# Approximations for two-dimensional discrete scan statistics in some dependent models

#### Alexandru Amărioarei Cristian Preda

Laboratoire de Mathématiques Paul Painlevé Département de Probabilités et Statistique Université de Lille 1, INRIA Modal Team

16<sup>th</sup> SPSR Conference 26 April, 2013, București, România





- Introduction
  - Framework and Model
  - Previous Work
- Description of the method
  - Main Idea and Tools
  - The Approximation
- Error Bound
  - Approximation Error
  - Simulation Error
- Illustrative Example
  - Description of the Example
- References



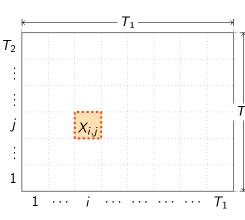


- Introduction
  - Framework and Model
  - Previous Work
- Description of the method
  - Main Idea and Tools
  - The Approximation
- Error Bound
  - Approximation Error
  - Simulation Error
- 4 Illustrative Example
  - Description of the Example
- 5 References





### Introducing the General Model



Let  $T_1$ ,  $T_2$  be positive integers

- Rectangular region  $\mathcal{R} = [0, T_1] \times [0, T_2]$
- $(X_{ij})_{\substack{1 \leq i \leq T_1 \\ 1 \leq j \leq T_2}}$  integer r.v.'s
  - Bernoulli( $\mathcal{B}(1,p)$ )
  - Binomial( $\mathcal{B}(n,p)$ )
  - Poisson( $\mathcal{P}(\lambda)$ )
- $X_{ij}$  number of observed events in the elementary subregion  $r_{ii} = [i-1, i] \times [i-1, j]$





### Introducing the Block-Factor Model

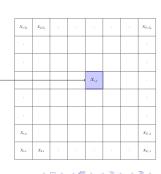
Consider for  $1 \le i \le T_1, 1 \le j \le T_2$  the following block-factor model:

$$X_{i,j} = f\big(Y_{i,j}, Y_{i,j-1}, Y_{i,j+1}, Y_{i-1,j-1}, Y_{i-1,j}, Y_{i-1,j+1}, Y_{i+1,j-1}, Y_{i+1,j}, Y_{i+1,j+1}\big),$$

with  $f: \mathbb{R}^9 \to \mathbb{R}_+$  and i.i.d. sequence

$$\{Y_{i,j} \mid 0 \le i \le T_1 + 1, 0 \le j \le T_2 + 1\}$$

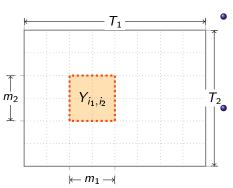
$Y_{0,T_2+1}$	$Y_{1,T_2+1}$						$Y_{T_1+1,T_2+1}$
			$Y_{i-1,j+1}$	$Y_{i,j+1}$	$Y_{i+1,j+1}$		
			$Y_{i-1,j}$	$Y_{i,j}$	$Y_{i+1,j}$		
			$Y_{i-1,j-1}$	$Y_{i,j-1}$	$Y_{i+1,j-1}$		
$Y_{0,1}$							$Y_{\Gamma_1+1,1}$
$Y_{0,0}$	$Y_{1,0}$		-		i.	-	$Y_{T_1+1,0}$





## Defining the Scan Statistic

Let  $m_1, m_2$  be positive integers



• Define for 
$$1 \le i_j \le T_j - m_j + 1$$
,

$$Y_{i_1 i_2} = \sum_{i=i_1}^{i_1+m_1-1} \sum_{j=i_2}^{i_2+m_2-1} X_{ij}$$

 $\frac{T_2}{1}$  The two dimensional scan statistic,

$$S_{m_1,m_2}(T_1,T_2) = \max_{\substack{1 \leq i_1 \leq T_1 - m_1 + 1 \\ 1 \leq i_2 \leq T_2 - m_2 + 1}} Y_{i_1 i_2}$$

 Used for testing the null hypotheses of randomness against the alternative hypothesis of clustering



- Introduction
  - Framework and Model
  - Previous Work
- - Main Idea and Tools
  - The Approximation
- - Approximation Error
  - Simulation Error
- Illustrative Example
  - Description of the Example





Bucuresti 2013

### Problem and related results

#### Problem

Approximate the distribution of two dimensional discrete scan statistic for the block-factor model

$$\mathbb{P}\left(S_{m_1,m_2}(T_1,T_2)\leq n\right).$$

- Dependent model: no results!
- Independent model:
  - No exact formulas
  - For Bernoulli case:
    - product type approximations (Boutsikas and Koutras 2000)
    - Poisson approximations (Chen and Glaz 1996)
    - bounds (Boutsikas and Koutras 2003)
  - For binomial and Poisson cases: (Glaz 2009)
    - Product type approximation
    - Lower bound





#### Literature







Scan 2d block factor







- Introduction
  - Framework and Model
  - Previous Work
- Description of the method
  - Main Idea and Tools
  - The Approximation
- Error Bound
  - Approximation Error
  - Simulation Error
- 4 Illustrative Example
  - Description of the Example
- 6 References





### Key Idea

Haiman(2000) proposed a different approach

#### Main Observation

The scan statistic r.v. can be viewed as a maximum of a sequence of 1-dependent stationary r.v..

- The idea:
  - discrete and continuous one dimensional scan statistic: Haiman (2000,2007)
  - discrete and continuous two dimensional scan statistic: Haiman and Preda (2002,2006)
  - discrete three dimensional scan statistic: Amarioarei (2013)





# Writing the Scan as an Extreme of 1-Dependent R.V.'s

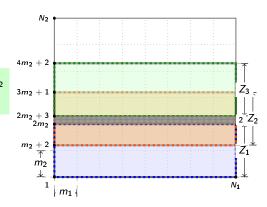
Let 
$$T_j = (L_j + 1)(m_j + 1) - 2$$
,  $j \in \{1, 2\}$  positive integers

• Define for  $I \in \{1, 2, \dots, L_2\}$ 

$$Z_{I} = \max_{\substack{1 \leq i_{1} \leq L_{1}(m_{1}+1) \\ (I-1)(m_{2}+1)+1 \leq i_{2} \leq I(m_{2}+1)}} Y_{i_{1}i_{2}}$$

- $(Z_I)_I$  is 1-dependent and stationary
- Observe

$$S_{m_1,m_2}(T_1,T_2) = \max_{1 \le l \le L_2} Z_l$$







#### Main Tool

Let  $(Z_i)_{i>1}$  be a strictly stationary 1-dependent sequence of r.v.'s and let  $q_m = q_m(x) = \mathbb{P}(\max(Z_1, \dots, Z_m) \le x)$ , with  $x < \sup\{u | \mathbb{P}(Z_1 \le u) < 1\}$ .

Main Theorem (Haiman 1999, Amarioarei 2012)

For x such that  $\mathbb{P}(Z_1 > x) = 1 - q_1 \le \alpha < 0.1$  and m > 3 we have

$$egin{split} \left|q_m - rac{6(q_1 - q_2)^2 + 4q_3 - 3q_4}{(1 + q_1 - q_2 + q_3 - q_4 + 2q_1^2 + 3q_2^2 - 5q_1q_2)^m}
ight| & \leq \Delta_1(1 - q_1)^3, \ \left|q_m - rac{2q_1 - q_2}{[1 + q_1 - q_2 + 2(q_1 - q_2)^2]^m}
ight| & \leq \Delta_2(1 - q_1)^2, \end{split}$$

- $\Delta_1 = \Delta_1(\alpha, q_1, m) = \Gamma(\alpha) + mK(\alpha)$
- $\Delta_2 = mE(\alpha, q_1, m) = m \left[1 + \frac{3}{m} + K(\alpha)(1 q_1) + \frac{\Gamma(\alpha)(1 q_1)}{m}\right]$ .





- Introduction
  - Framework and Model
  - Previous Work
- Description of the method
  - Main Idea and Tools
  - The Approximation
- 3 Error Bound
  - Approximation Error
  - Simulation Error
- 4 Illustrative Example
  - Description of the Example
- 6 References





### First Step Approximation

#### Using Main Theorem we obtain

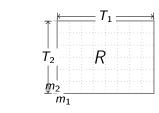
- Define  $Q_2=\mathbb{P}(Z_1\leq k)$   $Q_3=\mathbb{P}(Z_1\leq k,Z_2\leq k)$
- If  $1-Q_2 \leq \alpha_1 <$  0.1 the (first) approximation

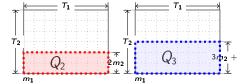
$$\mathbb{P}(S \le k) \approx \frac{2Q_2 - Q_3}{\left[1 + Q_2 - Q_3 + 2(Q_2 - Q_3)^2\right]^{L_2}}$$

where 
$$S = S_{m_1, m_2}(T_1, T_2)$$

Approximation error

$$L_2E(\alpha_1,L_2)(1-Q_2)^2$$









### Second Step Approximation

• For  $s \in \{1, 2, \dots, L_1\}$ 

$$Z_s^{(2)} = \max_{\substack{(s-1)(m_1+1)+1 \leq i_1 \leq s(m_1+1) \\ 1 \leq i_2 \leq m_2+1}} Y_{i_1 i_2}$$

• Define 
$$Q_{22}=\mathbb{P}(Z_1^{(2)}\leq k)$$
  $Q_{32}=\mathbb{P}(Z_1^{(2)}\leq k,Z_2^{(2)}\leq k)$ 

• Approximation  $(1 - Q_{22} \le \alpha_2)$ 

$$Q_2 pprox rac{2\,Q_{22} - Q_{32}}{\left[1 + Q_{22} - Q_{32} + 2(Q_{22} - Q_{32})^2
ight]^{L_1}}$$

Error

$$L_1E(\alpha_2,L_1)(1-Q_{22})^2$$

• For  $s \in \{1, 2, \dots, L_1\}$ 

$$Z_s^{(3)} = \max_{\substack{(s-1)(m_1+1)+1 \leq i_1 \leq s(m_1+1) \\ 1 \leq i_2 \leq 2(m_2+1)}} Y_{i_1 i_2}$$

$$Q_3 = \mathbb{P}\left(\max_{1 \le l \le L_1} Z_s^{(3)} \le k\right)$$

• Define 
$$Q_{23} = \mathbb{P}(Z_1^{(3)} \le k)$$
  $Q_{33} = \mathbb{P}(Z_1^{(3)} \le k, Z_2^{(3)} \le k)$ 

• Approximation  $(1 - Q_{23} \le \alpha_2)$ 

$$Q_3 pprox rac{2Q_{23} - Q_{33}}{\left[1 + Q_{23} - Q_{33} + 2(Q_{23} - Q_{33})^2\right]^{L_1}}$$

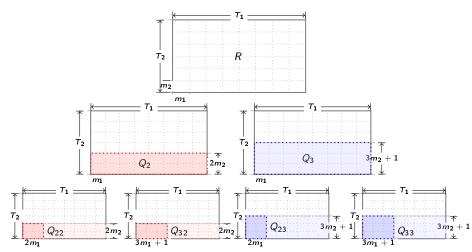
Error

$$L_1E(\alpha_2,L_1)(1-Q_{23})^2$$





### Illustration of the Approximation Process







- Introduction
  - Framework and Model
  - Previous Work
- Description of the method
  - Main Idea and Tools
  - The Approximation
- Error Bound
  - Approximation Error
  - Simulation Error
- 4 Illustrative Example
  - Description of the Example
- 6 References





### Theoretical Approximation Error

Define for  $s \in \{2,3\}$ 

$$H(x,y,m) = \frac{2x-y}{[1+x-y+2(x-y)^2]^m}, \ \alpha_1 = 1-Q_3, \ \alpha_2 = 1-Q_{23},$$

$$E_1 = E(\alpha_2, L_1), \ E_2 = E(\alpha_1, L_2), \ R_s = H(Q_{2s}, Q_{3s}, L_1),$$

The approximation error

$$E_{app} = L_2 F_2 B_2^2 + L_1 L_2 F_1 \left[ (1 - Q_{22})^2 + (1 - Q_{23})^2 \right]$$

where  $B_2$  is given by

$$B_2 = 1 - R_2 + L_1 F_1 (1 - Q_{22})^2$$





- Introduction
  - Framework and Model
  - Previous Work
- Description of the method
  - Main Idea and Tools
  - The Approximation
- Error Bound
  - Approximation Error
  - Simulation Error
- 4 Illustrative Example
  - Description of the Example
- 6 References





### Simulation Error for Approximation Formula

If ITER is the number of simulations, we can say, at 95% confidence level,

$$\left|Q_{rt} - \hat{Q}_{rt}\right| \le 1.96 \sqrt{\frac{\hat{Q}_{rt}(1-\hat{Q}_{rt})}{ITER}} = \beta_{rt}, \ r, t \in \{2,3\}$$

where  $\hat{Q}_{rt}$  is the simulated value.

Define for  $r \in \{2, 3\}$ ,

$$\hat{Q}_r = H\left(\hat{Q}_{2r}, \hat{Q}_{3r}, L_1\right)$$

The simulation error corresponding to the approximation formula

$$E_{sf} = L_1 L_2 (\beta_{22} + \beta_{23} + \beta_{32} + \beta_{33})$$





### Simulation Error for Approximation Error

#### Introducing

$$\begin{split} &C_{2r} = 1 - \hat{Q}_{2r} + \beta_{2r}, \quad r \in \{2,3\}, \\ &C_{2} = 1 - \hat{Q}_{2} + L_{1}(\beta_{22} + \beta_{32}) + L_{1}F_{1}C_{22}^{2}, \end{split}$$

The simulation error corresponding to the approximation

$$E_{sapp} = L_2 F_2 C_2^2 + L_1 L_2 F_1 \left[ C_{22}^2 + C_{23}^2 \right]$$

The total error

$$E_{total} = E_{app} + E_{sf} + E_{sapp}$$





- - Framework and Model
  - Previous Work
- - Main Idea and Tools
  - The Approximation
- - Approximation Error
  - Simulation Error
- Illustrative Example
  - Description of the Example





### Example Model

Consider for each  $1 \le i \le T_1$  and  $1 \le j \le T_2$ :

$$X_{ij}=\left\{egin{array}{ll} 1, & ext{if } Y_{ij}=1 ext{ and } \sum_{k\in\{-1,0,1\}}Y_{i+k,j+k}\geq 2, \\ 0, & ext{otherwise}. \end{array}
ight.$$

X<sub>ij</sub>'s are dependent Bernoulli r.v.'s with parameter

$$p'=p\left[1-(1-p)^8\right]$$

•  $X_{ij} = 1$  each time when  $Y_{ij} = 1$  and there is at least one success in its neighborhood (horizon one)





### Numerical Results

Table 1:  $\mathbb{P}(S_{m_1,m_2}(T_1,T_2) \le n)$ :  $m_1 = 4, m_2 = 6, T_1 = 53, T_2 = 75, ITER = 10^9$ 

n	Sim	Approx	Eapp	E <sub>sim</sub>	$E_{total}$	Sim	Approx
	Dep	Dep	• •			Indep	Indep
			p = 0.01	p' = 0.0	0077		
2	0.91937	0.91959	0.00351	0.00167	0.00518	0.99956	0.99921
3	0.98750	0.98748	0.00004	0.00046	0.00051	1	0.99999
4	0.99930	0.99915	0.00000	0.00010	0.00010	1	1
5	0.99993	0.99993	0.00000	0.00002	0.00002	1	1
			p = 0.1,	p' = 0.0!	5695	_	
9	0.93423	0.93247	0.00120	0.00111	0.00231	0.99957	0.99941
10	0.98847	0.98780	0.00003	0.00042	0.00045	0.99999	0.99995
11	0.99815	0.99812	0.00000	0.00015	0.00015	1	1
12	0.99971	0.99984	0.00000	0.00004	0.00004	1	1
13	0.99996	0.99999	0.00000	0.00001	0.00001	1	1

Scan 2d block factor

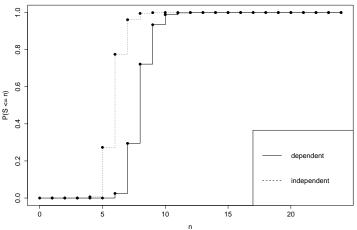


25 / 28



### Graphical Illustration









- 🍆 Glaz, J., Naus, J., Wallenstein, S.: Scan statistic. *Springer* (2001).
- Glaz, J., Pozdnyakov, V., Wallenstein, S.: Scan statistic: Methods and Applications. Birkhauser (2009).
  - Amarioarei, A.: Approximation for the distribution of extremes of one dependent stationary sequences of random variables, arXiv:1211.5456v1 (submitted)
  - Amarioarei, A.: Approximation for the Distribution of Three-dimensional Discrete Scan Statistic, rXiv:1303.3775 (submitted)
- Boutsikas, M.V., Koutras, M.: Reliability approximations for Markov chain imbeddable systems. *Methodol Comput Appl Probab* **2** (2000), 393–412.
- Boutsikas, M. and Koutras, M. Bounds for the distribution of two dimensional binary scan statistics, Probability in the Engineering and Information Sciences, 17, 509–525, 2003.

- Chen, J. and Glaz, J. *Two-dimensional discrete scan statistics*, Statistics and Probability Letters 31, 59–68, 1996.
- Haiman, G.: First passage time for some stationary sequence. Stoch Proc Appl 80 (1999), 231–248.
- Haiman, G.: Estimating the distribution of scan statistics with high precision. *Extremes* **3** (2000), 349–361.
- Haiman, G., Preda, C.: A new method for estimating the distribution of scan statistics for a two-dimensional Poisson process. *Methodol Comput Appl Probab* 4 (2002), 393–407.
- Haiman, G., Preda, C.: Estimation for the distribution of two-dimensional scan statistics. *Methodol Comput Appl Probab* 8 (2006), 373–381.
- Haiman, G.: Estimating the distribution of one-dimensional discrete scan statistics viewed as extremes of 1-dependent stationary sequences. J. Stat Plan Infer 137 (2007), 821–828.