

Beam current resolution

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July 24, 2017

In the transmission-experiment method of determining a double-polarized observable, one estimates the beam's rate of decay by fitting a linear model to the log-transformed beam current measurements:

$$\begin{aligned}\tilde{I}_t &= I_0 \cdot e^{-\nu\sigma\Theta \cdot t} + \epsilon_t^I = I_t + \epsilon_t^I, \\ \ln \tilde{I}_t &= \ln I_0 + \beta t + \delta_t^I,\end{aligned}$$

where ν is the circulation frequency, $\sigma = \sigma_0 (AP_y^b P_{xz}^t + A_{y,y} P_y^b P_y^t + \dots)$ is the total scattering cross section, Θ is the target thickness, ϵ_t^I is the measurement error at time t , I_t is the actual beam current, \tilde{I}_t is the measured beam current, and $\delta_t^I = \epsilon_t^I / I_t$. The observable A can then be estimated as a difference statistic of the slopes from a pair of appropriate polarization cases, and its variance will be proportional to the sum of the variances of the constituent slope estimates: $\sigma [\hat{A}] = C\sqrt{2} \cdot \sigma [\hat{\beta}]$.

For the mean statistic, its precision depends on the precision of the slope estimate $\sigma [\hat{\beta}]$ as in

$$\sigma [\langle \hat{A} \rangle] = \frac{\sigma [\hat{A}]}{\sqrt{N}} = \sqrt{2} \sqrt{\frac{h}{H}} \cdot \sigma [\hat{A}] = 2C \sqrt{\frac{h}{H}} \cdot \sigma [\hat{\beta}], \quad (1)$$

where H is the beam time, h the cycle length, and so the maximum number of estimate pairs $N = H/2h$.

Under the Gauss-Markov conditions, the Ordinary Least Squares estimator of the slope is zero-bias, minimum-variance, and has a standard error of

$$\sigma [\hat{\beta}] = \frac{\sigma [\delta^I]}{\sqrt{\sum_{k=1}^K (t_k - \langle t \rangle)^2}}, \quad (2)$$

where $\sigma [\delta^I]$ is termed the measurement resolution, K is the sample size, and t_k is the measurement time. For samples taken uniformly in time with step Δt , at sample sizes $K = h/\Delta t \gg 1$, the denominator can be expressed in physical terms as

$$\sqrt{\sum_{k=1}^K (t_k - \langle t \rangle)^2} \approx \frac{h\sqrt{h}}{2\sqrt{3}\sqrt{\Delta t}},$$

and hence

$$\sigma [\hat{\beta}] = 2\sqrt{3} \sqrt{\frac{\Delta t}{h}} \frac{\sigma [\delta^I]}{h}, \quad (3)$$

$$\sigma [\langle \hat{A} \rangle] = 4\sqrt{3}C \cdot \frac{\sqrt{\Delta t}}{h\sqrt{H}} \cdot \sigma [\delta^I], \quad (4)$$

from which the required measurement resolution can be estimated for the given precision $\sigma [\langle \hat{A} \rangle]$, beam time H , and cycle duration h .

1 Resolution lower bound

If, during measurement, the beam current slope varies (due to such factors as the variation of the target thickness, or drifting current transformer offset), that variation will influence the standard error of the estimate in accordance with the law of total variance:

$$\sigma^2 [\hat{\beta}] = \mathbb{E}_\beta [\sigma^2 [\hat{\beta} | \beta]] + \sigma_\beta^2 [\mathbb{E} [\hat{\beta} | \beta]]. \quad (5)$$

Table 1: Parameter values (June 2016)

Parameter	Symbol	Value	Dimension
Beam revolution frequency	ν	0.79	MHz
Target thickness	Θ	$1.1 \cdot 10^{14}$	at \cdot cm $^{-2}$
Target polarization	P^t	0.88	–
Beam spin up-down polarization difference	ΔP	1.48	–
pd scattering cross section	σ_0^a	70	mb
Slope-to-Asymmetry proportionality coefficient	C	$1.26 \cdot 10^5$	sec

^a From Particle Data Group http://pdg.lbl.gov/2016/hadronic-xsections/rpp2014-pd_pn_plots.pdf

Here,

$$\begin{aligned} \mathbb{E} [\hat{\beta} | \beta] &= \beta, \\ \sigma^2 [\hat{\beta} | \beta] &= 12 \frac{\Delta t}{h} \frac{\sigma^2 [\delta^I]}{h^2}, \end{aligned} \quad (\text{eq. (3)})$$

and hence

$$\sigma^2 [\langle \hat{A} \rangle] = \frac{4C^2}{H} \left(12\Delta t \cdot \frac{\sigma^2 [\delta^I]}{h^2} + h \cdot \sigma^2 [\beta] \right). \quad (6)$$

In the last equation, the first term describes the statistical precision of the estimate, the second its accuracy. The accuracy term constrains our ability to improve precision by reducing measurement resolution; this can be observed in Figure 1.

From equation (6), the best variance is achieved at

$$h_{best} = \sqrt[3]{24 \cdot \Delta t} \left(\frac{\sigma^2 [\delta^I]}{\sigma^2 [\beta]} \right)^{1/3}. \quad (7)$$

In Table 2, cycle durations for the given values of $\sigma^2 [\beta] = 10^{-15} \text{ sec}^{-2}$ and $\sigma [\delta^I]$ are summarized.

Table 2: Best achievable precision of \hat{A} , and the corresponding cycle time for a given resolution.

$\sigma [\delta^I]$	h_{best} (min)	$\sigma [\langle \hat{A} \rangle]$
$5 \cdot 10^{-3}$	141	$8 \cdot 10^{-4}$
$1 \cdot 10^{-3}$	48	$3 \cdot 10^{-4}$
$5 \cdot 10^{-4}$	30	$3 \cdot 10^{-4}$
$1 \cdot 10^{-4}$	10	$2 \cdot 10^{-4}$
$5 \cdot 10^{-5}$	7	$1 \cdot 10^{-4}$

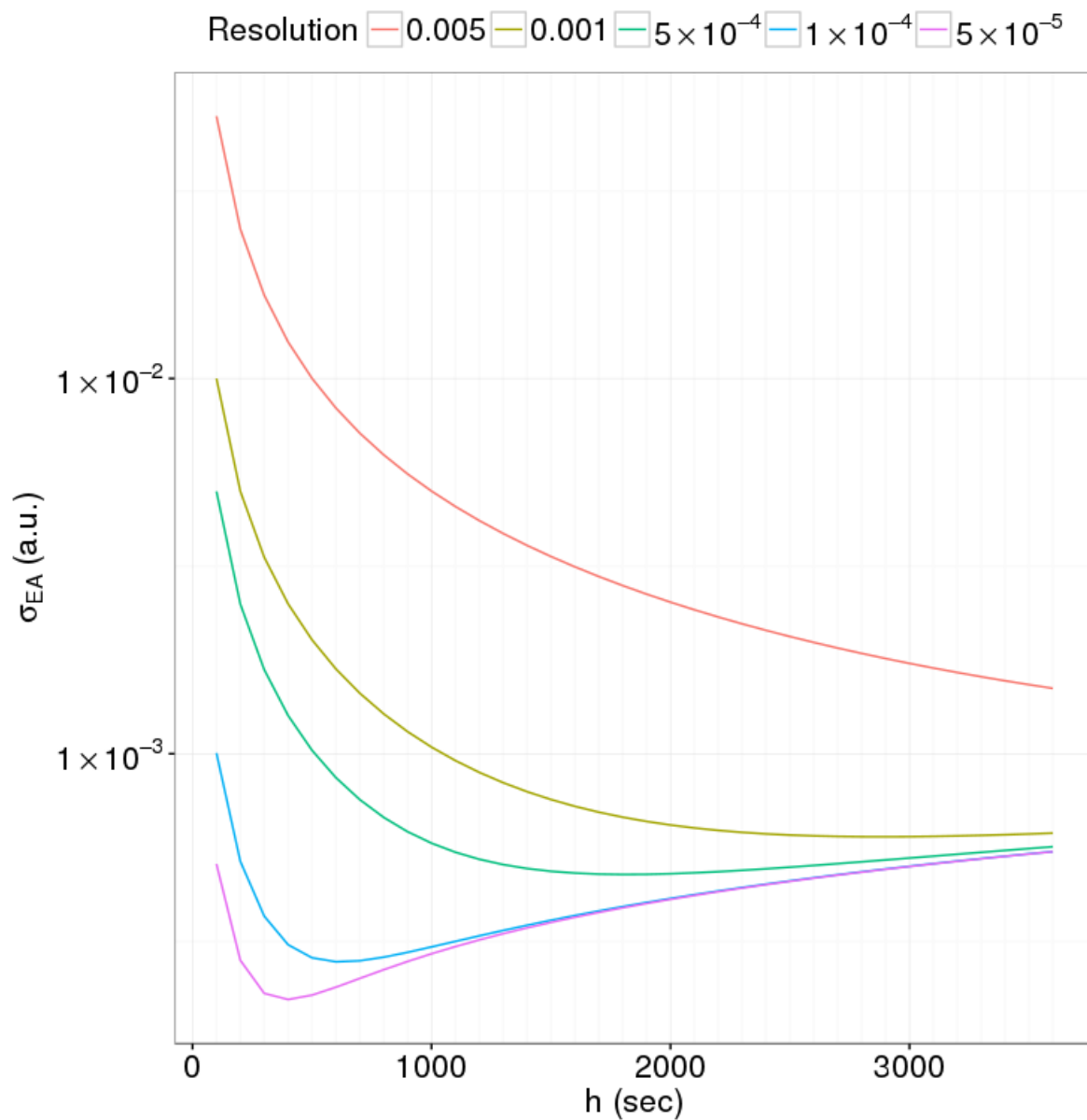


Figure 1: The standard error of the mean A estimate as a function of cycle length when the inherent slope variation $\sigma^2[\beta] = 10^{-15}$. The inherent variation limits the accuracy of the estimate.