## Question 1. (8 points)

(a) Are the rules mutually exclusive?

Answer: No

(b) Is the rule set exhaustive?

Answer: Yes

(c) Is ordering needed for this set of rules?

Answer: Yes because a test instance may trigger more than one rule.

(d) Do you need a default class for the rule set?

Answer: No because every instance is guaranteed to trigger at least one rule.

 $P(-|A=0,B=1,C=0) = \frac{P(A=0,B=1,C=0|-) \times P(-)}{P(A=0,B=1,C=0)}$ 

 $= \frac{P(A=0|-) \times P(B=1|-) \times P(C=0|-) \times P(-)}{K} = \frac{0}{K}$ 

#### Question 2. (10 points)

(a)
$$P(A = 1|+) = 3/5 = 0.6,$$

$$P(A = 1|-) = 2/5 = 0.4,$$

$$P(A = 0|+) = 2/5 = 0.4,$$

$$P(A = 0|-) = 3/5 = 0.6,$$

$$P(B = 1|+) = 1/5 = 0.2,$$

$$P(B = 1|-) = 2/5 = 0.4,$$

$$P(B = 0|+) = 4/5 = 0.8,$$

$$P(B = 0|-) = 3/5 = 0.6,$$

$$P(C = 1|+) = 4/5 = 0.8,$$

$$P(C = 1|-) = 1,$$

$$P(C = 0|+) = 1/5 = 0.2.$$

$$P(C = 0|-) = 0;$$
(b)
$$Let P(A = 0, B = 1, C = 0) = K.$$

$$P(+|A = 0, B = 1, C = 0) = \frac{P(A = 0, B = 1, C = 0|+) \times P(+)}{P(A = 0, B = 1, C = 0)}$$

$$= \frac{P(A = 0|+)P(B = 1|+)P(C = 0|+) \times P(+)}{K}$$

$$= \frac{0.4 \times 0.2 \times 0.2 \times 0.5}{K} = \frac{0.008}{K}$$

The class label should be '+';

$$\begin{split} P(A=0|+) &= (2+2)/(5+4) = 4/9, \\ P(A=0|-) &= (3+2)/(5+4) = 5/9, \\ P(B=1|+) &= (1+2)/(5+4) = 3/9, \\ P(B=1|-) &= (2+2)/(5+4) = 4/9, \\ P(C=0|+) &= (3+2)/(5+4) = 5/9, \\ P(C=0|-) &= (0+2)/(5+4) = 2/9. \end{split}$$

(d)

Let 
$$P(A = 0, B = 1, C = 0) = K$$

$$P(+|A = 0, B = 1, C = 0)$$

$$= \frac{P(A = 0, B = 1, C = 0|+) \times P(+)}{P(A = 0, B = 1, C = 0)}$$

$$= \frac{P(A = 0|+)P(B = 1|+)P(C = 0|+) \times P(+)}{K}$$

$$= \frac{(4/9) \times (3/9) \times (5/9) \times 0.5}{K}$$

$$= 0.0412/K$$

$$\begin{split} &P(-|A=0,B=1,C=0)\\ =& \frac{P(A=0,B=1,C=0|-)\times P(-)}{P(A=0,B=1,C=0)}\\ =& \frac{P(A=0|-)\times P(B=1|-)\times P(C=0|-)\times P(-)}{K}\\ =& \frac{(5/9)\times (4/9)\times (2/9)\times 0.5}{K}\\ =& 0.0274/K \end{split}$$

The class label should be '+'.

(e)

When one of the conditional probabilities is zero, the estimate for conditional probabilities using the m-estimate probability approach is better, since we don't want the entire expression becomes zero.

### Question 3. (12 points)

(b) 
$$\begin{split} &|P(Engine=Bad,Air\ Cond=Broken)\\ &=\sum_{\alpha\beta}P(Engine=Bad,Air\ Cond=Broken,Mileage=\alpha,Value=\beta)\\ &=\sum_{\alpha\beta}P(Value=\beta|Engine=Bad,Air\ Cond=Broken)\\ &\times P(Engine=Bad|Mileage=\alpha)P(Mileage=\alpha)P(Air\ Cond=Broken)\\ &=0.1453. \end{split}$$

# Question 4. (8 points)

## (a)

1-nearest neighbor: +,

3-nearest neighbor: -,

5-nearest neighbor: +,

9-nearest neighbor: -.

## (b)

1-nearest neighbor: +,

3-nearest neighbor: +,

5-nearest neighbor: +,

9-nearest neighbor: +.

### Question 5. (12 points)

(a) Answer: 2

(b) Answer:  $E = \sum_{i}^{N} (y_i - x_i^w)^2$ 

(c) Answer:

Use the fact that  $\frac{dx^w}{dw} = x^w \log x$ 

$$\frac{dE}{dw} = -\sum_{i=1}^{N} 2(y_i - x_i^w) x_i^w \log x_i$$

$$= -2\sum_{i=1}^{N} \delta_i x_i^w \log x_i$$

where we write  $\delta_i = (y_i - x_i^w)$ 

So, the required update rule is:

$$w \leftarrow w + 2\alpha \sum_{i=1}^{N} \delta_i x_i^w \log x_i$$