

Design and Analysis of Algorithms Divide-and-Conquer

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- Divide-and-Conquer Paradigm
- Closest Pair of Points
- Median and Selection Problems

Divide-and-Conquer Paradigm

Divide-and-Conquer.

- Divide problem into several subproblems.
- Solve each subproblem recursively.
- Combine solution to subproblems into overall solution.

Most common usage.

- Divide problem of size n into two subproblems of size n/2 in linear time.
- Solve two subproblems recursively.
- Combine two solutions into overall solution in linear time.

Consequence.

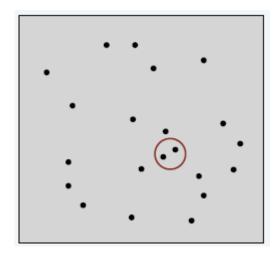
- Brute force: $\Theta(n^2)$.
- Divide-and-conquer: $\Theta(nlogn)$.

Closest Pair of Points

Closest pair problem. Given *n* points in the plane, fine a pair of points with the smallest Euclidean distance between them.

Fundamental geometric primitive.

- Graphics, computer vision, geographic information systems, molecular modeling, air traffic control.
- Special case of nearest neighbor.



Closest Pair of Points

Closest pair problem. Given *n* points in the plane, fine a pair of points with the smallest Euclidean distance between them.

Brute force. Check all pairs with $\Theta(n^2)$ distance calculations.

1D version. Easy O(nlogn) algorithm if points are on a line.

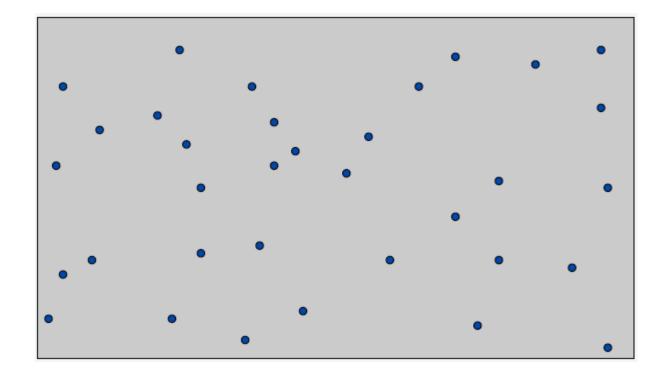
Nondegeneracy assumption. No two points have the same x-coordinate.



Closest Pair of Points: First Attempt

Sorting solution.

- Sort by x-coordinate and consider nearby points.
- Sort by y-coordinate and consider nearby points.

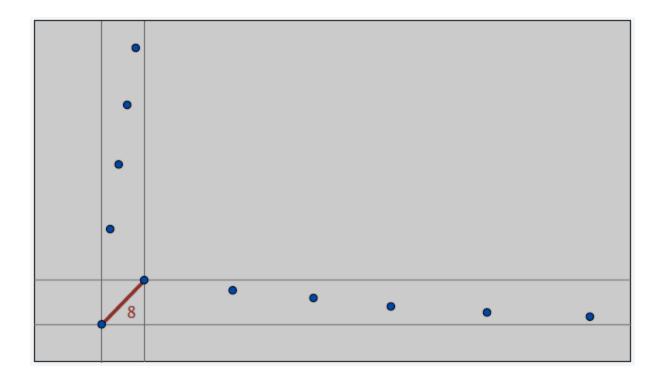




Closest Pair of Points: First Attempt

Sorting solution.

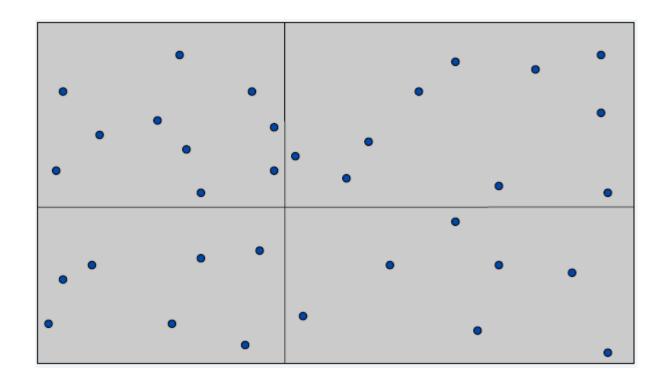
- Sort by x-coordinate and consider nearby points.
- Sort by y-coordinate and consider nearby points.





Closest Pair of Points: Second Attempt

Divide. Subdivide region into 4 quadrants.

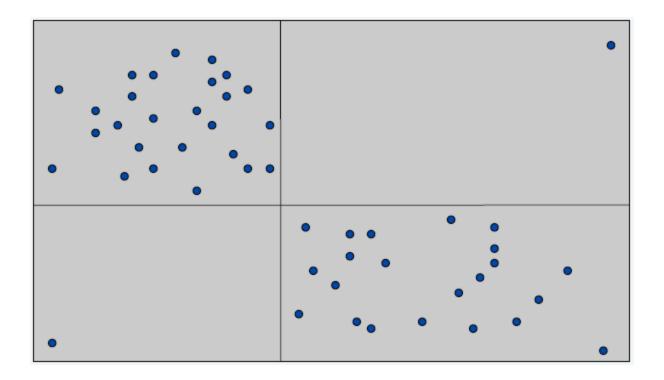




Closest Pair of Points: Second Attempt

Divide. Subdivide region into 4 quadrants.

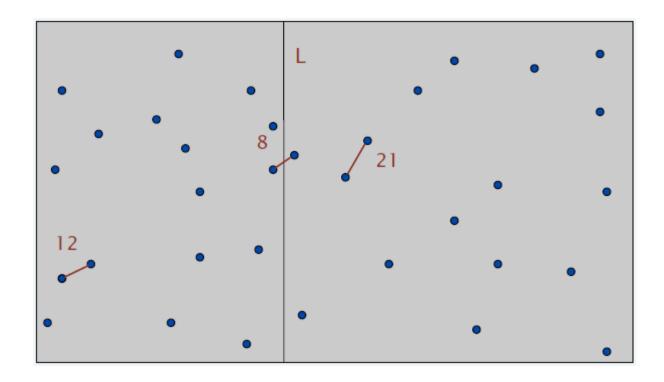
Obstacle. Impossible to ensure n/4 points in each piece.





Closest Pair of Points: Divide-and-Conquer Algorithm

- Divide: draw vertical line L so that n/2 points on each side.
- Conquer: find closet pair in each side recursively.
- Combine: find closet pair with one point in each side.
- Return best of 3 solutions.

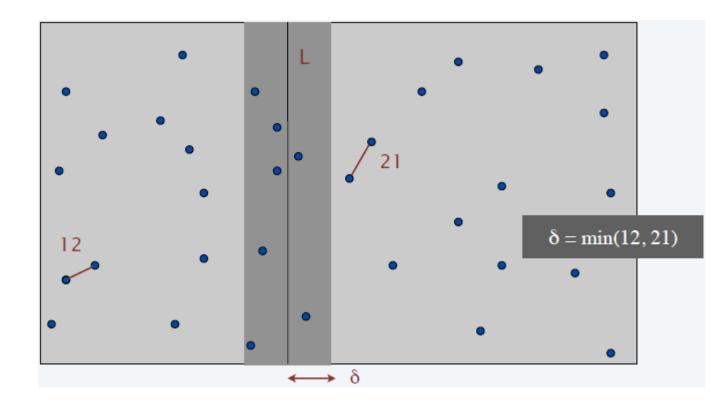




How to Find Closest Pair with One Point in Each Side?

Find closest pair with one point in each side, assuming that distance $< \delta$.

• Observation: only need to consider points within δ of line L.

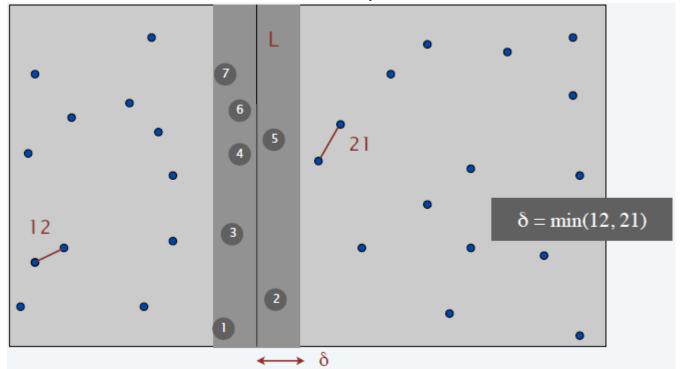




How to Find Closest Pair with One Point in Each Side?

Find closest pair with one point in each side, assuming that distance $< \delta$.

- Observation: only need to consider points within δ of line L.
- Sort points in 2δ -strip by their y-coordinate.
- Only check distances of those within 15 positions in sorted list.





How to Find Closest Pair with One Point in Each Side?

Def. Let s_i be the point in the 2δ -strip, with the i-th smallest y-coordinate.

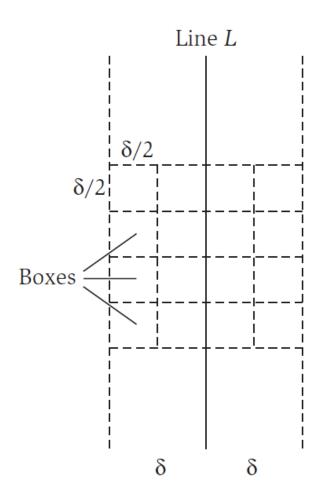
Each box can contain at most one input point.

Claim. If $|i - j| \ge 16$, then the distance between s_i and s_j is at least $\frac{3}{2}\delta$.

Pf.

- No two points lie in same $\frac{1}{2}\delta$ by $\frac{1}{2}\delta$ box.
- Two points at least 3 rows apart
- have distance $\geq 3(\frac{1}{2}\delta)$.

Note. The value of 15 can be reduced. The important thing is that it is an absolute constant.



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Closest Pair of Points: Divide-and-Conquer Algorithm

Closest-Pair $(p_1, p_2, ..., p_n)$

- Compute separation line L such that half the points are on each side of the line.
- $\delta_1 \leftarrow \text{Closest-Pair}$ (points in left half).
- $\delta_2 \leftarrow \text{Closest-Pair}$ (points in right half).
- $\delta \leftarrow \min\{\delta_1, \delta_2\}$.
- Delete all points further than δ from Line L.
- Sort remaining points by y-coordinate.
- Scan points in y-order and compare distance between each point and next 15 neighbors. If any of these distances is less than δ , update δ .

Return δ .

$$T(n) = ?$$

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Closest Pair of Points: Divide-and-Conquer Algorithm

Closest-Pair $(p_1, p_2, ..., p_n)$

- Compute separation line L such that half the points are on each side of the line.
- $\longleftarrow O(nlogn)$

• $\delta_1 \leftarrow \text{Closest-Pair}$ (points in left half).

 \leftarrow 2T(n/2)

- $\delta_2 \leftarrow \text{Closest-Pair}$ (points in right half).
- $\delta \leftarrow \min\{\delta_1, \delta_2\}$.
- Delete all points further than δ from Line L.

O(n)

Sort remaining points by y-coordinate.

- \leftarrow O(nlogn)
- Scan points in y-order and compare distance between each point and next 15 neighbors. If any of these distances is less than δ , update δ .

 \leftarrow O(n)

Return δ .

$$T(n) = 3$$

Closest Pair of Points: Analysis

Theorem. The divide-and-conquer algorithm for finding the closest pair of points in the plane can be implemented in ? time.

$$T(n) = \begin{cases} \Theta(1), & if \ n = 1 \\ T(\lceil n/2 \rceil) + T(\lfloor n/2 \rfloor) + O(nlogn), otherwise \end{cases}$$

Closest Pair of Points: Analysis

Theorem. The divide-and-conquer algorithm for finding the closest pair of points in the plane can be implemented in $O(n\log^2 n)$ time.

$$T(n) = \begin{cases} \Theta(1), & if \ n = 1 \\ T(\lceil n/2 \rceil) + T(\lfloor n/2 \rfloor) + O(nlogn), otherwise \end{cases}$$

Master Theorem - Case 2. If $f(n) = \Theta(n^k \log^p n)$ for $p \ge 0$ and $k = \log_b a$, then $T(n) = \Theta(n^k \log^{p+1} n)$.

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Median and Selection Problems

Selection. Given *n* elements, find *k*-th smallest.

- Minimum: k = 1; maximum: k = n.
- Median: $k = \lfloor (n+1)/2 \rfloor$.
- O(n) compares for min or max.
- O(nlogn) compares by sorting.

Applications. Find the "top k"...

Can we do it with O(n) compares?

Quick-Select

3-way partition array so that:

- Pivot element p is in place.
- Smaller elements in left subarray L.
- Equal elements in middle subarray M.
- Larger elements in right subarray R.

Recur in one subarray - the one containing the *k*-th smallest element.

```
Quick-Select (A, k)
```

```
Pick pivot p \in A uniformly at random. 3-way partitioning (L, M, R) \leftarrow \text{Partition-3-Way } (A, p). can be done in-place (using n-1 compares) if k \leq |L| Return Quick-Select (L, k). else if k > |L| + |M| Return Quick-Select (R, k - |L| - |M|). else Return p.
```

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An Example of Quick-Select

```
Quick-Select (A, k)
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Pick pivot $p \in A$ uniformly at random.

 $(L, M, R) \leftarrow \text{Partition-3-Way } (A, p).$

if $k \leq |L|$ Return Quick-Select (L, k).

else if k > |L| + |M| Return Quick-Select (R, k - |L| - |M|). else Return p.

Example: select the 8-th smallest element



3-way partition array so that:

- Pivot element p is in place.
- Smaller elements in left subarray L.
- Equal elements in middle subarray M.
- Larger elements in right subarray R.

Recur in one subarray-the one containing the k-th smallest element.

```
select the k = 8^{th} smallest
```

```
1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
65 28 59 33 21 56 22 95 50 12 90 53 28 77 39
```



3-way partition array so that:

- Pivot element p is in place.
- Smaller elements in left subarray L.
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Recur in one subarray-the one containing the k-th smallest element.

choose a pivot element at random and partition



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Recur in one subarray-the one containing the *k*-th smallest element.

partitioned array



3-way partition array so that:

- Pivot element p is in place.
- Smaller elements in left subarray L.
- Equal elements in middle subarray M.
- Larger elements in right subarray R.

Recur in one subarray-the one containing the k-th smallest element.

recursively select 8th smallest element in left subarray



3-way partition array so that:

- Pivot element p is in place.
- Smaller elements in left subarray L.
- Equal elements in middle subarray M.
- Larger elements in right subarray R.

Recur in one subarray-the one containing the k-th smallest element.

choose a pivot element at random and partition



3-way partition array so that:

- Pivot element p is in place.
- Smaller elements in left subarray L.
- Equal elements in middle subarray M.
- Larger elements in right subarray R.

Recur in one subarray-the one containing the k-th smallest element.

partitioned array



3-way partition array so that:

- Pivot element p is in place.
- Smaller elements in left subarray L.
- Equal elements in middle subarray M.
- Larger elements in right subarray R.

Recur in one subarray-the one containing the k-th smallest element.

recursively select the 3rd smallest element in right subarray



3-way partition array so that:

- Pivot element p is in place.
- Smaller elements in left subarray L.
- Equal elements in middle subarray M.
- Larger elements in right subarray R.

Recur in one subarray-the one containing the k-th smallest element.

choose a pivot element at random and partition



3-way partition array so that:

- Pivot element p is in place.
- Smaller elements in left subarray L.
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Recur in one subarray-the one containing the k-th smallest element.

partitioned array



3-way partition array so that:

- Pivot element p is in place.
- Smaller elements in left subarray L.
- Equal elements in middle subarray M.
- Larger elements in right subarray R.

Recur in one subarray-the one containing the k-th smallest element.

stop: desired element is in middle subarray

Intuition. Split candy bar uniformly \Rightarrow expected size of larger piece is ?

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$$T(n) \le T\left(\frac{3}{4}n\right) + ?$$

Intuition. Split candy bar uniformly \Rightarrow expected size of larger piece is $\frac{3}{4}$.

$$T(n) \le T\left(\frac{3}{4}n\right) + n \implies T(n) \le ?$$

AN THE SECOND OF THE SECOND OF

Quick-Select Analysis

Intuition. Split candy bar uniformly \Rightarrow expected size of larger piece is $\frac{3}{4}$.

$$T(n) \le T\left(\frac{3}{4}n\right) + n \implies T(n) \le 4n$$

Def. T(n,k) = expected # compares to select k-th smallest in an array of size $\leq n$.

Def.
$$T(n) = \max_{k} T(n, k)$$
.

Proposition. $T(n) \le 4n$ Pf.

- Assume true for 1,2,...,n-1.
- T(n) satisfies for the following recurrence:

$$T(n) \le n + \frac{2}{n} \left[T\left(\frac{n}{2}\right) + \dots + T(n-3) + T(n-2) + T(n-1) \right]$$

Proposition. $T(n) \le 4n$ Pf.

- Assume true for 1,2,...,n-1.
- T(n) satisfies for the following recurrence:

$$T(n) \le n + \frac{2}{n} \left[T\left(\frac{n}{2}\right) + \dots + T(n-3) + T(n-2) + T(n-1) \right]$$

$$\le n + \frac{2}{n} \left[\frac{4n}{2} + \dots + 4(n-3) + 4(n-2) + 4(n-1) \right]$$

$$\le n + 4\left(\frac{3n}{4}\right)$$

$$= 4n.$$

can assume we always recur on largest subarray since T(n) is monotonic and we are trying to get an upper bound

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Selection in Worst Case (Linear Time)

Goal. Find pivot element p that divides list of n elements into two pieces so that each piece is guaranteed to have $\leq \frac{7}{10}n$ elements.

How to find approximate median in linear time?

Selection in Worst Case (Linear Time)

Goal. Find pivot element p that divides list of n elements into two pieces so that each piece is guaranteed to have $\leq \frac{7}{10}n$ elements.

How to find approximate median in linear time?

Recursively compute median of $\leq \frac{2}{10}n$ elements.

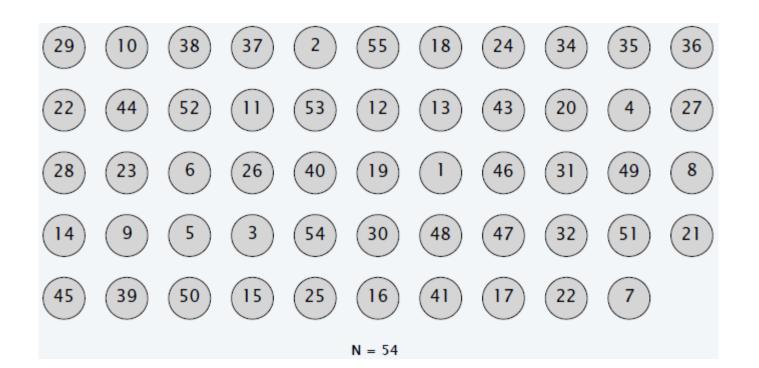
$$T(n) = \begin{cases} \Theta(1), & if \ n = 1 \\ T\left(\frac{7}{10}n\right) + T\left(\frac{2}{10}n\right) + \Theta(n), otherwise \end{cases}$$

two sub-problems of different sizes



Choosing the Pivot Element

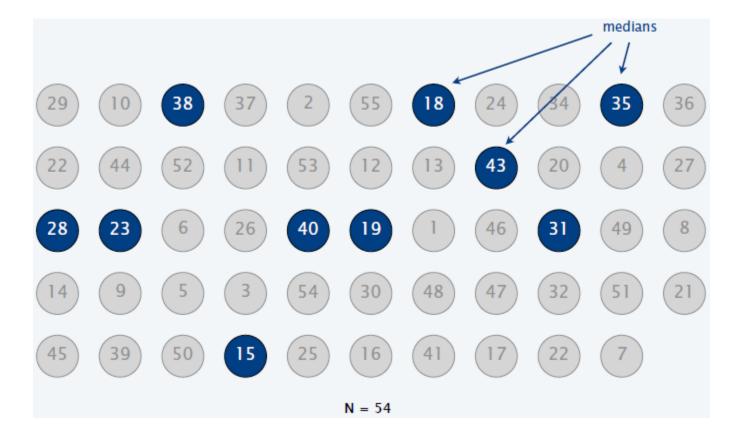
• Divide n elements into $\lfloor n/5 \rfloor$ groups of 5 elements each.





Choosing the Pivot Element

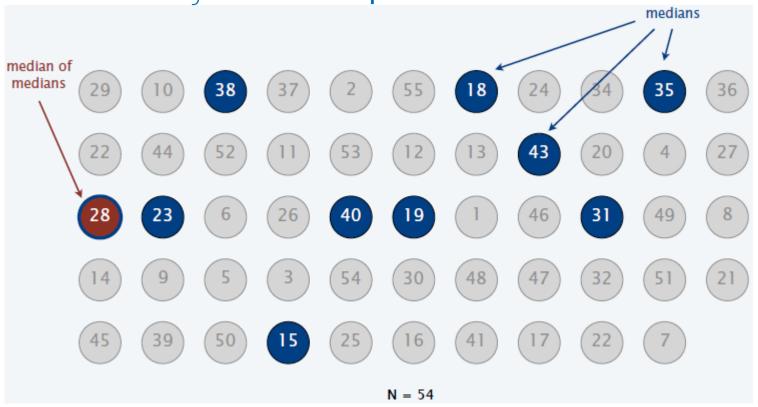
- Divide n elements into $\lfloor n/5 \rfloor$ groups of 5 elements each.
- Find median of each group.





Choosing the Pivot Element

- Divide n elements into $\lfloor n/5 \rfloor$ groups of 5 elements each.
- Find median of each group.
- Find median of $\lfloor n/5 \rfloor$ medians recursively.
- Use median-of-medians as pivot element.



Median-of-Medians Selection Algorithm

MoM-Select (A, k)

```
n \leftarrow |A|.
```

if n < 50 Return k-th smallest of element of A via Merge-Sort.

Group A into $\lfloor n/5 \rfloor$ groups of 5 elements each.

 $B \leftarrow \text{median of each group of 5.}$

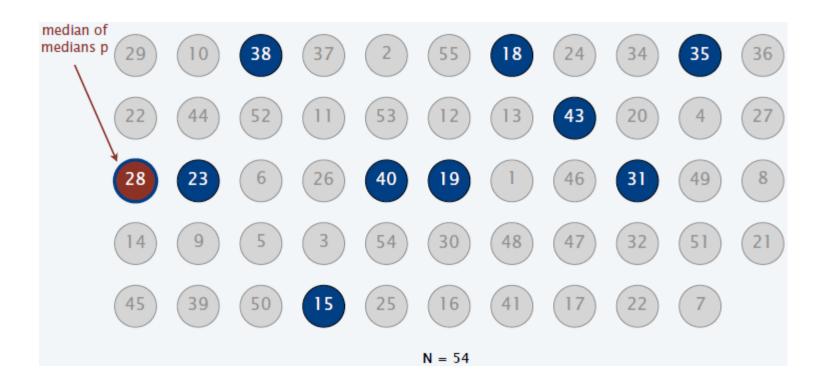
 $p \leftarrow \text{MoM-Select (B, } \lfloor n/10 \rfloor)$. \leftarrow median of medians

 $(L, M, R) \leftarrow \text{Partition-3-Way } (A, p).$ if $k \leq |L|$ Return MoM-Select (L, k). else if k > |L| + |M| Return MoM-Select (R, k - |L| - |M|). else Return p.



Analysis of Median-of-Medians Selection Algorithm

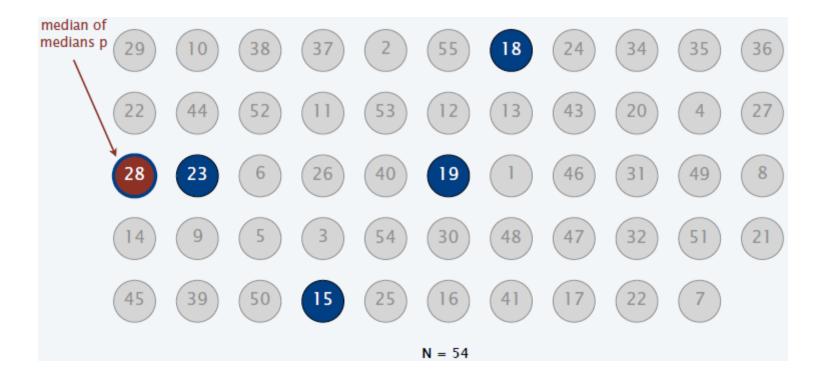
• At least half of 5-element medians $\leq p$.





Analysis of Median-of-Medians Selection Algorithm

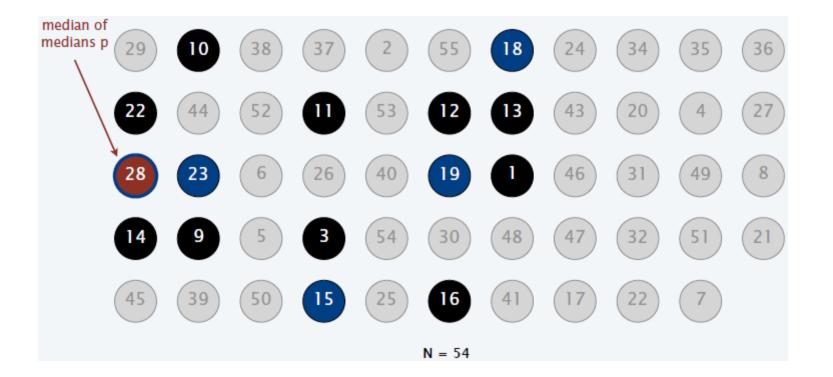
• At least half of 5-element medians $\leq p$. At least $|\lfloor n/5 \rfloor/2| = \lfloor n/10 \rfloor$ medians $\leq p$.





Analysis of Median-of-Medians Selection Algorithm

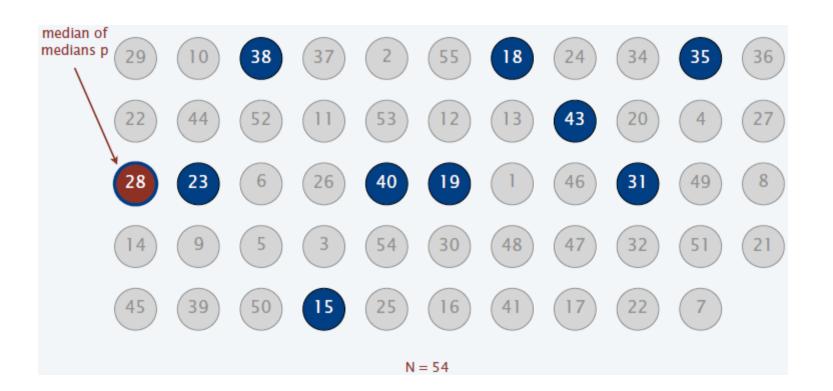
At least half of 5-element medians ≤ p.
 At least [[n/5]/2] = [n/10] medians ≤ p.
 At least 3[n/10] elements ≤ p.





Analysis of Median-of-Medians Selection Algorithm

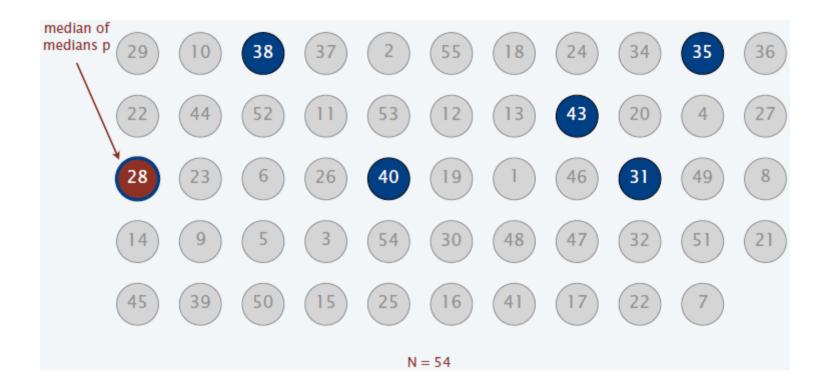
• At least half of 5-element medians $\geq p$.





Analysis of Median-of-Medians Selection Algorithm

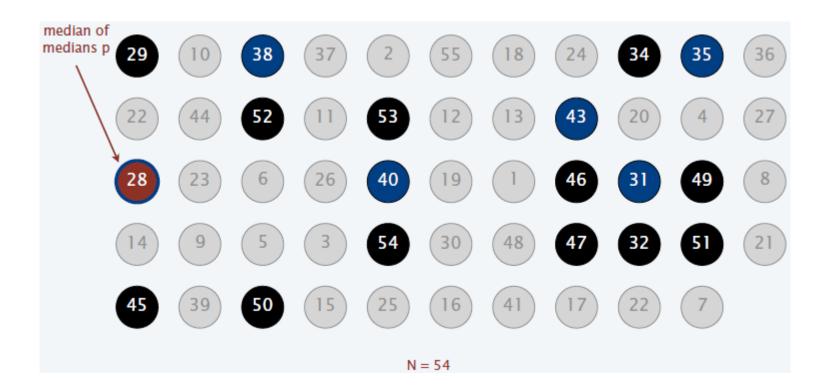
• At least half of 5-element medians $\geq p$. Symmetrically, at least $\lfloor n/10 \rfloor$ medians $\geq p$.





Analysis of Median-of-Medians Selection Algorithm

At least half of 5-element medians ≥ p.
 Symmetrically, at least [n/10] medians ≥ p.
 At least 3[n/10] elements ≥ p.





Median-of-Medians Selection Algorithm Recurrence

Median-of-medians selection algorithm recurrence.

- Select called recursively with $\lfloor n/5 \rfloor$ elements to compute MoM p.
- At least 3[n/10] elements $\leq p$.
- At least 3|n/10| elements $\geq p$.
- Select called recursively with at most n 3[n/10]elements.

Def. $T(n) = \max \#$ compares on an array of $\le n$ elements.

$$T(n) \le \begin{cases} 6n, & if \ n < 50 \\ T\left(\left\lfloor \frac{n}{5} \right\rfloor\right) + T\left(n - 3\left\lfloor \frac{n}{10} \right\rfloor\right) + \frac{11}{5}n, otherwise \end{cases}$$

median of recursive medians

select

computing median of 5 (6 compares per group) partitioning (n compares)



Median-of-Medians Selection Algorithm Recurrence

$$T(n) \le \begin{cases} 6n, & if \ n < 50 \\ T\left(\left\lfloor \frac{n}{5} \right\rfloor\right) + T\left(n - 3\left\lfloor \frac{n}{10} \right\rfloor\right) + \frac{11}{5}n, otherwise \end{cases}$$

Claim. $T(n) \leq 44n$.

- Base case: $T(n) \le 6n$ for n < 50 (Merge-Sort).
- Inductive hypothesis: assume true for 1,2,..., n-1.
- Inductive step: for $n \ge 50$, we have:

$$T(n) \le T\left(\left[\frac{n}{5}\right]\right) + T\left(n - 3\left[\frac{n}{10}\right]\right) + \frac{11}{5}n$$

$$\le 44\left(\left[\frac{n}{5}\right]\right) + 44\left(n - 3\left[\frac{n}{10}\right]\right) + \frac{11}{5}n$$

$$\le 44\left(\frac{n}{5}\right) + 44n - 44\left(\frac{n}{4}\right) + \frac{11}{5}n$$

$$= 44n.$$
for $n \ge 50, 3\left|\frac{n}{10}\right| \ge n/4$