

Frequency Domain Method to Search for the Deuteron Electric Dipole Moment in a Storage Ring Environment

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Abstract

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1. Introduction

Spin rotations belong to the Spin(3) group, which is isomorphic to SU(2).

Rotations in SU(2). Rotation by angle ψ about direction \vec{n}

$$R_{\vec{n}}(\psi) = \exp \left[-i \frac{\psi}{2} (\vec{n} \cdot \vec{\sigma}) \right],$$

where $\vec{\sigma}$ is the Pauli matrix vector.

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5 1.1. General spin rotation matrices

6 Denote

- 7 • $(\Theta^{mi}, \bar{n}_{mi})$ from machine imperfections;
- 8 • $(\Theta^+, \bar{n}_{sol})$ for the $+\Delta$ solenoidal field;
- 9 • $(\Theta^-, -\bar{n}_{sol})$ for the $-\Delta$ solenoidal field.

$$\begin{aligned} R^{+\Delta} &= \exp \left[-i \left(\frac{\Theta^{mi}}{2} (\bar{n}_{mi} \cdot \vec{\sigma}) + \frac{\Theta^+}{2} (\bar{n}_{sol} \cdot \vec{\sigma}) \right) \right] \\ &= \exp \left[-\frac{i}{2} (\Theta^{mi} \bar{n}_{mi} + \Theta^+ \bar{n}_{sol}) \cdot \vec{\sigma} \right], \end{aligned} \quad (1)$$

$$R^{-\Delta} = \exp \left[-\frac{i}{2} (\Theta^{mi} \bar{n}_{mi} - \Theta^- \bar{n}_{sol}) \cdot \vec{\sigma} \right], \quad (2)$$

10 2. Preliminary analytic of the Spin Wheel method

11 In SW we posit

$$\left(\vec{\Omega}_{MDM}^{+\Delta} \cdot \hat{x} \right) = - \left(\vec{\Omega}_{MDM}^{-\Delta} \cdot \hat{x} \right). \quad (3)$$

12 The spin precession angular velocity vector can be expressed via spin tune
13 and invariant spin axis as

$$\vec{\Omega}_{spin} = \frac{2\pi}{\tau_{ring}} \cdot \nu \cdot \bar{n},$$

14 hence

$$\nu^{+\Delta} (\bar{n}_{+\Delta} \cdot \hat{x}) + \nu^{-\Delta} (\bar{n}_{-\Delta} \cdot \hat{x}) = 0 \quad (4)$$

15 From $\Delta\Theta = \tau\Delta\Omega$ and $\Delta\Omega_x^{MDM} = \frac{q}{m}GB_x$, and **assuming**

$$B_{sol}^{\pm} \tau_{sol} = \langle B_{sol}^{\pm} \rangle \tau_{ring} : \quad (5)$$

16

$$\begin{cases} \Theta^+ &= \tau_{sol} \frac{q}{m} G B_{sol}^+ \stackrel{(5)}{=} \tau_{ring} \frac{q}{m} G \langle B_{sol}^+ \rangle, \\ \Theta^- &= \tau_{sol} \frac{q}{m} G B_{sol}^- \stackrel{(5)}{=} \tau_{ring} \frac{q}{m} G \langle B_{sol}^- \rangle. \end{cases} \quad (6)$$

17 **Remark 1.** Assumption (5) is **required** if we want to obtain B_{sol}^\pm from
 18 equations of group (11).

19 From eqs (1) and (2):

$$\begin{cases} \Theta^{mi} \bar{n}_{mi} + \Theta^+ \bar{n}_{sol} = \nu^{+\Delta} \bar{n}_{+\Delta}, \\ \Theta^{mi} \bar{n}_{mi} - \Theta^- \bar{n}_{sol} = \nu^{-\Delta} \bar{n}_{-\Delta}. \end{cases} \quad (7)$$

20 Substituting eq (7) into (4), and assuming $\bar{n}_{sol} = \hat{x}$:

$$2\Theta^{mi}(\bar{n}_{mi} \cdot \hat{x}) + (\Theta^+ - \Theta^-) = 0. \quad (8)$$

21 **Assuming**¹

$$\Theta^{mi} = \tau_{ring} \cdot \frac{q}{m} G \cdot \langle B_x \rangle^{mi}, \quad (9)$$

22 from (8) and (5) obtain:

$$2\langle B_x \rangle^{mi} + (\langle B_{sol}^+ \rangle - \langle B_{sol}^- \rangle) = 0. \quad (10)$$

23 From eq (9) in Koop2015, assuming in the $+\Delta$ case the machine imper-
 24 fections and solenoid fields are co-aligned, in the $-\Delta$ anti-aligned:

$$\begin{cases} \Delta^+ = \frac{\beta_1 - \beta_2}{\langle G_z \rangle} \langle B_x \rangle = \frac{\beta_1 - \beta_2}{\langle G_z \rangle} (\langle B_x \rangle^{mi} + \langle B_{sol}^+ \rangle), \\ \Rightarrow \langle B_{sol}^+ \rangle = \frac{\langle G_z \rangle}{\beta_1 - \beta_2} \Delta^+ - \langle B_x \rangle^{mi}; \\ \Delta^- = \frac{\beta_1 - \beta_2}{\langle G_z \rangle} \langle B_x \rangle = \frac{\beta_1 - \beta_2}{\langle G_z \rangle} (\langle B_x \rangle^{mi} - \langle B_{sol}^- \rangle), \\ \Rightarrow -\langle B_{sol}^- \rangle = \frac{\langle G_z \rangle}{\beta_1 - \beta_2} \Delta^- - \langle B_x \rangle^{mi}. \end{cases} \quad (11)$$

25 Substituting this into (10):

$$2\langle B_x \rangle^{mi} + \left(\frac{\langle G_z \rangle}{\beta_1 - \beta_2} [\Delta^+ - \Delta^-] - 2\langle B_x \rangle^{mi} \right) = 0.$$

26 In the original method, we are to make

$$\Delta^- = -\Delta^+, \quad (12)$$

¹This is a generous assumption implying that $\bar{n}_{mi} = \hat{x}$; i.e., this is **not** a non-commutativity-based argument; we assume all spin rotations commute.

so the term in the square brackets is zero, and we are left with

$$(1 - 1) \langle B_x \rangle^{mi} = 0. \quad (13)$$

So, seems that SW works, but we did two important assumptions here: (a) commutativity (in order to get eq (9)), and (b) “averaging” of B_{sol} over the ring (in order to get eq (5) and remove the τ_{sol}/τ_{ring} from (10)).

Remark 2. If we don’t use (9) (but still use (5) in order to obtain B_{sol}^\pm from group (11)), then eq (13) becomes

$$\Theta^{mi} (\bar{n}_{mi} \cdot \hat{x}) - \frac{q}{m} G \cdot \tau_{ring} \langle B_x \rangle^{mi} = 0, \quad (14)$$

which is not very informative.

Remark 3. To check that eq (14) is correct, assume (9). Then

$$\frac{q}{m} G \tau_{ring} \langle B_x \rangle^{mi} (\bar{n}_{mi} \cdot \hat{x}) - \frac{q}{m} G \tau_{ring} \langle B_x \rangle^{mi} = 0,$$

and hence

$$\bar{n}_{mi} \cdot \hat{x} = 1,$$

which is implied by machine imperfection spin rotations adding up commutatively.

Remark 4. In general, since

$$\Theta^{mi} = \tau_{ring} \cdot \frac{q}{m} G \sqrt{\langle B_x^{mi} \rangle^2 + \langle B_y^{mi} \rangle^2 + \langle B_z^{mi} \rangle^2},$$

eq (14) implies that

$$\begin{aligned} (\bar{n}_{mi} \cdot \hat{x}) &= \frac{\frac{q}{m} G \tau_{ring} \langle B_x \rangle^{mi}}{\Theta^{mi}} \\ &= \frac{\langle B_x^{mi} \rangle}{\sqrt{\langle B_x^{mi} \rangle^2 + \langle B_y^{mi} \rangle^2 + \langle B_z^{mi} \rangle^2}}. \end{aligned} \quad (15)$$

Which is correct.

Conclusion. In view of Remark 4, since eq (14) implies a valid statement, our conclusion is that the SW method resists the argument from non-commutativity.

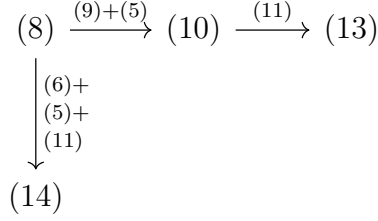


Figure 1: Argument diagram.

3. Assumptions of the Spin Wheel method

Orbital dynamics. Koop2015 eq (7) (henceforth referred to as K(7)) and

$$\langle E_z \rangle = \langle E_z(0) \rangle + \langle G_z \rangle \cdot z \quad (\text{K}\langle E_z \rangle)$$

$$\rightarrow \langle z \rangle = \frac{\langle E_z(0) \rangle}{\langle G_z \rangle} - \frac{\beta}{\langle G_z \rangle} \cdot \langle B_x \rangle \quad (16)$$

$$\rightarrow \Delta = \frac{\beta_1 - \beta_2}{\langle G_z \rangle} \langle B_x \rangle. \quad (17)$$

This is as far as the argument from the non-linearity of the closed orbit shift dependence on the magnetic field is concerned. So long as we believe K(7) and $\text{K}\langle E_z \rangle$, we must believe K(9), and hence we cannot use that argument.

Spin dynamics. This is the argument from non-commutativity. For this argument cf. eq (14) and Remark 4, and the following conclusion.

4. Argument against the SW method

The three-fold argument against the SW method is as follows (in the order of strength):

- (1) The possibility of measuring the vertical orbit separation of two co-circulating beams at the sensitivity level of 10^{-12} m has not been shown by experiment. **Counter-argument:** there's reference [1] to commercially-available SQUIDS capable of detecting magnetic fields on the order of fT, which is equivalent to the beam separation of 10^{-12} m.

- 60 (2) Even if a SQUID-based BPM is capable of measuring orbit separation
61 to such precision *locally*, the evaluation of the *mean* orbit separation
62 requires multiple local measurements, and is not identical to the local
63 measurement precision.
- 64 (3) Orbital and spin dynamics are independent of each other, meaning that
65 the observables $\vec{\Omega}$ and Δ are not directly related.

66 Regarding part (3) of the above argument: suppose the amplitude a_y of
67 betatron oscillations is on the order of a micro-meter;

68 References

- 69 [1] D. Kawal, “Relative Beam Position Monitors for the pEDM
70 Experiment.” [https://apps.fz-juelich.de/pax/paxwiki/images/a/
71 a9/DKawal_longapp_dmk_20110621.pdf](https://apps.fz-juelich.de/pax/paxwiki/images/a/a9/DKawal_longapp_dmk_20110621.pdf)