

Comparison of Frozen Spin type EDM search methods

Yury Senichev ¹ Alexander Aksentev ^{2,3}

¹Institute for Nuclear Research of RAS

²Forschungszentrum Jülich

³NRNU “MEPhI”

19 February 2019

Considered methods

- ▶ BNL Frozen Spin
- ▶ I.Koop's Spin Wheel
- ▶ Frequency Domain Method

- ▶ Observation of the vertical polarization component¹
 $\Delta P_V \approx P \cdot \omega_{EDM} \cdot t$
- ▶ Cross section asymmetry $\varepsilon_{LR} \approx 5 \cdot 10^{-6}$ for smallest practical values of (horizontal plane) ω_{MDM} ²
- ▶ Challenging task for polarimetry³

¹D. Anastassopoulos et al., *AGS Proposal: Search for a permanent electric dipole moment of the deuteron nucleus at the 10^{-29} e · cm level.* p. 9.

²Ibid., p. 18.

³Mane, “Spin Wheel”, p. 6.

- ▶ Only known first-order systematic effect pertaining to the spin dynamics is the existence of $\langle E_V \rangle \neq 0$ ⁴
- ▶ Error frequency $\omega_{syst} \approx \frac{\mu \langle E_V \rangle}{\beta c \gamma^2}$ changes sign when reversing the beam circulation direction (CW/CCW)⁵
- ▶ However, at practical values of element alignment error, $\omega_{syst} \gg \omega_{EDM}$, hence $P_V = P \frac{\omega_{EDM}}{\omega} \sin(\omega t + \Theta_0) \approx P \omega_{EDM} t$
- * Since it's a Phase Domain method, it's vulnerable to the geometric phase error⁶

⁴D. Anastassopoulos et al., *AGS Proposal: Search for a permanent electric dipole moment of the deuteron nucleus at the 10^{-29} e · cm level.* p. 10.

⁵Ibid., p. 11.

⁶V. Anastassopoulos et al., *A Storage Ring Experiment to Detect a Proton Electric Dipole Moment*, p. 6.

Geometric phase error

- ▶ Caused by the non-commutativity of rotations
- ▶ In “Frequency Domain Logic” it means the absence of a definite orientation of the spin precession axis (SPA)
 - * Call that the *3D Frozen Spin* state

FS-type methodology

Conditions of success

- ▶ One must always have a definite direction of the SPA
- ▶ Frequency (not phase) must be measured

These conditions are satisfied by two methods:

- ▶ Spin Wheel
- ▶ Frequency Domain

Spin Wheel

The Spin Wheel is great; it satisfies both success conditions.

- ▶ Apply a radial magnetic field of strength B_x sufficient to turn the spin vector about the \hat{x} -axis with a frequency of 1 Hz
- ▶ $\omega_{B_x} \parallel \omega_{EDM}$ hence $\omega_{net} \propto \omega_{EDM} + \omega_{B_x}$ ⁷
- ▶ EDM effect $\hat{\omega}_{EDM} = \frac{1}{2} [\omega_{net}(+B_x) + \omega_{net}(-B_x)]$
- ▶ Value of B_x is calibrated by measuring the vertical orbit splitting

⁷Mane, “Spin Wheel”, p. 6.

Spin Wheel

The good, the bad, the ugly

- ▶ Higher polarization growth rate greatly simplifies the task for polarimetry
- ▶ Magnetic field calibration by means of orbit split measurements seems unfeasible
- ▶ Element misalignment-induced error is not accounted for:

$$\begin{aligned}\hat{\omega}_{EDM} &= \frac{1}{2} (\omega_{EDM} + \cancel{\omega_{B_X}} + \omega_{mis} + \omega_{EDM} - \cancel{\omega_{B_X}} + \omega_{mis}) \\ &= \omega_{EDM} + \omega_{mis}\end{aligned}$$

Frequency domain method

This methodology has been developed specifically to deal with misalignment error.

- ▶ No reason to apply an external B-field; misalignment B_X -field provides a sufficiently fast wheel
- ▶ The FS condition ensures that $\omega_{net} \propto \omega_{EDM} + \omega_{mis}$
- ▶ The same EDM estimator $\hat{\omega}_{EDM} = \frac{\omega_{net}(+B_X) + \omega_{net}(-B_X)}{2}$
- ▶ To flip the sign of B_X one must reverse the guide field polarity (CW/CCW comeback)
- ▶ The value of B_X is calibrated via horizontal plane precession frequency