

Implementation of Parallelization

SIMD/SIMT & Multithreading: Numba (with CUDA), OpenMP,
Python Threading & PThreads

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May 15, 2025



Outline

1 OpenMP (SIMD & Threads)

2 Python/threading

3 POSIX Threads





(SIMD & Threads)



OpenMP - Goals



Standardization provide standard for variety of platforms/shared-mem architectures



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Portability public API, implementations for C, C++, Fortran



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- Supported/shipped with various compilers for various platforms (e.g. Intel and GNU compilers for Linux), i.e. to compile simply add option:

e.g. `gcc -fopenmp`

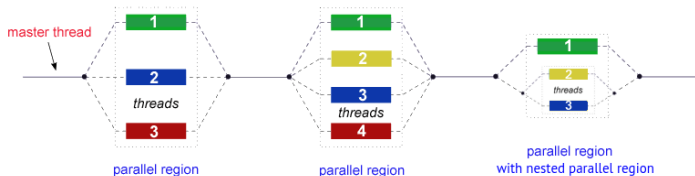


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- uses a form-join model



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We will focus here on C/C++ syntax, FORTRAN syntax slightly different:

```
#pragma omp [simd] <directive name> [<clauses>]    (C/C++)  
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Used for:

- Defining parallel regions: requesting vectorization or spawning threads
- Specifying strip-mining / inter-thread distribution strategy of loop iterations or sections of code
- Serializing sections of code (e.g. for access to I/O or shared variables)
- Synchronizing threads

You can find a reference sheet for the C/C++ API for OpenMP 4.0 in the source code archive for this workshop.



OpenMP/SIMD: Example

```
void test(const float* A, const float* B, float* C) {  
    #pragma omp simd  
    for (int j = 0; j < N; j++) {  
        for (int i = 0; i < N; i++) {  
            C[i] = A[i] + B[i];  
        }  
    }  
}
```



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        }  
    }  
}
```

icc vectorize.c -qopenmp-simd -no-vec -qopt-report=5

```
LOOP BEGIN at test-vec.c(25,4)  
    remark #15540: loop was not vectorized: auto-vectorization is disabled with  
-no-vec flag  
LOOP END  
  
LOOP BEGIN at test-vec.c(12,15) inlined into test-vec.c(29,4)  
    remark #15305: vectorization support: vector length 4  
    remark #15309: vectorization support: normalized vectorization overhead 0.500  
    remark #15301: OpenMP SIMD LOOP WAS VECTORIZED  
    remark #15475: --- begin vector cost summary ---  
    remark #15476: scalar cost: 8  
    remark #15477: vector cost: 1.000  
    remark #15478: estimated potential speedup: 7.990  
    remark #15488: --- end vector cost summary ---  
    remark #25015: Estimate of max trip count of loop=25000  
  
LOOP BEGIN at test-vec.c(13,6) inlined into test-vec.c(29,4)  
    remark #25456: Number of Array Refs Scalar Replaced In Loop: 1  
LOOP END  
LOOP END
```



OpenMP/Threads - Runtime Library Routines



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- These routines are provided by the openmp library are used to configuring and monitoring the multithreading during execution: e.g.
`omp_get_num_threads` returns number of threads in current team
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- There are further routines for locks for synchronization/access control (see later)
- as well as timing routines for recording elapsed time for each thread.



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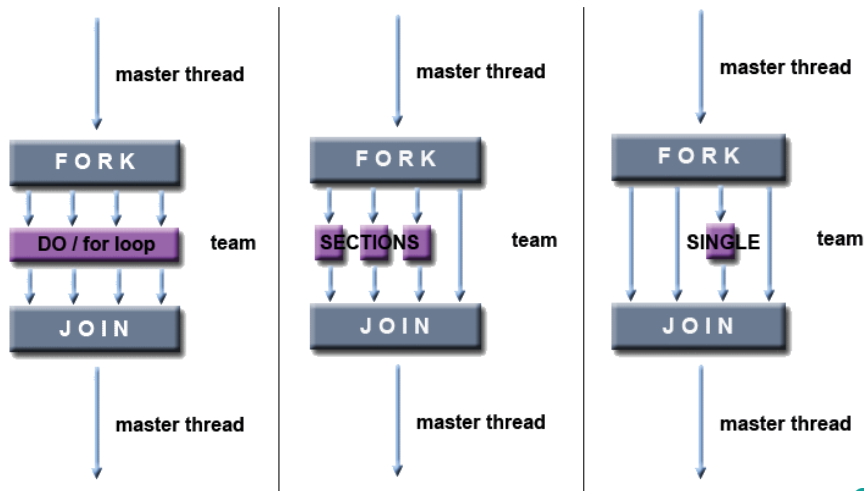


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- While most of these settings can also be done using clauses in the compiler directives of runtime library routines, environmental variables provide a user an easy way to change these crucial settings without the need of an additional config file (parsed by your program) or even rewriting/recompiling the openmp-enhanced program.



OpenMP/Threads - Worksharing



OpenMP/Threads - Worksharing: Examples

```
#include <omp.h>
#define N 1000
#define CHUNKSIZE 100

main(int argc, char *argv[]) {

    int i, chunk;
    float a[N], b[N], c[N];

    /* Some initializations */
    for (i=0; i < N; i++)
        a[i] = b[i] = i * 1.0;
    chunk = CHUNKSIZE;

    #pragma omp parallel shared(a,b,c,chunk) private(i)
    {
        #pragma omp for schedule(dynamic,chunk) nowait
        for (i=0; i < N; i++)
            c[i] = a[i] + b[i];
    } /* end of parallel region */
}
```

```
#include <omp.h>
#define N 1000

main(int argc, char *argv[]) {

    int i;
    float a[N], b[N], c[N], d[N];

    /* Some initializations */
    for (i=0; i < N; i++) {
        a[i] = i * 1.5;
        b[i] = i + 22.35;
    }

    #pragma omp parallel shared(a,b,c,d) private(i)
    {
        #pragma omp sections nowait
        {
            #pragma omp section
            for (i=0; i < N; i++)
                c[i] = a[i] + b[i];

            #pragma omp section
            for (i=0; i < N; i++)
                d[i] = a[i] * b[i];
        } /* end of sections */
    } /* end of parallel region */
}
```

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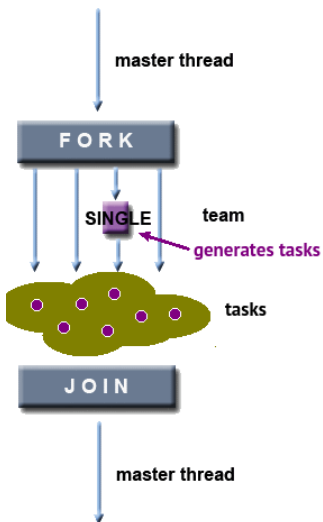
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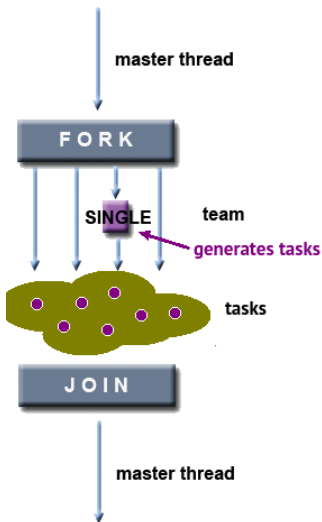
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OpenMP/Threads - advanced Worksharing

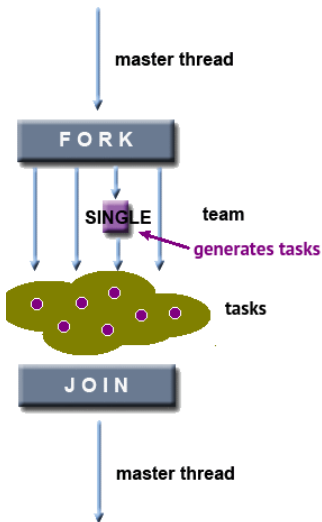


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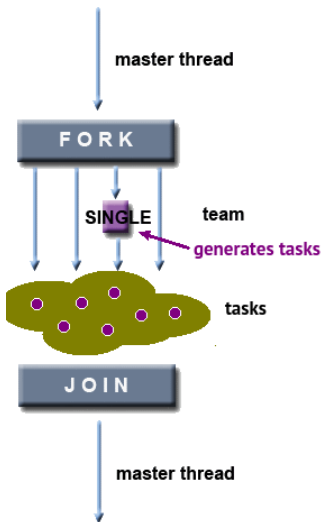
- defines explicit tasks similar to sections that are generated (usually by a single task) and then deferred to any thread in the team via a queue/scheduler

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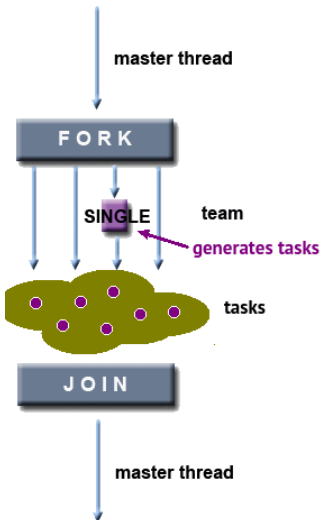
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- tasks are not necessarily tied to a single thread, can be e.g. postponed or migrated to other threads

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- defines explicit tasks similar to sections that are generated (usually by a single task) and then deferred to any thread in the team via a queue/scheduler
- tasks are not necessarily tied to a single thread, can be e.g. postponed or migrated to other threads
- allows for defining dependencies among tasks (e.g. task X has to finish before any thread can work on task Y)

OpenMP/Threads - advanced Worksharing: Example



```
#include <omp.h>

float sum(const float *a, size_t n)
{
    // base cases
    if (n == 0) {
        return 0;
    }
    else if (n == 1) {
        return 1;
    }

    // recursive case
    size_t half = n / 2;
    float x, y;

    #pragma omp parallel shared(x,y)

    #pragma omp single nowait
    {
        #pragma omp task shared(x)
        x = sum(a, half);
        #pragma omp task shared(y)
        y = sum(a + half, n - half);
        #pragma omp taskwait
        x += y;
    }

    return x;
}
```



OpenMP/Threads - Synchronization / Flow control

In the 'Introduction to Parallelization', we discussed the need of controlling the execution of threads at certain points to e.g. synchronize them to exchange intermediate results or to protect resources from getting accessed simultaneously with non-deterministic outcome ('race condition'). OpenMP provides two ways to do this:



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- Compiler Directives:
 - ▶ (for general parallel regions) e.g.
`cancel, single, master, critical, atomic, barrier`
 - ▶ (for loops) `ordered`
 - ▶ (for tasks) `taskwait, taskyield`



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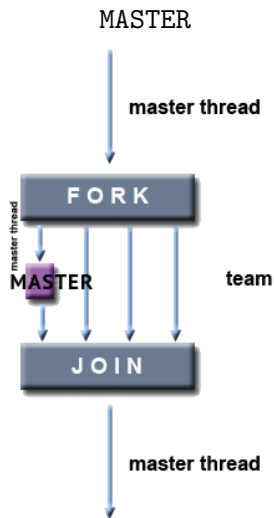
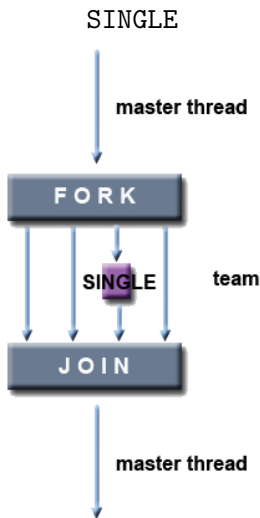
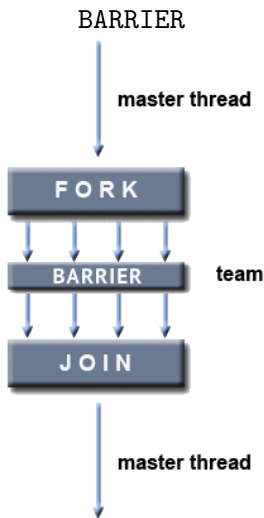
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- Runtime Library Routines:

`omp_set_lock, omp_unset_lock, omp_test_lock`



OpenMP/Threads - Synchronization / Flow control (RESTRICTION)

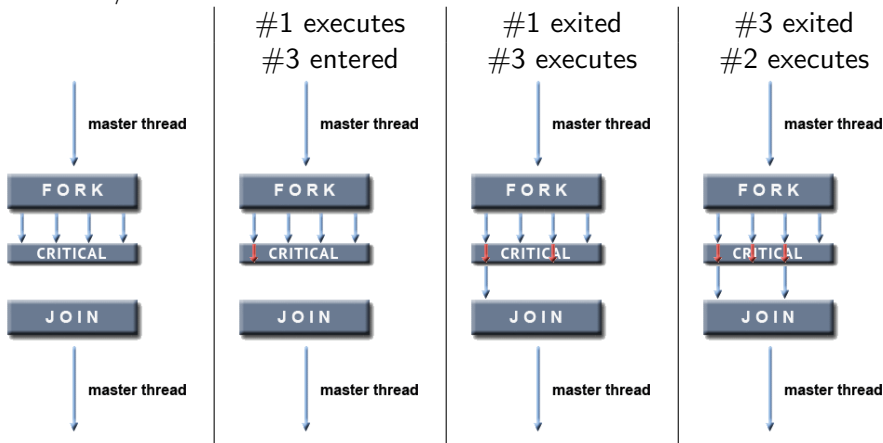


implicit BARRIER

NO implicit BARRIER

OpenMP/Threads - Synchronization / Flow control (MUTEX)

CRITICAL / ATOMIC



- CRITICAL, ATOMIC exclusive for ALL threads, not just team
- CRITICAL regions can be named, regions with same name treated as same region



OpenMP/Threads - Memory management (CLAUSES)

- Certain clauses for compiler directives allow us to specify how data is shared (e.g. `shared`, `private`, `threadprivate`) and how they are initialized (e.g. `firstprivate`, `copyin`)



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```
#include <omp.h>

main(int argc, char *argv[]) {

    int i, n, chunk;
    int a[100], b[100], result;

    n = 100;
    chunk = 10;
    result = 0.0;
    for (i=0; i < n; i++) {
        a[i] = i;
        b[i] = i*2;
    }

    #pragma omp parallel for \
        default(shared) private(i) \
        schedule(static,chunk) \
        reduction(+:result)

    for (i=0; i < n; i++)
        result = result + (a[i] * b[i]);

    printf("result= %d\n",result);
}
```



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- even if shared, sometimes variable may not be updated in the "global" view, e.g. if kept in a register or cache of a CPU instead of the shared memory

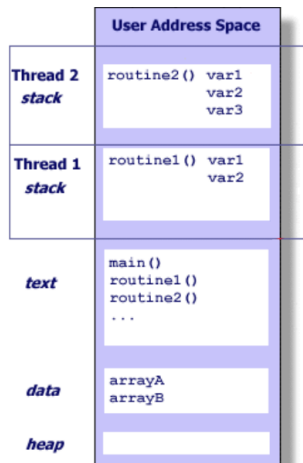


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- while many directives (e.g. `for`, `section`, `critical`) implicitly flush variable to synchronize them with other threads, sometimes explicit flushing using the `flush` may be necessary.



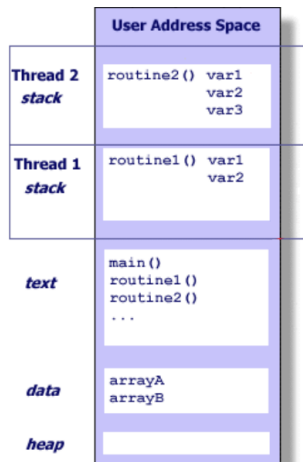
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Compiler	Approx Stack Limit
icc/ifort (Linux)	4 MB
gcc/gfort (Linux)	2 MB

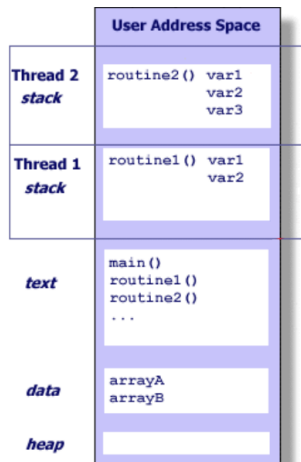


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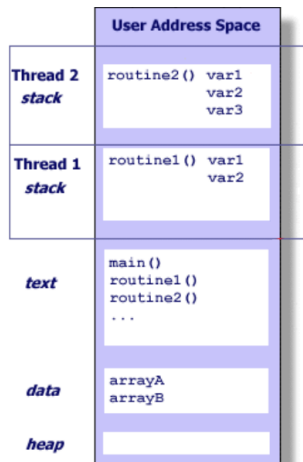


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- if stack allocation exceeded, may result in seg fault or (worse) data corruption.
- Env. variable `OMP_STACKSIZE` allows to set stacksize prior to execution. So if your program needs an significant amount of data on the stack, make sure to adapt the stacksize this way!



OpenMP/Threads - Cython wrappers



- Cython is currently using OpenMP as its (only) backend for its parallelisation.
- It provides some wrappers for it that can be used directly in cython's parallelisation module:

```
from cython.parallel import parallel
from cython.cimports.openmp import omp_set_dynamic, omp_get_num_threads

num_threads = cython.declare(cython.int)

omp_set_dynamic(1)
with cython.nogil, parallel():
    num_threads = omp_get_num_threads()
    # ...
```



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 - Portability** *Threading* module available for both Python2 & 3, a various different implementations (CPython, PyPy, Jython, etc.) and for a wide range of platforms/OS
- There are inherit design choices made for the most popular Python implementations that limit the utility of multithreading (see later)



Python/threading - Thread management: Creation & Term.

- Python threads are created explicitly by creating an instance of the Thread class
`(threading.Thread(target=...[,args=...][,name=...],...))`
 - ▶ `target` is the name of a function to be invoked by the Thread's `run()` method
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 - ▶ `name` is a unique name/identifier for the thread [default: `Thread-N`]
- They terminate when finishing their starting routine or, if 'daemonic' once the main program finishes with only daemon threads left
- Basic threads **cannot** be terminated by other threads (but you can implement a subclass with this property if needed)
- you can explicitly wait for a Thread to finish by invoking its `join()` method.
- there is also a `Timer` class, that allows to set up a delayed thread.



Python/threading - Thread management: Example 1

```
import threading
import time
import random

def do_something():
    time.sleep(random.randrange(1,5))
    print('%s RUNNING\n' % (threading.current_thread().name))

if __name__ == '__main__':
    threads = []

    for i in range(10):
        my_thread = threading.Thread(target=do_something)
        threads.append(my_thread)

    for t in threads:
        t.start()

    for t in threads:
        t.join()

    print('Done')
```



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Lock/RLock To secure a *critical* region, locks can be used. They can be held by either a single thread or no thread at all. Should a thread try to acquire a lock on a resource that is already locked, that thread will basically pause until the lock is released. RLocks allow same thread to lock multiple times.



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Condition Allows to keep threads waiting until explicitly notified and associated lock released

Semaphore Allows to limit access to locked are to a number of threads at a time



Python/threading: Example 2 (Barrier)

```
import threading
import time
import random

num = 4
bar = threading.Barrier(num)

def do_something():
    time.sleep(random.randrange(2, 20))
    print('%s REACHED the barrier\n' % (current_thread().name))
    try:
        bar.wait()
    except:
        pass
    finally:
        print('%s PASSED the barrier\n' % (current_thread().name))

if __name__ == '__main__':
    threads = []

    for i in range(10):
        my_thread = threading.Thread(target=do_something, args=())
        my_thread.start()

    time.sleep(30)
    print("Release stuck threads by breaking barrier...")
    bar.abort()
```



Python/threading: Example 3 (Lock/RLock)

```
import threading

total = 0
lock = threading.Lock()

def update_total(amount):
    #Updates the total

    global total
    lock.acquire()
    try:
        total += amount
    finally:
        lock.release()
    print (total)

if __name__ == '__main__':
    for i in range(10):
        my_thread = threading.Thread(
            target=update_total, args=(5,))
        my_thread.start()
```



Python/threading: Example 3 (Lock/RLock)

```
import threading

total = 0
lock = threading.Lock()

def update_total(amount):
    #Updates the total

    global total
    with lock:
        total += amount
    print (total)

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import threading

total = 0
lock = threading.RLock()

def do_something(amount):
    with lock:
        update_total(amount)

def update_total(amount):
    #Updates the total

    global total
    with lock:
        total += amount
    print (total)

if __name__ == '__main__':
    for i in range(10):
        my_thread = threading.Thread(
            target=do_something, args=(5,))
        my_thread.start()
```



Python/threading: Example 4 (Condition/Semaphore)

```
import threading
import time

def create(cond):
    while True:
        time.sleep(3)
        print('%s: New item PRODUCED\n' %
              (threading.current_thread().name))

        with cond:
            cond.notify()
            time.sleep(3)
            print('%s: Item AVAILABLE\n' %
                  (threading.current_thread().name))

def consume(cond):
    while True:
        with cond:
            print('%s: WAITING for new item ...\n' %
                  (threading.current_thread().name))
            cond.wait()
            print('%s: CONSUMING item\n' %
                  (threading.current_thread().name))
            time.sleep(10)

if __name__ == '__main__':
    cond = threading.Condition()

    thread_producer = threading.Thread(target=create, name='producer',
                                       args=(cond,))
    thread_consumer1 = threading.Thread(target=consume, args=(cond,))
    thread_consumer2 = threading.Thread(target=consume, args=(cond,))

    thread_creator.start()
    thread_consumer1.start()
    thread_consumer2.start()
```



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    thread_creator.start()
    thread_consumer1.start()
    thread_consumer2.start()
```

```
import threading
import time

total = 2
sem = threading.Semaphore(total)

def do_something():
    with sem:
        print(threading.currentThread().getName() + '\n')
        time.sleep(5)

if __name__ == '__main__':
    for i in range(10):
        my_thread = threading.Thread(
            target=do_something, args=(5,))
        my_thread.start()
```



Python/threading: Memory management

- since threads share the same process and therefore memory, global variables are automatically shared



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Queue The Queue class provides a FIFO structure that allow e.g. *producer* threads to pass on data to *consumer* threads

Event Event objects allow are simply binary structures to send signals across threads



Python/threading: Example 4 (Queue/Event)

```
import threading
import queue
import time

def create(data, q):
    for item in data:
        [-]
        q.put(item)

def consume(q):
    while True:
        data = q.get()
        [-]
        q.task_done()

if __name__ == '__main__':
    q = queue.Queue()
    data = range(10)

    thread_creator = threading.Thread(target=create, args=(data, q))
    thread_consumer = threading.Thread(target=consume, args=(q,))
    thread_consumer.daemon = True

    thread_creator.start()
    thread_consumer.start()

    time.sleep(2)
    q.join()
    print("Done")
```



Python/threading: Example 4 (Queue/Event)

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    thread_creator.start()
    thread_consumer.start()

    time.sleep(2)
    q.join()
    print("Done")
```

```
import threading
import queue

def create(data, q):
    for item in data:
        [...]
        q.put(item)

def consume(q, evt):
    while True:
        try:
            data = q.get(timeout=5)
        except:
            evt.set()
        [...]

if __name__ == '__main__':
    q = queue.Queue()
    evt = threading.Event()
    data = range(10)

    thread_creator = threading.Thread(target=create, args=(data, q,))
    thread_consumer = threading.Thread(target=consume, args=(q, evt,))
    thread_consumer.daemon = True

    thread_creator.start()
    thread_consumer.start()

    evt.wait()
    print("Done")
```



Python - Multithreading: Caveats

- The reference python implementation aka CPython as well as popular alternatives (e.g. PyPy) use a *Global Interpreter Lock* (GIL) that blocks running threads simultaneously within python



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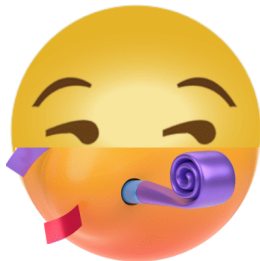
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- *Take-away:* The utility of multithreading in python is very situation-dependent



Python - Multithreading: Caveats (2023 update)



- The reference python implementation aka CPython as well as popular alternatives (e.g. PyPy) use a *Global Interpreter Lock* (GIL) that blocks running threads simultaneously within python
- CPython 3.13 may finally have full support of (sub)interpreters with own GILs!
- Lock-free implementations exist (e.g. Jython, IronPython) but are not suitable for every problem (some modules are not supported)
- alternatively, external libraries written in other languages can circumvent this problem as they release the GIL (see e.g. NumPy calls), so do blocking I/O calls
- *Take-away:* The utility of multithreading in python is very situation-dependent



POSIX Threads



PThreads - History/Goals



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- standardized API for multithreading to allow for portable threaded applications



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PThreads - History/Goals

- standardized API for multithreading to allow for portable threaded applications
- first defined in IEEE POSIX standard 1003.1c in 1995, but undergoes continuous evolution/revision
- historically implementations focused on Unix as OS, but implementations also exist now for others e.g. for Windows



PThreads - Compiling & Running



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- Like for OpenMP, POSIX Threads are included in most recent compiler suites by default



PThreads - Compiling & Running

- Like for OpenMP, POSIX Threads are included in most recent compiler suites by default
- To enable these included libraries, use e.g.

```
icc -pthread    for INTEL (Linux)  
gcc -pthread    for GNU (Linux)
```



PThreads - API



PThreads - API

- The subroutines defined in the API can be classified into four major groups:

Thread management For creating new threads, checking their properties and joining/destroying them and the end of their lifecycle (`pthread_`, `pthread_attr_`)

Mutexes For creating mutex locks to control excess to exclusive resources (`pthread_mutex_`, `pthread_mutexattr_`)

Condition variables routines for managing condition variable to allow for easy communication between threads that share a mutex (`pthread_cond_`, `pthread_condattr_`)

Semaphores Like in Python, there are semaphores. A semaphore is a signalling mechanism and a thread that is waiting on a semaphore can be signaled by another thread and use a counter to limit access.

Synchronization barriers, read/write locks
(`pthread_barrier_`, `pthread_rwlock_`)



PThreads - Thread management: Creation & Termination



PThreads - Thread management: Creation & Termination

- POSIX threads (`pthread_t`) are created explicitly using the `pthread_create(thread, attr, start_routine, arg)` where
 - ▶ `attr` is a thread attribute structure containing settings for creating/running thread
 - ▶ `start_routine` is a procedure that works as a starting point for the thread
 - ▶ `arg` is a pointer to the argument for the starting routine (can be pointing to a single data element, an array or a custom data structure)



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 - ▶ `attr` is a thread attribute structure containing settings for creating/running thread
 - ▶ `start_routine` is a procedure that works as a starting point for the thread
 - ▶ `arg` is a pointer to the argument for the starting routine (can be pointing to a single data element, an array or a custom data structure)
- They terminate when finishing their starting routine, calling `pthread_exit(status)` to return a status flag, by another thread by calling `pthread_cancel(thread)` with `thread` pointing to them or the host process finishing first (without `pthread_exit()` call)



PThreads - Thread management: Example 1

```
#include <pthread.h>
#include <stdio.h>
#define NUM_THREADS      5

void *PrintHello(void *threadid)
{
    long tid;
    tid = (long)threadid;
    printf("Hello World! It's me, thread #%ld!\n", tid);
    pthread_exit(NULL);
}

int main (int argc, char *argv[])
{
    pthread_t threads[NUM_THREADS];
    int rc;
    long t;
    for(t=0; t<NUM_THREADS; t++){
        printf("In main: creating thread %ld\n", t);
        rc = pthread_create(&threads[t], NULL, PrintHello, (void *)t);
        if (rc){
            printf("ERROR; return code from pthread_create() is %d\n", rc);
            exit(-1);
        }
    }

    /* Last thing that main() should do */
    pthread_exit(NULL);
}
```



PThreads - Thread management: Joining & Detaching



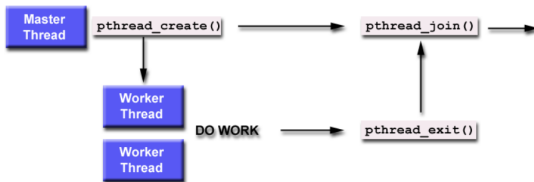
PThreads - Thread management: Joining & Detaching

- “Joining” threads allows the master thread to synchronize with its worker threads on completion of their task



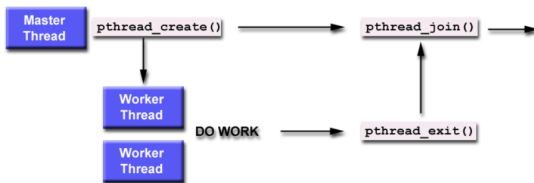
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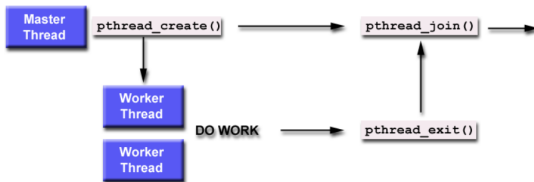
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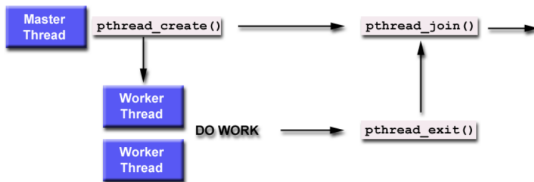
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- data (Thread Control Block) remains in memory after completion of a thread until `pthread_join` is called on this dead thread and the clean-up is triggered

PThreads - Thread management: Joining & Detaching

- “Joining” threads allows the master thread to synchronize with its worker threads on completion of their task



- threads can be declared “joinable” on creation
- data (Thread Control Block) remains in memory after completion of a thread until `pthread_join` is called on this dead thread and the clean-up is triggered
- “detached” threads do not keep such (potentially unnecessary) data, i.e. get cleaned up directly on completion



PThreads - Mutexes

- Mutexes work in similar way as the OpenMP and Python locks: once claimed by one thread, other threads encountering it will be hold until the mutex released again.



PThreads - Joining & Mutexes: Example

```
#define NUMTHRS 4
#define VECLEN 100000
DOTDATA dotstr;
pthread_t callThd[NUMTHRS];
pthread_mutex_t mutexsum;

void *dotprod(void *arg)
{
    [...]

    mysum = 0;
    for (i=start; i<end ; i++)
    {
        mysum += (x[i] * y[i]);
    }

    pthread_mutex_lock (&mutexsum);
    dotstr.sum += mysum;
    printf("Thread %ld did %d to %d: mysum=%f global sum=
%f\n",offset,start,end,mysum,dotstr.sum);
    pthread_mutex_unlock (&mutexsum);

    pthread_exit((void*) 0);
}

int main (int argc, char *argv[])
{
    long i;
    double *a, *b;
    void *status;
    pthread_attr_t attr;

    a = (double*) malloc (NUMTHRS*VECLEN*sizeof(double));
    b = (double*) malloc (NUMTHRS*VECLEN*sizeof(double));
```

```
[...]

pthread_mutex_init(&mutexsum, NULL);

/* Create threads to perform the dotproduct */
pthread_attr_init(&attr);
pthread_attr_setdetachstate(&attr, PTHREAD_CREATE_JOINABLE);

for(i=0;i<NUMTHRS;i++)
{
    /* Each thread works on a different set of data.
     * The offset is specified by 'i'. The size of
     * the data for each thread is indicated by VECLEN.
     */
    pthread_create(&callThd[i], &attr, dotprod, (void *)i);
}

pthread_attr_destroy(&attr);
/* Wait on the other threads */

for(i=0;i<NUMTHRS;i++) {
    pthread_join(callThd[i], &status);
}

/* After joining, print out the results and cleanup */

printf ("Sum =  %f \n", dotstr.sum);
free (a);
free (b);
pthread_mutex_destroy(&mutexsum);
pthread_exit(NULL);
}
```



PThreads - Condition variables



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- Conditions variables control the flow of threads like Mutexes



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- Conditions variables control the flow of threads like Mutexes
- instead of claiming a lock, it allows threads to wait (`pthread_cond_wait()`) until another thread send a signal (`pthread_cond_signal()`) through the condition variable to continue.



PThreads - Synchronization: Barriers



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- POSIX Threads also feature a synchronization barrier similar to OpenMP and Python.



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- POSIX Threads also feature a synchronization barrier similar to OpenMP and Python.
- Since there are no "team" structure like in OpenMP, on creation a number of threads is defined, that has to reach the barrier before any of them is allowed to pass.



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- So better explicitly allocate enough stack to provide portability and avoid segmentation faults or data corruption



PThreads - Memory management

- As for OpenMP, POSIX does not dictate the (default) stack size for a thread and thus can vary greatly.
- So better explicitly allocate enough stack to provide portability and avoid segmentation faults or data corruption
- use `pthread_attr_setstacksize` to set the desired stacksize in the attribute object used for creating the thread.

