

# C++ Performance optimization

Alexander Maslennikov

#### About the speaker

- Software Development Engineer at Intel
- Responsibilities: transforming a desktop performance profiler, named Intel® VTune™ Profiler, into a cloud service



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# Do you really need to tune your performance?

#### You don't need this if:

- You have no demand for higher performance
- You can afford to run your service on better HW

## Optimization criteria and stopping condition

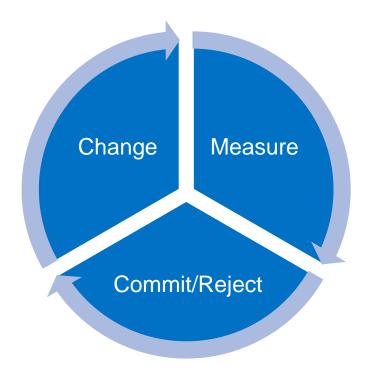
**Optimization criterion** is a metric by which you evaluate the performance of your workload

- Execution time
- Frame rate
- Throughput
- Latency

**Stopping condition** defines the optimization criteria value good enough to stop the process

- < 10s
- > 60 FPS
- etc.

#### **Optimization Process**



#### Start with baseline

Baseline measurement reflects the absolute best performance the solution is capable of exhibiting in its current state

**Break** when stopping condition is met

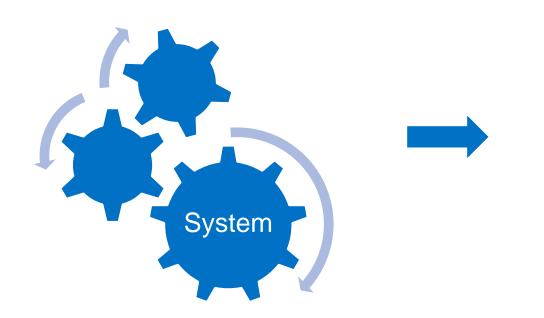


#### Build a solid baseline

- Use right compiler flags
  - Compile in release mode
  - Compile with optimization flags (O2 or O3 for gcc, icl, and msvc)
- Compile for the target CPU
  - Your target microarchitecture might have support of a more advanced instruction set
  - Benefit from Intel® Advanced Vector Extensions (Intel® AVX, AVX2, AVX-512)
  - march, -mtune, -mcpu
- Use optimized libraries



# What makes a good workload



#### Workload

- Measurable
- Reproducible
- Representative

## Ways to optimize performance and their impact

# Performance increase is unknown and might be huge

- Algorithmic optimization
- Design optimization

#### **Limited performance increase**

- Vectorization
- Parallelization
- Other microarchitecture optimizations



# Let's get down to business

### Sample application

- A small model of in-memory database
- Keeps data about employees:
  - Name
  - Position
  - Age
  - Salary
- Allows applying filters and getting results
- Holds 50 million records

# Sample application data flow

- 1. Client makes a request and provides filters
- 2. Registry, that holds all records, performs filtration
- 3. Filtered data is returned in JSON response

#### Sample workload

- Workload: filtering operations
- Performance metric: Queries per Second (QPS) (higher is better)
- Stopping condition: QPS > 30
- Instrumentation and Tracing technology (ITT) API is used for code instrumentation and extracting the workload from a system

#### **Baseline and setup**

- Intel® Xeon® Gold 6152 Processor
  - 22 cores, 2 sockets
  - Supports AVX-512
- 128GB RAM
- Intel® Compiler 19.0
- Baseline performance: 3.9 QPS



### Algorithmic optimization

- Choose algorithms of the best complexity and the most suitable
- Use libraries that contain algorithms optimized for target HW

### Design optimization

Revise code architecture and design to avoid performance bottlenecks

- Eliminate unnecessary copies
- Use async operations instead of active waits
- Use caching
- etc.



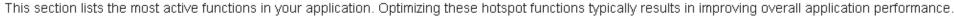
#### Hotspots

- Don't guess use a profiler
- Focus on unexpected hotspots
- Focus on large hotspots doesn't make sense to optimize insignificant hotspots
- Potential gain might be the most significant if algorithms aren't optimal



#### Top hotspots

#### Top Hotspots 🖆



Function	Module	CPU Time®
std::vector <filtering::employee, std::allocator<filtering::employee=""> &gt;::_Emplace_reallocate</filtering::employee,>	baseline.exe	5.122s
filtering::EmployeeRegistry::filter	baseline.exe	3.363s
func@0x1401be877	ntoskrnl.exe	1.909s
std::getline	baseline.exe	1.574s
filtering::EqualsFilter <class std::basic_string<char,struct="" std::char_traits<char="">,class std::allocator<char> &gt; &gt;::match</char></class>	baseline.exe	1.373s
[Others]		15.301s

#### Unexpectedly long copy operation – who calls?



### Design optimization

```
std::vector<Employee> EmployeeRegistry::filter(
    IFilter<std::string>::Ptr nameFilter,
   IFilter<std::string>::Ptr positionFilter,
    IFilter<int>::Ptr ageFilter,
    IFilter<float>::Ptr salaryFilter) const
    std::vector<Employee> result;
    std::copy if(
        m employees.begin(),
        m employees.end(),
        std::back inserter(result),
        [&](const Employee& employee)
       bool match = true;
        // Filtering stuff
        return match;
    });
    return result;
```

- Return a vector of Employee objects after filtration
- Copy filtered employees into result vector
- No space reservation for result vector

### Remove unnecessary copying

```
std::vector<size t> EmployeeRegistry::filter(
    IFilter<std::string>::Ptr nameFilter,
    IFilter<std::string>::Ptr positionFilter,
    IFilter<int>::Ptr ageFilter,
    IFilter<float>::Ptr salaryFilter) const
    std::vector<size t> result;
    result.reserve(m employees.size());
    for (size t i = 0; i < m employees.size(); i++)</pre>
        bool match = true;
        // Filtering stuff
       if (match) result.push back(i);
    return result;
```

- Return a vector of indices of filtered records in the main container
- Return a vector of all records in a separate method
- Performance after the change: 9.3 QPS
- $\frac{9.3 \ QPS}{3.9 \ QPS} \approx 2.38x$  performance gain against baseline

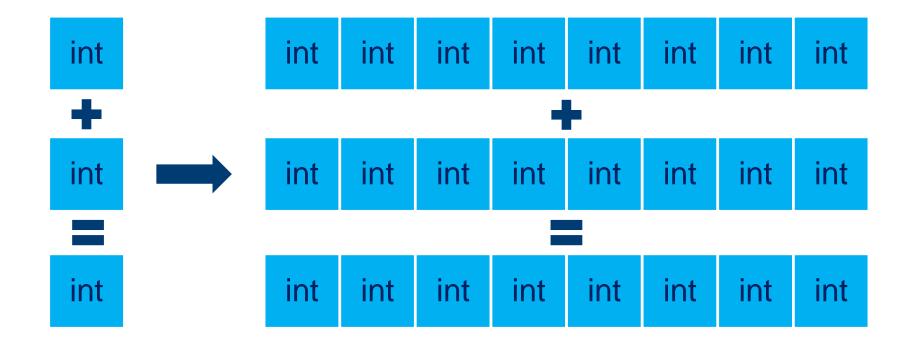
# Top hotspots after removing unnecessary copies

#### Expensive copy operation is not a top hotspot anymore

▶ filtering::EmployeeRegistry::filter	1.643s
▶ filtering::EqualsFilter <class std::basic_string<char,struct="" std::char_traits<char="">,class std::allocator<char> &gt; ::match</char></class>	0.665s <b></b>
▶ filtering::NotEqualsFilter <class std::basic_string<char,struct="" std::char_traits<char="">,class std::allocator<char> &gt; ::match</char></class>	0.554s <b></b>
▶ intel_fast_memcmp	0.542s
▶ filtering::GreaterFilter <int>::match</int>	0.283s 🔳
▶ filtering::LessFilter <float>::match</float>	0.198s 📕
▶ filtering::AnyFilter <float>::match</float>	0.196s 📕
▶ filtering::GreaterFilter <float>::match</float>	0.193s 🛢
▶ filtering::LessFilter <int>::match</int>	0.161s 🛢

Now top hotspots are simple filtering functions and it doesn't make sense to continue with algorithmic optimization

#### Vectorization



#### Vectorization boundaries

AVX-512 zmm register size

int	int	int	int	int	int	int	int	16x 32-bit int								
dou	ıble	dou	ble	dou	ıble	dou	ıble	8x 64-bit double								

### Vectorization report

Туре	Why No Vectorization?
Function	

No loops were detected in filtering functions

#### Before

```
std::vector<size t> EmployeeRegistry::filter(
    IFilter<std::string>::Ptr nameFilter,
    IFilter<std::string>::Ptr positionFilter,
    IFilter<int>::Ptr ageFilter,
    IFilter<float>::Ptr salaryFilter) const
    std::vector<size t> result;
    result.reserve(m employees.size());
    for (size_t i = 0; i < m employees.size(); i++)</pre>
        bool match = true;
        match &= nameFilter->match(m employees[i].name);
        match &= positionFilter->match(<u>m employees[i].position</u>);
        match &= ageFilter->match(m employees[i].age);
        match &= salaryFilter->match(m employees[i].salary);
        if (match) result.push back(i);
    return result;
```

```
template<class T>
class IFilter
{
    ...
    virtual bool match(const T& value) const = 0;
};

template<class T>
class EqualsFilter final : public ISingleValueFilter<T>
{
    ...
    bool match(const T& value) const override
    {
        return value == m_value;
    }
};
```

#### **After**

```
std::vector<size t> EmployeeRegistry::filter(
    IFilter<std::array<char, 32>>::Ptr nameFilter,
    IFilter<std::array<char, 32>>::Ptr positionFilter,
    IFilter<int>::Ptr ageFilter,
    IFilter<float>::Ptr salaryFilter) const
    std::vector<<u>char</u>> matched(m size, 1);
    nameFilter->match(m names, matched);
    positionFilter->match(m positions, matched);
    ageFilter->match(m ages, matched);
    salaryFilter->match(m salaries, matched);
    std::vector<size t> result;
    result.reserve(matched.size());
    for (size t i = 0; i < m names.size(); i++)</pre>
        if (matched[i]) result.push back(i);
    return result;
```

```
template<class T. class Filter>
void match(const std::vector<T>& values, std::vector<char>& result, Filter filter)
    const int valuesSize = values.size();
#pragma ivdep
#pragma vector always
   for (int i = 0; i < valuesSize; i++)</pre>
        result[i] = result[i] & filter(values[i]);
template<class Filter>
void match<std::array<char, 32>, Filter>(const std::vector<std::array<char, 32>>& values, std::vector<char>
& result, Filter filter)
    const char* pValues = reinterpret_cast<const char*>(values.data());
    int counter = 0;
    const int valuesSize = values.size();
   // Inner loop is already vectorized, no need for #pragma vector here
    for (int i = 0; i < valuesSize * 32; i += 32, counter++)</pre>
        result[counter] = result[counter] & filter(pValues + i);
template<>
class EqualsFilter<std::array<char, 32>> final : public ISingleValueFilter<std::array<char, 32>>
   void match(const std::vector<std::array<char, 32>>& values, std::vector<char>& result) const override
        filtering::match(values, result, [this](auto value)
            bool result = true:
#pragma ivdep
#pragma vector always
            for (int i = 0; i < 32; i++) if (value[i] != m value[i]) result = false;</pre>
            return result;
       });
```

#### Vectorization report

Туре	Why No Vectorization?
Function	
Function	
Function	
Scalar	a exception handling for a call prevents vectorization
Scalar	
Scalar	a exception handling for a call prevents vectorization
Scalar	
Vectorized (Body) Completely Unrolled	
Scalar	■ inner loop was already vectorized
Vectorized (Body)	
Scalar	inner loop was already vectorized
Vectorized (Body) Completely Unrolled	
	Function Function Function Scalar Vectorized (Body) Completely Unrolled Scalar Vectorized (Body)

All filter loops were vectorized and some were completely unrolled

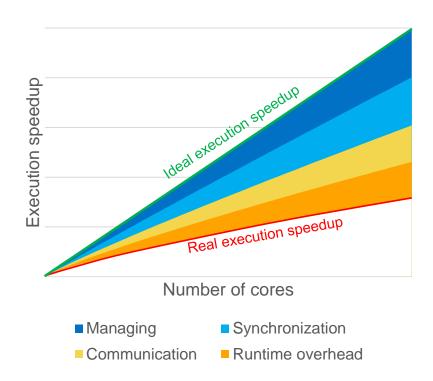


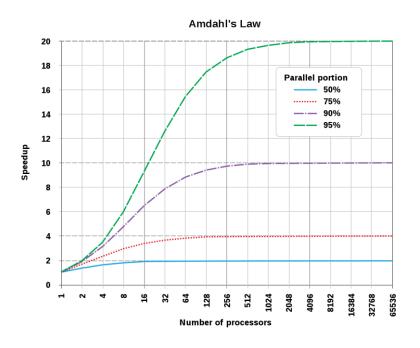
## Performance gain

- Performance after vectorization: 24.0 QPS
- 6.2x faster than the baseline
- ~2.6x faster than the previous step
- Still not good enough



# Parallel execution speedup

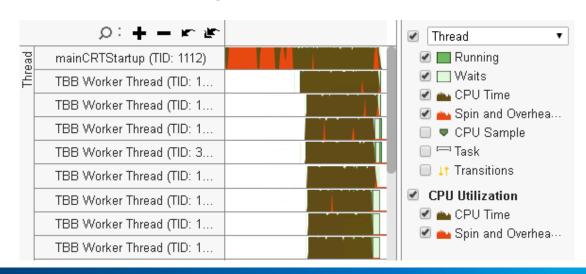




# Threading Building Blocks

```
#include <tbb/task_scheduler_init.h>
#include <tbb/task group.h>
tbb::task scheduler init();
tbb::task group group;
. . .
for (auto filter : filters)
    group.run([filter, &registry]
        ... // Initializing filters
        auto result = registry->filter(
            std::move(nameFilter),
            std::move(positionFilter),
            std::move(ageFilter),
            std::move(salaryFilter));
    });
group.wait();
```

- Performance: 130.5 QPS
- 33x faster than the baseline
- Stopping condition is met

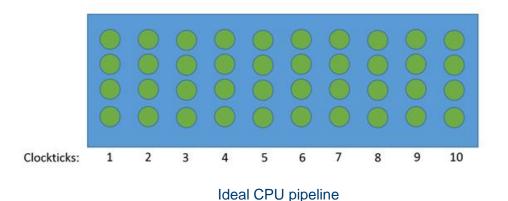


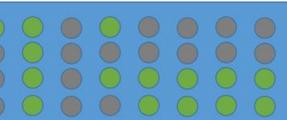
#### Bold attempt to parallelize baseline

- Performance: 5.2 QPS
- 25x slower than optimized code
- < 2x faster than the baseline</li>
- Optimization of the single thread performance is multiplied after parallelization

## uArch optimizations

- µArch performance gain is limited by ideal CPI (Clocks Per Instruction) of 0.25
- CPI does not depend on CPU frequency which may change

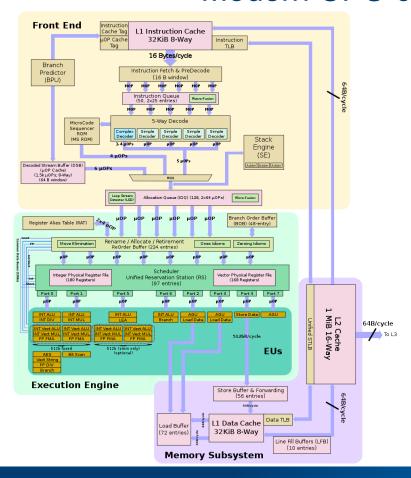




Clockticks: 1 2 3 4 5 6 7 8 9 10

Real CPU pipeline

#### Modern CPU core architecture

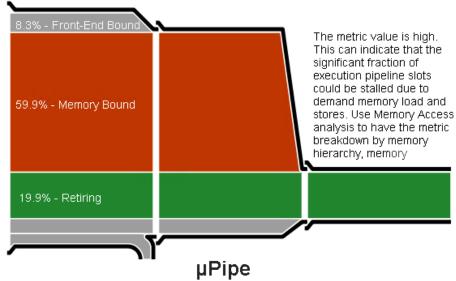


#### Why instructions might not retire:

- Front-end bound
- Back-end bound
- Bad speculation

### Microarchitecture efficiency

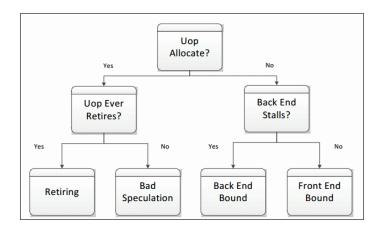
- CPI rate: 1.627
- > 50% of instruction are stalled due to demand of memory



This diagram represents inefficiencies in CPU usage. Treat it as a pipe with an output flow equal to the "pipe efficiency" ratio: (Actual Instructions Retired)/(Maximum Possible Instruction Retired). If there are pipeline stalls decreasing the pipe efficiency, the pipe shape gets more narrow.

## Dig deeper?

- Rewrite everything in assembly?
- Whatever you do measure the CPI (Clocks Per Instruction) (use Top-down approach and focus on execution problems)
- CPI in general is not actionable look for CPI of specific operations
- Only if you're desperate
- You're left behind when a new HW is released



Top-Down characterization

## Summary

- 1. Use optimized libraries
- 2. Get a solid baseline
- 3. Define optimization criterion for your workload
- 4. Profile your code
- 5. Fix your code design and algorithms first
- 6. Vectorize and parallelize
- 7. Help the compiler rather than go wild with assembly code

#### Useful links

- Sample project: <a href="https://github.com/AlexCombat/cpp-performance-optimization">https://github.com/AlexCombat/cpp-performance-optimization</a>
- Intel® VTune™ Profiler: <a href="https://software.intel.com/vtune">https://software.intel.com/vtune</a>
- Intel® Advisor: <a href="https://software.intel.com/advisor">https://software.intel.com/advisor</a>
- Intel® Threading Building Blocks: <a href="https://software.intel.com/tbb">https://software.intel.com/tbb</a>
- Top-down Microarchitecture Analysis Method: <u>https://software.intel.com/content/www/us/en/develop/documentation/vtune-cookbook/top/methodologies/top-down-microarchitecture-analysis-method.html</u>

