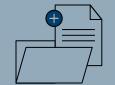


BATTLEBOTS DESIGN

Team 1!

Alex Carlson, Chuck Madueke, Kareena Patel, Javier Ramirez, Abhi Vedire, Elaine Williams



TA: Chris Hong



DESIGN PROCESS

RESEARCH



Interviews



Customer Needs Analysis



House of Quality



Online Resources

GOALS

- Cause substantial damage
- Outlast its competitors
- Exceptional mobility
- Achieve high speeds and also retain operability if flipped over
- Electronic and control systems are reliable but also intuitive, allowing drivers to adapt in dynamic situations
- Safety system with discernible hard stops and a kill switch for the electronics

IDEATION



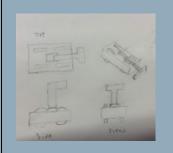
Morph. Matrix

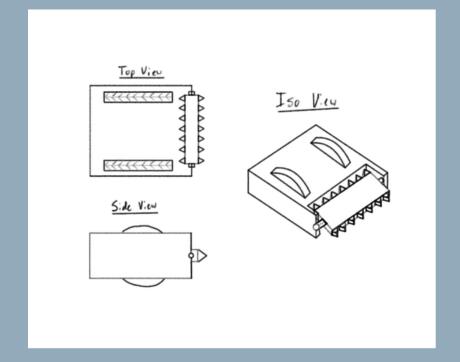


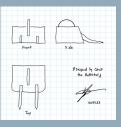
Pugh Chart



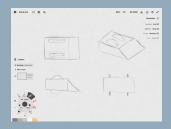
LEADING CONCEPT





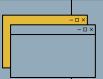








DESIGN CHOICES & REASONING



Component	Design Choice	Reasoning
Weapon	Spinning weapon	Easy to keep constantly spinning, easier to control and do not need to take time recharging
	Aluminum	Easy to machine (mill)
	Steel screws on perimeter of weapon for strength & durability	Impact zone now on the opposing robot
		Steel less likely to deform / can be replaced
		Screws increases moment of inertia → increased total rotational kinetic energy of weapon, providing 'bite' and can grab/flip opponents
	Use pulleys to change torque	Gears = direct impact = backlash = breaks teeth
		Instead, pulleys slips and absorbs any backlash



DESIGN CHOICES & REASONING

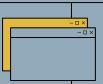


Component	Design Choice	Reasoning
Drive Train	Directly mounted	Saves space
		No gears
	Foam wheels	Wheels absorb impact instead of bouncing
		Lightweight → more weight into structural chassis
		Wheels are inside exterior frame in order to protect the wheels
	Drive motor into shaft	Outside axle connects to exterior chassis → wheels are supported by motor, axle is supported by outside bearing









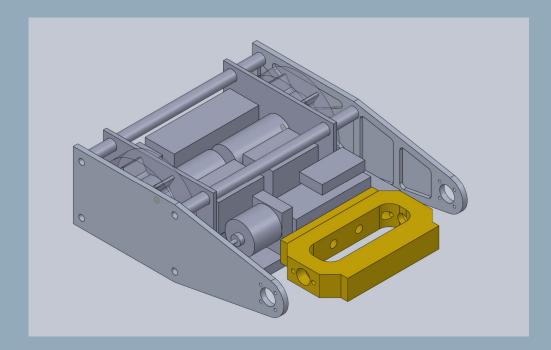
DESIGN CHOICES & REASONING

Component	Design Choice	Reasoning
Electronics	Lithium battery	Lightweight
	Brushless motor for weapon	More powerful, more speed
	2 brushed motors for drivetrain	Lower RPM
Chassis	CNC Aluminum side pieces	2 profile is easier to machine, no contours or 3D curves
	Standoffs	Rigid frame



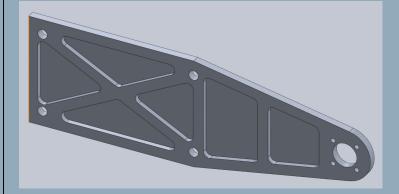


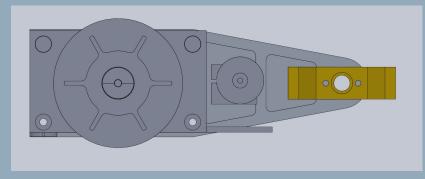
FINAL PROTOTYPE

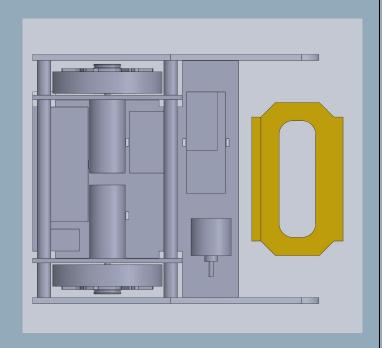




FINAL PROTOTYPE







X

Most interesting aspect: CNC Side Plates

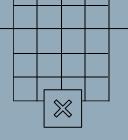
Started with 6061 aluminum 9"x4"x0.25"

- Faced down to 4.25mm thickness to save weight
- 2. Added holes for critical mounting points
- 3. Cleared pockets to reduce weight while maintaining structural integrity
- 4. Cut out outer geometry

2.7 oz final weight per side







+

THANK YOU



