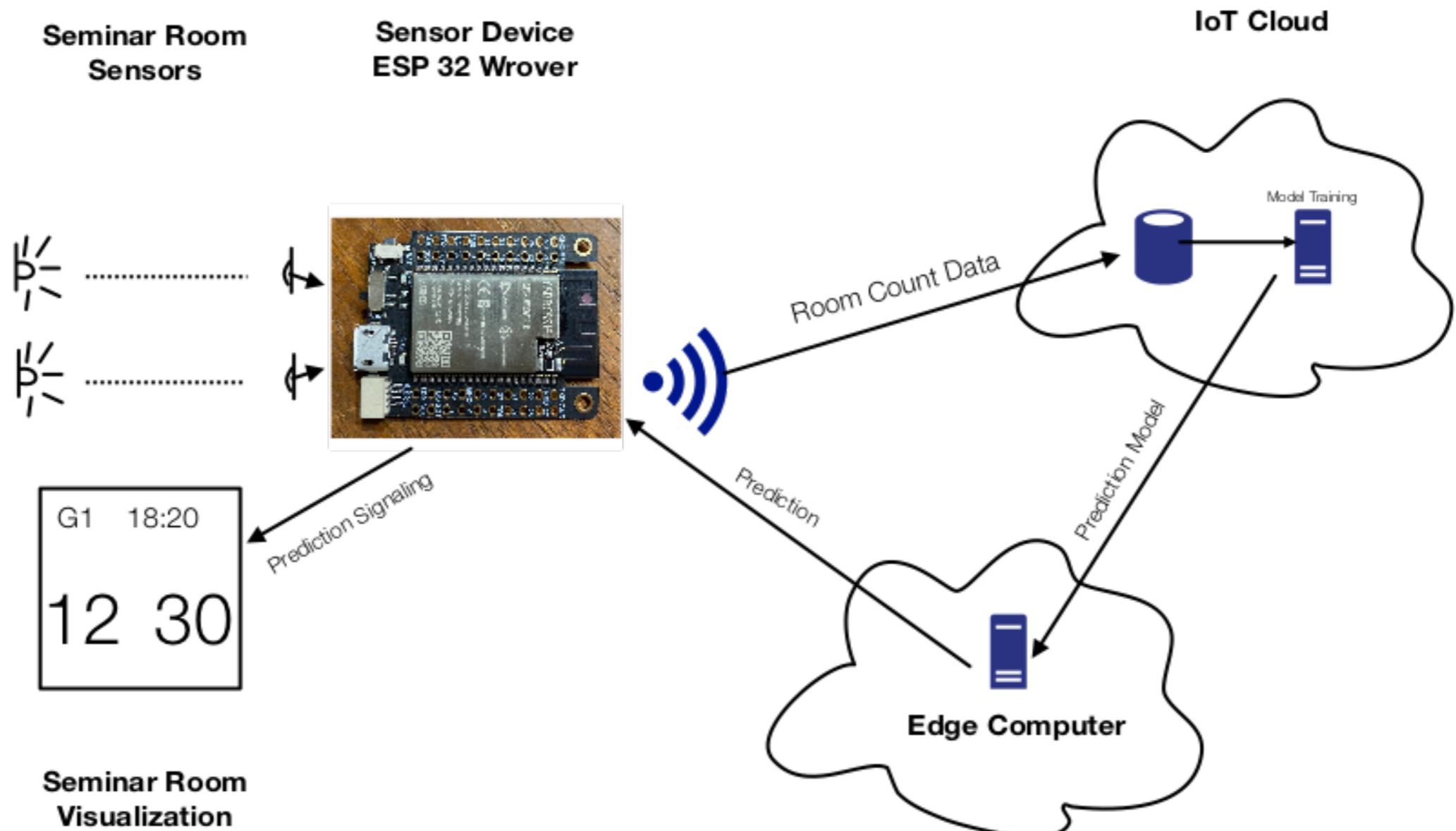
# Use Case

Seminar Room Monitoring

# Features

Room Occupancy Prediction

# Final Architecture



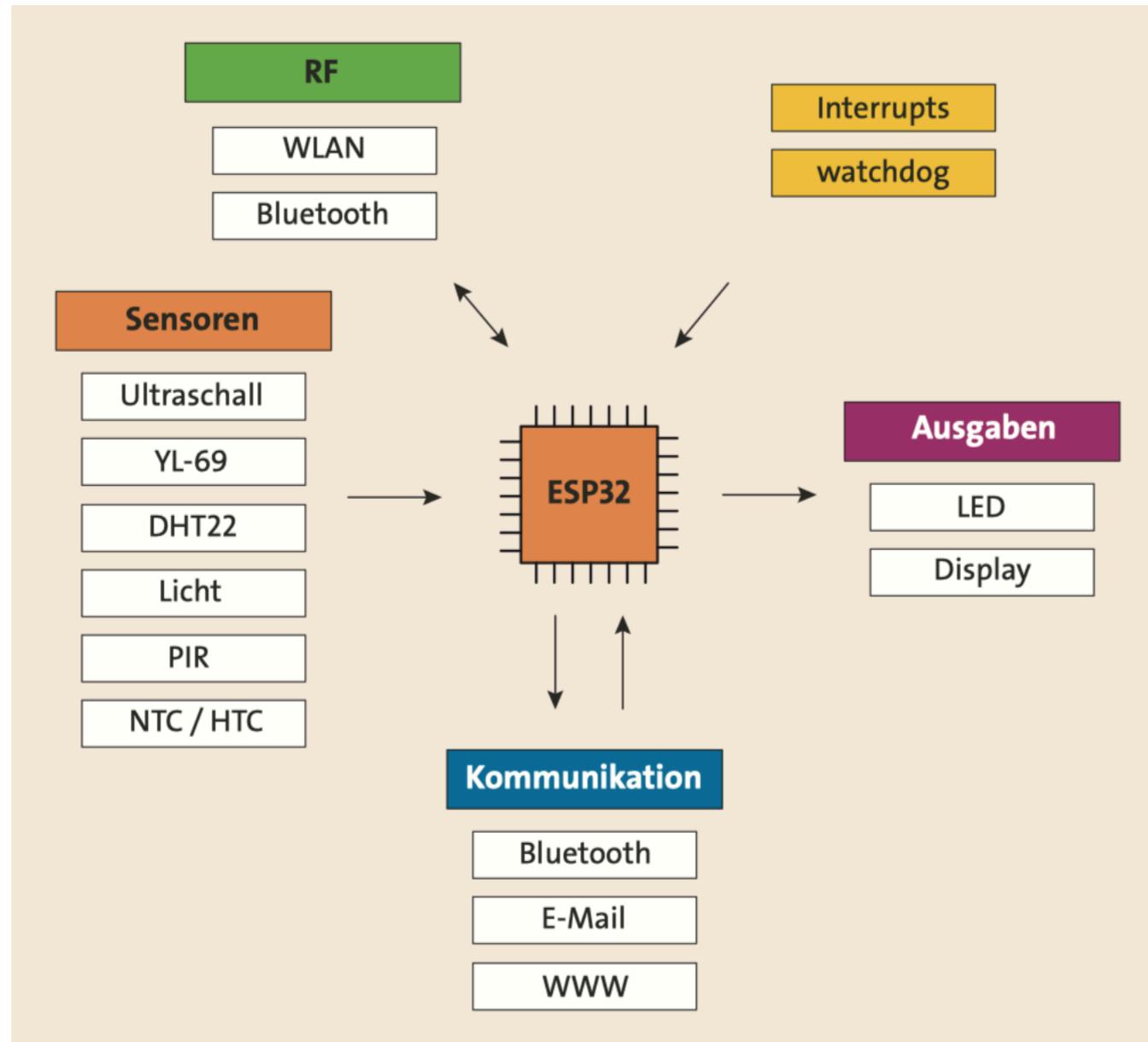
# Main Technologies

- Microcontroller ESP32 with WLAN and Bluetooth
- Photoelectric barrier for sensing
- IoT platform provided by previous lab courses
- Data modeling and prediction algorithms
- Cloud for edge VM

# Microcontroller vs Microprocessor

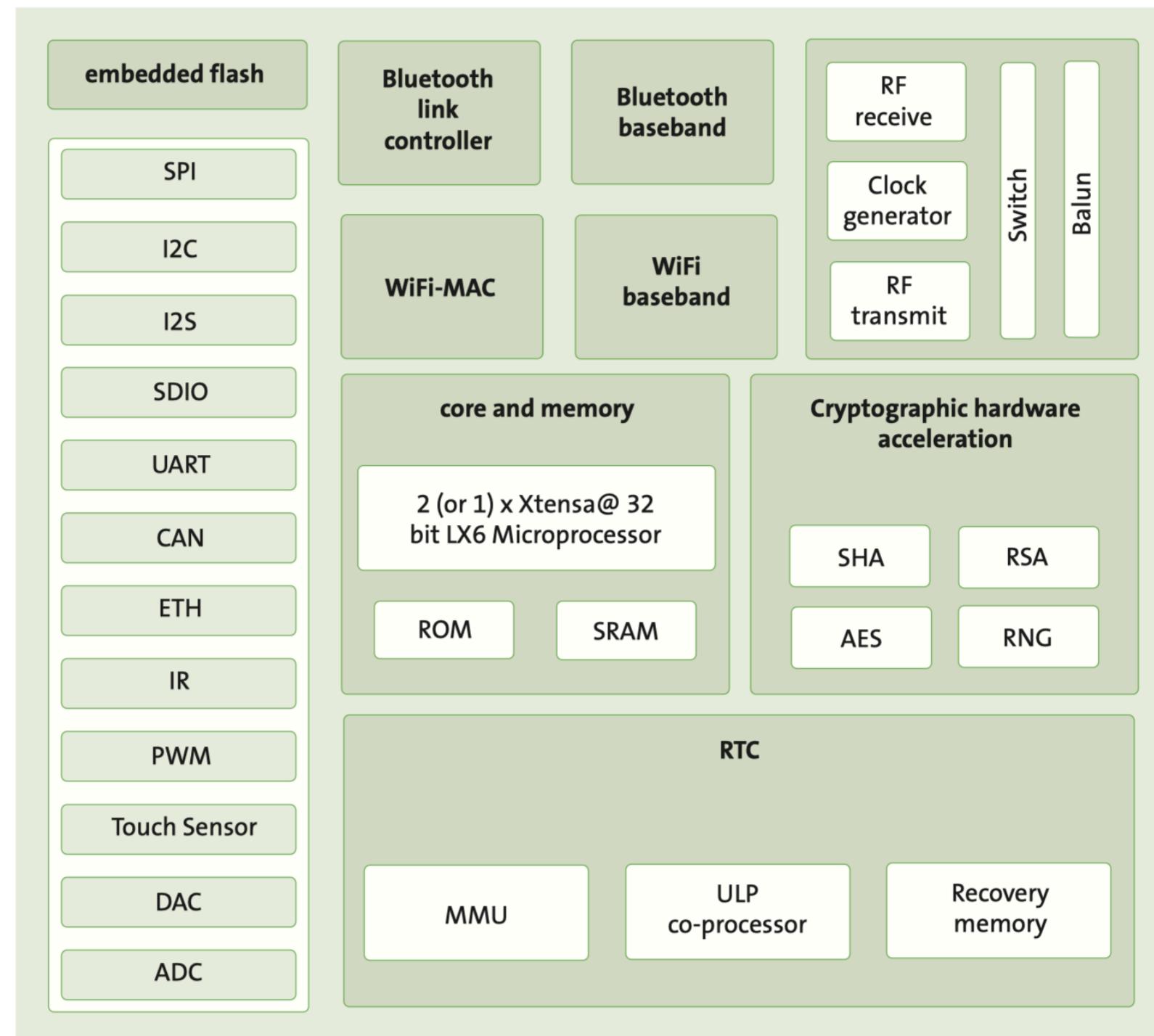
- Microprocessor
  - Processor with external memory
- Microcontroller
  - Processor with integrated memory
  - Commonly flash + SRAM
  - A lot of I/O interfaces

# Espressif ESP32



<https://www.espressif.com/en/products/socs/esp32>

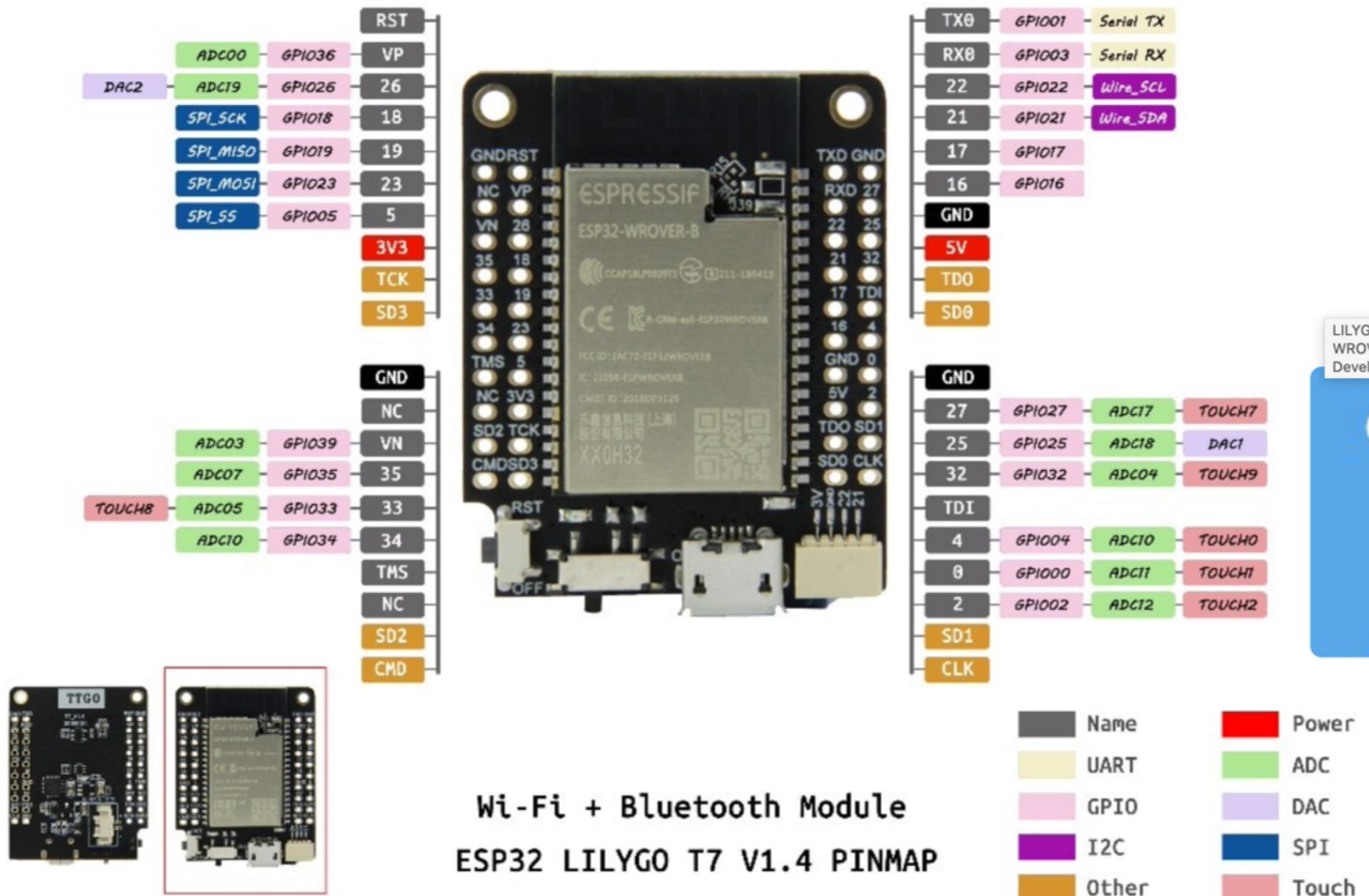
# ESP32 Block Diagram



# ESP32 Memory

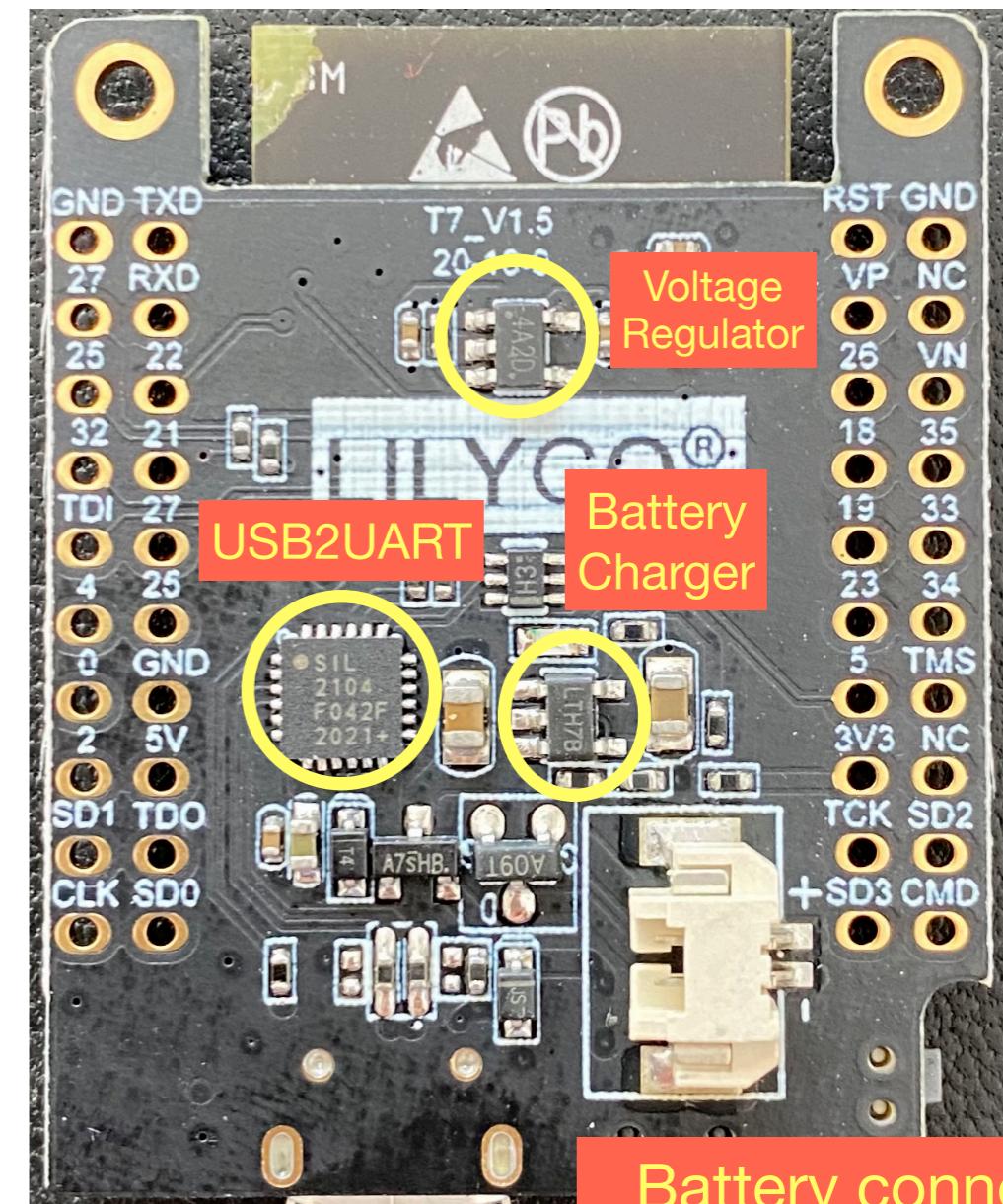
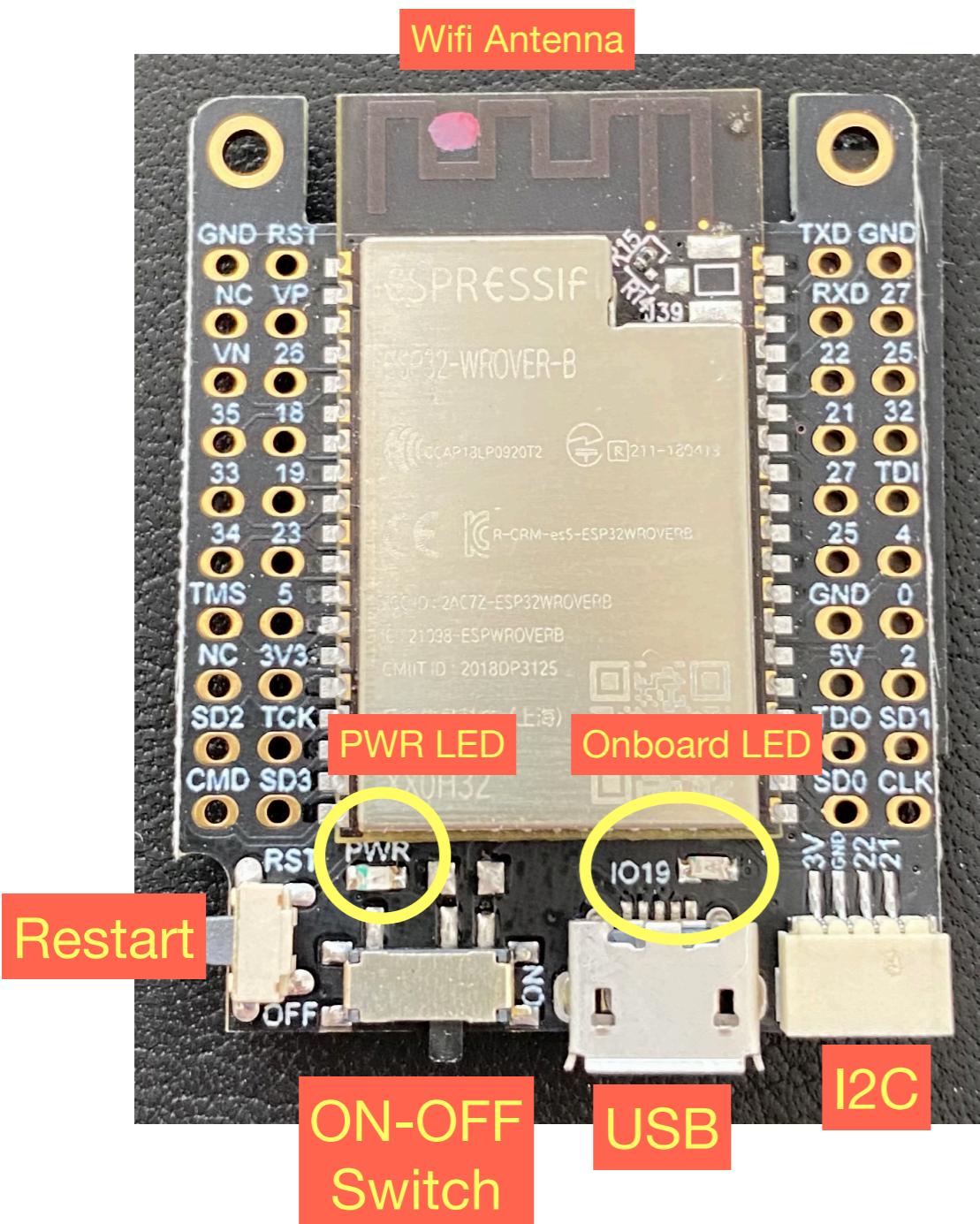
- 520 KB SRAM for data and instructions
- 448 KB ROM for boot and kernel functions
- 8 KB SRAM in RTC (RTC-FAST Memory) safe data over deep sleep
- 8 KB SRAM in RTC (RTC-SLOW Memory) for coprocessor during deep sleep
- ESP Wrover-B
  - 4 MB QSPI Flash memory
  - Additional 8 MB PSRAM (Pseudo Static RAM)

# LILYGO Wrover-B



[http://www.lilygo.cn/prod\\_view.aspx?TypeId=50033&Id=978](http://www.lilygo.cn/prod_view.aspx?TypeId=50033&Id=978)

# LILYGO Wrover-B Board



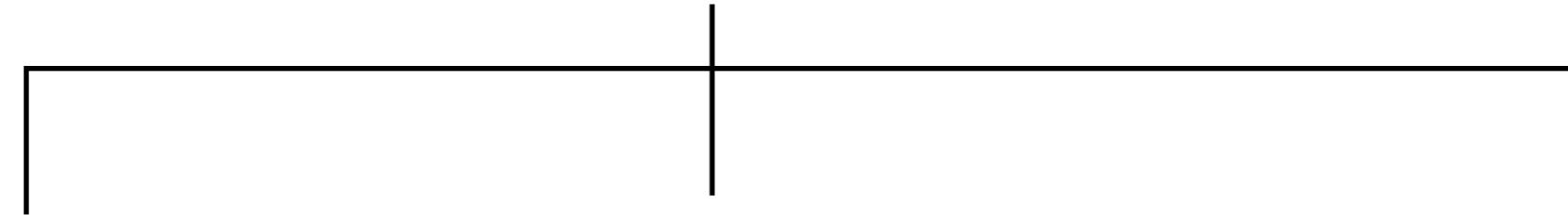
# ESP IDF

- Several development environments available
  - **ESP IDF**
  - Arduino
  - MS Visual Studio Code
  - platform.io
- Espressif IoT Development Framework (ESP-IDF)
  - Provided by Espressif: <https://docs.espressif.com/projects/esp-idf/>
  - Installation instructions for Windows, Linux, Mac OS
  - Combines
    - Compiler
    - Build environment
    - freeRTOS
    - Components: MQTT, Camera, ...

# Application Structure

## Project directory

CMakeLists.txt  
README.md  
sdkconfig



### main

CMakeLists.txt  
.c source files  
.h header files  
Kconfig.projbuild

### components

Subdirectories for  
libraries. They have own  
CMakeLists.txt

### build

Directory constructed  
from cmake for  
building.

# Project Building

- Python script idf.py
  - build: Triggers configuration and building
  - flash: Triggers linking and flashing to board
  - monitor: Triggers serial connection to board for monitoring
  - fullclean: clean the whole generated files
- idf.py is based on cmake and make

# FreeRTOS

- ESP IDF is based on the Free Real Time Operating System (FreeRTOS)
  - [freertos.org](http://freertos.org)
  - Maintenance taken over by Amazon from Real Time Engineers Ltd.
    - Integration of sensors with the Greengrass edge runtime
  - It is free: No need to publish your code if developed with FreeRTOS, no fees
- Basically a runtime system linked to the application
- Managing resources: CPU, memory, timers, IO
- Supports soft and hard realtime requirements

# FreeRTOS

- Terminology
  - What is usually called a **thread** is a **task** in FreeRTOS
- Provides
  - Multitasking: time slicing with task preemption
    - The task scheduler is the heart of FreeRTOS
    - Soft and hard realtime constraints are supported through task prioritization
  - Synchronization: locks, semaphores, ...
  - Software timers: countdown clocks triggering an attached callback function
  - HEAP management
- Write embedded software without a kernel
  - For simple applications may be easier: Arduino style (setup and loop routine)
  - In case of multiple tasks to be run with a certain frequency it becomes complex. The frequency has to be implemented in the code of the loop, e.g., display task, read sensors, handle input from Wifi ...

# ESP IDF and FreeRTOS

- ESP IDF provides a port of FreeRTOS for ESP32
- Extended version for multicore system
  - Two application cores
  - Low power coprocessor

# Hardware

ⓘ You last purchased this item on 21. February 2020.  
Number Of Items: 1 | [View this order](#)

AZDelivery OLED Parent 128 x 64 Pixel 0.96 Inches  
Visit the AZDelivery Store  
★★★★★ 1,288 ratings | 28 answered questions  
Amazon's Choice for "az-delivery"

Price: €5.79  
Prices for items sold by Amazon include VAT. Depending on your delivery address, VAT may vary at Checkout. For other items, please see [details](#).

Promotion Message: €5 on Arduino book with microcontroller. 1 Promotion(s)

New (3) from €5.79 & FREE Shipping on orders over €29.00

Number Of Items: 1

1 €5.79	3 €9.99 (€3.33 / Item)	5 €17.99 (€3.60 / Item)	25 €84.99 (€3.40 / Item)
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Brand AZDelivery  
Computer memory size 1 MB  
RAM type EEPROM

About this item

- Strong Contrast the using the innovative OLED technology in the big 0.96 inch display.
- Due to high resolution of 128 Mal 64 Pixels provides space for easy displaying the screen elements.
- Easier connect the displays with Arduino, Raspberry Pi and co. using the I<sup>2</sup>C Interface via only 4 pins.
- Libraries for Arduino Raspberry Pi and Co. thanks to standard controller (SSD 1306) already available, was programming a piece of cake.
- Usually high quality and fast delivery thanks to when buying Azdelivery. Also free: Getting Started know-how of Azdelivery experts in eBook format.

Roll over image to zoom in



ⓘ You last purchased this item on 24. February 2021.  
[View this order](#)

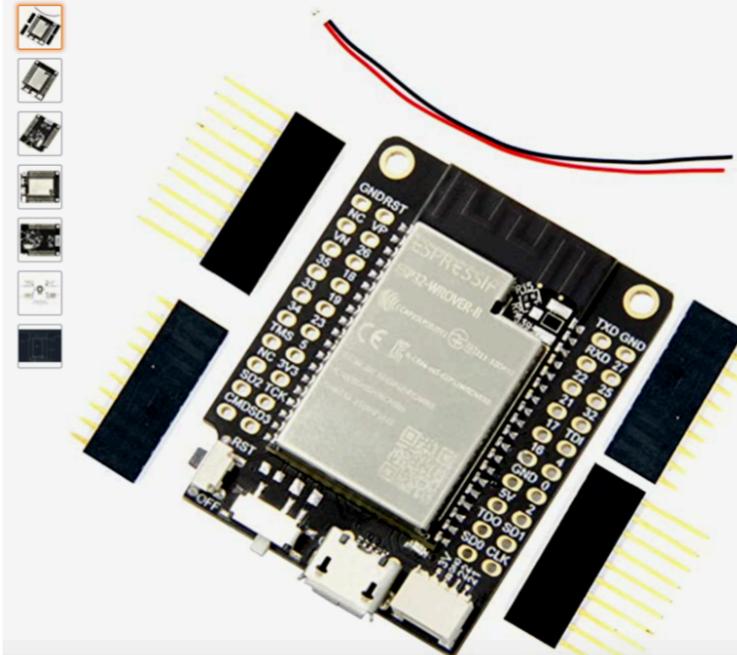
ICQUANZX Mini32 V1.3 ESP32-WROVER-B  
PSRAM Wi-Fi Bluetooth Module Development Board  
Brand: ICQUANZX  
★★★★★ 13 ratings

Price: €16.99  
Prices for items sold by Amazon include VAT. Depending on your delivery address, VAT may vary at Checkout. For other items, please see [details](#).

- Chipset: ESPRESSIF-ESP32 (Wi-Fi & Bluetooth) 240MHz Xtensa Single / Dual Core 32-bit LX6 microprocessor
- FLASH: QSPI-Flash 4 MB / PSRAM 8 MB
- Working current: over 30mA, sleep current: over 10uA.
- JST connection: 2-pin, 1.25 mm, 4-pin, 1.0 mm
- Modular Interface: UART, SPI, SDIO, I<sup>2</sup>C, LED PWM, TV PWM I<sup>2</sup>S, GPIO, ADC, capacitor touch sensor, DAC/INA preamplifier FLASH: QSPI-Flash 4MB / PSRAM 8MB

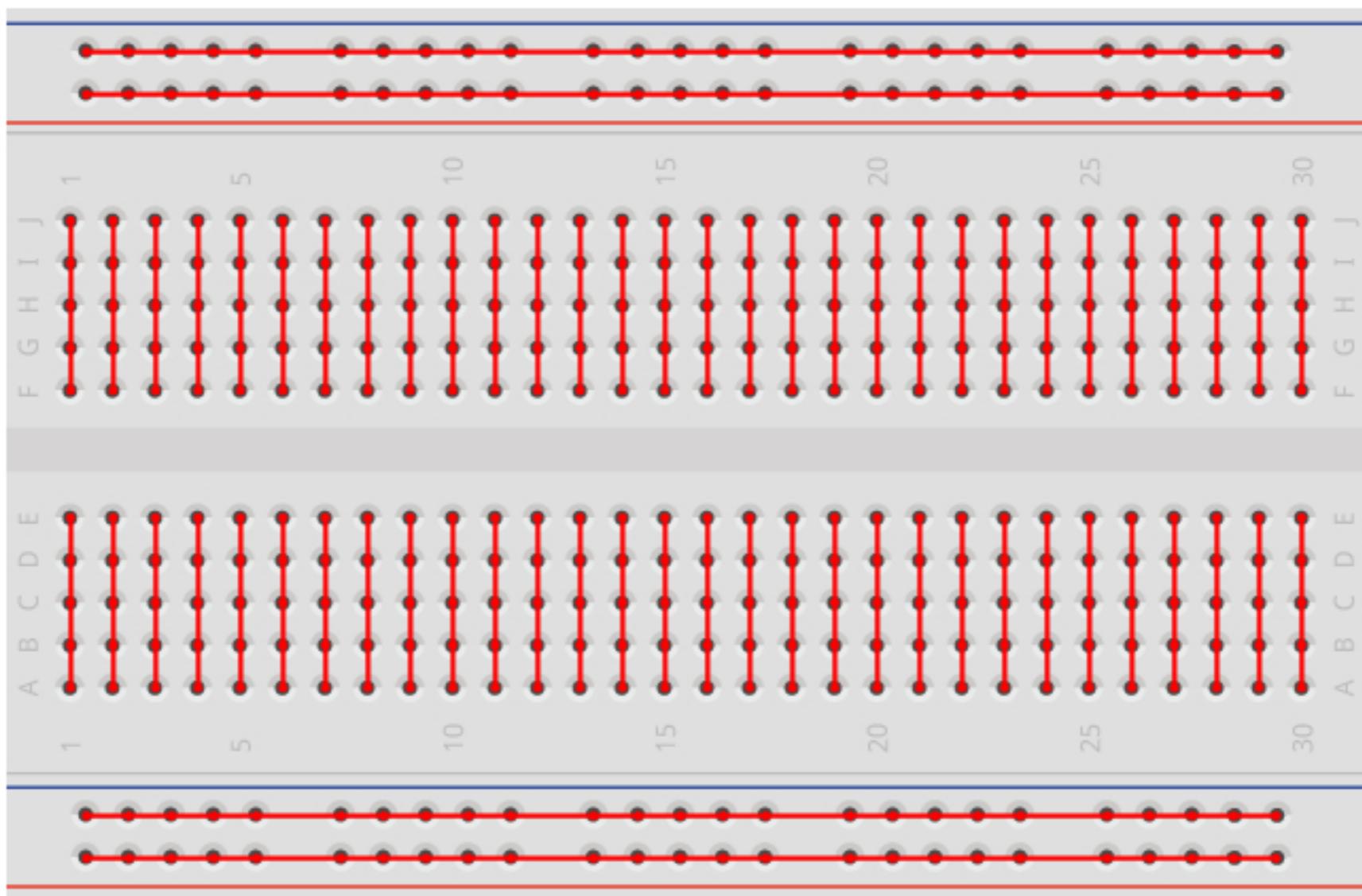
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# Hardware

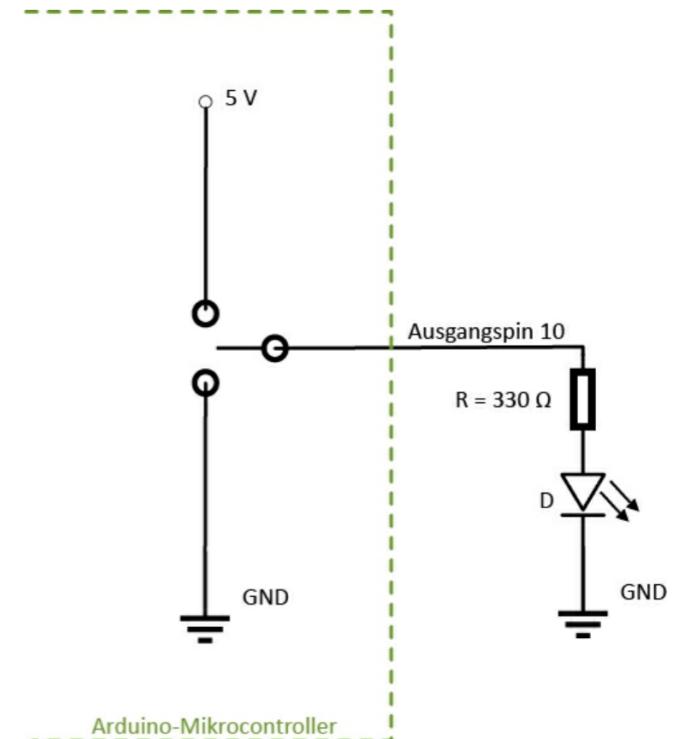
- Breadboard



# I/O Pins

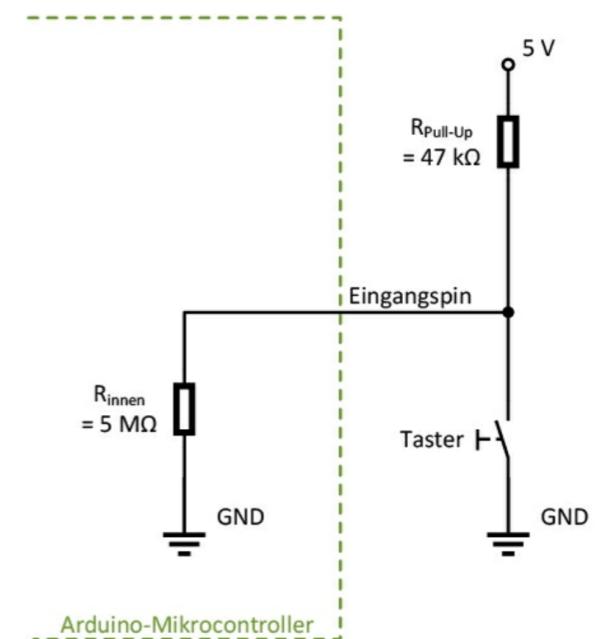
- Digital Outputs

- Switches pin between LOW and HIGH
- Be careful of maximum current
- E.g. trigger an LED



- Digital Inputs

- Sense LOW and HIGH
- Be careful that input is always defined.
- E.g. button



# GPIO Handling

```
esp_err_t gpio_set_level(gpio_num_t gpio_num, uint32_t level)
// level is 0 or 1

int gpio_get_level(gpio_num_t gpio_num)

esp_err_t gpio_set_direction(gpio_num_t gpio_num, gpio_mode_t mode)
//GPIO_MODE_INPUT, GPIO_MODE_OUTPUT
//pins 34 - 39 can only be used for input

esp_err_t gpio_pullup_en  (gpio_num_t gpio_num)
esp_err_t gpio_pullup_dis (gpio_num_t gpio_num)
esp_err_t gpio_pulldown_en (gpio_num_t gpio_num)
esp_err_t gpio_pulldown_dis(gpio_num_t gpio_num)

//pins 34 - 39 do not have software pullup/pulldown resistors
```

# Visual Studio

- Visual Studio is an integrated development environment on Windows, Linux, Mac
- Microsoft
- Market place with extensions with tools for various programming languages
- Espressif ESP32 extension
- Configuration files in .vscode
  - *settings.json*: paths, ESP32 port, baud rate, ...
  - *c\_cpp\_properties.json*: settings for intellisense
  - *launch.json*: settings for debugging
  - *tasks.json*: define tasks that can be run from the menu
- Blink source code comes with configuration files for visual studio
  - replace user specific paths in *settings.json*

# Blink Example

```
1 #include <stdio.h>
2 #include "freertos/FreeRTOS.h"
3 #include "freertos/task.h"
4 #include "driver/gpio.h"
5 #include "sdkconfig.h"
6 #include "esp_log.h"
7
8 #define BLINK_GPIO CONFIG_BLINK_GPIO
9
10 static const char *TAG = "BLINK";
11
12 void app_main(void){
13     //esp_log_level_set("BLINK", ESP_LOG_ERROR);
14     esp_log_level_set("BLINK", ESP_LOG_INFO);
15
16     gpio_set_direction(BLINK_GPIO, GPIO_MODE_OUTPUT);
17
18     while(1) {
19         /* Blink on (output high) */
20         ESP_LOGI(TAG, "Turning on the LED");
21         gpio_set_level(BLINK_GPIO, 1);
22         vTaskDelay(1000 / portTICK_PERIOD_MS);
23         /* Blink off (output low) */
24         ESP_LOGI(TAG, "Turning off the LED");
25         gpio_set_level(BLINK_GPIO, 0);
26         vTaskDelay(1000 / portTICK_PERIOD_MS);
27     }
28 }
```

# Demo Blink Basic

1. cd into root directory of the example
2. ls /dev/cu.usb-\*
3. export ESPPORT=/dev/cu.usbserial-0215EAEE
4. idf.py menuconfig: on board led pin 19
5. idf.py build
6. idf.py flash
7. idf.py monitor
8. Exit monitor ctrl-]
9. idf.py menuconfig: led pin 32
10. idf.py build flash monitor
11. ctrl-] to close the monitoring

# Assignment for next week

1. Install ESP IDF V4.4
2. Download blink sources from moodle. It is a modified version of the blink example .../esp-idf/examples/get-started/blink
3. Try on board LED and external LED with resistor
4. Develop a version that polls a button. Press button->LED on
  - Configure GPIO with pullup or pulldown resistor
5. Make the length and frequency configurable through idf.py menuconfig

# Group Building

# Schedule

# Next Meeting

- Bring your hardware and demonstrate the blink example

# Questions