

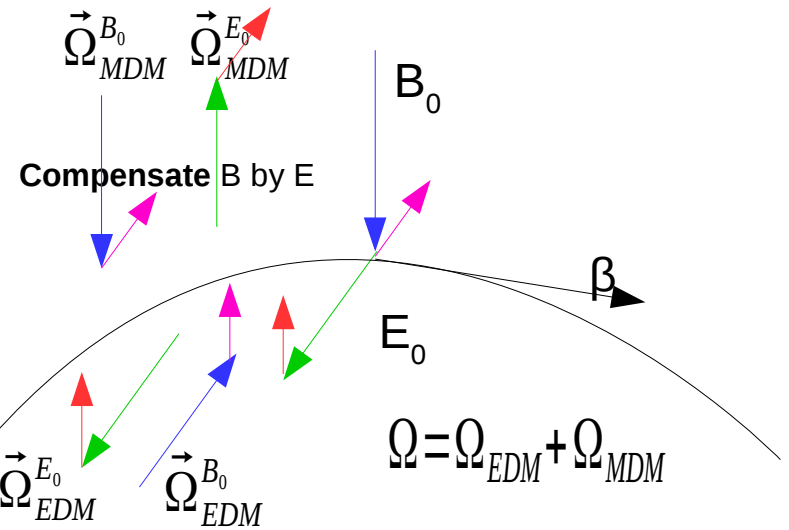
Misalignment

Principally unfixable in a deuteron ring (Lorentz force)

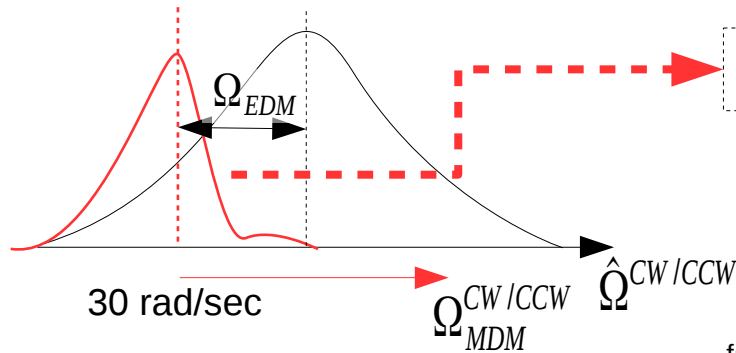
Non-zero
MDM
precession

Frequency
measurement

CW/CCW
comparison



$$\hat{\Omega}_{EDM} = \frac{\hat{\Omega}^{CW} + \hat{\Omega}^{CCW}}{2} + \frac{\Omega_{MDM}^{CW} - \Omega_{MDM}^{CCW}}{2}$$



solenoid

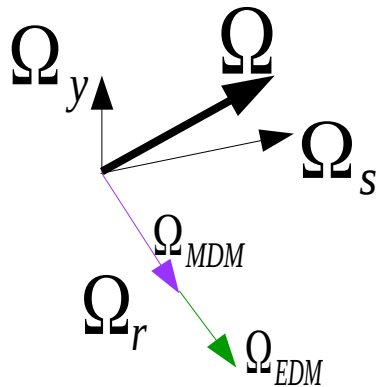
$$\Omega_y \equiv 0$$

Calibration
in the **rs** plane

$$\vec{\Omega}_{MDM} = a_0 \underbrace{(\gamma G) \vec{B}}_{\vec{\Omega}_{MDM}^B} - a_1 \underbrace{(\gamma G) \vec{\beta} \times \vec{E}}_{\vec{\Omega}_{MDM}^E}$$

$$\vec{\Omega}_{EDM} = b_0 \underbrace{\vec{\beta} \times \vec{B}}_{\vec{\Omega}_{EDM}^B} + b_1 \underbrace{\vec{E}}_{\vec{\Omega}_{EDM}^E}$$

Cross-correlation



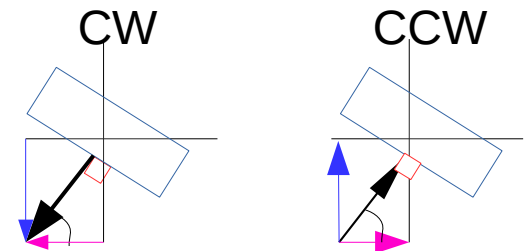
fading
effect

$$\Omega_{rs}(\gamma_{eff})$$

measure

adjust

B_y



Geometry fixes $B_y : B_r$
reproduce **error** by reproducing
signal